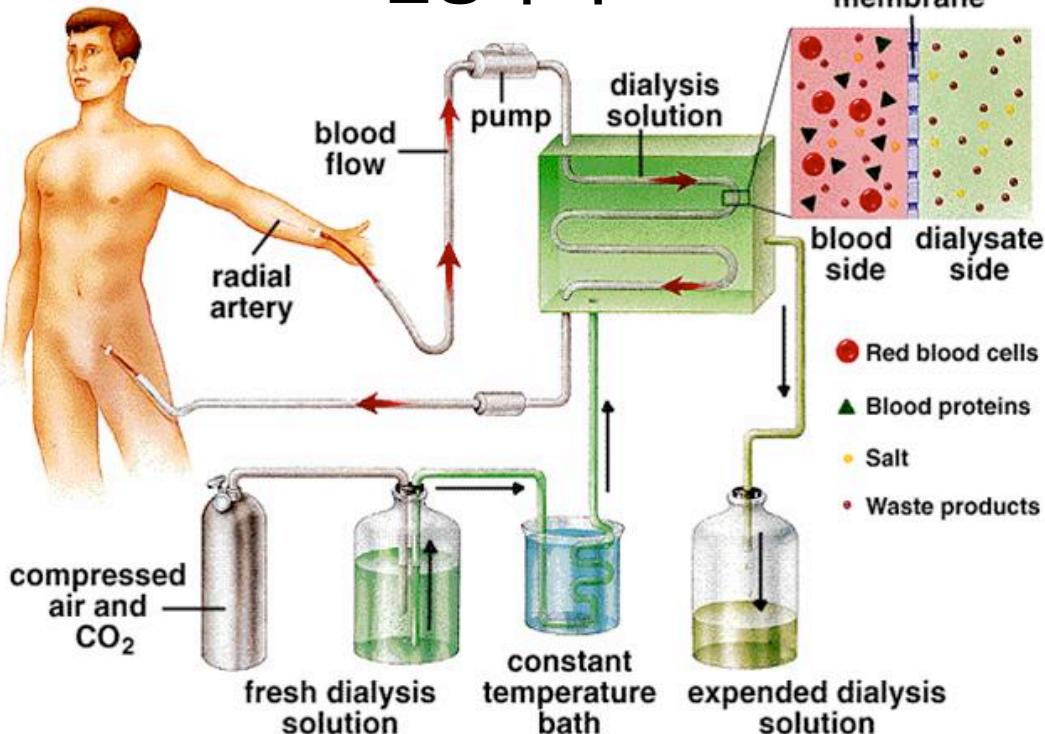


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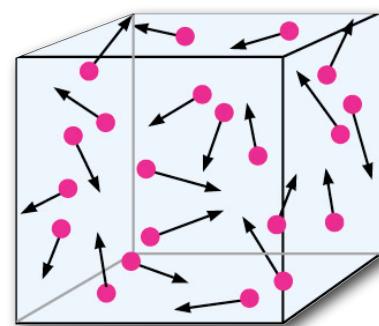


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Forces on Microscopic objects:

- **Microscopic** objects are objects that are so small that we need a microscope to see them
- Microscopic objects behave completely differently than macroscopic objects
- Every fluid (air, water, oil, alcohol) is made out of molecules
- All of these molecules are moving in random directions due to the fluids temperature

Water molecules move around at ~ 600 m/s at room temperature



- If you put an object in the fluid, then the fluid molecules will hit the object randomly with a force in a random direction
- For macroscopic objects, these random forces can be ignored because the object is too big.
- For microscopic objects, these random forces are the largest forces on the object!
- These random forces are even stronger than the gravitational force

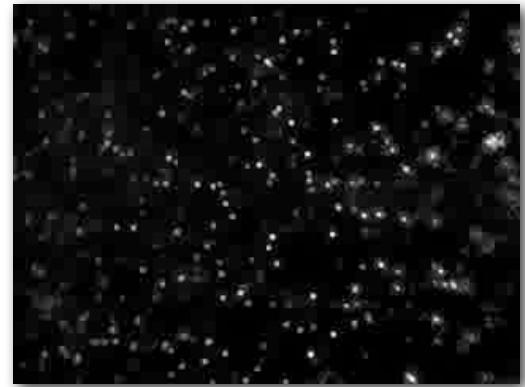


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- In a fluid, microscopic objects move in random directions.

- This random motion is called **Brownian Motion**

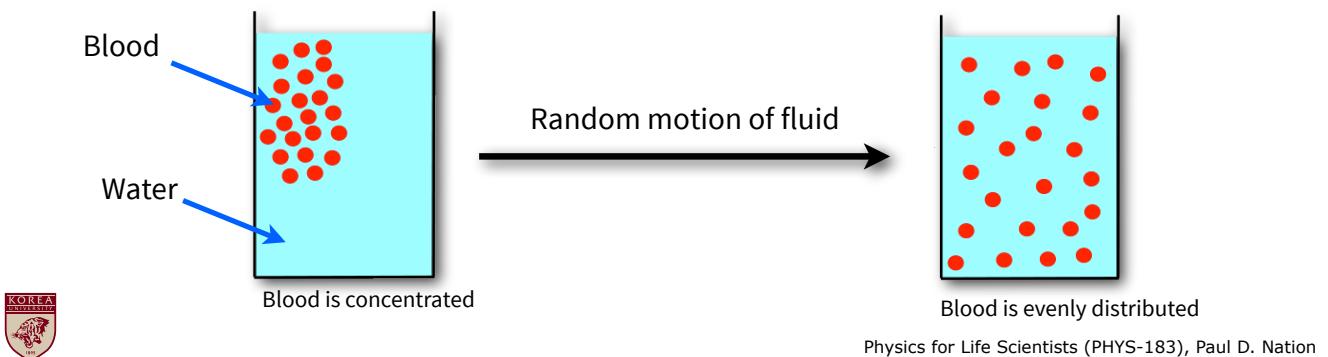
Discovered by a biologist:
Robert Brown (1827)



Brownian motion of nanoparticles in water

Diffusion:

- Although the motion of microscopic objects is random, the resulting motion is extremely important for biological molecules



- Suppose I have many objects (blood cells, sodium ions,...) in a small volume of fluid

→ We say that the objects are **concentrated** or have **high concentration**

- If I have a few objects in a large volume of fluid, then we call the objects **diluted** or have **low concentration**

- The random motion of fluid molecules takes concentrations of objects and makes them diluted

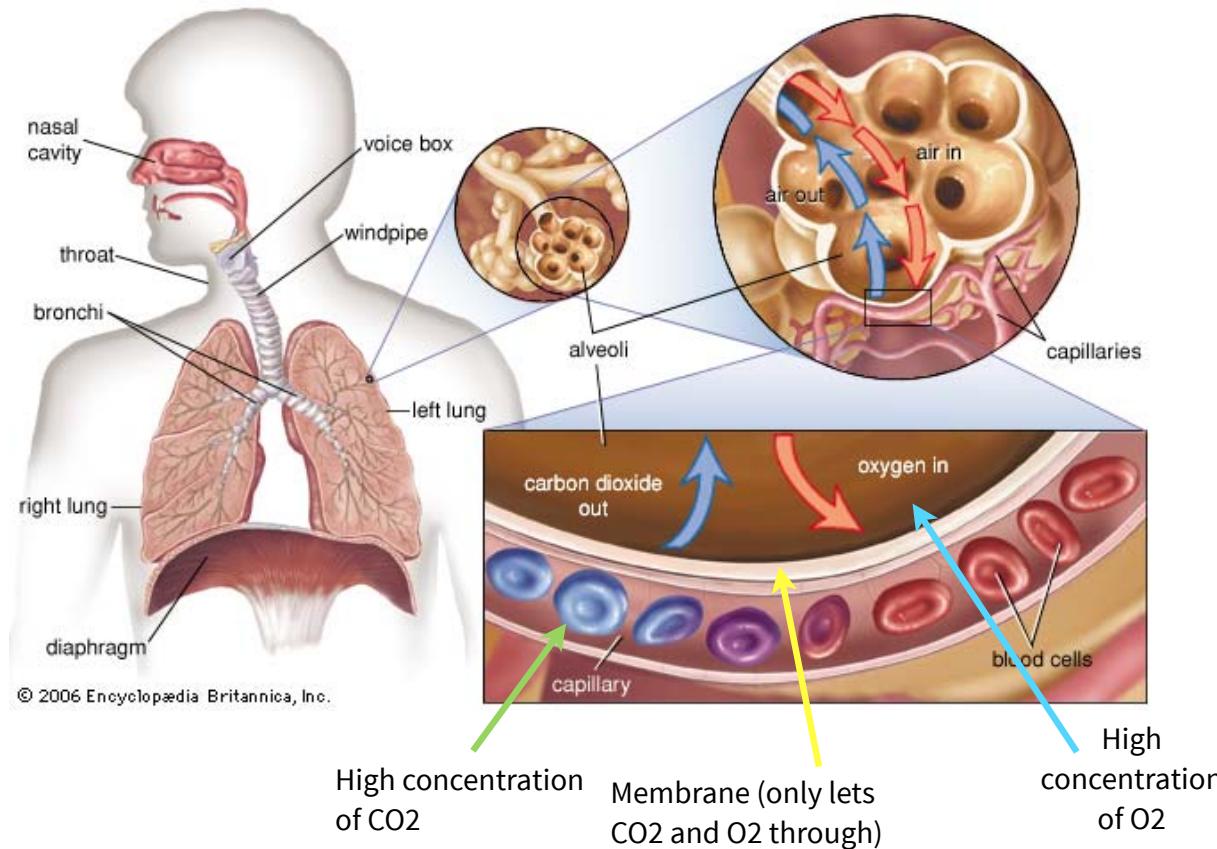
- This process is called **diffusion**

- Diffusion is extremely important in biology!



Diffusion of Bromine in air

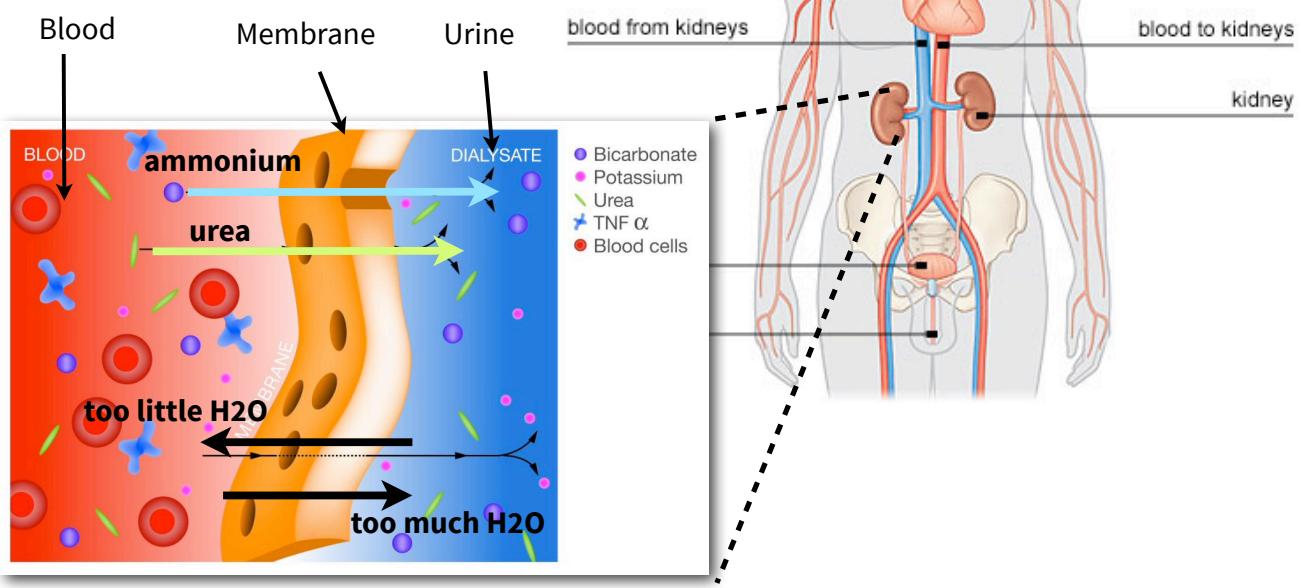
Ex. Diffusion of oxygen and carbon dioxide in lungs:



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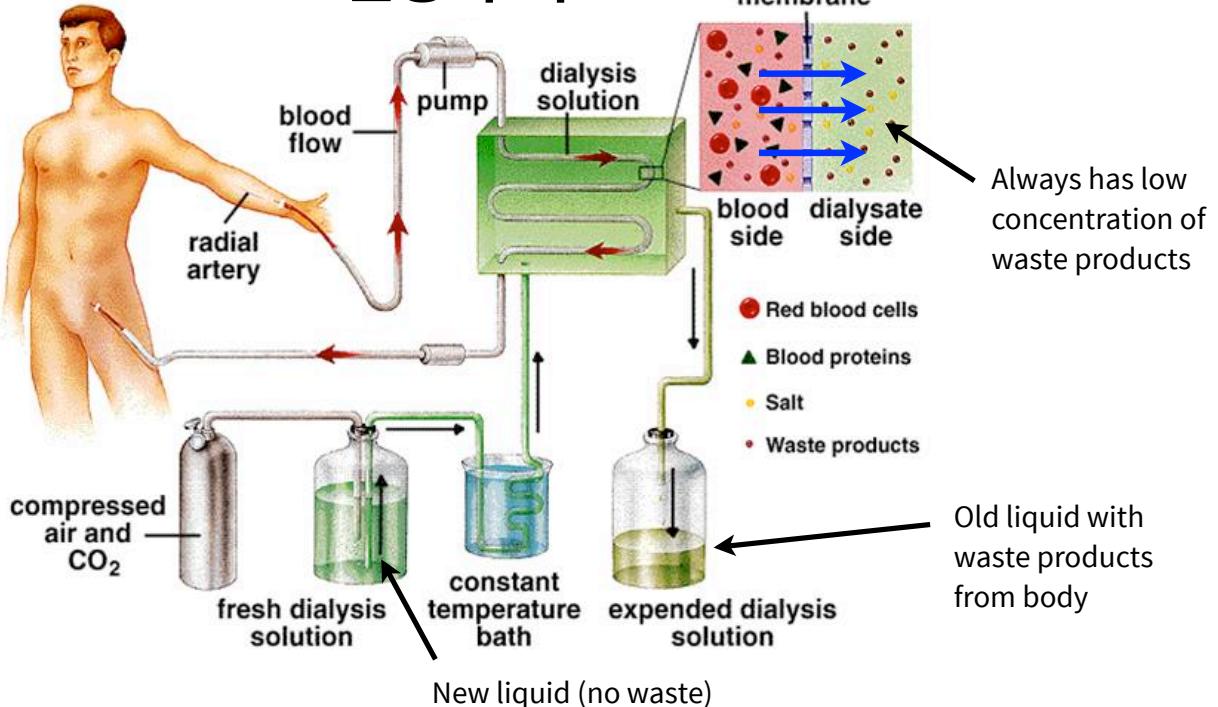
Ex. Diffusion waste products from kidneys:

- Waste products (urea, ammonium) to go from blood to your urine via diffusion in your kidneys
- Diffusion in the kidneys also balances the amount of water in your body



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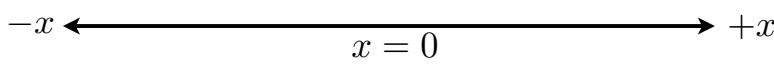


Understanding how diffusion works in kidneys save 2 millions lives every year!



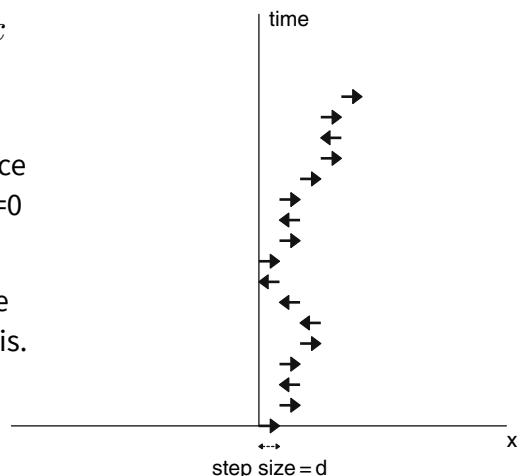
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- Since diffusion is caused by the random motion of atoms, how do we write this mathematically?
- The mathematical description is called a **random walk** or a **drunk walk**:
- Suppose I have a drunk person who can only walk to the left or right



- If he is so drunk that he randomly walks either left or right for each step

- What does his motion look like?



- Since there is a 50% chance of going left, and 50% chance of going right, his average displacement will always be $x=0$

- However, as we see, over time the person starts to move away from $x=0$ so we need a new equation to describe this.



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- Instead of displacement, let us measure the average displacement squared: $\overline{(\Delta x)^2}$
 - Since this is the displacement squared, this number is always positive or zero.
 - Since the motion is random, we must always deal with averages.
 - The square root of this measures how far the average drunk man can walk away from $x=0$
 - For the drunk walker, his averaged displacement squared is given by

$$\overline{(\Delta x)^2} = Nd^2$$

number of steps he took how big his steps are

Ex. If $N=10$ and $d=1\text{m}$ then $\overline{(\Delta x)^2} = 10 \text{ m}^2$. To see how far the average person can walk, take square root $\Delta x_{\text{avg}} = \sqrt{10} \text{ m} \approx 3 \text{ m}$

- We also need an equation for other objects such as molecules, proteins,....
 - Obviously things like molecules do not take steps, so we need to modify this expression



- For any object undergoing random motion in one-dimension the average squared displacement is

$$\overline{(\Delta x)^2} = 2Dt \quad \text{time}$$

D is called the **diffusion coefficient**

- The diffusion constant coefficient depends the size and shape of the object, the viscosity (“stickiness”) of the fluid, temperature,

- **Key Idea:** Since $(\Delta x)^2$ depends on time, the average displacement Δx_{avg} depends on the square root of time

$$\Delta x_{\text{avg}} \propto \sqrt{t}$$

- compare to constant velocity in one-dimension: $\Delta x = vt \rightarrow x \propto t$

If $\Delta x = 2$ after t=2 sec, then $\Delta x_{\text{avg}} = 2$ would require about t=4 sec

- This is also true in two and three-dimensions
 - Although objects in diffusion move quite fast in random directions, on average they do not move very fast away from where they started ($x=0$)



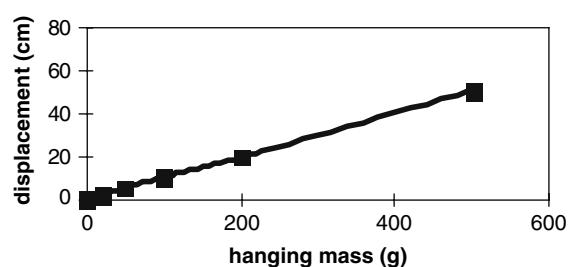
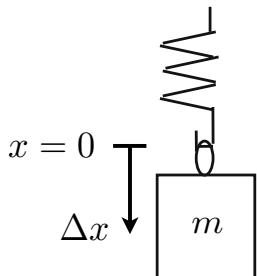
Hooke's Law and Oscillations.

- In this section we are switching topics and are going to study springs and the motion of objects attached to springs

- Springs are some of the most important objects in all of physics!

- About 50% of all of physics can be explained by using springs as a model.

- Suppose we hang a spring from the ceiling and measure the displacement of the spring for different masses



- For all of the masses tested we see that the displacement of the spring is linearly proportional to the mass on it



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- Since the force of gravity is also proportional to the mass $F_g = mg_E$, this tells us that the springs displacement is linearly proportional to the force on it

- If the spring and mass are not moving then we know by Newton's laws that the spring must also have a force equal in magnitude, but pointed in the opposite direction

- If we let x be the displacement of the spring from equilibrium ($x=0$) then the force-displacement relationship can be written as

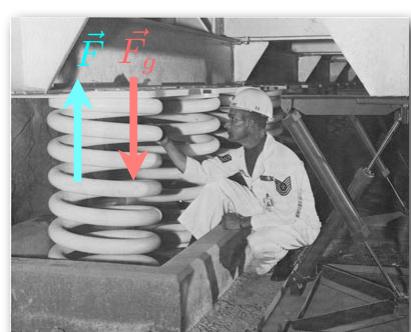
$$F = -kx$$

(Hooke's Law)

k is called the spring constant and tells us how hard we have push or pull on the spring to change its length

k has units of N/m

- The minus sign tells us that the force from the spring is always pointed in the opposite direction as the displacement x

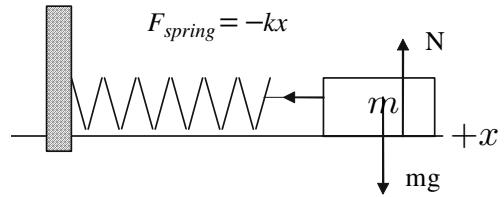


Very large spring constant k



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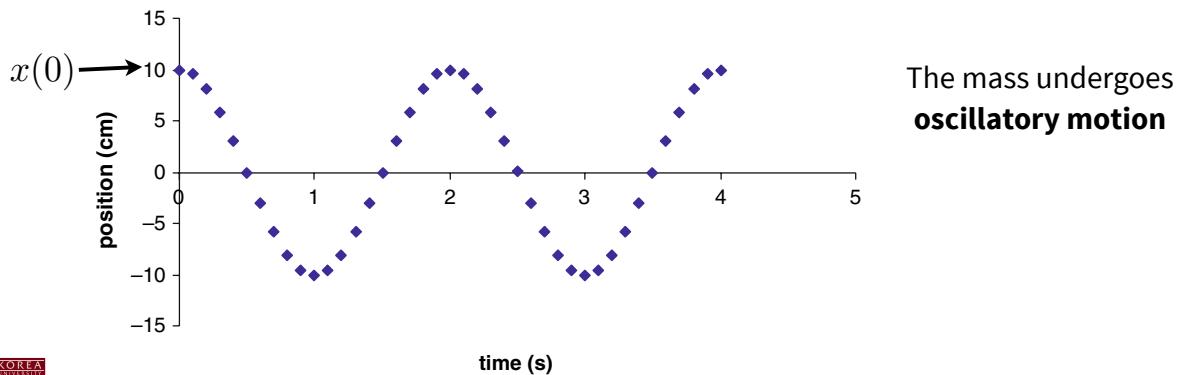
- Suppose we now take our mass and spring and place them sideways on the table
- Have three forces acting on mass, but two cancel



- Therefore, using Newton's 2nd law, we can find the spring's acceleration

$$F_{\text{net}} = -kx = ma$$

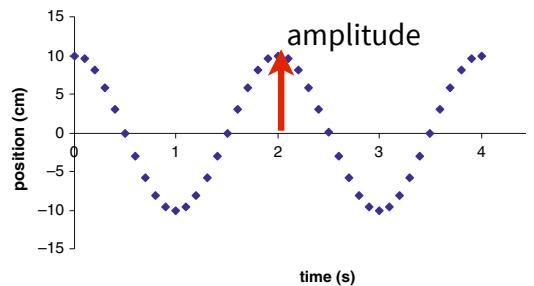
- If we stretch a spring with $k = 10 \text{ N/m}$ from equilibrium by $x = 10 \text{ cm}$ with a 1kg mass and then at time $t=0$ we let the mass go. What is the position as a function of time?



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- At $t=0$, $x=10\text{cm}$ therefore the acceleration at $t=0$ is

$$a(0) = -\frac{k}{m}x = -\frac{10 \text{ N/m}}{1 \text{ kg}} 0.1 \text{ m} = -1.0 \text{ m/s}^2$$



- The mass gains velocity in the $-x$ -direction, but the acceleration gets reduced until $x=0$ where

$$a(0) = -\frac{k}{m}x = 0$$

- After $x=0$, the displacement becomes negative, so the acceleration becomes positive, and the mass begins to slow down

- At $x=-10\text{cm}$, $t=1\text{ sec}$, the velocity is once again zero, and the acceleration is

$$a(1) = -\frac{k}{m}x = -\frac{10 \text{ N/m}}{1 \text{ kg}} (-0.1 \text{ m}) = +1.0 \text{ m/s}^2$$

- The mass moves from $+10\text{cm}$ to -10cm . This maximum displacement, 10cm , is called the **amplitude** of the motion



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- With the mass initially displaced, the position of the mass as a function of time is given by

$$x(t) = A \cos\left(\frac{2\pi t}{T}\right)$$

A = amplitude

T = period (or period of motion)

- Amplitude are always positive

- The period tells us how long it takes for the mass to come back to its original location for the first time

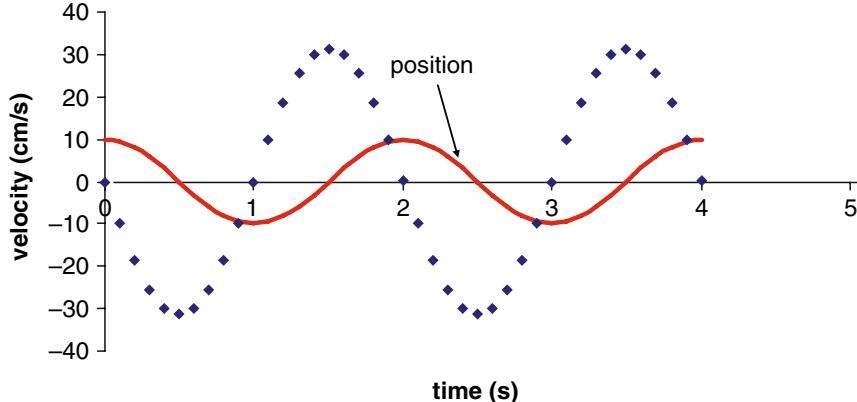
- The equation is an example of **simple harmonic motion**

- harmonic means “sine” or “cosine” functions
- here simple means the motion goes forever

- If the mass started at $x=0$ at $t=0$, then we would need to use sin instead of cos



- To get the velocity of the mass, we need to find the slope of the positive curve at every point.



- The velocity is also a simple harmonic function :

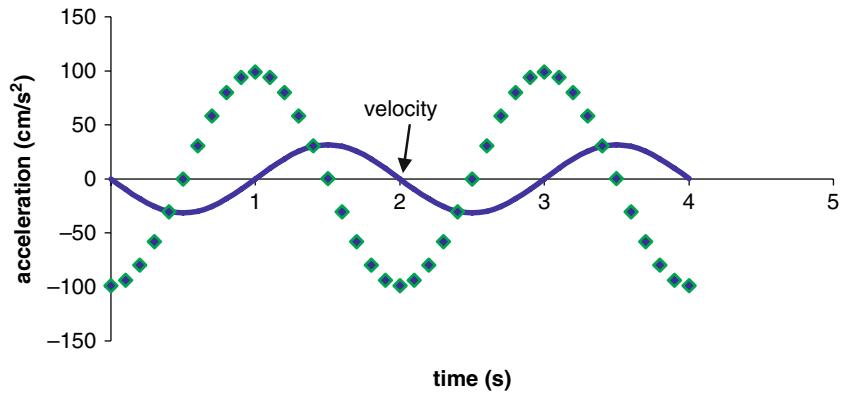
$$v(t) = -v_{\max} \sin\left(\frac{2\pi t}{T}\right)$$

- The amplitude of the velocity v_{\max} is given by:

$$v_{\max} = \left(\frac{2\pi}{T}\right) A$$



- We can do the same thing to get the acceleration (slope of velocity graph)



- Again, we get a simple harmonic function for the acceleration:

$$a(t) = -a_{\max} \cos\left(\frac{2\pi t}{T}\right)$$

starts out negative

with the amplitude:

$$a_{\max} = \left(\frac{2\pi}{T}\right)^2 A = v_{\max} \left(\frac{2\pi}{T}\right)$$



- Since both position and acceleration are cosine functions

$$x(t) = A \cos\left(\frac{2\pi t}{T}\right) \quad a(t) = -\left(\frac{2\pi}{T}\right)^2 A \cos\left(\frac{2\pi t}{T}\right)$$

this means that the acceleration and position are proportional to each other

$$a(t) = -\left(\frac{2\pi}{T}\right)^2 A \cos\left(\frac{2\pi t}{T}\right) = -\left(\frac{2\pi}{T}\right)^2 x(t)$$

- But we already knew this since $F_{net} = -kx = ma$

- We can use these two equations to solve for the period of motion T

$$\frac{a}{x} = -\frac{k}{m} = -\left(\frac{2\pi}{T}\right)^2 \quad \rightarrow \quad T = 2\pi \sqrt{\frac{m}{k}}$$

- The bigger the mass, the longer the period.

- The stronger the spring, the shorter the period.



- The period measures how long it takes for the spring to go from +A to -A and back one time.

- Another important quantity is the **frequency** (f) of the motion that measures how many times per second the mass goes back and forth

$$f = \frac{1}{T} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

- We can make things much simpler if we use the **angular frequency**:

$$\omega = 2\pi f = \frac{2\pi}{T} = \sqrt{\frac{k}{m}}$$

- Since $(2\pi/T)$ is everywhere, all of our equations become very simple when using ω :

$$\begin{aligned}x(t) &= A \cos(\omega t) \\v(t) &= -A\omega \sin(\omega t) & w = \sqrt{\frac{k}{m}} \\a(t) &= -\omega^2 x(t)\end{aligned}$$

