

# Ch 05: World of Sensors

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by Dr. Sethavidh Gertphol

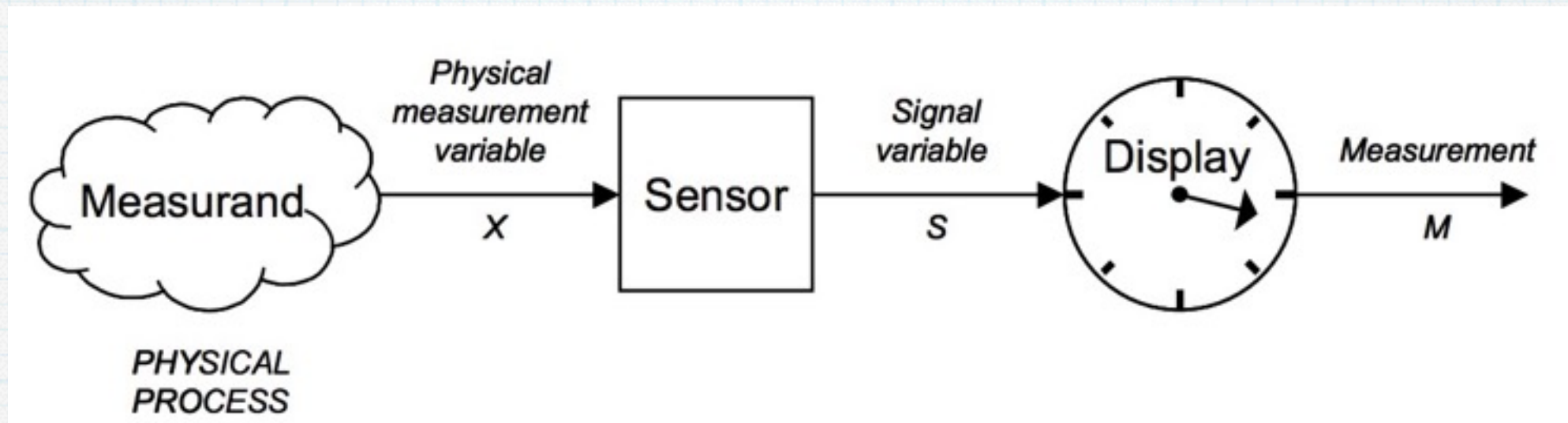


# Outline

- \* characteristics of sensors
- \* sensor calibration
- \* show several types of sensors



# sensors characteristics



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## \* range

- \* minimum and maximum measured value that sensor can detect
- \* usually designed that way
- \* try to measure value outside of range can damage sensor



# sensors characteristics

- \* **accuracy:**

- \* how close the sensor output is to the true (actual) value
- \* usually reported as relative errors (  $\pm\%$  )

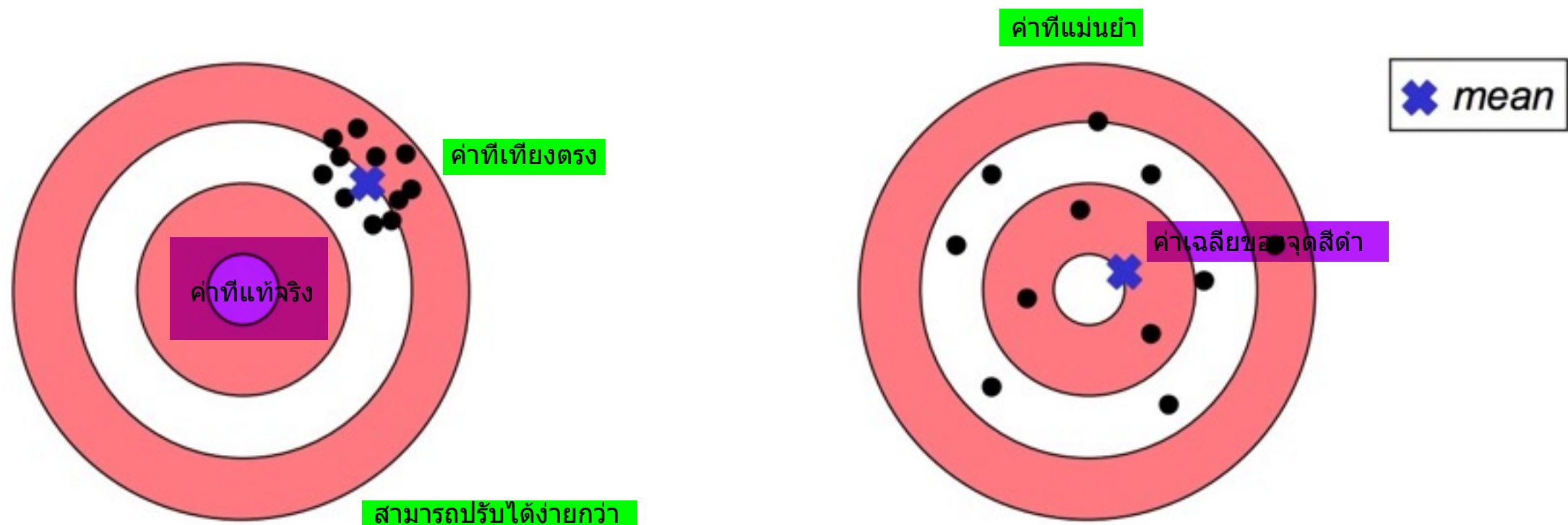
- \* **precision:**

- \* how close are successive output when measure the same value
- \* also called **repeatability**



# accuracy v.s. precision

- Which shooter is more accurate?
- Which shooter is more precise?



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# sensors characteristics

- \* **resolution**

ค่าน้อยสุดที่มันตรวจจับได้

- \* smallest change in value that is detectable by that sensor

- \* **response time**

เวลาที่ output ออกมาแบบเสถียร



- \* how long the sensor will reach its stable output

- \* **sensitivity**

เป็นกราฟ input-output เป็นความชันของกราฟ

- \* how large does the output change compared to measured value
- \* slope of sensor response graph



# sensor characteristics

- \* **linearity**

ความเป็นเส้นตรงของกราฟ เป็นเส้นตรงคือดี

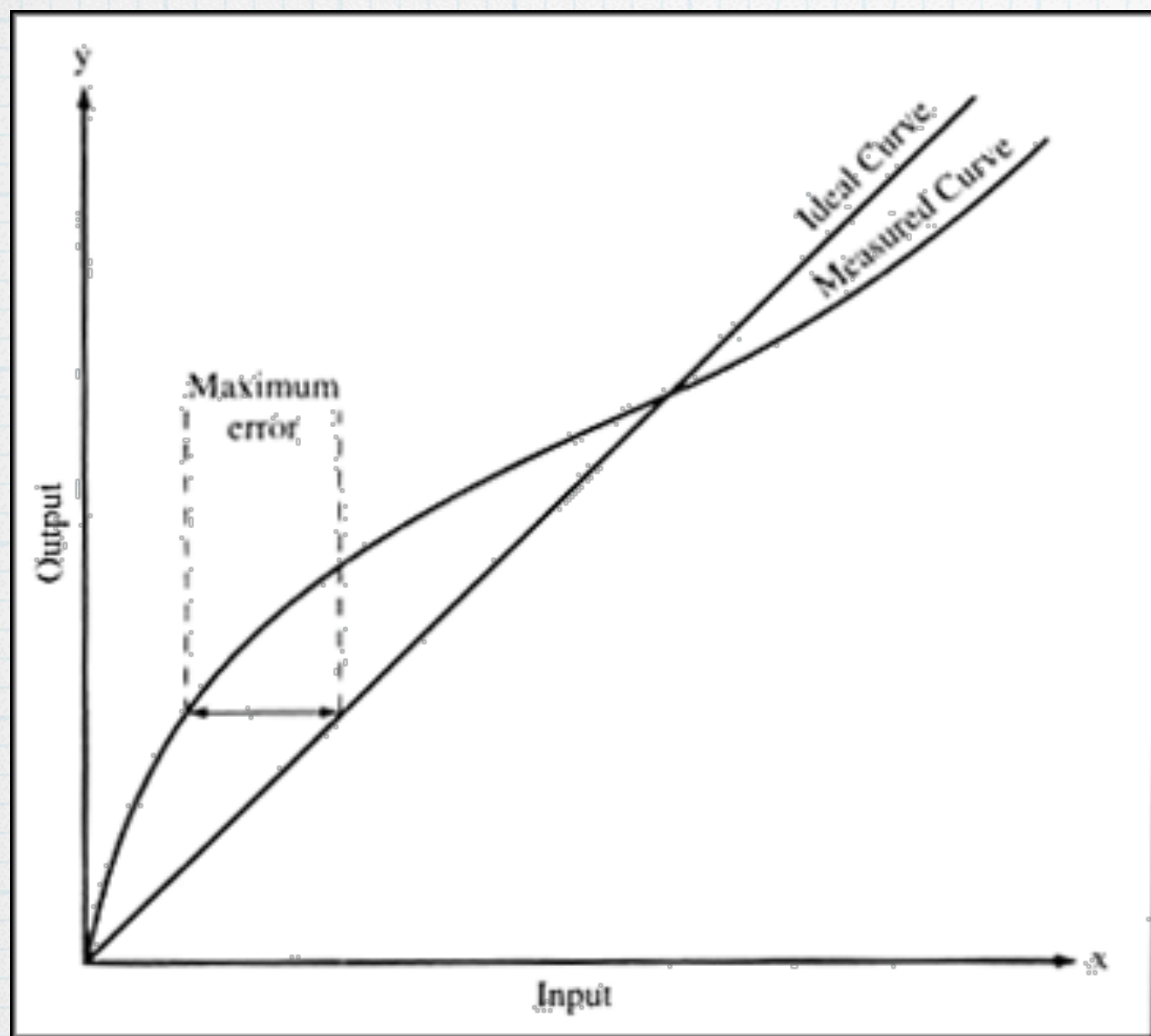
- \* is the **relationship between measured value and output linear** across its range

- \* **hysteresis**

ค่าที่เราวัดจากน้อย-มาก กับ มาก-น้อย จะได้ผลไม่เหมือนกัน

- \* how different the outputs are when measuring one way compared with the other





<http://www.ni.com/white-paper/14860/en/>

<http://www.mfg.mtu.edu/cyberman/machtool/machtool/sensors/fundamental.html>

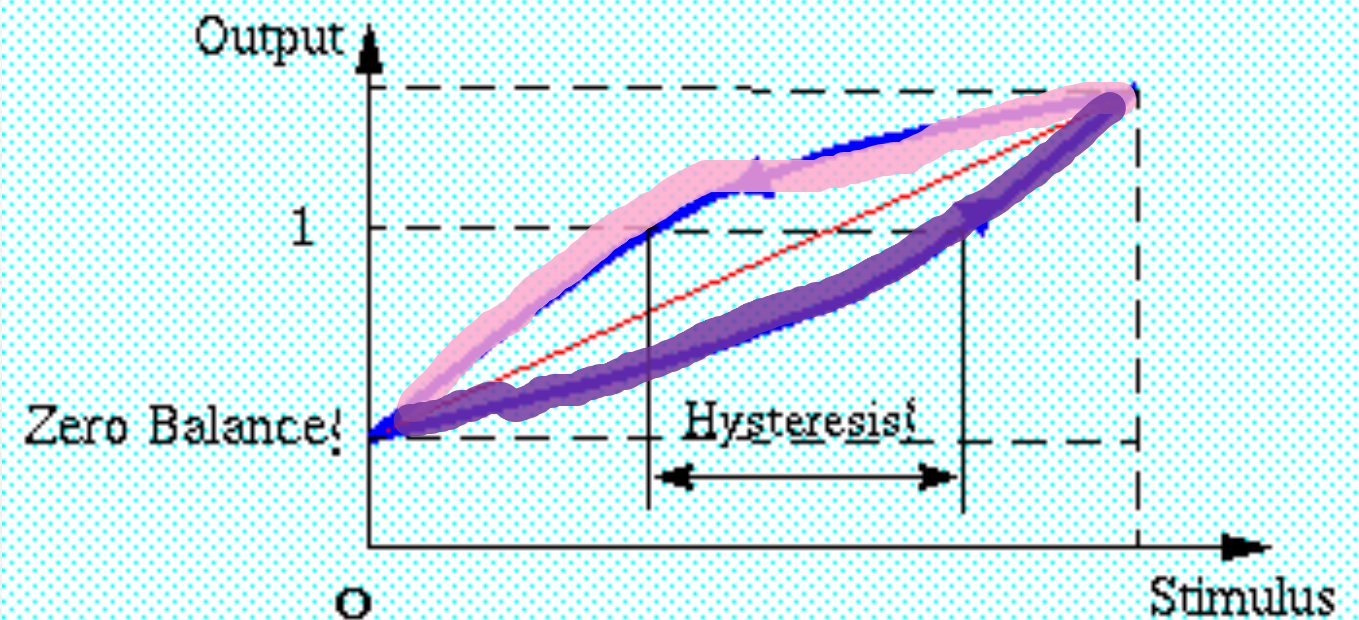


Figure 2 Transfer function with hysteresis

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# sensor calibration

- \* out-of-the-box sensor may have errors in its reading

การปรับเทียบว่า sensor อ่านมาได้ตรงกับความเป็นจริงแค่ไหน

- \* need to **calibrate** before use
- \* must have **standard reference** or trusted readings to calibrate against
- \* temperature: boiling water ice
- \* rangefinder: rulers measuring tape



# type of errors

ค่าที่วัดได้คลาดกับความเป็นจริงเท่าไร

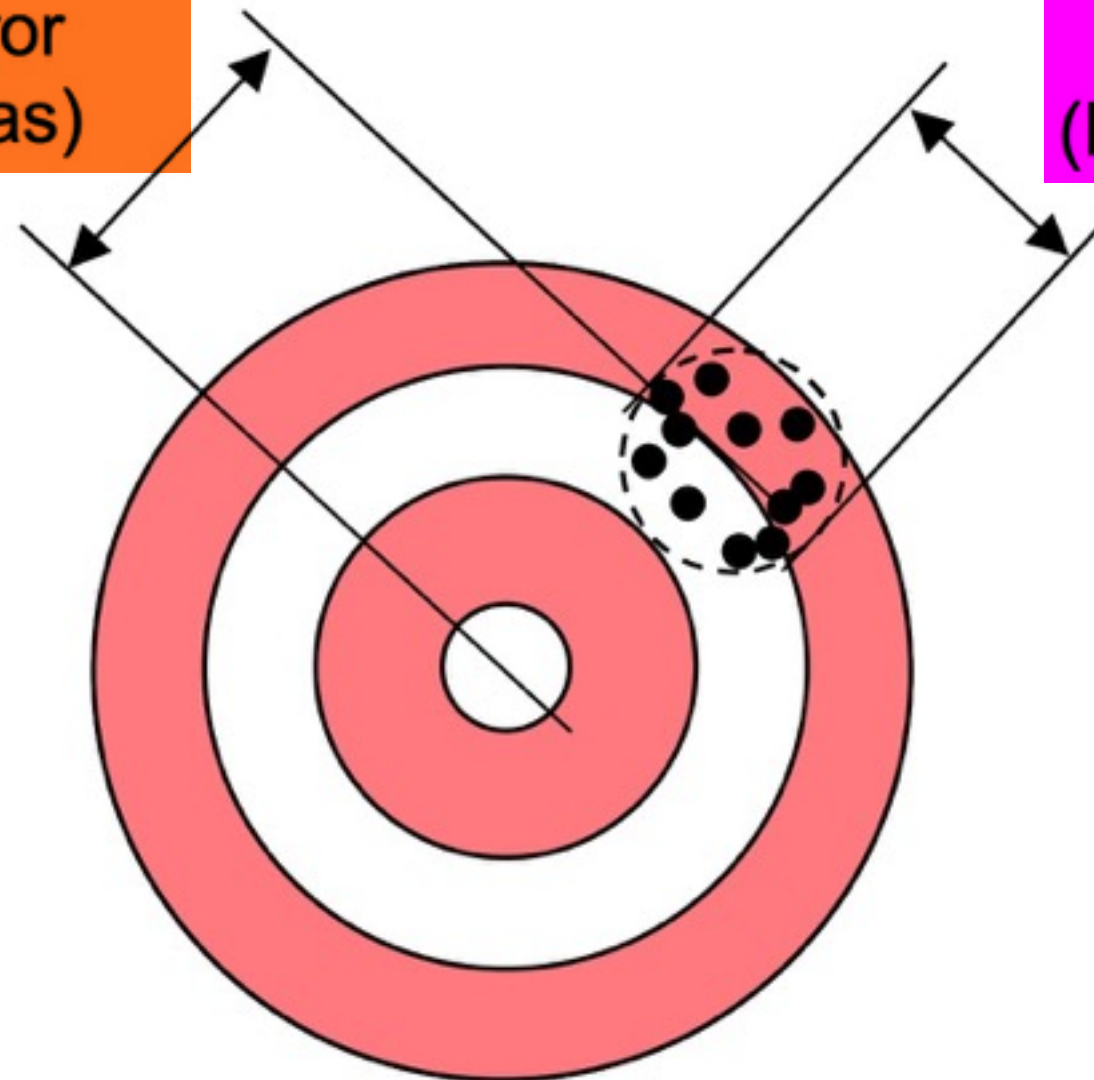
**Systematic  
error  
(Bias)**

เราปรับเทียบได้

ความคลาดเคลื่อนของ sensor

**Random  
error  
(Precision)**

เราแก้ไขอะไรไม่ได้

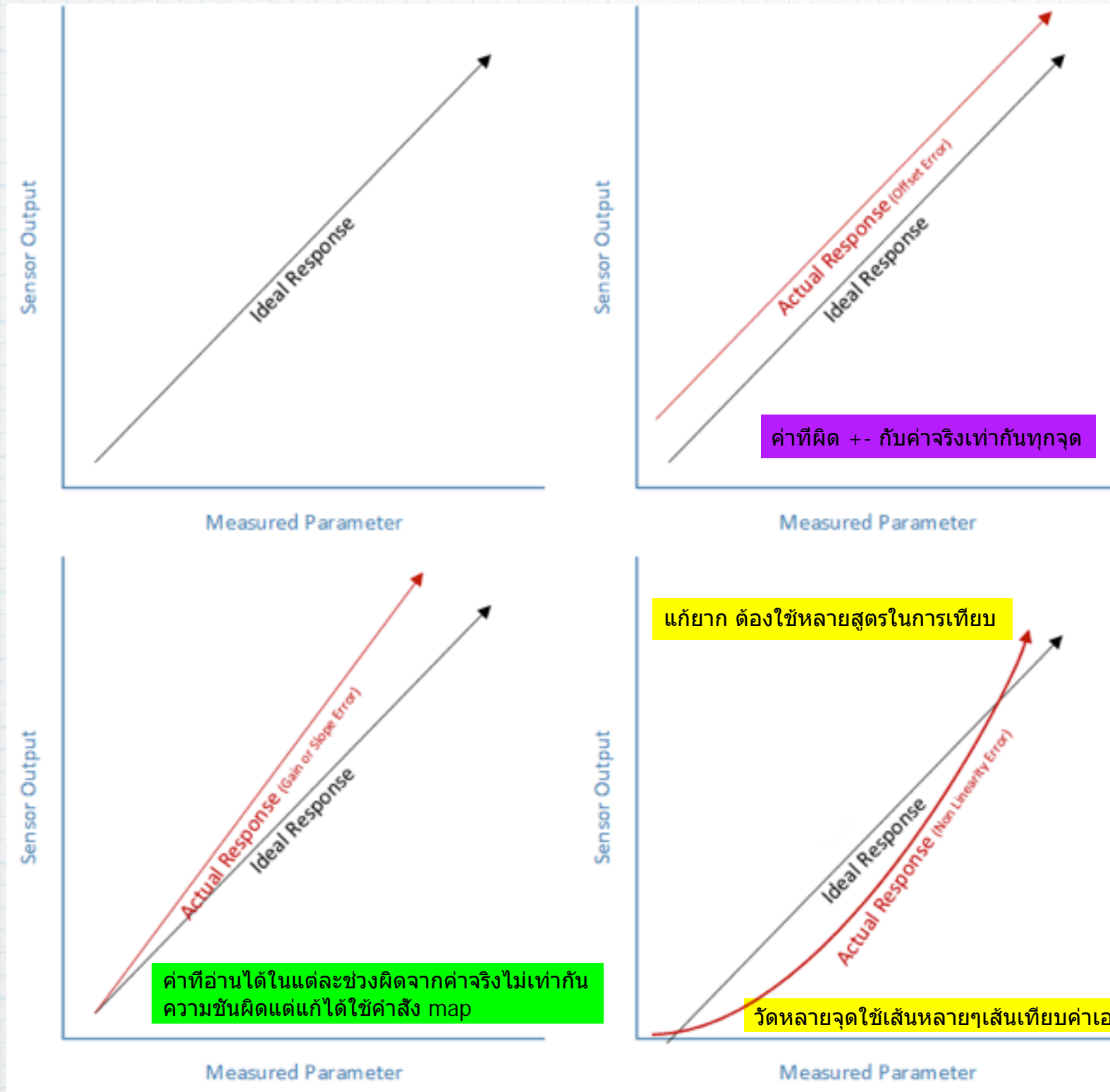


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# type of errors



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# type of calibration

- \* one-point calibration

- \* can fix offset error

- \* two-point calibration

- \* fix gain and offset error
  - \* can use `map()` function

- \* multipoint calibration

- \* fix non-linear error



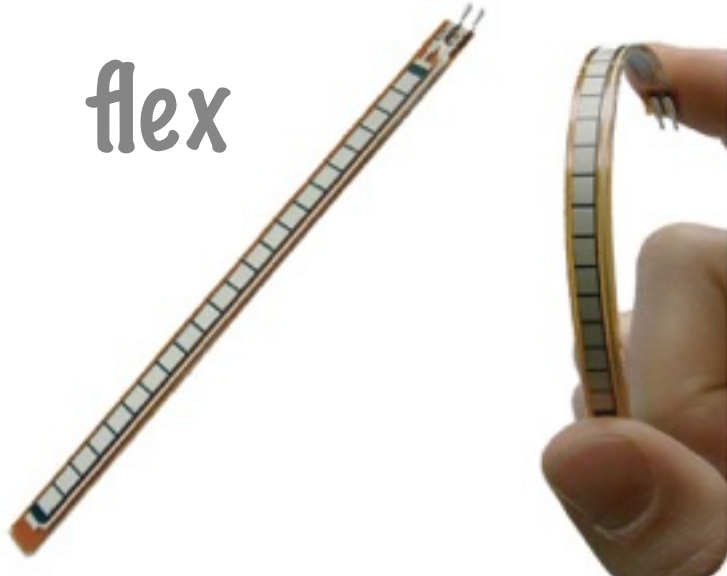
# There is a sensor for that

- \* several types of sensors created for industrial applications
- \* many are now very cheap
- \* there is a sensor to detect almost anything



# Force-based sensor

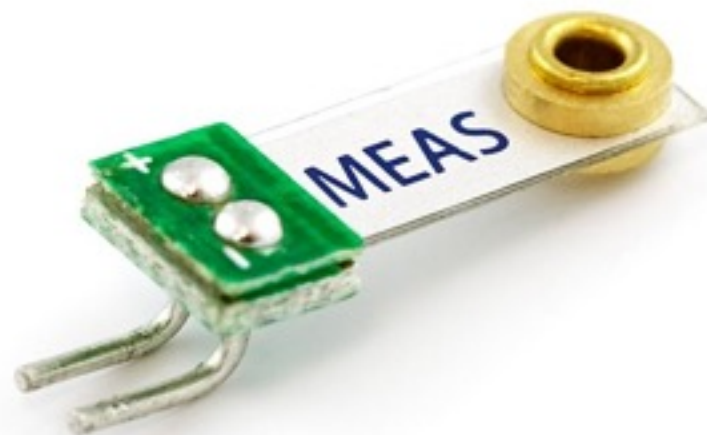
flex



force



soft pot



vibration

load



tilt



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# light, sound, color, range

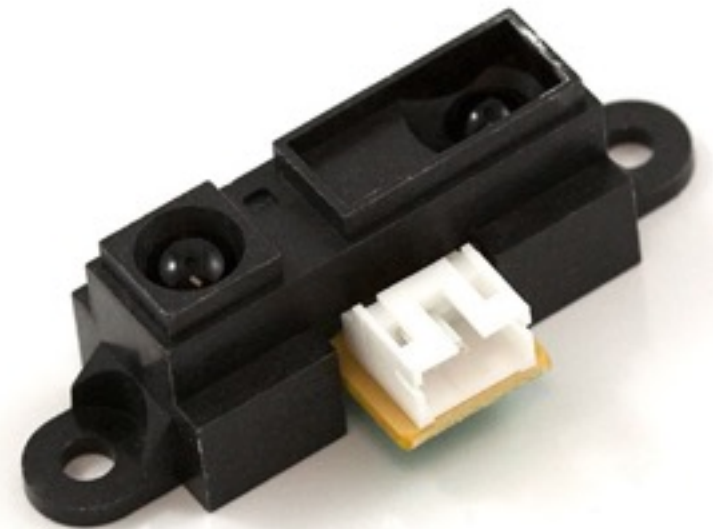


light



sound

ir range finder



color



ultrasonic  
range finder



passive ir

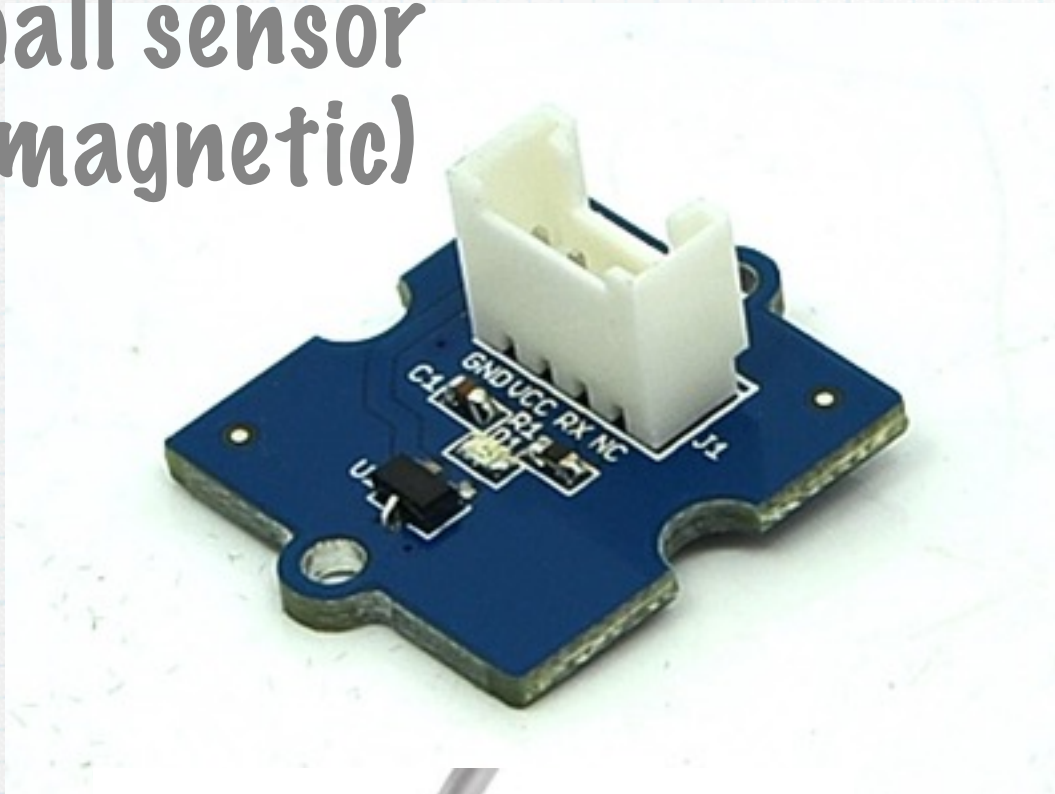
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# field, current, temperature

hall sensor  
(magnetic)



temperature  
(water-proof)



current  
clamp



accelerometer and gyro





# earth, air, water



LPG/Methane/Hydrogen



dust sensor



pH sensor



alcohol/carbon monoxide



soil  
moisture



geophone



water  
conductance



# biometric

fingerprint scanner



pulse sensor

heart rate sensor



mind wave  
sensor



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muscle sensor



images from [www.sparkfun.com](http://www.sparkfun.com)



# References

1. Sensor Fundamentals, retrieved from <http://www.mfg.mtu.edu/cyberman/machtool/machtool/sensors/fundamental.html>
2. Ricardo Gutierrez-Osuna, Lecture Notes on Intelligent Sensor Systems, retrieved from, [http://research.cs.tamu.edu/prism/lectures/iss/iss\\_l2.pdf](http://research.cs.tamu.edu/prism/lectures/iss/iss_l2.pdf)
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4. Bill Earl, Why Calibrate?, adafruit, retrieved from <https://learn.adafruit.com/calibrating-sensors?view=all>