**Changelog for Version 2:**

Changelog for V2.1

-Fully redesigned program for new robot design.

-Support for four wheel drive.

-Support for arm-based claw.

Changelog for V2.2

-Changed arm controls to a one button system.

Changelog for V2.2.1

-Reversed driving motors.

Changelog for V2.3

-Changed the arm and conveyer belt's control.

Changelog for V2.4

-Changed the arm and conveyer belt's control.

Changelog for V2.5

-Added a virtual counter weight for the arm

Changelog for V2.5.2

-Tweaked the arm motor directions

Changelog for V2.6

-Added Autonomous

-Switched to Competition format

Changelog for V2.7

-Tweak times in autonomous

-Split program for the red and blue sides of the field

Changelog for version 2.7.1

-Switched the left and right motors

Changelog for version 2.7.2

-Cut tower portion of autonomous program