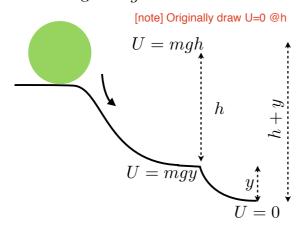
## What is Potential?

- Recall from gravity, the change in potential energy of an object above the Earth is:  $\Delta U_G = mgh$ 



- The mass doesn't matter, only the change in height matters, lets divide out the mass:

$$\frac{U_G}{m} = gh = V_G$$

This is the "Gravitational Potential": it is a measure of the amount of work required that does not require knowing the mass.

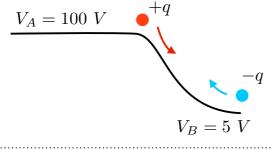
- This is a measure of the amount of energy (work) that was required to push the ball up the hill to height h.
- This is also equal to the kinetic energy if the ball rolled back down the hill to h=0
- But what if h does not measure entire height of the hill?

$$\Delta U_G = mg(h+y) - mgy = mgh$$

- The change in potential does not care where U=0 is, only the difference matters.
- If  $\Delta h=0$  then the change in potential is zero, for any mass.

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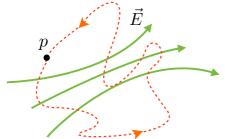
# Electric potential works the exact same:



#### "Electrostatic Potential"

$$\frac{U_{el}}{e} = \frac{Q}{4\pi\epsilon_0 r} = V$$

- You can think of (+) charges as rolling down the potential hill to lower V. (-) charges go up the hill to higher potentials.



- Suppose I am given an E-field and a point p
- Now starting at p, I go along an arbitrary path and at the end, go back to point p
- Forces are conservative -> work from p->p is zero

$$V_p - V_p = \oint_A^A \vec{E} \cdot \vec{dl} = 0$$
 integrate over closed

We now have 4 important equations for electrostatics

#### Important Electrostatic Equations:

(1) 
$$\oint_{\mathcal{S}} \vec{E} \cdot d\vec{A} = \frac{Q_{enc}}{\epsilon_0}$$

(2) 
$$V_p = \int_p^\infty \vec{E} \cdot \vec{dl}$$

Gives E-field when charge distribution is known

Relates potential to E-field along path from  $\,p o \infty$ 

(3) 
$$V_A - V_B = \int_A^B \vec{E} \cdot d\vec{l}$$
 or  $\Delta V = V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{l}$ 

The change in potential from A -> B is related to the amount of E-field along the path from A -> B

(4) 
$$\oint ec{E} \cdot ec{dl} = 0$$
 The work done along any closed path is zero.

- If we know the E-field everywhere then (2) tells use that we know potential everywhere.
- But given the potential V everywhere, can we find the E-field?
- From (2) we see that the potential V is the integral of the E-field.
  - So E-field must be the derivative of the potential
  - Must worry about whether there is a minus sign or not.

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- Single point charge:

- We have already derived the potential:  $V_p = \frac{Q}{4\pi\epsilon_0 r}$  scalar function
- Want to show that E is derivative of V:

$$\frac{dV}{dr} = -\frac{Q}{4\pi\epsilon_0 r^2}$$

- We want a vector equation, so multiply both sides by  $\hat{r}$ :

$$\frac{dV}{dr}\hat{r} = -\frac{Q}{4\pi\epsilon_0 r^2}\hat{r} = -\vec{E}$$

$$\vec{E} = -\frac{dV}{dr}\hat{r}$$



If you know the potential everywhere in space then you can find the E-field.

- Recall: E-field lines are always perpendicular to

equipotential surfaces:

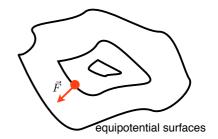
- Suppose you have a charge q and you always move perpendicular to E-field:

$$\int_{A}^{B} q\vec{E} \cdot d\vec{l} = \int_{A}^{B} \vec{F} \cdot d\vec{l} = \int_{A}^{B} F dl \cos \theta$$

$$\vec{F} = \frac{\theta - \pi/2}{\vec{dl}} \qquad \cos \theta = 0$$

$$\int_A^B \vec{F} \cdot \vec{dl} = W_{A \to B} = 0 \qquad \text{- Work from A->B is zero -> potential is constant}$$

A charge released on an equipotential surface will always move perpendicular to the surface, the the direction of the E-field if (+), or opposite direction if (-).



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### Deeper Connection Between E-field and V:

- Suppose I am at point P in space with potential Vp and some E-field
- Now I take a step **only** in the x-direction:
  - If potential does not change -> no E-field in the x-direction.
    - E-field (if any) must be perpendicular since V=constant
  - If potential does change, then the electric field in the x-direction can be written as

$$|E_x| = \left|\frac{\Delta V}{\Delta x}\right|_{y,z={\rm const}} \ \left[\frac{V}{m}\right] \qquad \begin{array}{c} \text{Electric field is the change in potential over some distance} \\ \end{array}$$

- Same in other directions:

$$|E_y| = \left| \frac{\Delta V}{\Delta y} \right|_{x,z=\text{const}}$$
  $|E_z| = \left| \frac{\Delta V}{\Delta y} \right|_{x,y=\text{const}}$ 

- In x,y,z coordinates, the E-field can be written as:  $\vec{E} = E_x \hat{x} + E_y \hat{y} + E_z \hat{z}$ 

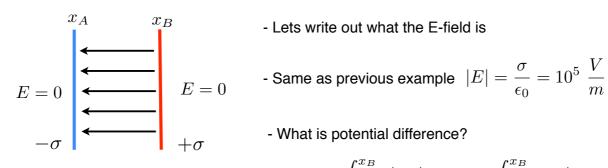
$$\vec{E} = -\left(\frac{\partial V}{\partial x}\hat{x} + \frac{\partial V}{\partial y}\hat{y} + \frac{\partial V}{\partial z}\hat{z}\right) = -\nabla V$$
  $\frac{\partial}{\partial x} \to y, z = \text{const}$ 

- What is E?

$$\vec{E} = -\frac{\partial V}{\partial x} = -10^5 \hat{x}$$
  $x \in [0, 0.01 \text{ m}]$   $E_y = E_z = 0$ 

$$x \in [0, 0.01 \text{ m}]$$
  $E_y = E_z = 0$ 

- This corresponds to the example of two charged conducting planes



Lets write out what the E-field is

- Same as previous example 
$$\;|E|=rac{\sigma}{\epsilon_0}=10^5\;rac{V}{m}\;$$

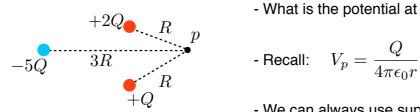
$$V_A - V_B = \int_{x_A}^{x_B} \vec{E} \cdot \vec{dx} = -10^5 \int_{x_A}^{x_B} \hat{x} \cdot \vec{dx}$$

$$V_A - V_B = -10^5 \int_{x_A}^{x_B} dx = -10^5 (x_B - x_A)$$

- Since distance between A & B is 0.01m:  $V_A - V_B = -1000 \; 
m{V}$  Potential grows linearly from A - > B

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# Ex. Three point charges:



- What is the potential at point P?

- Recall: 
$$V_p = rac{Q}{4\pi\epsilon_0 r}$$

- We can always use superposition to add up individual potential terms

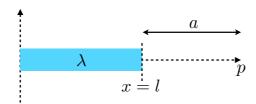
$$V_p = V_p^{+Q} + V_p^{+2Q} + V_p^{-5Q}$$

- Problem is simple now:

$$V_p^{+Q} = \frac{Q}{4\pi\epsilon_0 R}$$
  $V_p^{+2Q} = \frac{2Q}{4\pi\epsilon_0 R}$   $V_p^{-5Q} = \frac{-5Q}{4\pi\epsilon_0 (3R)}$ 

$$V_p = \frac{4}{3} \frac{Q}{4\pi\epsilon_0 R}$$

# Ex. Charged rod:



- What is the potential at point P from rod with length I and charge density  $\lambda$  .
- We can calculate the E-field and use

$$V_p = \int_p^\infty \vec{E} \cdot \vec{dl}$$

but we are not given E and this is too much work.

- Instead we know that charged rod is just a collection of small individual charges dq.
- So lets add up the potential from each little charge dq to get answer:

$$dV_p = \frac{dq}{4\pi\epsilon_0 d} = \frac{\lambda dx}{4\pi\epsilon_0 \left[ (a+l) - x \right]}$$

$$V_p = \frac{\lambda}{4\pi\epsilon_0} \int_0^l \frac{dx}{\left[ (a+l) - x \right]} = \frac{\lambda}{4\pi\epsilon_0} \left[ \log\left( a + l \right) - \log\left( a \right) \right]$$

$$V_p = \frac{\lambda}{4\pi\epsilon_0} \log\left( \frac{a+l}{a} \right)$$