HCMC University Of Technology
Faculty of Computer Science & Engineering

Lab 3
Synchronization
Course: Operating Systems

November 22, 2022

Goal This lab helps student to practice with the synchronization in OS, and understand the reason why we need the synchronization.

Contents In detail, this lab requires student practice with examples using synchronization techniques to solve the problem called **race condition**. The synchronization is performed on Thread using the following mechanism:

- mutual exclusion (mutex)
- semaphore
- conditional variable

Besides, the practices also introduce and include some locking variants, i.e. spinlock, read/write spinlock, sequence lock. In addition to using a lock, we may reach a **deadlock** state.

Result After doing this lab, student can understand the definition of synchronization and write a program without the race condition using the techniques above.

Requirements Student need to review the theory of synchronization.

Contents

1 Background

1.1 Race condition

Race condition is the condition of software where the system'substain behavior is dependent on the sequences of uncontrollable events. Therefore, we need mechanisms that provide mutual exclusion ability.

1.1.1 Race condition caused by atomicity

In high level programming language, we can note that a statement may be implemented in machine language (on a typical machine) as follows:

```
instruction1:= register load
instruction2:= arithmetic operation
instruction3:= register store
```

If there are two or more threads accessing a single storage, the data manipulation which is splitable may result in an incorrect final state. Such tools are provided by POSIX pthread as follows:

Mutex Lock The problem with mutex is that the thread is put into a sleep state and later is woken to process the task. This sleeping and waking action are expensive operations.

Spin lock In a short description, spin lock provides a (CPU) poll waiting until it has got previliege. If the mutex sleeps in a very short time, then it wastes the cost of expensive operations of sleeping and waking up. But if the long time is quite long, CPU polling is a big waste of computation.

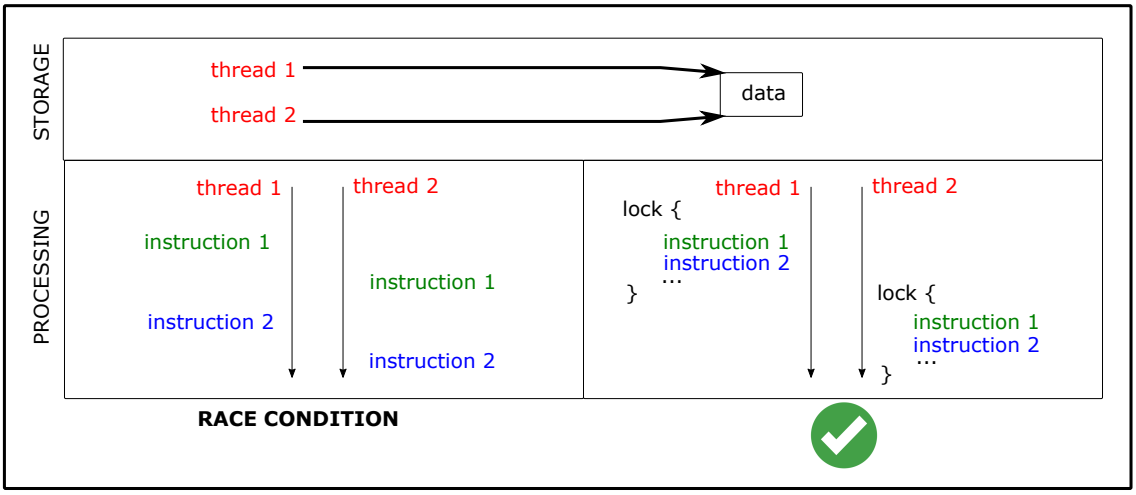

Figure 1: The race condition caused by atomicity

1.1.2 Race condition caused by in-correct ordering

In the previous chapter of process shared memory, we introduced the bounded buffer problem. Even with mutex setting, the race conditional may still happen when a producer fills in a buffer an item before a consumer empties it causing an overwriting with a loosing data. Another example of system behavior happens when a consumer retrieves a garbage value if an item is retrieved before a producer fills in a meaningful value. These wrong system behaviors are caused by the in-correct ordering of the sequence of events.

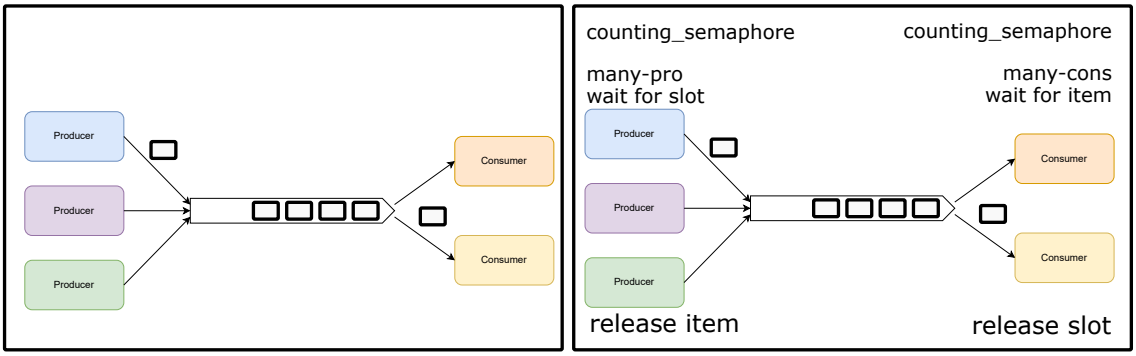

Figure 2: BoundedBuffer or Producer-Consumer problem

A **semaphore** is suited cleanly to a producer-consumer model. A semaphore is basically an object that includes an internal counter, a waiting list of threads, and supports two different operations, i.e., wait and signal. The internal counter with a proper initialization provides a good mechamism to manage the limited number of storage slot in bounded buffer.

Although semaphore is perfect fit for bounded buffer problem, it constrains on the equal number of consumers(/readers) and producers(/writer). Some updated models such as few writers many readers is not a good application for semaphore. It relaxes the matching of internal counter with the number of slot then it helps in the unbalancing context between actors who access the buffer. These following tools provide the ordering mechanism with more relaxation on the number of system actors:

Conditional variable Conditional variable is a synchronization primitive that allows threads to wait until a particular condition occur. It just allows a thread to be signaled when something of interest to

that thread occurs. It includes two operations: wait and signal. The conditional_variable can be used by a thread to block other threads until it notifies the conditional_variable.

Read-write spin lock and sequence lock In the previous section, we have seen some locking methods like mutex, spinlock, etc. In a high-speed manner, i.e., kernel driver, high-speed/fast communication, when you want to treat both the reader and the writer equally, then you have to use spin lock. The two following mechanisms provide a different priority policy between reader and writer. We introduce the main characteristics of them and then, we discuss the reader/writer conflict problem later as an exercise. (See more details in Section4.1)

Read-write spinlock: In some situations, we may have to give more access frequencies to the reader. The reader-writer spinlock is a suitable solution in this case.

Sequence lock: Reader-writer lock can cause writer starvation. Seqlock gives more permission to writer. Sequential lock is a reader-writer mechanism which is given high priority to the writer, so this avoids the writer starvation problem.

2 Programming Interface of synchronization tools

POSIX Thread library provides a standard based thread API for C/C++. The functions and declarations of many common APIs in this library are conformed to POSIX.1 standards through many versions (2003, 2017 etc.). In Linux, the library is not integrated by default, so it requires an explicit linking declaration with "-pthread". Semaphore is belong to POSIX (not pthread) standard. Sequence lock is not implemented in the both library but has added to the kernel since Linux 2.5.x.

2.1 Mutex lock

provided in POSIX Thread (pthread) library

```
#include <pthread.h>
pthread_mutex_t lock;

int pthread_mutex_init(pthread_mutex_t *mutex,
    const pthread_mutexattr_t *attr);
int pthread_mutex_destroy(pthread_mutex_t *mutex);
-----------------------------------------------------------------------
int pthread_mutex_lock(pthread_mutex_t *mutex );
int pthread_mutex_unlock(pthread_mutex_t *mutex ) ;
```

Example:

```
pthread_mutex_t lock;
pthread_mutex_init(&lock,NULL);
...
pthread_mutex_lock(&lock);
< CS >
pthread_mutex_unlock(&lock);
< RS >
```

2.2 Spin lock

provided in POSIX Thread (pthread) library

```
#include <pthread.h>
pthread_spinlock_t lock;
int pshare; /* PTHREAD_PROCESS_SHARED
             * or PTHREAD_PROCESS_PRIVATE (creator only)
             */

int pthread_spin_init(pthread_spinlock_t *lock, int pshared);
int pthread_spin_destroy(pthread_spinlock_t *lock);
-----------------------------------------------------------------------
int pthread_spin_lock(pthread_spinlock_t *lock);
int pthread_spin_unlock(pthread_spinlock_t *lock);
```

Example:

pthread_spinlock_t lock;
pthread_spin_init(&lock,PTHREAD_PROCESS_SHARED); //we can use pshared=0 for NULL setting or PTHREAD_PROCESS_SHARED
...
pthread_spin_lock(&lock);
$< CS >$
pthread_spin_unlock(&lock);
$< RS >$

2.3 Semaphore

provided in POSIX semaphore (not PTHREAD)

```
#include <semaphore.h>
sem_t sem;

int sem_init(sem_t *sem, int pshared, unsigned int value)
int sem_destroy(sem_t *sem);
-----------------------------------------------------------------------
int sem_wait(sem_t *sem);
int sem_post(sem_t *sem);
```

Example:

sem_t sem;
sem_init(&sem,0,5); //we can use pshared=0 for NULL setting or PTHREAD_PROCESS_SHARED
...
sem_wait(&sem);
$< CS >$
sem_post(&sem);
$< RS >$

2.4 Conditional Variable

provided in POSIX Thread (pthread) library

```
#include <pthread.h>
pthread_cond_t cv_count;

int pthread_cond_init(pthread_cond_t *cond, const pthread_condattr_t *attr);
int pthread_cond_destroy(pthread_cond_t *cond);
-----------------------------------------------------------------------
int pthread_cond_wait (pthread_cond_t *cond , pthread_mutex_t *mutex ) ;
int pthread_cond_signal (pthread_cond_t *cond ) ;
```

Example:

pthread_mutex_t mtx;
pthread_cond_t lock;
pthread_mutex_init(&mtx,NULL);
pthread_cond_init(&lock,NULL);
...
pthread_cond_wait(&lock,&mtx); /* May be locked if no signal is triggered */
$< CS >$
pthread_cond_signal(&lock);
$< RS >$

2.5 Reader-writer lock

provided in POSIX Thread (pthread) library

```
#include <pthread.h>

pthread_rwlock_t lock;

int pthread_rwlock_init(pthread_rwlock_t *rwlock, const pthread_rwlockattr_t *attr);
int pthread_rwlock_destroy(pthread_rwlock_t *rwlock);
-----------------------------------------------------------------------
int pthread_rwlock_rdlock(pthread_rwlock_t *rwlock);
int pthread_rwlock_wrlock(pthread_rwlock_t *rwlock);
int pthread_rwlock_unlock(pthread_rwlock_t *rwlock);
```

pthread_rwlock_init(&lock,NULL);
...
pthread_rwlock_rdlock(&lock);
$< CS >$
pthread_rwlock_unlock(&lock);
$< RS >$
...
pthread_rwlock_rdlock(&lock);
$< CS >$

pthread_rwlock_wrunlock(&lock);
< *RS* >

2.6 Sequence lock

has not provided in POSIX Thread library yet. Its implementation has existed in kernel (and hence, can be used only in kernel space) since 2.5.60.

```
is N/A Not available, implement as a flavor (exercise) an API in userspace
```

Although it lacks a userspace implementation, it is widely used in the kernel to protect buffer data in modern programming patterns with many readers, many writers, .i.e SMP Linux kernel support.

3 Practice

In this section, we work on various "native" problems to regcognize the "real" wrong behaviors. All these experiments are derived from theory slides with a minor modification. We practice the provided synchronization mechanisms and see how they work to correct the wrong things.

3.1 Shared buffer problem

```
#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>


int MAX_COUNT = 1e9;
static int count = 0;

void *f_count(void *sid) {
  int i;
  for (i = 0; i < MAX_COUNT; i++) {
    count = count + 1;
  }

  printf("Thread %s: holding %d \n", (char *) sid, count);
}

int main() {
  pthread_t thread1, thread2;

  /* Create independent threads each of which will execute function */
  pthread_create( &thread1, NULL, &f_count, "1");
  pthread_create( &thread2, NULL, &f_count, "2");


  // Wait for thread th1 finish
  pthread_join( thread1, NULL);

  // Wait for thread th1 finish
```

```
  pthread_join( thread2, NULL);

  return 0;
}
```

Step 3.1.1 Compile and execute the program

```
# The program name must match your own code,
# copycat may result error gcc: fatal error: no input files
$ gcc -pthread  -o shrdmem shrdmem.c
$ ./shrdmem
Thread 1: holding 1990079976
Thread 2: holding 1991664743
```

Step 3.1.2 Recognize the wrong issue and propose a fix mechanism using the provided synchronization tool.

Hint: pthread_mutex_lock() and pthread_mutex_unlock() are useful to protect f_count() thread worker

```
# Implement by your self the fixed shrdmem_mutex program (it is not available yet)
# copycat may result error gcc: fatal error: no input files
$ gcc -pthread -o shrdmem_mutex shrdmem.c
$ ./shrdmem_mutex
Thread 2: holding 1001990720
Thread 1: holding 2000000000
```

3.2 Bounded buffer problem

```
#include <stdio.h>
#include <stdlib.h>
#include <semaphore.h>
#include <pthread.h>

#define MAX_ITEMS 1
#define THREADS 1 // 1 producer and 1 consumer
#define LOOPS 2 * MAX_ITEMS // variable

// Initiate shared buffer
int buffer[MAX_ITEMS];
int fill = 0;
int use = 0;

/*TODO: Fill in the synchronization stuff */
void put(int value); // put data into buffer
int get(); // get data from buffer

void * producer(void * arg) {
  int i;
  int tid = (int) arg;
  for (i = 0; i < LOOPS; i++) {
    /*TODO: Fill in the synchronization stuff */
```

```
    put(i); // line P2
    printf("Producer %d put data %d\n", tid, i);
    sleep(1);
    /*TODO: Fill in the synchronization stuff */
  }
  pthread_exit(NULL);
}

void * consumer(void * arg) {
  int i, tmp = 0;
  int tid = (int) arg;
  while (tmp != -1) {
    /*TODO: Fill in the synchronization stuff */
    tmp = get(); // line C2
    printf("Consumer %d get data %d\n", tid, tmp);
    sleep(1);
    /*TODO: Fill in the synchronization stuff */
  }
  pthread_exit(NULL);
}

int main(int argc, char ** argv) {
  int i, j;
  int tid[THREADS];
  pthread_t producers[THREADS];
  pthread_t consumers[THREADS];

  /*TODO: Fill in the synchronization stuff */

  for (i = 0; i < THREADS; i++) {
    tid[i] = i;
    // Create producer thread
    pthread_create( & producers[i], NULL, producer, (void * ) tid[i]);

    // Create consumer thread
    pthread_create( & consumers[i], NULL, consumer, (void * ) tid[i]);
  }

  for (i = 0; i < THREADS; i++) {
    pthread_join(producers[i], NULL);
    pthread_join(consumers[i], NULL);
  }

  /*TODO: Fill in the synchronization stuff */

  return 0;
}

void put(int value) {
  buffer[fill] = value; // line f1
  fill = (fill + 1) % MAX_ITEMS; // line f2
```

```
}

int get() {
  int tmp = buffer[use]; // line g1
  use = (use + 1) % MAX_ITEMS; // line g2
  return tmp;
}
```

Step 3.2.1 Compile and execute the program

```
# The program name must match your own code
$ gcc -pthread -o pc pc.c
$ ./pc
Consumer 0 get data 0
Producer 0 put data 0
Consumer 0 get data 0
Producer 0 put data 1
Consumer 0 get data 1
Consumer 0 get data 1
Consumer 0 get data 1
...
```

Step 3.2.2 Recognize the wrong issue and propose a fix mechanism using the provided synchronization tool.

Hint: sem_wait() and sem_signal() are useful to protect consumer() and producer() thread worker

```
# Implement by your self the fixed pc_sem program (it is not available yet)
# copycat may result error gcc: fatal error: no input files
$ ./pc_sem
Producer 0 put data 0
Consumer 0 get data 0
Producer 0 put data 1
Consumer 0 get data 1
Producer 0 put data 2
Consumer 0 get data 2
Producer 0 put data 3
Producer 0 put data 4
Consumer 0 get data 3
Producer 0 put data 5
Consumer 0 get data 4
Consumer 0 get data 5
...
```

3.3 Dining-Philosopher problem

```
#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>
```

```
#include <semaphore.h>
#include <unistd.h>

#define N 5

pthread_mutex_t mtx;
pthread_cond_t chopstick[N];

void *philosopher(void*);
void eat(int);
void think(int);
int main()
{
   int i, a[N];
   pthread_t tid[N];

   /* BEGIN PROTECTION MECHANISM */
//    pthread_mutex_init(&mtx, NULL);

//    for (i = 0; i < N; i++)
//          pthread_cond_init(&chopstick[i], NULL);
   /* END PROTECTION MECHANISM */

   for (i = 0; i < 5; i++)
   {
      a[i] = i;
      pthread_create(&tid[i], NULL, philosopher, (void*) &a[i]);
   }

   for (i = 0; i < 5; i++)
      pthread_join(tid[i], NULL);
}

void *philosopher(void *num)
{
   int phil = *(int*) num;
   printf("Philosopher %d has entered room\n", phil);

   while (1)
   {
      /* PROTECTION MECHANISM */
//       pthread_cond_wait(&chopstick[phil], &mtx);
//       pthread_cond_wait(&chopstick[(phil + 1) % N], &mtx);
      printf("Philosopher %d takes fork %d and %d\n",
                  phil, phil, (phil + 1) % N);

      eat(phil);
      sleep(2);

       printf("Philosopher %d puts fork %d and %d down\n",
                  phil, (phil + 1) % N, phil);
```

```
        /* PROTECTION MECHANISM */
//        pthread_cond_signal(&chopstick[phil]);
//        pthread_cond_signal(&chopstick[(phil + 1) % N]);

            think(phil);
            sleep(1);
    }
}

void eat(int phil)
{
    printf("Philosopher %d is eating\n", phil);
}

void think(int phil)
{
    printf("Philosopher %d is thinking\n", phil);
}
```

Step 3.3.1 Compile and execute the program

```
# The program name must match your own code,
$ gcc -pthread -o din dinPhl.c
$ ./din
Philosopher 4 has entered room
Philosopher 4 takes fork 4 and 0
Philosopher 4 is eating
Philosopher 3 has entered room
Philosopher 3 takes fork 3 and 4
Philosopher 3 is eating
Philosopher 2 has entered room
Philosopher 2 takes fork 2 and 3
Philosopher 2 is eating
Philosopher 1 has entered room
Philosopher 1 takes fork 1 and 2
Philosopher 1 is eating
Philosopher 0 has entered room
Philosopher 0 takes fork 0 and 1
Philosopher 0 is eating
Philosopher 4 puts fork 0 and 4 down
Philosopher 4 is thinking
Philosopher 3 puts fork 4 and 3 down
Philosopher 3 is thinking
...
```

Step 3.3.2 Analyze the output and figure out the in-correct execution. Enable the PROTECTION MECHANISM and compare the output.

Step 3.3.3 With the enabled code, the problem still falls into a deadlock state, refers the illustration in Figure 3. Use the provided material in the theory background section to explain the experimental

phenomenon.

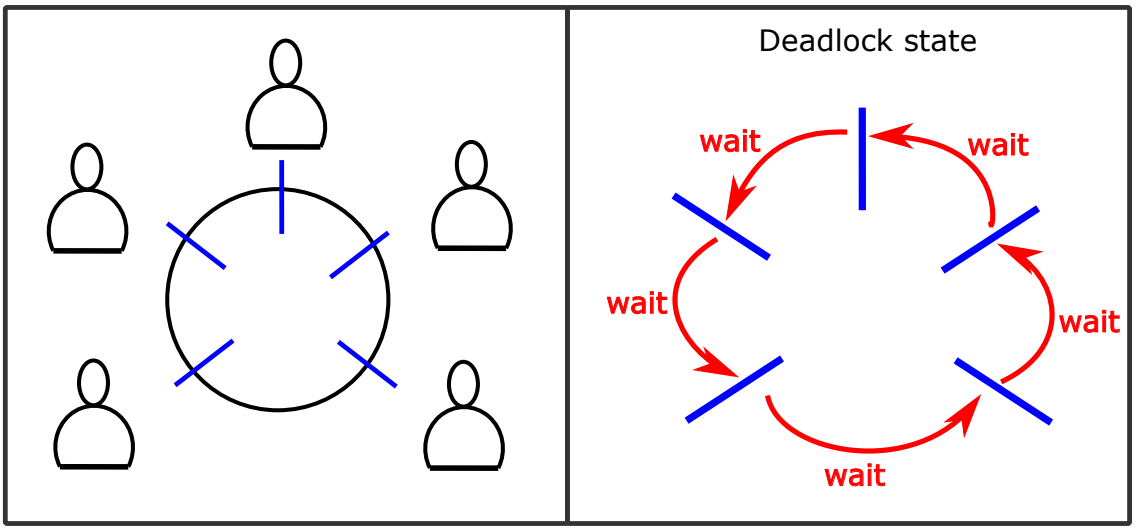

Figure 3: The dining Philosophers Problem and a deadlock state

Recall the experiment to manipulate a running process in the previous lab. Analyze the status of the working process.

```
$ ps aux  | grep din
oslab     10532  0.0  0.0  47492   800 pts/4    Sl+  13:42   0:00 ./din
oslab     10577  0.0  0.2  11760  2144 pts/0    S+   13:42   0:00 grep --
$ sudo cat /proc/<PID>/status
Name:   din
State:  S (sleeping)
...
$ sudo cat /proc/<PID>/stack
[<ffffffff811011a4>] futex_wait_queue_me+0xc4/0x120
[<ffffffff811020eb>] futex_wait+0x17b/0x270
[<ffffffff811039b6>] do_futex+0xe6/0xbc0
[<ffffffff81104501>] SyS_futex+0x71/0x150
[<ffffffff8182bedb>] entry_SYSCALL_64_fastpath+0x22/0xcb
[<ffffffffffffffff>] 0xffffffffffffffff
```

From kernel.org

```
futex_wait_queue_me:  queue_me and wait for wakeup, timeout, or signal
```

Step 3.3.4 Propose a solution to make it work.

Hint: pthread_cond_signal() is helpful here to provide the trigger to start the whole program work. Try at your own risk

```
# Implement by your self the fixed din program (it is not available yet)
# copycat may result error gcc: fatal error: no input files
$ ./din
Philosopher 4 has entered room
Philosopher 3 has entered room
```

```
Philosopher 2 has entered room
Philosopher 1 has entered room
Philosopher 0 has entered room
Philosopher 4 takes fork 4 and 0
Philosopher 4 is eating
Philosopher 4 puts fork 0 and 4 down
Philosopher 4 is thinking
Philosopher 3 takes fork 3 and 4
Philosopher 3 is eating
Philosopher 3 puts fork 4 and 3 down
Philosopher 3 is thinking
Philosopher 2 takes fork 2 and 3
Philosopher 2 is eating
Philosopher 2 puts fork 3 and 2 down
Philosopher 2 is thinking
Philosopher 1 takes fork 1 and 2
Philosopher 1 is eating
```

Step 3.3.5 Advance step It completely wrong from the scratch with an in-appropriate (or garbage) synchronization mechanism. The last working execution still contains fatal risk. Propose/design and implement an alternative protection mechanism.

Hint: Through this experiment, you learn by yourself the importance of using the correct synchronization mechanism at the begining; otherwise, we fix something and yield another work of fixing the workaround mechanism. It is important to choose the right synchronization tool in tackling a real problem.

4 Exercise

4.1 Problem 1

Design and implement sequence lock API.

```
#include "seqlock.h" /* TODO: implement this header file */

/*
 *  TODO: Implement these following APIs
 */
pthread_seqlock_t lock;

/* Init with default NULL attribute attr=NULL */
int pthread_seqlock_init(pthread_seqlock_t *seqlock);
int pthread_rwlock_destroy(pthread_seqlock_t *seqlock);
-------------------------------------------------------------------------
int pthread_seqlock_rdlock(pthread_seqlock_t *seqlock);
int pthread_seqlock_rdunlock(pthread_seqlock_t *seqlock);
int pthread_seqlock_wrlock(pthread_seqlock_t *seqlock);
int pthread_seqlock_wrunlock(pthread_seqlock_t *seqlock);
```

The reader/writer conflict resolution following the description:
Reader-writer lock conflict resolution

- When there is no thread in the critical section, any reader or writer can enter into a critical section. But only one thread can enter.
- If the reader is in critical section, the new reader thread can enter ocasionally, but the writer cannot enter.
- If the writer is in critical section, no other reader or writer can enter.
- If there are some readers in the critical section by taking the lock, and there is a writer want to enter. That writer has to wait if another reader is coming until all of readers have finish. That why this mechanism is reader prefer.

Sequence lock conflict resolution the conflict resolution mechanism in teader-writer lock can cause writer starvation. The following policy is implemented by the sequence lock:

- When no one is in the critical section, one writer can enter the critical section and takes the lock, increasing the sequence number by one to an odd value. When the sequence number is an odd value, the writing is happening. When the writing has been done, the sequence is back to even value. Only one writer is allow into critical section.
- When the reader wants to read data, it checks the sequence number which is an odd value, then it has to wait until the writer finish.
- When the value is even, many readers can enter the critical section to read the value.
- When there are only a reader and no writer in the critical section, if a writer want to enter the critical section it can take the lock without blocking.

4.2 Problem 2

(***Aggregated Sum***) Implement the thread-safe program to calculate the sum of a given integer array using $< tnum >$ number of threads. The size of the given array $< arrsz >$ and the $< tnum >$ value is provided in the program arguments. You are provided a pre-processed argument program with the usage as the following description.

```
aggsum, version 0.01

 usage:  aggsum arrsz tnum [seednum]

 Generate randomly integer array size <arrsz> and calculate sum parallelly
 using <tnum> threads. The optional <seednum> value use to control the
 randomization of the generated array.

   Arguments:

     arrsz    specifies the size of array.
     tnum     number of parallel threads.
     seednum  initialize the seed of the randomized generator srand().
```

The last argument < *seednum* > is used in srand(), generating a fixed sequence of integer values. Call the following routine to generate a random array *buf* of integer with *arraysize* elements.

```
int generate_array_data (int* buf, int arraysize, int seednum);
```

TODO: You have to implement the following thread routine.

```
struct _range {
  int start;
  int end;
};

void* sum_worker (struct _range idx_range) {
  //printf("In worker from %d to %d\n", idx_range.start, idx_range.end);

  /*
   * TODO implement a thread safe sum operator works in the range
   *       i.e. for (i=idx_range.start; i<= idx_range.end; i++){}
   *      and write the sum to sumbuff  (in program global data)
   */
}

int main()
{
   pthread_t tid; /* Sample code is only single thread */
   struct _range thread_idx_range;

   ...
   /* Sample code use full range */
   thread_idx_range.start = 0;
   thread_idx_range.end = arrsz - 1;

   ...
   /* TODO: implement multi-thread mechanism */
   pthread_create(&tid, NULL, sum_worker, thread_idx_range));
}
```

You need to implement a single-threaded program to compare the result of aggregated Sum with the one of the multi-threaded program.

4.3 Problem 3

(*Interruptable system logger*) Design and implement a logger support the two operations *wrlog*() and *flushlog*() to manipulate the log data buffer "logbuf"

```
#define MAX_LOG_LENGTH 10
#define MAX_BUFFER_SLOT 5
char ** logbuf;
```

```
int wrlog(char** logbuf, char* new_data);
int flushlog(char** logbuf);
```

In this problem, there are many programs or actors that call wrlog() to append the log data to a shared buffer (i.e., log-file cache) which can be flushed to disk eventually. For simplicity, we assume the buffer contains 5 (= MAX_BUFFER_SLOT) data slots and the flush event occurs periodically at time out. We also assume a LOG is a fixed length string, i.e. *char* $new\_log[MAX\_LOG\_LENGTH]$.

In practical point of view, the behavior of the system can be illustrated as a sequence of writing log data and the flush will be periodically triggered when a timeout is reached.

```
int main()
{
  wrlog(data1);
  wrlog(data1);
  wrlog(data1);
  ...
  wrlog(datan);
}
```

In summary, the draft operations of the logger are:

wrlog() append data to shared buffer but not exceed the buffer size. If it reaches the limits, it needs to wait until the buffer is flushed.

flushlog() clean buffer aka. move all the stored items to somewhere (in here is printing to screen) and then delete all of them. This action runs eventually; for simplicy we just make a periodical call here.

Further development: The interruptable mechanism of flush log can (further) support more unpredict events, i.e., it can handle a signall $SIGUSR1$, $SIGUSR2$ which are introduced in Lab 1 appendix.

You are provided a referenced code with non-protected buffer by default, the program's output is:

```
$./logbuf
flushlog()
wrlog(): 0
wrlog(): 1
wrlog(): 2
wrlog(): 3
wrlog(): 4
wrlog(): 7
wrlog(): 12
wrlog(): 13
wrlog(): 16
wrlog(): 17
wrlog(): 21
wrlog(): 24
wrlog(): 11
wrlog(): 26
wrlog(): 14
wrlog(): 6
```

```
wrlog(): 27
wrlog(): 28
wrlog(): 8
wrlog(): 20
wrlog(): 9
wrlog(): 22
wrlog(): 10
wrlog(): 19
wrlog(): 25
wrlog(): 29
wrlog(): 18
wrlog(): 23
wrlog(): 5
wrlog(): 15
flushlog()
Slot  0: 0
Slot  1: 1
Slot  2: 2
Slot  3: 3
Slot  4: 4
Slot  5: 7
Slot  6: 12
flushlog()
flushlog()
flushlog()
```

TODO: Implement the protection mechanism for wrlog() and flushlog() routines to make it a safe data accessing (to buffer). If it has a proper configuration then the program behavior is somehow like this illustration (**comment out** the print function name in wrlog() and flushlog() to make **this clean output**).

```
$ ./logbuf
Slot  0: 0
Slot  1: 1
Slot  2: 2
Slot  3: 3
Slot  4: 4
Slot  5: 5
Slot  0: 12
Slot  1: 6
Slot  2: 7
Slot  3: 10
Slot  4: 8
Slot  5: 11
Slot  0: 17
Slot  1: 13
```

```
Slot  2: 16
Slot  3: 15
Slot  4: 14
Slot  5: 18
Slot  0: 25
Slot  1: 20
Slot  2: 19
Slot  3: 21
Slot  4: 22
Slot  5: 23
Slot  0: 27
Slot  1: 28
Slot  2: 26
Slot  3: 24
Slot  4: 29
Slot  5: 9
```