RefTarget < VehicleController > # mRefCount # cEmbedded + RefTarget() NonCopyable + RefTarget() + ~RefTarget() + NonCopyable() + SetEmbedded() + NonCopyable() + operator=() + operator=() + GetRefCount() + AddRef() + Release() + sInternalGetRefCountOffset() VehicleController # mConstraint + VehicleController() + ~VehicleController() # ConstructWheel() # AllowSleep() # PreCollide() # PostCollide() # SolveLongitudinalAndLateral Constraints() # SaveState() # RestoreState() WheeledVehicleController TrackedVehicleController # mForwardInput # mForwardInput # mRightInput # mLeftRatio # mBrakeInput # mRightRatio # mHandBrakeInput # mBrakeInput # mEngine # mEngine # mTransmission # mTransmission # mDifferentials # mTracks # mDifferentialLimitedSlip Ratio + TrackedVehicleController() # mPreviousDeltaTime + SetDriverInput() + WheeledVehicleController() + SetForwardInput() + GetForwardInput() + SetDriverInput() + SetForwardInput() + SetLeftRatio() + GetForwardInput() + GetLeftRatio() + SetRightInput() + SetRightRatio() + GetRightInput() + GetRightRatio() + SetBrakeInput() + SetBrakeInput() + GetBrakeInput() + GetBrakeInput() + SetHandBrakeInput() and 6 more... + GetHandBrakeInput() # SyncLeftRightTracks() and 9 more... # ConstructWheel() # ConstructWheel() # AllowSleep() # AllowSleep() # PreCollide() # PostCollide() # PreCollide() # PostCollide() # SolveLongitudinalAndLateral Constraints() # SolveLongitudinalAndLateral Constraints() # SaveState()

mEnableLeanSteeringLimit

MotorcycleController

mMaxLeanAngle

mEnableLeanController

- # mLeanSpringConstant
- # mLeanSpringDamping

SaveState()

RestoreState()

RestoreState()

- # mLeanSpringIntegrationCoefficient
- Decay # mLeanSmoothingFactor

mLeanSpringIntegrationCoefficient

- # mTargetLean # mLeanSpringIntegratedDelta
- Angle
- # mAppliedImpulse + MotorcycleController()
- + GetWheelBase()
- + EnableLeanController()
- + IsLeanControllerEnabled()
- + EnableLeanSteeringLimit()
- + IsLeanSteeringLimitEnabled()
- + SetLeanSpringConstant() + GetLeanSpringConstant()
- + SetLeanSpringDamping()
- + GetLeanSpringDamping()
 - and 6 more...
- # PreCollide()
- # SolveLongitudinalAndLateral
 - Constraints()
- # SaveState() # RestoreState()