Deep Learning - Foundations and Concepts Chapter 3. Standard Distributions

nonlineark@github

February 6, 2025

Outline

Discrete Variables

2 The Multivariate Gaussian

Bernoulli distribution

- Consider a binary random variable $x \in \{0, 1\}$ and a parameter $0 \le \mu \le 1$, such that $p(x = 1) = \mu$ and $p(x = 0) = 1 \mu$.
- Probability distribution: Bern $(x; \mu) = \mu^x (1 \mu)^{1-x}$.
- Expectation: $E(x) = \mu$.
- Variance: $var(x) = \mu(1 \mu)$.

Bernoulli distribution

Model the Bernoulli distribution given observations $\{x_1, \ldots, x_N\}$.

$$p(x_1, \dots, x_N; \mu) = \prod_{n=1}^{N} \mu^{x_n} (1 - \mu)^{1 - x_n}$$

$$\log p(x_1, \dots, x_N; \mu) = \sum_{n=1}^{N} (x_n \log \mu + (1 - x_n) \log(1 - \mu))$$

$$= \log \mu \sum_{n=1}^{N} x_n + \log(1 - \mu)(N - \sum_{n=1}^{N} x_n)$$

$$\mu_{ML} = \frac{1}{N} \sum_{n=1}^{N} x_n$$

Binomial distribution

- Consider a random variable $m = \sum_{n=1}^{N} x_n$, where x_n are independent random variables obey Bernoulli distribution with parameter μ .
- Probability distribution: $Bin(m; N, \mu) = \binom{N}{m} \mu^m (1 \mu)^{N-m}$.
- Expectation: $E(m) = N\mu$.
- Variance: $var(m) = N\mu(1-\mu)$.



Multinomial distribution

- Consider a random variable $x \in \{e_1, \dots, e_K\}$ and a parameter $\mu \in \mathbb{R}^K$, such that $p(x = e_k) = \mu_k$.
- Probability distribution: $p(x; \mu) = \prod_{k=1}^{K} \mu_k^{x_k}$.
- Expectation: $E(x) = \mu$.
- Covariance: $cov(x) = diag(\mu_1, \dots, \mu_K) \mu \mu^T$.



Multinomial distribution

Model the generalized Bernoulli distribution given observations x^1, \ldots, x^N .

$$p(x^{1},...,x^{N};\mu) = \prod_{n=1}^{N} \prod_{k=1}^{K} \mu_{k}^{x_{k}^{n}}$$
$$\log p(x^{1},...,x^{N};\mu) = \sum_{n=1}^{N} \sum_{k=1}^{K} x_{k}^{n} \log \mu_{k} = \sum_{k=1}^{K} (\sum_{n=1}^{N} x_{k}^{n}) \log \mu_{k}$$
$$\mu_{ML} = \frac{1}{N} \sum_{n=1}^{N} x^{n}$$

For the last step, we used Lagrange multiplier to take into the constraint $\sum_{k=1}^K \mu_k = 1$.

Multinomial distribution

- Consider a random variable $m=\sum_{n=1}^N x^n$, where x^n are independent random variables obey the generalized Bernoulli distribution with parameter μ .
- Probability distribution: $\operatorname{Mult}(m; N, \mu) = \frac{N!}{\prod_{k=1}^K m_k!} \prod_{k=1}^K \mu_k^{m_k}$.
- Expectation: $E(m) = N\mu$.
- Covariance: $cov(m) = N(diag(\mu_1, ..., \mu_K) \mu \mu^T).$

Definition

For a single variable x, the Gaussian distribution can be written in the form:

$$\mathcal{N}(x;\mu,\sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp(-\frac{(x-\mu)^2}{2\sigma^2})$$

where μ is the mean and σ^2 is the variance. For a D-dimensional vector x, the multivariate Gaussian distribution takes the form:

$$\mathcal{N}(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{D}{2}} (\det \Sigma)^{\frac{1}{2}}} \exp(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu))$$

where μ is the D-dimensional mean vector, Σ is the $D \times D$ covariance matrix.

Geometry of the Gaussian

Without loss of generality, we assume Σ is symmetric. As a self-adjoint operator, there exists an orthonormal basis (u_1,\ldots,u_D) under which Σ is diagonalized:

$$\operatorname{diag}(\lambda_1,\ldots,\lambda_D) = U^T \Sigma U$$

where U is the orthogonal matrix whose jth column is u_j . Now let $x-\mu=Uy$, we see that under the new basis, the multivariate Gaussian takes the form:

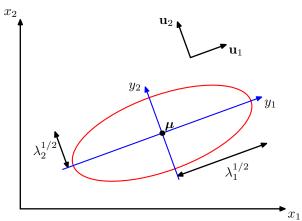
$$\mathcal{N}(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{D}{2}} (\lambda_1 \dots \lambda_D)^{\frac{1}{2}}} \exp(-\frac{1}{2} y^T \operatorname{diag}^{-1}(\lambda_1, \dots, \lambda_D) y) |\det U|$$

$$= \frac{1}{\sqrt{2\pi\lambda_1} \dots \sqrt{2\pi\lambda_D}} \exp(-\frac{1}{2} \sum_{d=1}^D \frac{y_d^2}{\lambda_d})$$

$$= \prod_{d=1}^D \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d})$$

Geometry of the Gaussian

Figure: Geometry of the Gaussian



Geometry of the Gaussian

It's easy to see that the multivariate Gaussian is indeed normalized:

$$\int \mathcal{N}(x; \mu, \Sigma) dx = \int \prod_{d=1}^{D} \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d}) dy$$
$$= \prod_{d=1}^{D} \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d}) dy_d$$
$$= 1$$

Expectation and covariance

Similarly, we can calculate the expectation and covariance of the multivariate Gaussian:

$$\begin{split} E(x) &= \int \mathcal{N}(x; \mu, \Sigma) x \mathrm{d}x \\ &= \int \prod_{d=1}^{D} \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d}) (\mu + Uy) |\det U| \mathrm{d}y \\ &= \mu + U \int \prod_{d=1}^{D} \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d}) y \mathrm{d}y \\ &= \mu \end{split}$$

Expectation and covariance

$$\begin{split} E(xx^T) &= \int \mathcal{N}(x; \mu, \Sigma) x x^T \mathrm{d}x \\ &= \int \prod_{d=1}^D \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d}) (\mu + Uy) (\mu + Uy)^T |\det U| \mathrm{d}y \\ &= \mu \mu^T + U (\int \prod_{d=1}^D \frac{1}{\sqrt{2\pi\lambda_d}} \exp(-\frac{y_d^2}{2\lambda_d}) y y^T \mathrm{d}y) U^T \\ &= \mu \mu^T + U \mathrm{diag}(\lambda_1, \dots, \lambda_D) U^T = \mu \mu^T + \Sigma \\ &\cot(x) &= E(xx^T) - E(x) E(x^T) = \Sigma \end{split}$$

The good and the bad about the Gaussian

- The Gaussian distribution arises in many different contexts:
 - The distribution that maximizes the entropy is the Gaussian.
 - Central limit theorem.
- The Gaussian distribution has many important analytical properties.
- For large D, the total number of parameters grows quadratically with D, manipulating and inverting the large matrices can become prohibitive.
- The Gaussian distribution is intrinsically unimodal, and so is unable to provide a good approximation to multimodal distributions.

Problem

Suppose x obeys the Gaussian distribution $\mathcal{N}(x;\mu,\Sigma)$. If we partition x into x_a and x_b , that is $x=\begin{pmatrix} x_a \\ x_b \end{pmatrix}$, what is the expression for the conditional distribution $p(x_a|x_b)$ and the marginal distribution $p(x_a)$?

First step, let's also partition the mean and covariance accordingly:

$$\mu = \begin{pmatrix} \mu_a \\ \mu_b \end{pmatrix}$$

$$\Sigma = \begin{pmatrix} \Sigma_{aa} & \Sigma_{ab} \\ \Sigma_{ba} & \Sigma_{bb} \end{pmatrix}$$

Because Σ^{-1} (called the precision matrix) appears frequently, we also partition Σ^{-1} :

$$\Sigma^{-1} = \begin{pmatrix} \Lambda_{aa} & \Lambda_{ab} \\ \Lambda_{ba} & \Lambda_{bb} \end{pmatrix}$$

Notice that because Σ and Σ^{-1} are symmetric, Σ_{aa} , Σ_{bb} , Λ_{aa} and Λ_{bb} are symmetric as well. Further, we have $\Sigma_{ba}=\Sigma_{ab}^T$ and $\Lambda_{ba}=\Lambda_{ab}^T$.

Second step, let's complete the square! Notice:

$$(x - \mu)^T \Sigma^{-1} (x - \mu) = x \Sigma^{-1} x - 2x^T \Sigma^{-1} \mu + \text{const}$$

For conditional distribution $p(x_a|x_b)$:

$$(x - \mu)^T \Sigma^{-1}(x - \mu) = \begin{pmatrix} x_a^T - \mu_a^T & x_b^T - \mu_b^T \end{pmatrix} \begin{pmatrix} \Lambda_{aa} & \Lambda_{ab} \\ \Lambda_{ba} & \Lambda_{bb} \end{pmatrix} \begin{pmatrix} x_a - \mu_a \\ x_b - \mu_b \end{pmatrix}$$
$$= x_a^T \Lambda_{aa} x_a - 2x_a^T (\Lambda_{aa} \mu_a - \Lambda_{ab} (x_b - \mu_b)) + \text{const}$$

Compare, we see:

$$\Sigma_{a|b}^{-1} = \Lambda_{aa}$$

$$\Sigma_{a|b} = \Lambda_{aa}^{-1}$$

$$\Sigma_{a|b}^{-1} \mu_{a|b} = \Lambda_{aa} \mu_a - \Lambda_{ab} (x_b - \mu_b)$$

$$\mu_{a|b} = \mu_a - \Lambda_{aa}^{-1} \Lambda_{ab} (x_b - \mu_b)$$

For marginal distribution, $p(x_a) = \int p(x_a, x_b) dx_b$. Let's first complete the square for x_b to integrate it out:

$$(x - \mu)^T \Sigma^{-1}(x - \mu) = \begin{pmatrix} x_a^T - \mu_a^T & x_b^T - \mu_b^T \end{pmatrix} \begin{pmatrix} \Lambda_{aa} & \Lambda_{ab} \\ \Lambda_{ba} & \Lambda_{bb} \end{pmatrix} \begin{pmatrix} x_a - \mu_a \\ x_b - \mu_b \end{pmatrix}$$
$$= x_b^T \Lambda_{bb} x_b - 2x_b^T (\Lambda_{bb} \mu_b - \Lambda_{ba} (x_a - \mu_a)) + \cdots$$