

- We have shown that the maximum current occurs on resonance, but what about if we use a different frequency while keeping R, L, and C fixed?

$$I_{\text{max}} = \frac{V_0}{Z}$$
 $Z = \sqrt{R^2 + X^2} = \sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}$

First Case:

$$\omega \to 0, Z \to \infty$$
 $I_{\text{max}} \to 0$

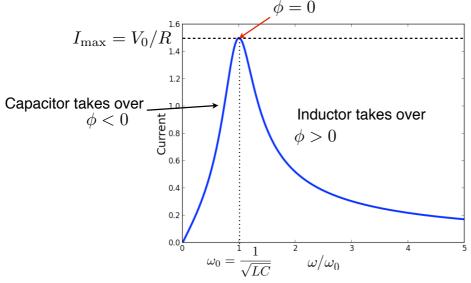
- Due to the capacitor
- As the frequency -> 0, the current is no longer AC but DC. DC-current builds up charge on the capacitor until no more current can flow.

Second Case:

$$\omega \to \infty, Z \to \infty$$
 $I_{\text{max}} \to 0$

- Due to the inductor
- If frequency is very high then current changes extremely rapidly. Self-inductor tries really hard to fight rapid changes in current that generate rapid B-field changes

222

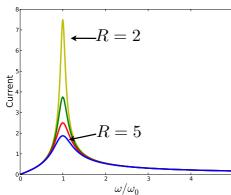




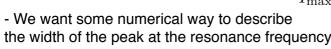
Parameters

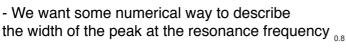
$$V = 7.5 \text{ V}$$

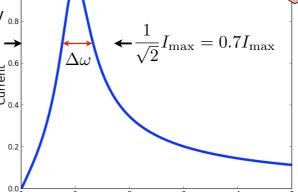
 $R = 5 \Omega$
 $L = 8.2 \text{ mH}$
 $C = 100 \mu\text{F}$



- What happens if R is decreased?
- The width of the peak decreases and the maximum current increases rapidly.
- If resistance is too low, can destroy your circuit if driving frequency is on resonance.







 ω/ω_0

- This is called the Quality Factor:

$$Q = \frac{\omega_0}{\Delta \omega}$$

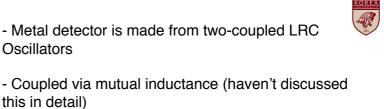
- $\Delta\omega$ is the width of the peak at $I=\frac{I_{\text{max}}}{\sqrt{2}}$
- The quality factor can also be written in terms of R, L, and C.

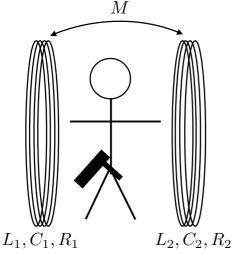
$$Q = \frac{\omega_0}{\Delta \omega} = \frac{1}{\sqrt{LC}} \frac{L}{R} = \frac{1}{R} \sqrt{\frac{L}{C}}$$

- The quality factor tells us how strongly the system behaves on resonance, and how weakly it responses when not on resonance.
- Because Q~1/R, the Q-factor also tells us how much energy is lost during each period T.

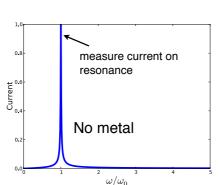
224

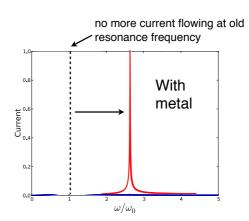
Ex. Metal Detector:





- Two different resonance peaks (just going to show one)
- Oscillators have extremely large Q-factors (i.e. very sensitive to change in frequency)
- Eddy currents generated in metal, generated Bfield that shifts resonance frequency





Power in AC-Circuits:



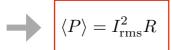
- Why did we define the Q-factor as the width at $I=\frac{I_{\max}}{\sqrt{2}}$ and not $I=\frac{I_{\max}}{2}$?
- In the real-world we are not interested in the current, but rather the power $P \propto I^2$

$$P = I^2 R = \left[I_{\text{max}} \cos(\omega t - \phi) \right]^2 R = I_{\text{max}}^2 R \cos^2(\omega t - \phi)$$

- The current oscillates in time, so lets calculate the average power using:

$$\langle I
angle = rac{1}{\sqrt{2}} I_{
m max}$$
 Average over one-period \Longrightarrow $\langle P
angle = rac{1}{2} I_{
m max}^2 R$

- It is also common to define the RMS (Root-Mean-Squared) Current: $I_{\rm rms}=rac{1}{\sqrt{2}}I_{\rm max}$



- \quad \langle P \rangle = I_{rms}^2 R \quad \quad \text{- In AC-circuits, when people talk about current, they always mean the RMS current.}
- We can also define the RMS Voltage: $V_{
 m rms} = V_{
 m max}/\sqrt{2}$

$$I_{
m rms} = rac{V_{
m rms}}{Z}$$

226



- The average power can now be expressed using RMS values for both the current and the voltage:

$$\langle P \rangle = I_{\rm rms}^2 R = \frac{V_{\rm rms}}{Z} I_{\rm rms} R = I_{\rm rms} V_{\rm rms} \frac{R}{Z}$$

$$X \longrightarrow \frac{R}{Z} = \cos \phi \qquad \longrightarrow \langle P \rangle = I_{\rm rms} V_{\rm rms} \cos \phi$$