

Ambient Light Transfer

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1 Data Structure Index

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4 Data Structure Documentation

4.1 Calibrate Class Reference

The Calibration Loop.

```
#include <calibrate.h>
```

Data Structures

- struct [params](#)
Configuration of [Calibrate](#) class.

Public Member Functions

- [Calibrate](#) ([Lightprobe](#) *p, [Lamps](#) *l, [params](#) c)
- [Calibrate](#) ([Lightprobe](#) *p, [Lamps](#) *l, string path, double rate)
- [~Calibrate](#) ()
- [params](#) getConfig ()
- void [runCaptureImpacts](#) ()
- void [runCalibrateLamps](#) ()

Private Attributes

- [params config](#)
- [Lightprobe * probe](#)
- [Lamps * lamps](#)

4.1.1 Detailed Description

The Calibration Loop.

Author

Manuel Jerger <nom@nomnom.de> The Calibration Loop for use with the webcam probe. Can also measure the response curve of our lighting system.

4.1.2 Constructor & Destructor Documentation

4.1.2.1 Calibrate::Calibrate (Lightprobe * *p*, Lamps * *l*, params *c*)

Author

Manuel Jerger <nom@nomnom.de>

The Calibration Loop for use with the webcam probe. Can also measure the response curve of our lighting system.

4.1.2.2 Calibrate::Calibrate (Lightprobe * *p*, Lamps * *l*, string *path*, double *rate*)

4.1.2.3 Calibrate::~~Calibrate ()

4.1.3 Member Function Documentation

4.1.3.1 Calibrate::params Calibrate::getConfig ()

4.1.3.2 void Calibrate::runCalibrateLamps ()

Run the Lamp-Calibration and calculate LED response using an image source and pre-recorded images.

4.1.3.3 void Calibrate::runCaptureImpacts ()

Run the calibration loop using the webcam.

4.1.4 Field Documentation

4.1.4.1 params Calibrate::config [private]

4.1.4.2 Lamps* Calibrate::lamps [private]

4.1.4.3 Lightprobe* Calibrate::probe [private]

The documentation for this class was generated from the following files:

- [src/calibrate.h](#)
- [src/calibrate.cpp](#)

4.2 Calibrate::params Struct Reference

Configuration of [Calibrate](#) class.

```
#include <calibrate.h>
```

Public Member Functions

- [params](#) ()

Data Fields

- string [dataDir](#)
- double [captureRate](#)

4.2.1 Detailed Description

Configuration of [Calibrate](#) class.

4.2.2 Constructor & Destructor Documentation

4.2.2.1 Calibrate::params::params () [inline]

4.2.3 Field Documentation

4.2.3.1 double Calibrate::params::captureRate

4.2.3.2 string Calibrate::params::dataDir

The documentation for this struct was generated from the following file:

- [src/calibrate.h](#)

4.3 circle Struct Reference

A circle.

```
#include <utils.h>
```

Public Member Functions

- [circle](#) (double [x](#), double [y](#), double [r](#))
- [circle](#) ()
- bool [isValid](#) ()

Data Fields

- double [x](#)
- double [y](#)
- double [r](#)

4.3.1 Detailed Description

A circle.

4.3.2 Constructor & Destructor Documentation

4.3.2.1 `circle::circle (double x, double y, double r)` `[inline]`

4.3.2.2 `circle::circle ()` `[inline]`

4.3.3 Member Function Documentation

4.3.3.1 `bool circle::isValid ()` `[inline]`

4.3.4 Field Documentation

4.3.4.1 `double circle::r`

4.3.4.2 `double circle::x`

4.3.4.3 `double circle::y`

The documentation for this struct was generated from the following file:

- [src/utlis.h](#)

4.4 dirCone Struct Reference

Stores the neighborhood of one sampling direction.

```
#include <utlis.h>
```

Public Member Functions

- [dirCone](#) ()

- [dirCone](#) (Vector3d dir)
- void [add](#) (Vector3d dir, Vector2i pixel, double weight)

Data Fields

- Vector3d [direction](#)
- [directions](#) dirs
- vector< Vector2i > [pixels](#)
- vector< double > [weights](#)
- double [weightSum](#)

4.4.1 Detailed Description

Stores the neighborhood of one sampling direction.

4.4.2 Constructor & Destructor Documentation

4.4.2.1 **dirCone::dirCone ()** [[inline](#)]

4.4.2.2 **dirCone::dirCone (Vector3d dir)** [[inline](#)]

4.4.3 Member Function Documentation

4.4.3.1 **void dirCone::add (Vector3d dir, Vector2i pixel, double weight)** [[inline](#)]

4.4.4 Field Documentation

4.4.4.1 **Vector3d dirCone::direction**

4.4.4.2 **directions dirCone::dirs**

4.4.4.3 **vector<Vector2i> dirCone::pixels**

4.4.4.4 **vector<double> dirCone::weights**

4.4.4.5 **double dirCone::weightSum**

The documentation for this struct was generated from the following file:

- [src/utlis.h](#)

4.5 Gui Class Reference

The user interface.

```
#include <gui.h>
```


Public Member Functions

- [Gui](#) ()
- [Gui](#) (int width, int height)
- [~Gui](#) ()
- void [start](#) (int width, int height)
- const void [drawLine](#) ([point](#) f, [point](#) t)
- const void [drawLine](#) (int x1, int y1, int x2, int y2)
- const void [drawBox](#) ([rect](#) box)
- const void [drawBox](#) (int x1, int y1, int x2, int y2)
- const void [drawCircle](#) ([circle](#) c)
- const void [drawCircle](#) ([circle](#) c, int x, int y)
- const void [drawCircleFilled](#) (int xpos, int ypos, int radius)
- const void [drawPoints](#) (vector< [Vector2i](#) >)
- const void [drawPoints](#) (vector< [Vector2i](#) >, int x, int y)
- const void [drawImage](#) (imglib::Image< float > &, int, int)
- const void [drawImage](#) (imglib::Image< float > &img, int xpos, int ypos, bool is-Linear)
- const void [drawCircularImage](#) (imglib::Image< float > &img, [circle](#), int x, int y)
- const void [drawCircularImage](#) (imglib::Image< float > &, [circle](#))
- const void [drawStickRGBGrid](#) ([Lamps](#) *, int x, int y, int w, int h, int space, bool)
- const void [drawMonochromeLamps](#) ([Lamps](#) *lamps, int x, int y, int box_width, int box_height, int space, bool vertical)
- const [circle](#) [runSphereSelection](#) ([Source](#) *)
- const [point](#) [runPixelSelection](#) ([Source](#) *)

4.5.1 Detailed Description

The user interface.

Author

Manuel Jerger <nom@nomnom.de>

The graphic user interface. Uses OpenGL via the glfw abstraction layer.

4.5.2 Constructor & Destructor Documentation

4.5.2.1 [Gui::Gui](#) () [[inline](#)]

4.5.2.2 [Gui::Gui](#) (int *width*, int *height*)

4.5.2.3 [Gui::~~Gui](#) ()

4.5.3 Member Function Documentation

4.5.3.1 const void [Gui::drawBox](#) ([rect](#) *box*)

4.5.3.2 `const void Gui::drawBox (int x1, int y1, int x2, int y2)`

4.5.3.3 `const void Gui::drawCircle (circle c)`

4.5.3.4 `const void Gui::drawCircle (circle c, int x, int y)`

4.5.3.5 `const void Gui::drawCircleFilled (int xpos, int ypos, int radius)`

4.5.3.6 `const void Gui::drawCircularImage (imglib::Image< float > &img, circle area, int x, int y)`

4.5.3.7 `const void Gui::drawCircularImage (imglib::Image< float > &img, circle area)`

4.5.3.8 `const void Gui::drawImage (imglib::Image< float > &img, int xpos, int ypos)`

4.5.3.9 `const void Gui::drawImage (imglib::Image< float > &img, int xpos, int ypos, bool isLinear)`

4.5.3.10 `const void Gui::drawLine (point f, point t)`

4.5.3.11 `const void Gui::drawLine (int x1, int y1, int x2, int y2)`

4.5.3.12 `const void Gui::drawMonochromeLamps (Lamps * lamps, int x, int y, int box_width, int box_height, int space, bool vertical)`

Draw value of monochrome lamps as white rectangle.

4.5.3.13 `const void Gui::drawPoints (vector< Vector2i > points)`

4.5.3.14 `const void Gui::drawPoints (vector< Vector2i > points, int x, int y)`

4.5.3.15 `const void Gui::drawStickRGBGrid (Lamps * lamps, int x, int y, int box_width, int box_height, int space, bool vertical)`

Draw the lamp's RGB values as a table of rectangles

Parameters

<i>x</i>	Top left position inside window.
<i>y</i>	Top left position inside window.
<i>box_width</i>	Width of rectangle.
<i>box_height</i>	Height of rectangle.
<i>space</i>	Spacing between rectangles.
<i>vertical</i>	Orientation

4.5.3.16 `const point Gui::runPixelSelection (Source * source)`

Displays images acquired from source and asks user to select a pixel / 2D coordinate.

Parameters

<i>source</i>	Image source.
---------------	---------------

Returns

The pixel position.

4.5.3.17 `const circle Gui::runSphereSelection (Source * source)`

Displays images acquired from source and asks user to select a sphere by clicking three points on the border of a circle.

Parameters

<i>source</i>	Image source.
---------------	---------------

Returns

The parameters of the circle.

4.5.3.18 `void Gui::start (int width, int height)`

Start the GUI with a specified window size. Sets up OpenGL and displays the window.

Parameters

<i>width</i>	Width of window in pixel.
<i>height</i>	Height of window in pixel.

The documentation for this class was generated from the following files:

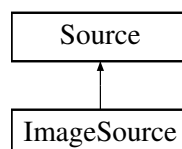
- [src/gui.h](#)
- [src/gui.cpp](#)

4.6 ImageSource Class Reference

[Source](#) that uses image files.

```
#include <imagesource.h>
```

Inheritance diagram for ImageSource:



Data Structures

- struct [params](#)
Configuration of the [ImageSource](#) class.

Public Member Functions

- [ImageSource](#) ([params](#) c)
- [~ImageSource](#) ()
- [params getConfig](#) ()
- bool [hasNewData](#) ()
- void [acquire](#) ()

Private Attributes

- [params config](#)
- int [curlImageID](#)

4.6.1 Detailed Description

[Source](#) that uses image files.

Author

Manuel Jerger <nom@nomnom.de>

Specialization of the source class that uses image files. Loads either a single image file or a whole sequence of frames from a directory.

4.6.2 Constructor & Destructor Documentation

4.6.2.1 ImageSource::ImageSource (params c)

Author

Manuel Jerger <nom@nomnom.de>

Specialization of the source class that uses image files. Loads either a single image file or a whole sequence of frames from a directory. Constructor checks if config specifies a single image (ending in .ppm) or a directory. It then loads the first image to check for the dimensions.

4.6.2.2 ImageSource::~ImageSource () [inline]

4.6.3 Member Function Documentation

4.6.3.1 void ImageSource::acquire () [virtual]

Loads either a single image or a whole directory of frames. The latter one requires the files to be named img_#.ppm where # is a number w/o trailing zeroes.

Implements [Source](#).

4.6.3.2 ImageSource::params ImageSource::getConfig ()

4.6.3.3 bool ImageSource::hasNewData () [virtual]

Implements [Source](#).

4.6.4 Field Documentation

4.6.4.1 params ImageSource::config [private]

4.6.4.2 int ImageSource::curlImageID [private]

The documentation for this class was generated from the following files:

- [src/imagesource.h](#)
- [src/imagesource.cpp](#)

4.7 ImageSource::params Struct Reference

Configuration of the [ImageSource](#) class.

```
#include <imagesource.h>
```

Public Member Functions

- [params](#) ()

Data Fields

- string [imagePath](#)

4.7.1 Detailed Description

Configuration of the [ImageSource](#) class.

4.7.2 Constructor & Destructor Documentation

4.7.2.1 ImageSource::params::params () [inline]

4.7.3 Field Documentation

4.7.3.1 string ImageSource::params::imagePath

The documentation for this struct was generated from the following file:

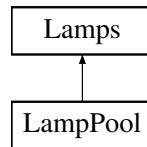
- [src/imagesource.h](#)

4.8 LampPool Class Reference

Groups instances of [Lamps](#).

```
#include <lamppool.h>
```

Inheritance diagram for LampPool:



Public Member Functions

- [LampPool](#) ()
- [~LampPool](#) ()
- int [getNumLamps](#) ()
- void [setValue](#) (int, double)
- double [getValue](#) (int)
- void [setAll](#) (double)
- bool [doStep](#) (double delta_t)
- void [setFadeSpeed](#) (double speed)
- void [setUpdateRate](#) (double rate)
- void [start](#) ()
- void [stop](#) ()
- bool [isReady](#) ()
- bool [send](#) ()
- int [getNumMembers](#) ()
- [Lamps](#) * [getMember](#) (int m)
- void [addMember](#) ([Lamps](#) *lamps)

Private Member Functions

- int [getMemberForLampIndex](#) (int)
- int [getMappedLampIndex](#) (int)

Private Attributes

- vector< [Lamps](#) * > [members](#)

4.8.1 Detailed Description

Groups instances of [Lamps](#).

4.8.2 Constructor & Destructor Documentation

4.8.2.1 LampPool::LampPool ()

Author

Manuel Jerger <nom@nomnom.de>

This class represents a pool of lamps. It controls multiple [Lamps](#) classes and behaves like a single lamp class.

4.8.2.2 LampPool::~~LampPool () [inline]

4.8.3 Member Function Documentation

4.8.3.1 void LampPool::addMember (Lamps * lamps)

4.8.3.2 bool LampPool::doStep (double delta_t) [virtual]

Does one fading step (if fadespeed > 0) and calls [send\(\)](#) at the end.

Reimplemented from [Lamps](#).

4.8.3.3 int LampPool::getMappedLampIndex (int lampID) [private]

4.8.3.4 Lamps * LampPool::getMember (int m)

4.8.3.5 int LampPool::getMemberForLampIndex (int lampID) [private]

4.8.3.6 int LampPool::getNumLamps () [virtual]

Reimplemented from [Lamps](#).

4.8.3.7 int LampPool::getNumMembers ()

4.8.3.8 double LampPool::getValue (int lampID) [virtual]

Return the current brightness of a single lamp.

Reimplemented from [Lamps](#).

4.8.3.9 `bool LampPool::isReady ()` [virtual]

Implements [Lamps](#).

4.8.3.10 `bool LampPool::send ()` [virtual]

Implements [Lamps](#).

4.8.3.11 `void LampPool::setAll (double brightness)` [virtual]

Set all lamps to the specified brightness.

Reimplemented from [Lamps](#).

4.8.3.12 `void LampPool::setFadeSpeed (double speed)` [virtual]

Reimplemented from [Lamps](#).

4.8.3.13 `void LampPool::setUpdateRate (double rate)` [virtual]

Reimplemented from [Lamps](#).

4.8.3.14 `void LampPool::setValue (int lampID, double brightness)` [virtual]

Sets the brightness of a lamp. If fading is enabled, it sets the target fade-to value.

Reimplemented from [Lamps](#).

4.8.3.15 `void LampPool::start ()`

Starts fading thread for automatic updating and fading.

Reimplemented from [Lamps](#).

4.8.3.16 `void LampPool::stop ()`

Stops automatic updating.

Reimplemented from [Lamps](#).

4.8.4 Field Documentation

4.8.4.1 `vector<Lamps*> LampPool::members` [private]

The documentation for this class was generated from the following files:

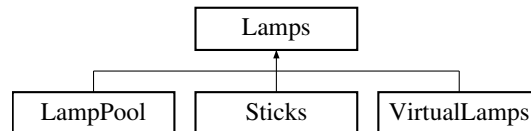
- [src/lamppool.h](#)
- [src/lamppool.cpp](#)

4.9 Lamps Class Reference

A monochrome lamp.

```
#include <lamps.h>
```

Inheritance diagram for Lamps:



Public Member Functions

- [Lamps](#) ()
- [~Lamps](#) ()
- virtual int [getNumLamps](#) ()
- virtual void [setValue](#) (int, double)
- virtual double [getValue](#) (int)
- virtual void [setAll](#) (double)
- void [start](#) ()
- void [stop](#) ()
- virtual bool [doStep](#) (double delta_t)
- virtual void [setFadeSpeed](#) (double speed)
- virtual void [setUpdateRate](#) (double rate)
- virtual bool [isReady](#) ()=0
- virtual bool [send](#) ()=0

Static Protected Member Functions

- static void * [start_thread](#) (void *ptr)

Protected Attributes

- bool [running](#)
- int [numLamps](#)
- vector< double > [lampValues](#)
- vector< double > [previousLampValues](#)
- vector< double > [lampTargetValues](#)
- double [fadeSpeed](#)
- double [updateRate](#)

4.9.1 Detailed Description

A monochrome lamp.

4.9.2 Constructor & Destructor Documentation

4.9.2.1 Lamps::Lamps ()

Author

Manuel Jerger <nom@nomnom.de>

This abstract class represents a group of lamps of identical type (controlled by the same hardware). A lamp is monochrome and takes a rational value from 0..1 , where 1.0 is the maximum brightness and 0 turns the lamp off. It provides virtuals for setting lamp values, driving the hardware, automatic fading. It provides threaded updating.

4.9.2.2 Lamps::~~Lamps ()

4.9.3 Member Function Documentation

4.9.3.1 bool Lamps::doStep (double *delta.t*) [virtual]

Does one fading step (if fadespeed > 0) and calls [send\(\)](#) at the end.

Reimplemented in [LampPool](#).

4.9.3.2 int Lamps::getNumLamps () [virtual]

Reimplemented in [LampPool](#).

4.9.3.3 double Lamps::getValue (int *lampID*) [virtual]

Return the current brightness of a single lamp.

Reimplemented in [LampPool](#).

4.9.3.4 virtual bool Lamps::isReady () [pure virtual]

Implemented in [Sticks](#), [LampPool](#), and [VirtualLamps](#).

4.9.3.5 virtual bool Lamps::send () [pure virtual]

Implemented in [Sticks](#), [LampPool](#), and [VirtualLamps](#).

4.9.3.6 void Lamps::setAll (double *brightness*) [virtual]

Set all lamps to the specified brightness.

Reimplemented in [LampPool](#).

4.9.3.7 void Lamps::setFadeSpeed (double *speed*) [virtual]

Reimplemented in [LampPool](#).

4.9.3.8 void Lamps::setUpdateRate (double *rate*) [virtual]

Reimplemented in [LampPool](#).

4.9.3.9 void **Lamps::setValue** (int *lampID*, double *brightness*) [virtual]

Sets the brightness of a lamp. If fading is enabled, it sets the target fade-to value.

Reimplemented in [LampPool](#).

4.9.3.10 void **Lamps::start** ()

Starts fading thread for automatic updating and fading.

Reimplemented in [LampPool](#).

4.9.3.11 void * **Lamps::start_thread** (void * *ptr*) [static, protected]

The updating thread.

4.9.3.12 void **Lamps::stop** ()

Stops automatic updating.

Reimplemented in [LampPool](#).

4.9.4 Field Documentation

4.9.4.1 double **Lamps::fadeSpeed** [protected]

4.9.4.2 vector<double> **Lamps::lampTargetValues** [protected]

4.9.4.3 vector<double> **Lamps::lampValues** [protected]

4.9.4.4 int **Lamps::numLamps** [protected]

4.9.4.5 vector<double> **Lamps::previousLampValues** [protected]

4.9.4.6 bool **Lamps::running** [protected]

4.9.4.7 double **Lamps::updateRate** [protected]

The documentation for this class was generated from the following files:

- [src/lamps.h](#)
- [src/lamps.cpp](#)

4.10 Lightprobe Class Reference

Our light probe model.

```
#include <lightprobe.h>
```

Data Structures

- struct [params](#)

Configuration of the light probe.

- struct [samplingParams](#)

Configures sampling.

Public Member Functions

- [Lightprobe](#) ([Source](#) *, [params](#) c, [samplingParams](#) sampling)
- [Lightprobe](#) ([Source](#) *, string configFile, [samplingParams](#) sampling)
- [Lightprobe](#) ([Source](#) *, [params](#) c, [samplingParams](#) sampling, [directions](#) sampling-Dirs)
- [~Lightprobe](#) ()
- [params](#) getConfig ()
- [samplingParams](#) getSamplingConfig ()
- [Source](#) * getSource ()
- void acquire ()
- [imglib::Image](#)< float > & getImage ()
- bool hasNewData ()
- void setRotationY (double rad)
- void precalculateDirectionPixelData ()
- void precalculateSamplingDirections ()
- void precalculateSamplingStructure ()
- void precalculateSamplingCones ()
- void precalculateSamplingNearestNeighbors ()
- void precalculateSamplingAllPixels ()
- [vector](#)< [rgb](#) > getImpact ()
- [vector](#)< [rgb](#) > getImpact ([imglib::Image](#)< float > &img)
- [Vector3d](#) getDirectionFromPixel ([Vector2i](#) pos)
- [Vector3d](#) getDirectionFromPixelDebevec ([Vector2i](#) pos)

Data Fields

- [vector](#)< [Vector2i](#) > allPixels
- [directions](#) allDirs
- [directions](#) samplingDirs
- [vector](#)< [dirCone](#) > samplingCones
- [vector](#)< bool > usedDirections

Private Member Functions

- void init ()

Private Attributes

- [params](#) [config](#)
- [samplingParams](#) [samplingConfig](#)
- [Source](#) * [source](#)
- [imglib::Image](#)< float > [maskImage](#)
- double [planeShift](#)

4.10.1 Detailed Description

Our light probe model.

4.10.2 Constructor & Destructor Documentation

4.10.2.1 **Lightprobe::Lightprobe (Source * *s*, params *c*, samplingParams *sampling*)**

Set up light probe model from a given model config and sampling config.

4.10.2.2 **Lightprobe::Lightprobe (Source * *s*, string *configFile*, samplingParams *sampling*)**

Set up light probe model using a given sampling configuration. Loads model config from file.

4.10.2.3 **Lightprobe::Lightprobe (Source * *s*, params *c*, samplingParams *sampling*, directions *samplingDirs*)**

Set up light probe model using a given sampling configuration and sampling directions. Loads model config from file.

4.10.2.4 **Lightprobe::~~Lightprobe ()**

4.10.3 Member Function Documentation

4.10.3.1 **void Lightprobe::acquire ()**4.10.3.2 **Lightprobe::params Lightprobe::getConfig ()**4.10.3.3 **Vector3d Lightprobe::getDirectionFromPixel (Vector2i *pos*)**

Our light probe model. Calculates the reflected light direction from pixel coordinates.

4.10.3.4 **Vector3d Lightprobe::getDirectionFromPixelDebevec (Vector2i *pos*)**

Light probe model that use the Debevec parametrisation.

4.10.3.5 **imglib::Image< float > & Lightprobe::getImage ()**

4.10.3.6 `vector< rgb > Lightprobe::getImpact ()`

Calculates the impact of a lamp: Acquires an image from the source, performs down-sampling and returns the sampled values.

4.10.3.7 `vector< rgb > Lightprobe::getImpact (imglib::Image< float > & img)`

Samples a light probe image.

4.10.3.8 `Lightprobe::samplingParams Lightprobe::getSamplingConfig ()`**4.10.3.9** `Source * Lightprobe::getSource ()`**4.10.3.10** `bool Lightprobe::hasNewData ()`**4.10.3.11** `void Lightprobe::init ()` [private]

Initializes the light probe model.

4.10.3.12 `void Lightprobe::precalculateDirectionPixelData ()`

Precalculates the direction of reflected light for all available, unmasked pixels within the sampling range.

4.10.3.13 `void Lightprobe::precalculateSamplingAllPixels ()`

Generates sampling structure for all-pixel sampling (every pixel becomes one direction).

4.10.3.14 `void Lightprobe::precalculateSamplingCones ()`

Generate sampling data structure for Gaussian sampling.

4.10.3.15 `void Lightprobe::precalculateSamplingDirections ()`

Precalculates the sampling directions.

4.10.3.16 `void Lightprobe::precalculateSamplingNearestNeighbors ()`

Generates sampling datastructure for nearest-neighbor sampling.

4.10.3.17 `void Lightprobe::precalculateSamplingStructure ()`

Generates the sampling data structure.

4.10.3.18 `void Lightprobe::setRotationY (double rad)`

Set new value for rotation around y axis (on planar plane) and recalculate sampling datastructures

4.10.4 Field Documentation

4.10.4.1 directions Lightprobe::allDirs

4.10.4.2 vector<Vector2i> Lightprobe::allPixels

4.10.4.3 params Lightprobe::config [private]

4.10.4.4 imglib::Image<float> Lightprobe::maskImage [private]

4.10.4.5 double Lightprobe::planeShift [private]

4.10.4.6 vector<dirCone> Lightprobe::samplingCones

4.10.4.7 samplingParams Lightprobe::samplingConfig [private]

4.10.4.8 directions Lightprobe::samplingDirs

4.10.4.9 Source* Lightprobe::source [private]

4.10.4.10 vector<bool> Lightprobe::usedDirections

The documentation for this class was generated from the following files:

- [src/lightprobe.h](#)
- [src/lightprobe.cpp](#)

4.11 Lightprobe::params Struct Reference

Configuration of the light probe.

```
#include <lightprobe.h>
```

Public Member Functions

- [params](#) ()
- void [load](#) (string file)
- void [save](#) (string file)

Data Fields

- double [camDistance](#)
- double [sphereRadius](#)
- [circle](#) [sphereCircle](#)
- double [gamma](#)
- [rgb](#) [whitepoint](#)
- double [exposure](#)
- Vector3d [rotation](#)
- double [horizonAngle](#)
- string [responseCurve](#)

- string [maskFile](#)
- int [type](#)

4.11.1 Detailed Description

Configuration of the light probe.

4.11.2 Constructor & Destructor Documentation

4.11.2.1 Lightprobe::params::params () `[inline]`

4.11.3 Member Function Documentation

4.11.3.1 void Lightprobe::params::load (string *file*)

Loads model config from a file.

4.11.3.2 void Lightprobe::params::save (string *file*)

Saves model config to a file.

4.11.4 Field Documentation

4.11.4.1 double Lightprobe::params::camDistance

4.11.4.2 double Lightprobe::params::exposure

4.11.4.3 double Lightprobe::params::gamma

4.11.4.4 double Lightprobe::params::horizonAngle

4.11.4.5 string Lightprobe::params::maskFile

4.11.4.6 string Lightprobe::params::responseCurve

4.11.4.7 Vector3d Lightprobe::params::rotation

4.11.4.8 circle Lightprobe::params::sphereCircle

4.11.4.9 double Lightprobe::params::sphereRadius

4.11.4.10 int Lightprobe::params::type

4.11.4.11 rgb Lightprobe::params::whitepoint

The documentation for this struct was generated from the following files:

- [src/lightprobe.h](#)
- [src/lightprobe.cpp](#)

4.12 Lightprobe::samplingParams Struct Reference

Configures sampling.

```
#include <lightprobe.h>
```

Public Types

- enum { [UNIFORM_OLD](#), [UNIFORM](#), [FROM_FILE](#), [ALLPIXELS](#) }
- enum { [NEIGHBOR](#), [GAUSS](#), [NONE](#) }

Public Member Functions

- [samplingParams](#) ()

Data Fields

- enum Lightprobe::samplingParams:: { ... } [samplingMode](#)
- int [numSamplesH](#)
- int [numSamplesA](#)
- int [numSamples](#)
- string [filename](#)
- enum Lightprobe::samplingParams:: { ... } [kernelMode](#)
- double [coneSize](#)
- double [coneSigma](#)
- int [minConeSize](#)

4.12.1 Detailed Description

Configures sampling.

4.12.2 Member Enumeration Documentation

4.12.2.1 anonymous enum

Enumerator:

UNIFORM_OLD

UNIFORM

FROM_FILE

ALLPIXELS

4.12.2.2 anonymous enum

Enumerator:

NEIGHBOR
GAUSS
NONE

4.12.3 Constructor & Destructor Documentation

4.12.3.1 `Lightprobe::samplingParams::samplingParams ()` `[inline]`

4.12.4 Field Documentation

4.12.4.1 `double Lightprobe::samplingParams::coneSigma`

4.12.4.2 `double Lightprobe::samplingParams::coneSize`

4.12.4.3 `string Lightprobe::samplingParams::filename`

4.12.4.4 `enum { ... } Lightprobe::samplingParams::kernelMode`

4.12.4.5 `int Lightprobe::samplingParams::minConeSize`

4.12.4.6 `int Lightprobe::samplingParams::numSamples`

4.12.4.7 `int Lightprobe::samplingParams::numSamplesA`

4.12.4.8 `int Lightprobe::samplingParams::numSamplesH`

4.12.4.9 `enum { ... } Lightprobe::samplingParams::samplingMode`

The documentation for this struct was generated from the following file:

- [src/lightprobe.h](#)

4.13 Log Class Reference

A simple logger.

```
#include <utils.h>
```

Public Member Functions

- [Log](#) ()
- virtual [~Log](#) ()
- `ostream& log` (int lvl)
- `ostream& msg` ()
- `ostream& err` ()

Private Attributes

- ostreamstream [ss](#)
- int [level](#)

4.13.1 Detailed Description

A simple logger.

4.13.2 Constructor & Destructor Documentation

4.13.2.1 **Log::Log ()** [[inline](#)]

4.13.2.2 **Log::~~Log ()** [[virtual](#)]

4.13.3 Member Function Documentation

4.13.3.1 **std::ostream & Log::err ()**

4.13.3.2 **std::ostream & Log::log (int lvl)**

4.13.3.3 **std::ostream & Log::msg ()**

4.13.4 Field Documentation

4.13.4.1 **int Log::level** [[private](#)]

4.13.4.2 **ostreamstream Log::ss** [[private](#)]

The documentation for this class was generated from the following files:

- [src/utlis.h](#)
- [src/utlis.cpp](#)

4.14 MaxExposure Class Reference

Adjusts the Exposure of a UVC webcam.

```
#include <maxexposure.h>
```

Public Member Functions

- [MaxExposure](#) ([Source](#) *s)
- [~MaxExposure](#) ()
- void [run](#) ()
- int [getExposure](#) ()
- void [setExposure](#) (int)

Private Attributes

- `Source * source`
- `int exposure`

Static Private Attributes

- `static const string videoDevice = "/dev/video0"`

4.14.1 Detailed Description

Adjusts the Exposure of a UVC webcam.

Author

Manuel Jerger <nom@nomnom.de>

For maximizing the exposure of an UVC controlled webcam.

4.14.2 Constructor & Destructor Documentation

4.14.2.1 `MaxExposure::MaxExposure (Source * s)`

4.14.2.2 `MaxExposure::~~MaxExposure ()` [inline]

4.14.3 Member Function Documentation

4.14.3.1 `int MaxExposure::getExposure ()` [inline]

4.14.3.2 `void MaxExposure::run ()`

4.14.3.3 `void MaxExposure::setExposure (int exp)`

Set exposure on uvc video device.

4.14.4 Field Documentation

4.14.4.1 `int MaxExposure::exposure` [private]

4.14.4.2 `Source* MaxExposure::source` [private]

4.14.4.3 `const string MaxExposure::videoDevice = "/dev/video0"` [static, private]

Author

Manuel Jerger <nom@nomnom.de>

For maximizing the exposure of an UVC controlled webcam.

The documentation for this class was generated from the following files:

- [src/maxexposure.h](#)
- [src/maxexposure.cpp](#)

4.15 point Struct Reference

A point.

```
#include <utils.h>
```

Public Member Functions

- [point](#) (double [x](#), double [y](#))
- [point](#) ()

Data Fields

- double [x](#)
- double [y](#)

4.15.1 Detailed Description

A point.

4.15.2 Constructor & Destructor Documentation

4.15.2.1 `point::point (double x, double y)` [[inline](#)]

4.15.2.2 `point::point ()` [[inline](#)]

4.15.3 Field Documentation

4.15.3.1 `double point::x`

4.15.3.2 `double point::y`

The documentation for this struct was generated from the following file:

- [src/utils.h](#)

4.16 rect Struct Reference

A rectangle.

```
#include <utils.h>
```

Public Member Functions

- [rect](#) (double [x](#), double [y](#), double [w](#), double [h](#))
- [rect](#) ()
- bool [isValid](#) ()

Data Fields

- double [x](#)
- double [y](#)
- double [w](#)
- double [h](#)

4.16.1 Detailed Description

A rectangle.

4.16.2 Constructor & Destructor Documentation

4.16.2.1 `rect::rect (double x, double y, double w, double h)` [[inline](#)]

4.16.2.2 `rect::rect ()` [[inline](#)]

4.16.3 Member Function Documentation

4.16.3.1 `bool rect::isValid ()` [[inline](#)]

4.16.4 Field Documentation

4.16.4.1 `double rect::h`

4.16.4.2 `double rect::w`

4.16.4.3 `double rect::x`

4.16.4.4 `double rect::y`

The documentation for this struct was generated from the following file:

- [src/utils.h](#)

4.17 rgb Struct Reference

RGB color.

```
#include <utils.h>
```

Public Member Functions

- [rgb](#) ()
- [rgb](#) (double [r](#), double [g](#), double [b](#))
- [rgb](#) (vector< double > [vec](#))
- vector< double > [getVec](#) ()

Data Fields

- double [r](#)
- double [g](#)
- double [b](#)

4.17.1 Detailed Description

RGB color.

4.17.2 Constructor & Destructor Documentation

4.17.2.1 [rgb::rgb](#) () `[inline]`

4.17.2.2 [rgb::rgb](#) (double [r](#), double [g](#), double [b](#)) `[inline]`

4.17.2.3 [rgb::rgb](#) (vector< double > [vec](#)) `[inline]`

4.17.3 Member Function Documentation

4.17.3.1 [vector<double> rgb::getVec](#) () `[inline]`

4.17.4 Field Documentation

4.17.4.1 double [rgb::b](#)

4.17.4.2 double [rgb::g](#)

4.17.4.3 double [rgb::r](#)

The documentation for this struct was generated from the following file:

- [src/utils.h](#)

4.18 Sandbox Class Reference

A sandbox for experiments.

```
#include <sandbox.h>
```

Public Member Functions

- [Sandbox](#) ([Source](#) *s, [Lightprobe](#) *p, [Lamps](#) *l)
- [~Sandbox](#) ()
- void [run](#) ()

Private Attributes

- [Source](#) * [source](#)
- [Lightprobe](#) * [probe](#)
- [Lamps](#) * [lamps](#)

4.18.1 Detailed Description

A sandbox for experiments.

Author

Manuel Jerger <nom@nomnom.de>

[Sandbox](#) for experiments.

4.18.2 Constructor & Destructor Documentation

4.18.2.1 [Sandbox::Sandbox](#) ([Source](#) * s, [Lightprobe](#) * p, [Lamps](#) * l) [inline]

4.18.2.2 [Sandbox::~~Sandbox](#) () [inline]

4.18.3 Member Function Documentation

4.18.3.1 void [Sandbox::run](#) ()

Author

Manuel Jerger <nom@nomnom.de>

[Sandbox](#) for experiments.

4.18.4 Field Documentation

4.18.4.1 **Lamps*** `Sandbox::lamps` [private]4.18.4.2 **Lightprobe*** `Sandbox::probe` [private]4.18.4.3 **Source*** `Sandbox::source` [private]

The documentation for this class was generated from the following files:

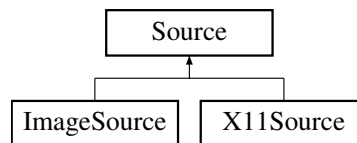
- [src/sandbox.h](#)
- [src/sandbox.cpp](#)

4.19 Source Class Reference

Acquires and linearizes images.

```
#include <source.h>
```

Inheritance diagram for Source:



Public Member Functions

- [Source](#) ()
- [~Source](#) ()
- [int getWidth](#) ()
- [int getHeight](#) ()
- [imglib::Image< float > & getImage](#) ()
- [void setResponseCurve](#) (string)
- [void setWhitepoint](#) (rgb wp)
- [void setExposure](#) (double exp)
- [virtual bool hasNewData](#) ()=0
- [virtual void acquire](#) ()=0
- [void start](#) ()
- [void stop](#) ()

Protected Types

- [enum { RESPONSE_LINEAR, RESPONSE_SRGB, RESPONSE_FILE }](#)

Protected Member Functions

- void [loadResponseCurve](#) (string filename)
- void [normalizeResponse](#) ()
- double [linearize](#) (double value, int channel)
- [imglib::Image](#)< float > & [linearize](#) ([imglib::Image](#)< float > &)

Static Protected Member Functions

- static void * [start_thread](#) (void *ptr)

Protected Attributes

- bool [running](#)
- bool [locked](#)
- [imglib::Image](#)< float > [imageBuffer](#)
- [imglib::Image](#)< float > [imageCopy](#)
- int [width](#)
- int [height](#)
- double [exposure](#)
- [rgb](#) whitepoint
- int [responseSize](#)
- double * [responseCurve](#) [3]
- enum [Source](#):: { ... } [responseType](#)
- double [updateRate](#)

4.19.1 Detailed Description

Acquires and linearizes images.

Author

Manuel Jerger <nom@nomnom.de>

The [Source](#) class acquires, linearizes and returns images. Supports threading.

4.19.2 Member Enumeration Documentation

4.19.2.1 anonymous enum [protected]

Enumerator:

RESPONSE_LINEAR
RESPONSE_SRGB
RESPONSE_FILE

4.19.3 Constructor & Destructor Documentation

4.19.3.1 Source::Source ()

Author

Manuel Jerger <nom@nomnom.de>

The [Source](#) class acquires, linearizes and returns images. Supports threading.

4.19.3.2 Source::~~Source ()

4.19.4 Member Function Documentation

4.19.4.1 virtual void Source::acquire () [pure virtual]

Implemented in [X11Source](#), and [ImageSource](#).

4.19.4.2 int Source::getHeight () [inline]

4.19.4.3 imglib::Image< float > & Source::getImage ()

4.19.4.4 int Source::getWidth () [inline]

4.19.4.5 virtual bool Source::hasNewData () [pure virtual]

Implemented in [X11Source](#), and [ImageSource](#).

4.19.4.6 double Source::linearize (double *value*, int *channel*) [protected]

Linearizes a single value using the supplied response curve and maps the white point.

4.19.4.7 imglib::Image< float > & Source::linearize (imglib::Image< float > & *A*) [protected]

Linearizes an image using the supplied response curve and maps the white point.

4.19.4.8 void Source::loadResponseCurve (string *filename*) [protected]

loads an three-channel response curve (either .m format created with hdrcalibrate, or a white-space separated three-column list)

4.19.4.9 void Source::normalizeResponse () [protected]

Normalizes the response curve so the image values fits in the range (0:1). The largest value of the three channels of the response curve is mapped to 1.0. The largest value at index 0 is mapped to zero, so we have no positive offset. All three channels are scaled with the same value to preserve the relative relation.

4.19.4.10 void Source::setExposure (double *exp*)4.19.4.11 void Source::setResponseCurve (string *reponseStr*)

4.19.4.12 void **Source::setWhitepoint**(*rgb wp*)

4.19.4.13 void **Source::start**()

4.19.4.14 void * **Source::start_thread**(void * *ptr*) [static, protected]

4.19.4.15 void **Source::stop**()

4.19.5 Field Documentation

4.19.5.1 double **Source::exposure** [protected]

4.19.5.2 int **Source::height** [protected]

4.19.5.3 *imglib::Image*<float> **Source::imageBuffer** [protected]

4.19.5.4 *imglib::Image*<float> **Source::imageCopy** [protected]

4.19.5.5 bool **Source::locked** [protected]

4.19.5.6 double* **Source::responseCurve**[3] [protected]

4.19.5.7 int **Source::responseSize** [protected]

4.19.5.8 enum { ... } **Source::responseType** [protected]

4.19.5.9 bool **Source::running** [protected]

4.19.5.10 double **Source::updateRate** [protected]

4.19.5.11 *rgb* **Source::whitepoint** [protected]

4.19.5.12 int **Source::width** [protected]

The documentation for this class was generated from the following files:

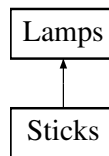
- [src/source.h](#)
- [src/source.cpp](#)

4.20 Sticks Class Reference

Our sticks lighting system.

```
#include <sticks.h>
```

Inheritance diagram for Sticks:



Data Structures

- struct [params](#)
Configuration of our lighting system.

Public Member Functions

- [Sticks](#) ([params config](#))
- [Sticks](#) (int segmentSize, string device, double rate)
- [~Sticks](#) ()
- [params getConfig](#) ()
- bool [hasRGBLamps](#) ()
- int [getNumRGBLamps](#) ()
- void [setRGBValue](#) (int lampID, [rgb](#))
- [rgb](#) [getRGBValue](#) (int lampID)
- void [setAllRGB](#) ([rgb](#))
- int [getNumSticks](#) ()
- int [getStickLength](#) (int lampID)
- void [setStickRGBValue](#) (int stickID, int lampID, [rgb](#))
- [rgb](#) [getStickRGBValue](#) (int stickID, int lampID)
- void [setStickChannelValue](#) (int stickID, int stickLampID, double val, int channel)
- void [setAllChannel](#) (double val, int channel)
- bool [isReady](#) ()
- bool [send](#) ()

Private Member Functions

- void [init](#) ()
- unsigned char [mapMono](#) (double brightness)

Private Attributes

- [params config](#)
- int [stripLengths](#) [8]
- int [maxStripLength](#)
- int [realStripLength](#)
- int [maxNumSegs](#)
- vector< unsigned char > [rawValues](#) [8][3]
- int [serialPort](#)

4.20.1 Detailed Description

Our sticks lighting system.

4.20.2 Constructor & Destructor Documentation

4.20.2.1 Sticks::Sticks (params *c*)

Author

Manuel Jerger <nom@nomnom.de>

This class represents our lighting system. Controls eight strips of 120 WS2812 LEDs via the Teensy microcontroller over the serial port. LEDs on a strip are segmented into a equal sized patches.

4.20.2.2 Sticks::Sticks (int *segmentSize*, string *device*, double *rate*)

4.20.2.3 Sticks::~~Sticks ()

4.20.3 Member Function Documentation

4.20.3.1 Sticks::params Sticks::getConfig ()

4.20.3.2 int Sticks::getNumRGBLamps ()

4.20.3.3 int Sticks::getNumSticks ()

4.20.3.4 rgb Sticks::getRGBValue (int *lampID*)

4.20.3.5 int Sticks::getStickLength (int *lampID*)

4.20.3.6 rgb Sticks::getStickRGBValue (int *stickID*, int *lampID*)

4.20.3.7 bool Sticks::hasRGBLamps ()

4.20.3.8 void Sticks::init () [private]

4.20.3.9 bool Sticks::isReady () [inline, virtual]

Implements [Lamps](#).

4.20.3.10 unsigned char Sticks::mapMono (double *brightness*) [private]

4.20.3.11 bool Sticks::send () [virtual]

Implements [Lamps](#).

4.20.3.12 void Sticks::setAllChannel (double *val*, int *channel*)

4.20.3.13 void Sticks::setAllRGB (rgb *color*)

4.20.3.14 void Sticks::setRGBValue (int *lampID*, rgb *color*)

4.20.3.15 void Sticks::setStickChannelValue (int *stickID*, int *stickLampID*, double *val*, int *channel*)

4.20.3.16 void Sticks::setStickRGBValue (int *stickID*, int *lampID*, rgb *color*)

4.20.4 Field Documentation

4.20.4.1 params Sticks::config [private]

4.20.4.2 int Sticks::maxNumSegs [private]

4.20.4.3 int Sticks::maxStripLength [private]

4.20.4.4 vector<unsigned char> Sticks::rawValues[8][3] [private]

4.20.4.5 int Sticks::realStripLength [private]

4.20.4.6 int Sticks::serialPort [private]

4.20.4.7 int Sticks::stripLengths[8] [private]

The documentation for this class was generated from the following files:

- [src/sticks.h](#)
- [src/sticks.cpp](#)

4.21 Sticks::params Struct Reference

Configuration of our lighting system.

```
#include <sticks.h>
```

Public Member Functions

- [params](#) ()
- void [load](#) (string file)

Data Fields

- int [segmentSize](#)
- int [numSticks](#)
- int [stickSize](#)
- double [fadeSpeed](#)
- string [serialDevice](#)
- double [updateRate](#)

4.21.1 Detailed Description

Configuration of our lighting system.

4.21.2 Constructor & Destructor Documentation

4.21.2.1 Sticks::params::params () [inline]

4.21.3 Member Function Documentation

4.21.3.1 void Sticks::params::load (string file)

4.21.4 Field Documentation

4.21.4.1 double Sticks::params::fadeSpeed

4.21.4.2 int Sticks::params::numSticks

4.21.4.3 int Sticks::params::segmentSize

4.21.4.4 string Sticks::params::serialDevice

4.21.4.5 int Sticks::params::stickSize

4.21.4.6 double Sticks::params::updateRate

The documentation for this struct was generated from the following files:

- src/[sticks.h](#)
- src/[sticks.cpp](#)

4.22 TestLamps Class Reference

Test lamps (for debug).

```
#include <testlamps.h>
```

Public Member Functions

- [TestLamps](#) ([Lamps](#) *l, [Source](#) *s)
- [~TestLamps](#) ()
- void [run](#) ()

Private Attributes

- [Lamps](#) * [lamps](#)
- [Source](#) * [source](#)

4.22.1 Detailed Description

Test lamps (for debug).

Author

Manuel Jerger <nom@nomnom.de>

Old class for testing and debugging the lamps.

4.22.2 Constructor & Destructor Documentation

4.22.2.1 TestLamps::TestLamps (Lamps * l, Source * s) [inline]

4.22.2.2 TestLamps::~~TestLamps ()

Author

Manuel Jerger <nom@nomnom.de>

Old class for testing and debugging the lamps.

4.22.3 Member Function Documentation

4.22.3.1 void TestLamps::run ()

4.22.4 Field Documentation

4.22.4.1 Lamps* TestLamps::lamps [private]

4.22.4.2 Source* TestLamps::source [private]

The documentation for this class was generated from the following files:

- [src/testlamps.h](#)
- [src/testlamps.cpp](#)

4.23 TestProbe Class Reference

Test light probe (for debug).

```
#include <testprobe.h>
```

Public Member Functions

- [TestProbe](#) ([Lightprobe](#) *p)
- [~TestProbe](#) ()
- void [run](#) ()

Private Attributes

- [Lightprobe](#) * [probe](#)

4.23.1 Detailed Description

Test light probe (for debug).

Author

Manuel Jerger <nom@nomnom.de>

Old class for testing and debugging the probe.

4.23.2 Constructor & Destructor Documentation

4.23.2.1 `TestProbe::TestProbe (Lightprobe * p)` `[inline]`

4.23.2.2 `TestProbe::~TestProbe ()`

Author

Manuel Jerger <nom@nomnom.de>

Old class for testing and debugging the probe.

4.23.3 Member Function Documentation

4.23.3.1 `void TestProbe::run ()`

4.23.4 Field Documentation

4.23.4.1 `Lightprobe* TestProbe::probe` `[private]`

The documentation for this class was generated from the following files:

- [src/testprobe.h](#)
- [src/testprobe.cpp](#)

4.24 Transfer Class Reference

The Ambient Light [Transfer](#) loop.

```
#include <transfer.h>
```

Data Structures

- class [CostSimple](#)
Faster CostFunction for ceres.
- struct [params](#)
Configuration.
- struct [Residual](#)
CostFunction for ceres.

Public Member Functions

- [Transfer](#) ([Lightprobe](#) *p, [Lamps](#) *l, [params](#) c)
- [~Transfer](#) ()
- [params](#) getConfig ()
- void [run](#) ()
- void [repaint](#) ()
- void [exp_plot_kernel](#) (vector< [dirCone](#) > cones)

Private Member Functions

- void [createResults](#) (int)
- bool [loadImpactData](#) ()
- void [prepareDataCeres](#) ()
- void [runCeres](#) ()
- void [prepareDataCVXOPT](#) ()
- void [runCVXOPT](#) ()
- bool [toggleByKey](#) (bool var, int key)

Private Attributes

- [params](#) config
- [Lightprobe](#) * probe
- [Lightprobe](#) * caliProbe
- [Lamps](#) * lamps
- [Gui](#) * gui
- int numLamps
- int numDirs
- int numSamples
- int width
- int height
- int width_cali
- int height_cali
- vector< [imglib::Image](#)< float > > impactImages
- vector< [rgb](#) > maximumImpacts
- vector< vector< [rgb](#) > > lightImpacts

- vector< int > [samplingDirectionsNearestPixel](#)
- double [averageBrightness](#)
- imglib::Image< float > [targetImage](#)
- vector< rgb > [targetImpact](#)
- bool [scaleImpact](#)
- bool [lowPrecision](#)
- bool [resetWeights](#)
- double [targetScale](#)
- double * [weights](#)
- double * [targetData](#)
- double * [impactData](#)
- PyObject * [qpsolver](#)
- PyObject * [qpsolverArgs](#)
- PyObject * [qp_c](#)
- PyObject * [qp_Q](#)
- PyObject * [qp_A](#)
- PyObject * [qp_b](#)
- bool [drawTarget](#)
- int [drawSamplingCones](#)
- bool [drawPseudoResult](#)
- bool [drawPseudoResultCones](#)
- bool [drawDifference](#)
- bool [doAutoAdjust](#)
- double [drawScalingFactor](#)
- int [keyPressFlag](#)

4.24.1 Detailed Description

The Ambient Light [Transfer](#) loop.

4.24.2 Constructor & Destructor Documentation

4.24.2.1 [Transfer::Transfer](#) ([Lightprobe](#) * *p*, [Lamps](#) * *l*, [params](#) *c*)

Author

Manuel Jerger <nom@nomnom.de>

Implements the Ambient Light [Transfer](#) loop.

4.24.2.2 [Transfer::~~Transfer](#) ()

4.24.3 Member Function Documentation

4.24.3.1 void [Transfer::createResults](#) (int *iter*) [[private](#)]

Dump image results if config.output specifies a directory/prefix

4.24.3.2 void `Transfer::exp_plot_kernel` (vector< `dirCone` > *cones*)

Experimental: was used to analyze the reconstruction quality of the Gaussian sampling. Reconstructs a white image using the Sampling datastructure and dumps the image as well as values of horizontal slices.

4.24.3.3 params `Transfer::getConfig` ()

4.24.3.4 bool `Transfer::loadImpactData` () [private]

Loads the calibration data from config.dataDir and performs the sampling.

4.24.3.5 void `Transfer::prepareDataCeres` () [private]

Sets up Ceres as optimizer.

4.24.3.6 void `Transfer::prepareDataCVXOPT` () [private]

Prepares the CVXOPT optimizer. Creates all matrices and vectors.

4.24.3.7 void `Transfer::repaint` ()

Repaints the GUI.

4.24.3.8 void `Transfer::run` ()

Starts the Ambient Light [Transfer](#)

4.24.3.9 void `Transfer::runCeres` () [private]

Starts the optimization.

4.24.3.10 void `Transfer::runCVXOPT` () [private]

Starts the optimization

4.24.3.11 bool `Transfer::toggleByKey` (bool *var*, int *key*) [private]

Returns the inverted value of a boolean iff a key is pressed

4.24.4 Field Documentation

4.24.4.1 double `Transfer::averageBrightness` [private]

4.24.4.2 `Lightprobe*` `Transfer::caliProbe` [private]

4.24.4.3 params `Transfer::config` [private]

4.24.4.4 bool `Transfer::doAutoAdjust` [private]

4.24.4.5 bool `Transfer::drawDifference` [private]

- 4.24.4.6 `bool Transfer::drawPseudoResult` [private]
- 4.24.4.7 `bool Transfer::drawPseudoResultCones` [private]
- 4.24.4.8 `int Transfer::drawSamplingCones` [private]
- 4.24.4.9 `double Transfer::drawScalingFactor` [private]
- 4.24.4.10 `bool Transfer::drawTarget` [private]
- 4.24.4.11 `Gui* Transfer::gui` [private]
- 4.24.4.12 `int Transfer::height` [private]
- 4.24.4.13 `int Transfer::height_cali` [private]
- 4.24.4.14 `double* Transfer::impactData` [private]
- 4.24.4.15 `vector<imglib::Image<float>> Transfer::impactImages` [private]
- 4.24.4.16 `int Transfer::keyPressFlag` [private]
- 4.24.4.17 `Lamps* Transfer::lamps` [private]
- 4.24.4.18 `vector<vector<rgb>> Transfer::lightImpacts` [private]
- 4.24.4.19 `bool Transfer::lowPrecision` [private]
- 4.24.4.20 `vector<rgb> Transfer::maximumImpacts` [private]
- 4.24.4.21 `int Transfer::numDirs` [private]
- 4.24.4.22 `int Transfer::numLamps` [private]
- 4.24.4.23 `int Transfer::numSamples` [private]
- 4.24.4.24 `Lightprobe* Transfer::probe` [private]
- 4.24.4.25 `PyObject* Transfer::qp_A` [private]
- 4.24.4.26 `PyObject* Transfer::qp_b` [private]
- 4.24.4.27 `PyObject* Transfer::qp_c` [private]
- 4.24.4.28 `PyObject* Transfer::qp_Q` [private]
- 4.24.4.29 `PyObject* Transfer::qpsolver` [private]
- 4.24.4.30 `PyObject* Transfer::qpsolverArgs` [private]
- 4.24.4.31 `bool Transfer::resetWeights` [private]

- 4.24.4.32 `vector<int> Transfer::samplingDirectionsNearestPixel` [private]
- 4.24.4.33 `bool Transfer::scaleImpact` [private]
- 4.24.4.34 `double* Transfer::targetData` [private]
- 4.24.4.35 `imglib::Image<float> Transfer::targetImage` [private]
- 4.24.4.36 `vector<rgb> Transfer::targetImpact` [private]
- 4.24.4.37 `double Transfer::targetScale` [private]
- 4.24.4.38 `double* Transfer::weights` [private]
- 4.24.4.39 `int Transfer::width` [private]
- 4.24.4.40 `int Transfer::width_cali` [private]

The documentation for this class was generated from the following files:

- [src/transfer.h](#)
- [src/transfer.cpp](#)

4.25 Transfer::CostSimple Class Reference

Faster CostFunction for ceres.

Public Member Functions

- [~CostSimple](#) ()
- virtual bool [Evaluate](#) (double const *const *parameters, double *residuals, double **jacobians) const
- [CostSimple](#) (double [target](#), double *[samples](#))

Private Attributes

- double [target](#)
- double * [samples](#)

4.25.1 Detailed Description

Faster CostFunction for ceres.

4.25.2 Constructor & Destructor Documentation

4.25.2.1 Transfer::CostSimple::~~CostSimple () [inline]

4.25.2.2 **Transfer::CostSimple::CostSimple** (double *target*, double * *samples*)
[inline]

4.25.3 Member Function Documentation

4.25.3.1 **virtual bool Transfer::CostSimple::Evaluate** (double const *const * *parameters*,
double * *residuals*, double ** *jacobians*) const [inline, virtual]

4.25.4 Field Documentation

4.25.4.1 **double* Transfer::CostSimple::samples** [private]

4.25.4.2 **double Transfer::CostSimple::target** [private]

The documentation for this class was generated from the following file:

- [src/transfer.h](#)

4.26 Transfer::params Struct Reference

Configuration.

```
#include <transfer.h>
```

Public Types

- enum { [OPT](#), [SAMPLER](#) }

Public Member Functions

- [params](#) ()

Data Fields

- enum Transfer::params:: { ... } [algorithm](#)
- double [rate](#)
- string [dataDir](#)
- int [mode](#)
- string [output](#)
- double [targetScale](#)
- double [rampScaleFrom](#)
- double [rampScaleTo](#)
- double [rampScaleSteps](#)
- bool [dynamicFading](#)
- string [exec](#)
- bool [useUniform](#)
- int [numIterations](#)

- bool [useAverageScale](#)
- int [numRepeats](#)
- bool [driveSeparateColors](#)

4.26.1 Detailed Description

Configuration.

4.26.2 Member Enumeration Documentation

4.26.2.1 anonymous enum

Enumerator:

OPT

SAMPLER

4.26.3 Constructor & Destructor Documentation

4.26.3.1 Transfer::params::params () `[inline]`

4.26.4 Field Documentation

4.26.4.1 enum { ... } Transfer::params::algorithm

4.26.4.2 string Transfer::params::dataDir

4.26.4.3 bool Transfer::params::driveSeparateColors

4.26.4.4 bool Transfer::params::dynamicFading

4.26.4.5 string Transfer::params::exec

4.26.4.6 int Transfer::params::mode

4.26.4.7 int Transfer::params::numIterations

4.26.4.8 int Transfer::params::numRepeats

4.26.4.9 string Transfer::params::output

4.26.4.10 double Transfer::params::rampScaleFrom

4.26.4.11 double Transfer::params::rampScaleSteps

4.26.4.12 double Transfer::params::rampScaleTo

4.26.4.13 double Transfer::params::rate

4.26.4.14 `double Transfer::params::targetScale`

4.26.4.15 `bool Transfer::params::useAverageScale`

4.26.4.16 `bool Transfer::params::useUniform`

The documentation for this struct was generated from the following file:

- [src/transfer.h](#)

4.27 Transfer::Residual Struct Reference

CostFunction for ceres.

Public Member Functions

- [Residual](#) (double *_target*, int *_size*, double * *_data*)
- `template<typename T >`
`bool operator\(\) (const T *const weights, T *residuals) const`

Data Fields

- const double [target](#)
- const int [size](#)
- const double * [data](#)

4.27.1 Detailed Description

CostFunction for ceres.

4.27.2 Constructor & Destructor Documentation

4.27.2.1 `Transfer::Residual::Residual (double _target, int _size, double * _data)`
`[inline]`

4.27.3 Member Function Documentation

4.27.3.1 `template<typename T > bool Transfer::Residual::operator() (const T *const weights, T * residuals) const` `[inline]`

4.27.4 Field Documentation

4.27.4.1 `const double* Transfer::Residual::data`

4.27.4.2 `const int Transfer::Residual::size`

4.27.4.3 `const double Transfer::Residual::target`

The documentation for this struct was generated from the following file:

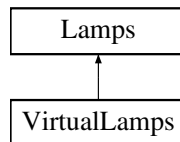
- [src/transfer.h](#)

4.28 VirtualLamps Class Reference

[Lamps](#) w/o hardware backend.

```
#include <virtuallamps.h>
```

Inheritance diagram for VirtualLamps:



Public Member Functions

- [VirtualLamps](#) (int [numLamps](#))
- [~VirtualLamps](#) ()
- bool [isReady](#) ()
- bool [send](#) ()

4.28.1 Detailed Description

[Lamps](#) w/o hardware backend.

4.28.2 Constructor & Destructor Documentation

4.28.2.1 `VirtualLamps::VirtualLamps (int numLamps)`

Author

Manuel Jerger <nom@nomnom.de>

This class represents a group of virtual monochrome lamps

4.28.2.2 `VirtualLamps::~~VirtualLamps ()` [inline]

4.28.3 Member Function Documentation

4.28.3.1 `bool VirtualLamps::isReady ()` [virtual]

Implements [Lamps](#).

4.28.3.2 `bool VirtualLamps::send () [virtual]`

Implements [Lamps](#).

The documentation for this class was generated from the following files:

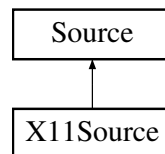
- [src/virtuallamps.h](#)
- [src/virtuallamps.cpp](#)

4.29 X11Source Class Reference

X11 desktop grabber.

```
#include <x11source.h>
```

Inheritance diagram for X11Source:



Data Structures

- struct [params](#)
Configuration of [X11Source](#).

Public Member Functions

- [X11Source](#) ([params](#) c)
- [X11Source](#) (string [display](#), [rect](#) area, double rate)
- [~X11Source](#) ()
- [params](#) getConfig ()
- void [acquire](#) ()
- bool [hasNewData](#) ()
- char * [getImageRaw](#) ()
- const [rect](#) [x11SelectAreaOnDesktop](#) (string [display](#))
- const [point](#) [x11SelectPointOnDesktop](#) (Display *disp)

Private Member Functions

- void [init](#) ()

Private Attributes

- [params](#) [config](#)
- string [display](#)
- Display * [dpy](#)
- XShmSegmentInfo [shminfo](#)
- XImage * [xImage](#)

4.29.1 Detailed Description

X11 desktop grabber.

Author

Manuel Jerger <nom@nomnom.de>

Specialization of the source class that grabs images from the X11 desktop.

4.29.2 Constructor & Destructor Documentation

4.29.2.1 **X11Source::X11Source** ([params](#) *c*)

4.29.2.2 **X11Source::X11Source** (string *display*, *rect area*, double *rate*)

4.29.2.3 **X11Source::~~X11Source** ()

4.29.3 Member Function Documentation

4.29.3.1 **void X11Source::acquire** () [virtual]

Grabs one image from desktop

Implements [Source](#).

4.29.3.2 **X11Source::params** **X11Source::getConfig** ()

4.29.3.3 **char *** **X11Source::getImageRaw** ()

Returns image data straight from X11 shared memory.

4.29.3.4 **bool X11Source::hasNewData** () [virtual]

Implements [Source](#).

4.29.3.5 **void X11Source::init** () [private]

Initialize X11 image grabbing.

4.29.3.6 `const rect X11Source::x11SelectAreaOnDesktop (string display)`

Asks the user to select two points on the desktop that define the top left and bottom right corner of the image area to grab.

4.29.3.7 `const point X11Source::x11SelectPointOnDesktop (Display * disp)`

Asks the user to select a points on the desktop. Uses X11 functions for displaying a cursor and reacting to the click.

4.29.4 Field Documentation

4.29.4.1 `params X11Source::config` [private]4.29.4.2 `string X11Source::display` [private]4.29.4.3 `Display* X11Source::dpy` [private]4.29.4.4 `XShmSegmentInfo X11Source::shminfo` [private]4.29.4.5 `XImage* X11Source::xImage` [private]

The documentation for this class was generated from the following files:

- [src/x11source.h](#)
- [src/x11source.cpp](#)

4.30 X11Source::params Struct Reference

Configuration of [X11Source](#).

```
#include <x11source.h>
```

Public Member Functions

- [params](#) ()

Data Fields

- string [x11Display](#)
- [rect captureArea](#)
- double [updateRate](#)

4.30.1 Detailed Description

Configuration of [X11Source](#).

4.30.2 Constructor & Destructor Documentation

4.30.2.1 `X11Source::params::params ()` `[inline]`

4.30.3 Field Documentation

4.30.3.1 `rect X11Source::params::captureArea`

4.30.3.2 `double X11Source::params::updateRate`

4.30.3.3 `string X11Source::params::x11Display`

The documentation for this struct was generated from the following file:

- [src/x11source.h](#)

5 File Documentation

5.1 `src/alt.cpp` File Reference

```
#include "alt.h"
```

Functions

- void [parseArgs](#) (int argc, char *argv[])
- void [segfaultHandler](#) (int sig)
- int [main](#) (int argc, char *argv[])

Variables

- int [progmode](#) = TRANSFER
- int [masterArg](#) = 0
- int [verbosity](#)
- [Calibrate::params](#) [caliConfig](#)
- [Transfer::params](#) [transferConfig](#)
- [Sticks::params](#) [sticksConfig](#)
- [X11Source::params](#) [x11sourceConfig](#)
- [ImageSource::params](#) [imagesourceConfig](#)
- [Lightprobe::params](#) [probeConfig](#)
- [Lightprobe::samplingParams](#) [samplingConfig](#)
- vector< pair< int, double > > [setLampsValues](#)
- [rgb](#) [setLampsRGB](#)
- string [setLampsFile](#)
- int [numVirtualLamps](#) = 0
- bool [useSticks](#) = false

- int [sourceType](#)
- bool [probeArgs](#) = false
- bool [stickArgs](#) = false
- static struct option [longOptions](#) []

5.1.1 Function Documentation

5.1.1.1 int main (int argc, char * argv[])

Program entry point.

Main() parses the command line arguments and sets up all our classes using the specified configurations. It then runs the specified program mode.

Parameters

<i>argc</i>	Number of arguments.
<i>argv</i>	Arguments

5.1.1.2 void parseArgs (int argc, char * argv[])

Parse command line arguments and set the program configuration accordingly.

Parameters

<i>argc</i>	Forwarded argc from main()
<i>argv</i>	Forwarded argv from main()

5.1.1.3 void segfaultHandler (int sig)

Add segfault handler and print a backtrace using backtrace() (a feature available in gcc)

Parameters

<i>sig</i>	signal number
------------	---------------

5.1.2 Variable Documentation

5.1.2.1 Calibrate::params caliConfig

5.1.2.2 ImageSource::params imagesourceConfig

5.1.2.3 struct option longOptions[] [static]

5.1.2.4 int masterArg = 0

5.1.2.5 int numVirtualLamps = 0

5.1.2.6 bool probeArgs = false

- 5.1.2.7 `Lightprobe::params probeConfig`
- 5.1.2.8 `int progmode = TRANSFER`
- 5.1.2.9 `Lightprobe::samplingParams samplingConfig`
- 5.1.2.10 `string setLampsFile`
- 5.1.2.11 `rgb setLampsRGB`
- 5.1.2.12 `vector<pair<int, double> > setLampsValues`
- 5.1.2.13 `int sourceType`
- 5.1.2.14 `bool stickArgs = false`
- 5.1.2.15 `Sticks::params sticksConfig`
- 5.1.2.16 `Transfer::params transferConfig`
- 5.1.2.17 `bool useSticks = false`
- 5.1.2.18 `int verbosity`

Author

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Utility functions and important datastructures.

- 5.1.2.19 `X11Source::params x11sourceConfig`

5.2 src/alt.h File Reference

```
#include "utils.h" #include "gui.h" #include "lamps.h" ×
#include "lamppool.h" #include "virtuallamps.h" #include
"sticks.h" #include "x11source.h" #include "lightprobe.-
h" #include "transfer.h" #include "calibrate.h" #include
"testlamps.h" #include "testprobe.h" #include "maxexposure.-
h" #include "sandbox.h" #include <iostream> #include <sstream> ×
#include <stdio.h> #include <string.h> #include <vector> ×
#include <Eigen/Core> #include <Eigen/Geometry> #include
<getopt.h> #include <X11/Xlib.h> #include <execinfo.h> ×
#include <signal.h>
```

Enumerations

- enum { `TRANSFER`, `TRANSFER_SAMPLER`, `CAPTURE`, `CALIBRATE_LAMP-`
`S`, `TESTLAMPS`, `TESTPROBE`, `SETLAMPS`, `MAX_EXPOSURE`, `SANDBOX`,
`SAMPLE_UNI_OLD`, `SAMPLE_UNI`, `SAMPLE_FILE`, `SAMPLE_ALL`, `X11SOU-`
`RCE`, `IMAGESOURCE`, `STICKS`, `VIRTUAL_LAMPS`, `LIGHTPROBE` }

5.2.1 Enumeration Type Documentation

5.2.1.1 anonymous enum

Enumerator:

TRANSFER
TRANSFER_SAMPLER
CAPTURE
CALIBRATE_LAMPS
TESTLAMPS
TESTPROBE
SETLAMPS
MAX_EXPOSURE
SANDBOX
SAMPLE_UNI_OLD
SAMPLE_UNI
SAMPLE_FILE
SAMPLE_ALL
X11SOURCE
IMAGESOURCE
STICKS
VIRTUAL_LAMPS
LIGHTPROBE

5.3 src/calibrate.cpp File Reference

```
#include "calibrate.h"
```

5.4 src/calibrate.h File Reference

```
#include "utils.h" #include "lamps.h" #include "lightprobe.-  
h" #include "gui.h" #include "ceres/ceres.h" #include  
<glog/logging.h>
```

Data Structures

- class [Calibrate](#)
The Calibration Loop.
- struct [Calibrate::params](#)
Configuration of [Calibrate](#) class.

5.5 src/gui.cpp File Reference

```
#include "gui.h"
```

5.6 src/gui.h File Reference

```
#include "utils.h" #include "lamps.h" #include "sticks.h"  
#include "image.h" #include "source.h" #include <unistd.-  
h> #include "GL/glFW.h" #include <GL/glu.h>
```

Data Structures

- class [Gui](#)

The user interface.

5.7 src/imagesource.cpp File Reference

```
#include "imagesource.h"
```

5.8 src/imagesource.h File Reference

```
#include "source.h" #include "image.h" #include <string>
```

Data Structures

- class [ImageSource](#)
Source that uses image files.
- struct [ImageSource::params](#)
Configuration of the [ImageSource](#) class.

5.9 src/lamppool.cpp File Reference

```
#include "lamppool.h"
```

5.10 src/lamppool.h File Reference

```
#include "lamps.h" #include "utils.h" #include <string>×  
#include <iostream> #include <vector> #include <pthread.-  
h> #include <time.h>
```

Data Structures

- class [LampPool](#)
Groups instances of [Lamps](#).

5.11 src/lamps.cpp File Reference

```
#include "lamps.h"
```

5.12 src/lamps.h File Reference

```
#include "utils.h" #include <vector>
```

Data Structures

- class [Lamps](#)
A monochrome lamp.

5.13 src/lightprobe.cpp File Reference

```
#include "lightprobe.h"
```

5.14 src/lightprobe.h File Reference

```
#include "utils.h" #include "source.h" #include "xllsource.-  
h" #include "imagesource.h" #include <iostream> #include  
<vector> #include <Eigen/Core> #include <Eigen/Geometry> x
```

Data Structures

- class [Lightprobe](#)
Our light probe model.
- struct [Lightprobe::params](#)
Configuration of the light probe.
- struct [Lightprobe::samplingParams](#)
Configures sampling.

5.15 src/maxexposure.cpp File Reference

```
#include "maxexposure.h"
```

5.16 src/maxexposure.h File Reference

```
#include "utils.h" #include "gui.h" #include "source.h" ×  
#include <unistd.h>
```

Data Structures

- class [MaxExposure](#)
Adjusts the Exposure of a UVC webcam.

5.17 src/sandbox.cpp File Reference

```
#include "sandbox.h"
```

5.18 src/sandbox.h File Reference

```
#include "utils.h" #include "gui.h" #include "source.-  
h" #include "lightprobe.h" #include "lamps.h" #include  
<unistd.h>
```

Data Structures

- class [Sandbox](#)
A sandbox for experiments.

5.19 src/source.cpp File Reference

```
#include "source.h"
```

Defines

- #define [FLOOR_NOISE_THRESHOLD](#) (0.000)
- #define [HIGHLIGHT_TRESHOLD](#) (0.9)

5.19.1 Define Documentation

5.19.1.1 #define [FLOOR_NOISE_THRESHOLD](#) (0.000)

5.19.1.2 #define [HIGHLIGHT_TRESHOLD](#) (0.9)

5.20 src/source.h File Reference

```
#include "utils.h"
```

Data Structures

- class [Source](#)
Acquires and linearizes images.

5.21 src/sticks.cpp File Reference

```
#include "sticks.h"
```

5.22 src/sticks.h File Reference

```
#include "lamps.h" #include "utils.h" #include <string>
#include <iostream> #include <stdlib.h> #include <unistd.-
h> #include <fcntl.h> #include <errno.h> #include <termios.-
h> #include <vector> #include <pthread.h> #include <time.-
h>
```

Data Structures

- class [Sticks](#)
Our sticks lighting system.
- struct [Sticks::params](#)
Configuration of our lighting system.

5.23 src/testlamps.cpp File Reference

```
#include "testlamps.h"
```

5.24 src/testlamps.h File Reference

```
#include "lamps.h" #include "source.h" #include "gui.h"
```

Data Structures

- class [TestLamps](#)
Test lamps (for debug).

5.25 src/testprobe.cpp File Reference

```
#include "testprobe.h"
```

5.26 src/testprobe.h File Reference

```
#include "lightprobe.h" #include "source.h" #include "gui.-  
h"
```

Data Structures

- class [TestProbe](#)
Test light probe (for debug).

5.27 src/transfer.cpp File Reference

```
#include "transfer.h"
```

Defines

- #define [MIN_WEIGHT_DISTANCE](#) 0.05

5.27.1 Define Documentation

5.27.1.1 #define MIN_WEIGHT_DISTANCE 0.05

5.28 src/transfer.h File Reference

```
#include "utils.h" #include "gui.h" #include "lamps.h" ×  
#include "lamppool.h" #include "virtuallamps.h" #include  
"source.h" #include "imagesource.h" #include "lightprobe.-  
h" #include "image.h" #include <vector> #include <time.-  
h> #include "GL/glwf.h" #include <GL/glu.h> #include <ceres/ceres.-  
h> #include <glog/logging.h> #include "cvxopt.h"
```

Data Structures

- class [Transfer](#)
The Ambient Light [Transfer](#) loop.
- struct [Transfer::params](#)
Configuration.
- struct [Transfer::Residual](#)
CostFunction for ceres.
- class [Transfer::CostSimple](#)
Faster CostFunction for ceres.

Defines

- #define [PENALTY](#) 100
- #define [NUMLAMPS](#) 108

5.28.1 Define Documentation

5.28.1.1 #define [NUMLAMPS](#) 1085.28.1.2 #define [PENALTY](#) 100

5.29 src/Utils.cpp File Reference

```
#include "utils.h" #include <getopt.h>
```

Defines

- #define [M_SQRT2PI](#) 2.50662827463100050241

Functions

- [imglib::Image< float > & imgAdd](#) ([imglib::Image< float > &A](#), [imglib::Image< float > &B](#))
- [imglib::Image< float > & imgSub](#) ([imglib::Image< float > &A](#), [imglib::Image< float > &B](#))
- [imglib::Image< float > & imgAdd](#) ([imglib::Image< float > &A](#), [rgb color](#))
- [imglib::Image< float > & imgMul](#) ([imglib::Image< float > &A](#), [float scalar](#))
- [float imgMax](#) ([imglib::Image< float > &A](#))
- [float imgMin](#) ([imglib::Image< float > &A](#))
- [imglib::Image< float > & imgScale](#) ([imglib::Image< float > &A](#))
- [rgb sampleGauss7](#) ([imglib::Image< float > image](#), [int xpos](#), [int ypos](#))
- [double normalDistribution](#) ([double sigma](#), [double mu](#), [double x](#))
- [rgb mapGamma](#) ([rgb value](#), [double gain](#), [double lambda](#))
- [double mapLinear](#) ([double val](#), [double wp](#), [double bp](#))
- [rgb mapLinear](#) ([rgb val](#), [rgb wp](#), [rgb bp](#))
- [rgb rgb2srgb](#) ([rgb linear](#))
- [double rgb2srgb_component](#) ([double value](#))
- [Vector3d rgb2xyY](#) ([rgb val](#))
- [rgb srgb2rgb](#) ([rgb sRGB](#))
- [double srgb2rgb_component](#) ([double value](#))
- [double clamp](#) ([double val](#))
- [rgb clamp](#) ([rgb val](#))
- [circle getCircumCircle](#) ([Vector2d p1](#), [Vector2d p2](#), [Vector2d p3](#))
- [directions sampleHemisphere](#) ([int numSamplesH](#), [int numSamplesA](#))
- [directions sampleSphere](#) ([int numSamplesH](#), [int numSamplesA](#), [double horizon-Angle](#))

- `directions sampleUniform` (int numSamples, double horizonAngle)
- `directions samplesFromFile` (string path, int numVecs, double horizonAngle)
- `directions loadVectors3d` (string path, int numVecs)
- int `findNearestNeighbor` (Vector3d vec, `directions` candidates)
- Vector2d `cartesian2spherical` (Vector3d cartesian)
- Vector3d `spherical2cartesian` (Vector2d spherical)
- double `angle` (Vector2d p1, Vector2d p2)

Variables

- int `verbosity` = 0
- const int `gf7` [7][7]

5.29.1 Define Documentation

5.29.1.1 `#define M_SQRT2PI 2.50662827463100050241`

5.29.2 Function Documentation

5.29.2.1 `double angle (Vector2d p1, Vector2d p2)`

5.29.2.2 `Vector2d cartesian2spherical (Vector3d cartesian)`

5.29.2.3 `double clamp (double val)`

5.29.2.4 `rgb clamp (rgb val)`

5.29.2.5 `int findNearestNeighbor (Vector3d vec, directions candidates)`

5.29.2.6 `circle getCircumCircle (Vector2d p1, Vector2d p2, Vector2d p3)`

5.29.2.7 `imglib::Image<float>& imgAdd (imglib::Image< float > & A, imglib::Image< float > & B)`

5.29.2.8 `imglib::Image<float>& imgAdd (imglib::Image< float > & A, rgb color)`

5.29.2.9 `float imgMax (imglib::Image< float > & A)`

5.29.2.10 `float imgMin (imglib::Image< float > & A)`

5.29.2.11 `imglib::Image<float>& imgMul (imglib::Image< float > & A, float scalar)`

5.29.2.12 `imglib::Image<float>& imgScale (imglib::Image< float > & A)`

5.29.2.13 `imglib::Image<float>& imgSub (imglib::Image< float > & A, imglib::Image< float > & B)`

5.29.2.14 `directions loadVectors3d (string path, int numVecs)`

- 5.29.2.15 `rgb mapGamma (rgb value, double gain, double lambda)`
- 5.29.2.16 `double mapLinear (double val, double wp, double bp)`
- 5.29.2.17 `rgb mapLinear (rgb val, rgb wp, rgb bp)`
- 5.29.2.18 `double normalDistribution (double sigma, double mu, double x)`
- 5.29.2.19 `rgb rgb2srgb (rgb linear)`
- 5.29.2.20 `double rgb2srgb_component (double value)`
- 5.29.2.21 `Vector3d rgb2xyY (rgb val)`
- 5.29.2.22 `rgb sampleGauss7 (imglib::Image< float > image, int xpos, int ypos)`
- 5.29.2.23 `directions sampleHemisphere (int numSamplesH, int numSamplesA)`
- 5.29.2.24 `directions samplesFromFile (string path, int numVecs, double horizonAngle)`
- 5.29.2.25 `directions sampleSphere (int numSamplesH, int numSamplesA, double horizonAngle)`
- 5.29.2.26 `directions sampleUniform (int numSamples, double horizonAngle)`
- 5.29.2.27 `Vector3d spherical2cartesian (Vector2d spherical)`
- 5.29.2.28 `rgb srgb2rgb (rgb sRGB)`
- 5.29.2.29 `double srgb2rgb_component (double value)`

5.29.3 Variable Documentation

5.29.3.1 `const int gf7[7][7]`

Initial value:

```
{ { 1, 1, 2, 2, 2, 1, 1 },
  { 1, 2, 2, 4, 2, 2, 1 },
  { 2, 2, 4, 8, 4, 2, 2 },
  { 2, 4, 8, 16, 8, 4, 2 },
  { 2, 2, 4, 8, 4, 2, 2 },
  { 1, 2, 2, 4, 2, 2, 1 },
  { 1, 1, 2, 2, 2, 1, 1 } }
```

5.29.3.2 `int verbosity = 0`

Author

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Utility functions and important datastructures.

5.30 src/utils.h File Reference

```
#include "image.h" #include <string> #include <sstream> ×
#include <iostream> #include <cmath> #include <vector>
#include <Eigen/Core> #include <X11/X.h> #include <X11/-
Xlib.h> #include <X11/cursorfont.h>
```

Data Structures

- class [Log](#)
A simple logger.
- struct [dirCone](#)
Stores the neighborhood of one sampling direction.
- struct [rgb](#)
RGB color.
- struct [circle](#)
A circle.
- struct [rect](#)
A rectangle.
- struct [point](#)
A point.

Typedefs

- typedef vector< Vector3d > [directions](#)

Functions

- void [err](#) (string msg, bool critical)
- imglib::Image< float > & [imgCircularCrop](#) (imglib::Image< float > &imgIn, [circle](#) area)
- imglib::Image< float > & [imgAdd](#) (imglib::Image< float > &A, imglib::Image< float > &B)
- imglib::Image< float > & [imgSub](#) (imglib::Image< float > &A, imglib::Image< float > &B)
- imglib::Image< float > & [imgAdd](#) (imglib::Image< float > &A, [rgb](#) color)
- imglib::Image< float > & [imgMul](#) (imglib::Image< float > &A, float scalar)
- float [imgMax](#) (imglib::Image< float > &A)
- float [imgMin](#) (imglib::Image< float > &A)
- imglib::Image< float > & [imgScale](#) (imglib::Image< float > &A)
- [rgb sampleGauss7](#) (imglib::Image< float > image, int xpos, int ypos)
- double [normalDistribution](#) (double sigma, double mu, double x)
- [rgb mapGamma](#) ([rgb](#) value, double gain, double lambda)
- double [mapLinear](#) (double val, double wp, double bp)
- [rgb mapLinear](#) ([rgb](#) value, [rgb](#) whitepoint, [rgb](#) blackpoint)

- [rgb rgb2srgb](#) ([rgb](#) linear)
- double [rgb2srgb_component](#) (double value)
- [rgb srgb2rgb](#) ([rgb](#) sRGB)
- double [srgb2rgb_component](#) (double value)
- Vector3d [rgb2xyY](#) ([rgb](#) val)
- double [clamp](#) (double val)
- [rgb clamp](#) ([rgb](#) val)
- [circle getCircumCircle](#) (Vector2d, Vector2d, Vector2d)
- [directions sampleHemisphere](#) (int, int)
- [directions sampleSphere](#) (int, int, double)
- [directions sampleUniform](#) (int numSamples, double horizonAngle)
- [directions samplesFromFile](#) (string path, int numVecs, double horizonAngle)
- [directions loadVectors3d](#) (string path, int numVecs)
- int [findNearestNeighbor](#) (Vector3d vec, [directions](#) candidates)
- Vector2d [cartesian2spherical](#) (Vector3d cartesian)
- Vector3d [spherical2cartesian](#) (Vector2d spherical)
- double [angle](#) (Vector2d p1, Vector2d p2)

5.30.1 Typedef Documentation

5.30.1.1 typedef vector<Vector3d> [directions](#)

5.30.2 Function Documentation

5.30.2.1 double [angle](#) (Vector2d *p1*, Vector2d *p2*)

5.30.2.2 Vector2d [cartesian2spherical](#) (Vector3d *cartesian*)

5.30.2.3 double [clamp](#) (double *val*)

5.30.2.4 [rgb clamp](#) ([rgb](#) *val*)

5.30.2.5 void [err](#) (string *msg*, bool *critical*)

5.30.2.6 int [findNearestNeighbor](#) (Vector3d *vec*, [directions](#) *candidates*)

5.30.2.7 [circle getCircumCircle](#) (Vector2d , Vector2d , Vector2d)

5.30.2.8 [imglib::Image<float>& imgAdd](#) ([imglib::Image< float > & A](#), [imglib::Image< float > & B](#))

5.30.2.9 [imglib::Image<float>& imgAdd](#) ([imglib::Image< float > & A](#), [rgb color](#))

5.30.2.10 [imglib::Image<float>& imgCircularCrop](#) ([imglib::Image< float > & imgIn](#), circle *area*)

5.30.2.11 float [imgMax](#) ([imglib::Image< float > & A](#))

5.30.2.12 float [imgMin](#) ([imglib::Image< float > & A](#))

- 5.30.2.13 `imglib::Image<float>& imgMul (imglib::Image< float > & A, float scalar)`
- 5.30.2.14 `imglib::Image<float>& imgScale (imglib::Image< float > & A)`
- 5.30.2.15 `imglib::Image<float>& imgSub (imglib::Image< float > & A, imglib::Image< float > & B)`
- 5.30.2.16 `directions loadVectors3d (string path, int numVecs)`
- 5.30.2.17 `rgb mapGamma (rgb value, double gain, double lambda)`
- 5.30.2.18 `double mapLinear (double val, double wp, double bp)`
- 5.30.2.19 `rgb mapLinear (rgb value, rgb whitepoint, rgb blackpoint)`
- 5.30.2.20 `double normalDistribution (double sigma, double mu, double x)`
- 5.30.2.21 `rgb rgb2srgb (rgb linear)`
- 5.30.2.22 `double rgb2srgb_component (double value)`
- 5.30.2.23 `Vector3d rgb2xyY (rgb val)`
- 5.30.2.24 `rgb sampleGauss7 (imglib::Image< float > image, int xpos, int ypos)`
- 5.30.2.25 `directions sampleHemisphere (int , int)`
- 5.30.2.26 `directions samplesFromFile (string path, int numVecs, double horizonAngle)`
- 5.30.2.27 `directions sampleSphere (int , int , double)`
- 5.30.2.28 `directions sampleUniform (int numSamples, double horizonAngle)`
- 5.30.2.29 `Vector3d spherical2cartesian (Vector2d spherical)`
- 5.30.2.30 `rgb srgb2rgb (rgb sRGB)`
- 5.30.2.31 `double srgb2rgb_component (double value)`

5.31 src/virtuallamps.cpp File Reference

```
#include "virtuallamps.h"
```

5.32 src/virtuallamps.h File Reference

```
#include "lamps.h" #include "utils.h" #include <string>×
#include <iostream> #include <vector> #include <pthread.-
h> #include <time.h>
```

Data Structures

- class [VirtualLamps](#)
Lamps w/o hardware backend.

5.33 src/x11source.cpp File Reference

```
#include "x11source.h"
```

5.34 src/x11source.h File Reference

```
#include "utils.h" #include "source.h" #include "image.-  
h" #include <X11/Xlib.h> #include <X11/Xutil.h> #include  
<sys/shm.h> #include <X11/extensions/XShm.h>
```

Data Structures

- class [X11Source](#)
X11 desktop grabber.
- struct [X11Source::params](#)
Configuration of [X11Source](#).