


ObservablePlane::Notify



```
graph LR; A[ObservablePlane::Notify] --> B[Observable::Notify]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a gray fill and a dark gray border, containing the text 'ObservablePlane::Notify'. The right box has a white fill and a dark gray border, containing the text 'Observable::Notify'.

Observable::Notify