# Deep Learning - Foundations and Concepts Chapter 3. Standard Distributions

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## Outline

Discrete Variables

2 The Multivariate Gaussian

#### Bernoulli distribution

- Consider a binary random variable  $x \in \{0, 1\}$  and a parameter  $0 \le \mu \le 1$ , such that  $p(x = 1) = \mu$  and  $p(x = 0) = 1 \mu$ .
- Probability distribution: Bern $(x; \mu) = \mu^x (1 \mu)^{1-x}$ .
- Expectation:  $E(x) = \mu$ .
- Variance:  $var(x) = \mu(1 \mu)$ .

#### Bernoulli distribution

Model the Bernoulli distribution given observations  $\{x_1, \ldots, x_N\}$ .

$$p(x_1, \dots, x_N; \mu) = \prod_{n=1}^{N} \mu^{x_n} (1 - \mu)^{1 - x_n}$$

$$\log p(x_1, \dots, x_N; \mu) = \sum_{n=1}^{N} (x_n \log \mu + (1 - x_n) \log(1 - \mu))$$

$$= \log \mu \sum_{n=1}^{N} x_n + \log(1 - \mu)(N - \sum_{n=1}^{N} x_n)$$

$$\mu_{ML} = \frac{1}{N} \sum_{n=1}^{N} x_n$$

#### Binomial distribution

- Consider a random variable  $m = \sum_{n=1}^{N} x_n$ , where  $x_n$  are independent random variables obey Bernoulli distribution with parameter  $\mu$ .
- Probability distribution:  $Bin(m; N, \mu) = \binom{N}{m} \mu^m (1 \mu)^{N-m}$ .
- Expectation:  $E(m) = N\mu$ .
- Variance:  $var(m) = N\mu(1-\mu)$ .

## Multinomial distribution

- Consider a random variable  $x \in \{e_1, \dots, e_K\}$  and a parameter  $\mu \in \mathbb{R}^K$ , such that  $p(x = e_k) = \mu_k$ .
- Probability distribution:  $p(x; \mu) = \prod_{k=1}^{K} \mu_k^{x_k}$ .
- Expectation:  $E(x) = \mu$ .
- Covariance:  $cov(x) = diag(\mu_1, \dots, \mu_K) \mu \mu^T$ .

## Multinomial distribution

Model the generalized Bernoulli distribution given observations  $x^1, \ldots, x^N$ .

$$p(x^{1},...,x^{N};\mu) = \prod_{n=1}^{N} \prod_{k=1}^{K} \mu_{k}^{x_{k}^{n}}$$
$$\log p(x^{1},...,x^{N};\mu) = \sum_{n=1}^{N} \sum_{k=1}^{K} x_{k}^{n} \log \mu_{k} = \sum_{k=1}^{K} (\sum_{n=1}^{N} x_{k}^{n}) \log \mu_{k}$$
$$\mu_{ML} = \frac{1}{N} \sum_{n=1}^{N} x^{n}$$

For the last step, we used Lagrange multiplier to take into the constraint  $\sum_{k=1}^K \mu_k = 1$ .

## Multinomial distribution

- Consider a random variable  $m=\sum_{n=1}^N x^n$ , where  $x^n$  are independent random variables obey the generalized Bernoulli distribution with parameter  $\mu$ .
- Probability distribution:  $\operatorname{Mult}(m; N, \mu) = \frac{N!}{\prod_{k=1}^K m_k!} \prod_{k=1}^K \mu_k^{m_k}$ .
- Expectation:  $E(m) = N\mu$ .
- Covariance:  $cov(m) = N(diag(\mu_1, ..., \mu_K) \mu \mu^T).$

#### **Definition**

For a single variable x, the Gaussian distribution can be written in the form:

$$\mathcal{N}(x;\mu,\sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp(-\frac{(x-\mu)^2}{2\sigma^2})$$

where  $\mu$  is the mean and  $\sigma^2$  is the variance. For a D-dimensional vector x, the multivariate Gaussian distribution takes the form:

$$\mathcal{N}(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{D}{2}} (\det \Sigma)^{\frac{1}{2}}} \exp(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu))$$

where  $\mu$  is the D-dimensional mean vector,  $\Sigma$  is the  $D \times D$  covariance matrix.

# Geometry of the Gaussian

Without loss of generality, we assume  $\Sigma$  is symmetric. As a self-adjoint operator, there exists an orthonormal basis  $(u_1,\ldots,u_D)$  under which  $\Sigma$  is diagonalized:

$$\operatorname{diag}(\lambda_1,\ldots,\lambda_D) = U^T \Sigma U$$

where U is the orthogonal matrix whose jth column is  $u_j$ . Now let  $x-\mu=Uy$ , we see that under the new basis, the multivariate Gaussian takes the form:

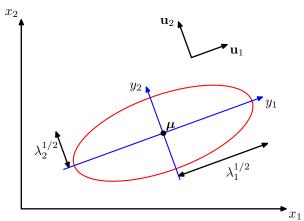
$$\mathcal{N}(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{D}{2}} (\lambda_1 \dots \lambda_D)^{\frac{1}{2}}} \exp(-\frac{1}{2} y^T \operatorname{diag}^{-1}(\lambda_1, \dots, \lambda_D) y) |\det U|$$

$$= \frac{1}{\sqrt{2\pi\lambda_1} \dots \sqrt{2\pi\lambda_D}} \exp(-\frac{1}{2} \sum_{d=1}^D \frac{y_d^2}{\lambda_d})$$

$$= \prod_{d=1}^D \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d})$$

# Geometry of the Gaussian

Figure: Geometry of the Gaussian



# Geometry of the Gaussian

It's easy to see that the multivariate Gaussian is indeed normalized:

$$\int \mathcal{N}(x; \mu, \Sigma) dx = \int \prod_{d=1}^{D} \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d}) dy$$
$$= \prod_{d=1}^{D} \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d}) dy_d$$
$$= 1$$

## Expectation and covariance

Similarly, we can calculate the expectation and covariance of the multivariate Gaussian:

$$\begin{split} E(x) &= \int \mathcal{N}(x; \mu, \Sigma) x \mathrm{d}x \\ &= \int \prod_{d=1}^{D} \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d}) (\mu + Uy) |\det U| \mathrm{d}y \\ &= \mu + U \int \prod_{d=1}^{D} \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d}) y \mathrm{d}y \\ &= \mu \end{split}$$

## Expectation and covariance

$$E(xx^{T}) = \int \mathcal{N}(x; \mu, \Sigma) x x^{T} dx$$

$$= \int \prod_{d=1}^{D} \frac{1}{\sqrt{2\pi\lambda_{d}}} \exp(-\frac{y_{d}^{2}}{2\lambda_{d}}) (\mu + Uy) (\mu + Uy)^{T} |\det U| dy$$

$$= \mu \mu^{T} + U(\int \prod_{d=1}^{D} \frac{1}{\sqrt{2\pi\lambda_{d}}} \exp(-\frac{y_{d}^{2}}{2\lambda_{d}}) y y^{T} dy) U^{T}$$

$$= \mu \mu^{T} + U \operatorname{diag}(\lambda_{1}, \dots, \lambda_{D}) U^{T} = \mu \mu^{T} + \Sigma$$

$$\operatorname{cov}(x) = E(xx^{T}) - E(x) E(x^{T}) = \Sigma$$

## The good and the bad about the Gaussian

- The Gaussian distribution arises in many different contexts:
  - The distribution that maximizes the entropy is the Gaussian.
  - Central limit theorem.
- The Gaussian distribution has many important analytical properties.
- For large D, the total number of parameters grows quadratically with D, manipulating and inverting the large matrices can become prohibitive.
- The Gaussian distribution is intrinsically unimodal, and so is unable to provide a good approximation to multimodal distributions.

#### **Problem**

Suppose x obeys the Gaussian distribution  $\mathcal{N}(x;\mu,\Sigma)$ . If we partition x into  $x_a$  and  $x_b$ , that is  $x=\begin{pmatrix} x_a \\ x_b \end{pmatrix}$ , what is the expression for the conditional distribution  $p(x_a|x_b)$  and the marginal distribution  $p(x_a)$ ?

First step, let's also partition the mean and covariance accordingly:

$$\mu = \begin{pmatrix} \mu_a \\ \mu_b \end{pmatrix}$$

$$\Sigma = \begin{pmatrix} \Sigma_{aa} & \Sigma_{ab} \\ \Sigma_{ba} & \Sigma_{bb} \end{pmatrix}$$

Because  $\Sigma^{-1}$  (called the precision matrix) appears frequently, we also partition  $\Sigma^{-1}$ :

$$\Sigma^{-1} = \begin{pmatrix} \Lambda_{aa} & \Lambda_{ab} \\ \Lambda_{ba} & \Lambda_{bb} \end{pmatrix}$$

Notice that because  $\Sigma$  and  $\Sigma^{-1}$  are symmetric,  $\Sigma_{aa}$ ,  $\Sigma_{bb}$ ,  $\Lambda_{aa}$  and  $\Lambda_{bb}$  are symmetric as well. Further, we have  $\Sigma_{ba}=\Sigma_{ab}^T$  and  $\Lambda_{ba}=\Lambda_{ab}^T$ .

Second step, let's complete the square! Notice:

$$(x - \mu)^T \Sigma^{-1} (x - \mu) = x \Sigma^{-1} x - 2x^T \Sigma^{-1} \mu + \mu^T \Sigma^{-1} \mu$$

For conditional distribution  $p(x_a|x_b)$ :

$$(x - \mu)^T \Sigma^{-1}(x - \mu) = \begin{pmatrix} x_a^T - \mu_a^T & x_b^T - \mu_b^T \end{pmatrix} \begin{pmatrix} \Lambda_{aa} & \Lambda_{ab} \\ \Lambda_{ba} & \Lambda_{bb} \end{pmatrix} \begin{pmatrix} x_a - \mu_a \\ x_b - \mu_b \end{pmatrix}$$
$$= x_a^T \Lambda_{aa} x_a - 2x_a^T (\Lambda_{aa} \mu_a - \Lambda_{ab} (x_b - \mu_b)) + \text{const}$$

Compare, we see:

$$\Sigma_{x_{a}|x_{b}}^{-1} = \Lambda_{aa}$$

$$\Sigma_{x_{a}|x_{b}} = \Lambda_{aa}^{-1}$$

$$\Sigma_{x_{a}|x_{b}}^{-1} \mu_{x_{a}|x_{b}} = \Lambda_{aa}\mu_{a} - \Lambda_{ab}(x_{b} - \mu_{b})$$

$$\mu_{x_{a}|x_{b}} = \mu_{a} - \Lambda_{aa}^{-1}\Lambda_{ab}(x_{b} - \mu_{b})$$

For marginal distribution,  $p(x_a) = \int p(x_a, x_b) dx_b$ . Let's first complete the square for  $x_b$  to integrate it out:

$$(x - \mu)^T \Sigma^{-1}(x - \mu) = \begin{pmatrix} x_a^T - \mu_a^T & x_b^T - \mu_b^T \end{pmatrix} \begin{pmatrix} \Lambda_{aa} & \Lambda_{ab} \\ \Lambda_{ba} & \Lambda_{bb} \end{pmatrix} \begin{pmatrix} x_a - \mu_a \\ x_b - \mu_b \end{pmatrix}$$

$$= x_b^T \Lambda_{bb} x_b - 2x_b^T \Lambda_{bb} (\mu_b - \Lambda_{bb}^{-1} \Lambda_{ba} (x_a - \mu_a)) + \cdots$$

$$= x_b^T \Lambda_{bb} x_b - 2x_b^T \Lambda_{bb} m + m^T \Lambda_{bb} m + \cdots$$

$$= (x_b - m)^T \Lambda_{bb} (x_b - m) + \cdots$$

where  $m = \mu_b - \Lambda_{bb}^{-1} \Lambda_{ba} (x_a - \mu_a)$ . We see that when integrating  $x_b$ , the result will be a constant not depending on  $x_a$ , although m depends on  $x_a$ .

Which means, we can take a look at the terms left in  $\cdots$ , and complete the square for  $x_a$  to get the mean and the covariance for  $x_a$ :

$$\cdots = (x_a - \mu_a)^T (\Lambda_{aa} - \Lambda_{ab}\Lambda_{bb}^{-1}\Lambda_{ba})(x_a - \mu_a)$$

We see that:

$$\Sigma_{x_a} = (\Lambda_{aa} - \Lambda_{ab}\Lambda_{bb}^{-1}\Lambda_{ba})^{-1}$$
$$\mu_{x_a} = \mu_a$$

Through a rather ugly equation (known as Schur complement), we can simplify the expression for  $\Sigma_{x_a}$  to a much nicer one:

$$\Sigma_{x_a} = \Sigma_{aa}$$

