RefTarget < Constraint > # mRefCount # cEmbedded + RefTarget() NonCopyable + RefTarget() + ~RefTarget() + NonCopyable() + SetEmbedded() + NonCopyable() + operator=() + operator=() + GetRefCount() + AddRef() + Release() + sInternalGetRefCountOffset() Constraint + Constraint() + ~Constraint() + GetType() + GetSubType() + GetConstraintPriority() + SetConstraintPriority() + SetNumVelocityStepsOverride() + GetNumVelocityStepsOverride() + SetNumPositionStepsOverride() + GetNumPositionStepsOverride() and 10 more... + IsActive() + SetupVelocityConstraint() + WarmStartVelocityConstraint() + SolveVelocityConstraint() + SolvePositionConstraint() # ToConstraintSettings() * IsActive() * SetupVelocityConstraint() * WarmStartVelocityConstraint() * SolveVelocityConstraint() * SolvePositionConstraint() TwoBodyConstraint # mBody1 # mBody2 + TwoBodyConstraint() + GetType() + IsActive() + GetBody1() + GetBody2() + GetConstraintToBody1Matrix() + GetConstraintToBody2Matrix() + BuildIslands() + BuildIslandSplits() **FixedConstraint** + FixedConstraint() + GetSubType() + NotifyShapeChanged() + SetupVelocityConstraint() + WarmStartVelocityConstraint() + SolveVelocityConstraint() + SolvePositionConstraint() + SaveState()

+ SolvePositionConstraint() + SaveState() + RestoreState() + GetConstraintSettings() + GetConstraintToBody1Matrix() + GetConstraintToBody2Matrix() * mLocalSpacePosition1 * mLocalSpacePosition2 * mInvInitialOrientation * mRotationConstraintPart

* mPointConstraintPart* GetTotalLambdaPosition()* GetTotalLambdaRotation()