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CPSC 213 Introduction to Computer Systems

Unit 1f Dynamic control flow

All slides adapted from materials by Mike Feeley, Jonatan Schroeder, Robert Xiao, and Jordon Johnson

Announcements

- Google doc for lecture questions
 - See Piazza for link, section 102

https://docs.google.com/document/d/1G6hkekQS7mT9lFpP8AVftYao8vLRuj

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- Add your question anonymously (at the top)
- Help answer questions too!

Overview

Reading

• Companion: 2.7.4, 2.7.7-2.7.8

Reference

■ Text: 3.6.7, 3.10

- Learning Goals
 - Write C programs that use function pointers
 - Explain how Java implements polymorphism
 - Identify the number of memory references that occur when a static method is called in Java and when an instance method is called
 - Convert Java instance-method call into equivalent C code that uses function pointers
 - Convert C programs that use function pointers into assembly code
 - Explain why switch statements in C (and Java until version 1.7) restrict case labels to cardinal types (i.e, things that map to natural numbers)
 - Convert C switch statement into equivalent C statement using gotos and an array of label pointers (a gcc extension to C)
 - Convert C switch statement into equivalent assembly language that uses a jump table
 - Determine whether a given switch statement would be better implemented using if statements or a jump table and explain the tradeoffs involved

Review: static procedure calls

- Static method invocations and procedure calls
 - target method/procedure address is known statically
- In Java:
 - *static* methods are class methods
 - invoked by naming the class, not an object

- In C:
 - specify procedure name

```
public class A {
   static void ping() {}
}

public class Foo {
   static void foo() {
      A.ping();
   }
}
```

```
void ping();
void foo() {
  ping();
}
```

Polymorphism

- Invoking a method on an object in Java
 - variable that stores the object has a static type (apparent type)
 - the object reference is dynamic and so is its type
 - object's actual type must be a subtype of the apparent type of the referring variable
 - but object's actual type may override methods of the apparent type
- Polymorphic Dispatch
 - target method address depends on the type of the referenced object
 - one call site can invoke different methods at different times

```
class A {
  void ping() {}
  void pong() {}
}

class B extends A {
  void ping() {}
  void wiff() {}
}
```

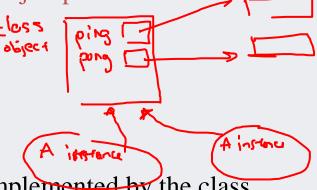
```
static void foo(A a) {
   a.ping();
   a.pong();
}

static void bar() {
   foo(new A());
   foo(new B());
}
```

Polymorphic dispatch

```
static void foo(A a) {
  a.ping();
}
```

- Method address is determined dynamically
 - compiler can not hardcode target address in procedure call
 - instead, compiler generates code to lookup procedure address at runtime
 - address is stored in memory in the object's class jump table
- Class jump table
 - every class is represented by a class object
 - objects store a pointer to their class object
 - the class object stores the class's jump table
 - the jump table stores the address of methods implemented by the class
- Static and dynamic of method invocation
 - address of jump table is determined dynamically
 - objects of different actual types will have different jump tables
 - method's offset into jump table is determined statically



Java dispatch example class A { void ping() {} void pong() {} class B extends A { jump table void ping() {} A.ping() {} void wiff() {} Class A ping• static void foo(A a) { pong A.pong() {} a.ping(); jump table a.pong(); Class B B.ping() {} ping • static void bar() { pong • foo(new A()); B.wiff() {} foo(new B()); wiff an A a B r5 foo(a): a a foo's 0x0: ra $r[0] \leftarrow m[r[5]+4] + r0 = a$ $r[1] \leftarrow m[r[0]]$ # r1 = a.class activation 0x4: a frame pc $\leftarrow m[r[1]+0*4] \# a.ping()$ Runtime stack $\leftarrow m[r[1]+1*4] \# a.pong()$ рс

Dynamic jumps in C

- Function pointer
 - a variable that stores a pointer to a procedure
 - declared as:

```
• <return-type> (*<variable-name>)(<formal-argument-list>);
```

- used to make dynamic call
 - <variable-name> (<actual-argument-list>);
- Example

```
void ping() {}
```

```
void foo() {
  void (*aFunc) ();

  aFunc = ping;
  aFunc(); // calls ping
}
```

assign using procedure name without () call using variable name with ()

• What is the difference between these two C snippets?

- A. (2) calls foo, but (1) does not
- B. (1) is not valid C
- (1) jumps to foo using a dynamic address and (2) a static address
- D. They both call foo using dynamic addresses
- E. They both call foo using static addresses

Exercise 1f.2

PrairieLearn – IC_11_03

- (a) write a function that
 - EITHER adds two numbers or multiplies them
 - depending on a parameter
 - using function pointers
- (b) write code that uses this function

- Use a struct to store jump table
 - Declaration of class:

```
struct A_class {
  void (*ping) (void*);
  void (*pong) (void*);
};
```

```
If we want something like this:

| class A {
| void ping() {...} |
| void pong() {...} |
| int i; |
| }
```

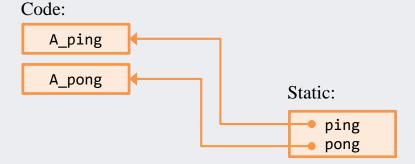
Declaration of instance methods:

```
void A_ping (void* thisv) { printf("A_ping\n"); }
void A_pong (void* thisv) { printf("A_pong\n"); }
```

```
void A_ping (void* thisv) {
   struct A* this = thisv;
   printf("A_ping %d\n", this->i);
}
}
```

Static allocation and initialization of class object (i.e. class jump table)

```
struct A_class A_class_table = {A_ping, A_pong};
```



(continued)

- Object (instance of class)
 - Object template

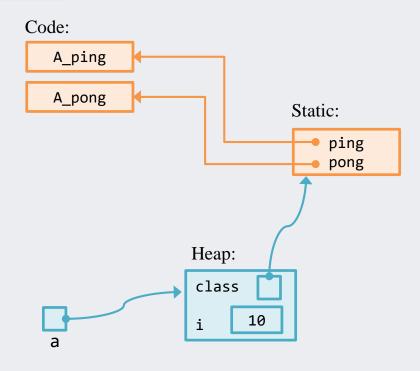
Constructor method

Allocating an instance

```
struct A* a = new_A(10);
```

Calling instance methods

```
a->class->ping(a);
a->class->pong(a);
```



mimicking class B extends A

• B's class struct (jump table) is a super-set of A's

```
struct B_class {
  void (*ping) (void*);
  void (*pong) (void*);
  void (*wiff) (void*);
};
```

```
struct A_class {
  void (*ping) (void*);
  void (*pong) (void*);
};
```

```
class B extends A {
  void ping() {...}
  void wiff() {...}
}
```

• B's method declarations and class object (static) allocation

```
void B_ping (void* thisv) { printf("B_ping\n"); }
void B_wiff (void* thisv) { printf("B_wiff\n"); }

struct B_class B_class_table = {B_ping, A_pong, B_wiff};
```

And we will construct/allocate struct B instances similarly

```
Code:

A_ping

Static:

ping
pong

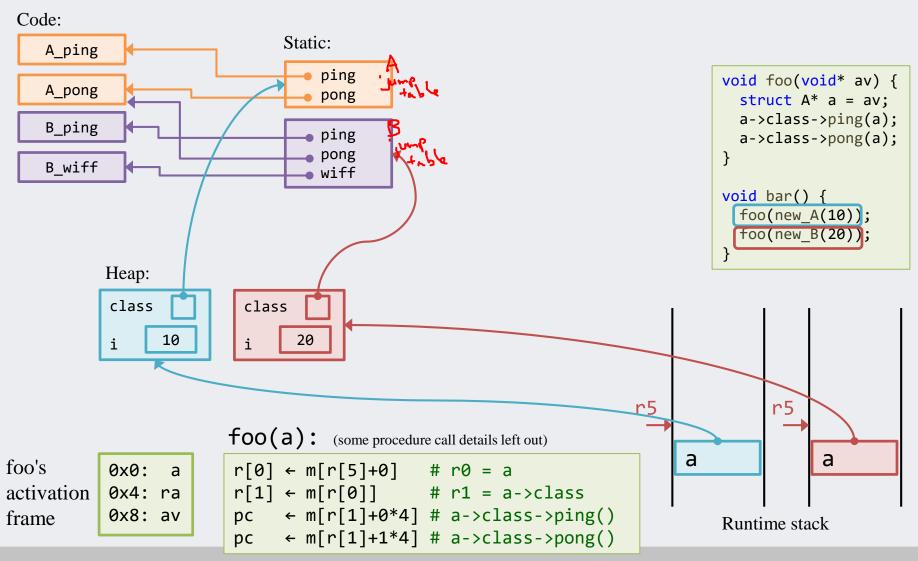
B_ping

ping
pong

pong

B_wiff
```

Dispatch diagram for C polymorphism



ISA for polymorphic dispatch

```
void foo(void* av) {
   struct A* a = av;
   a->class->ping(a);
   a->class->pong(a);
}
```

```
r[0] ← m[r[5]+0] # r0 = a
r[1] ← m[r[0]] # r1 = a->class
pc ← m[r[1]+0*4] # a->class->ping()
pc ← m[r[1]+1*4] # a->class->pong()
```

- How do we compile a->class->ping()?
- Pseudocode:
 - $pc \leftarrow m[r[1]+0*4]$
- Jumps currently supported by SM213 ISA (so far):

Name	Semantics	Assembly	Machine
jump	pc ← a	j a	b aaaaaaaa
indirect jump	$pc \leftarrow r[t] + o (or r[t] + pp*2)$	j o(rt)	ctpp

- We will benefit from a new instruction in our ISA
 - that jumps to an address that is stored in memory (not just in a register)

ISA for polymorphic dispatch

Double-indirect jump instruction (b+o)

• jump to address stored in memory using base+offset addressing

Name	Semantics	Assembly	Machine
jump	pc ← a	jа	b aaaaaaaa
indirect jump	$pc \leftarrow r[t] + o (or r[t] + pp*2)$	j o(rt)	ctpp
dbl-ind jump b+o	$pc \leftarrow m[r[t] + o] (or m[r[t] + pp*2])$	j *o(rt)	dtpp

```
r[0] \( m[r[5]+0] \) \( # r0 = a \)
r[1] \( \cdot m[r[0]] \) \( # r1 = a->class \)
pc \( \cdot m[r[1]+0*4] \) \( # a->class->ping() \)
pc \( \cdot m[r[1]+1*4] \) \( # a->class->pong() \)
```

```
ld 0(r5), r0 # r0 = a
ld (r0), r1 # r1 = a->class
j *0(r1) # a->class->ping()
j *4(r1) # a->class->pong()
```

```
1d \quad 0(r5), r0 + r0 = a
ld (r0), r1 # r1 = a \rightarrow class
deca r5 # allocate frame
st r0, (r5) # put a on stack
gpc $2, r6 # get return address
j *0(r1) # a->class->ping(a)
inca r5 # deallocate frame
deca r5
               # allocate frame
st r0 (r5)
               # put a on stack
gpc $2, r6
              # get return address
j *4(r1)
              # a->class->pong(a)
               # deallocate frame
inca r5
```

Other uses of function pointers

Consider: Quicksort, to sort integers

```
int partition (int* array, int left, int right, int pivotIndex) {
  int pivotValue, t;
  int storeIndex, i;
  pivotValue = array [pivotIndex];
  array [pivotIndex] = array [right];
  array [right] = pivotValue;
  storeIndex = left;
  for (i=left; i<right; i++)</pre>
   if (array [i] <= pivotValue) {</pre>
     t
           = array [i];
     array [i] = array [storeIndex];
     array [storeIndex] = t;
     storeIndex += 1;
 t
                    = array [storeIndex];
 array [storeIndex] = array [right];
 array [right]
 return storeIndex;
void quicksort (int* array, int left, int right) {
  int pivotIndex;
 if (left < right) {</pre>
   pivotIndex = partition (array, left, right, left + (right-left)/2);
   quicksort (array, left, pivotIndex - 1);
   quicksort (array, pivotIndex + 1, right
void sort (int* array, int n) {
  quicksort (array, 0, n-1);
}
```

Quicksort

- The logic/code for Quicksort/partition is *mostly* type-independent
 - change parameter to sort anything
 - actually, like Java, array parameter will be a pointer to anything (or anything the same size as a pointer)

```
int partition ( void** array, int left, int right, int pivotIndex) {
  void* pivotValue, * t;
  int
       storeIndex, i;
                                         Actually, only 3 parts of the code are type-dependent

    array parameter – easy to deal with

  pivotValue = array [pivotIndex];
                                             pivotValue type – easy to deal with
  array [pivotIndex] = array [right];
  array [right] = pivotValue;
                                             • comparison - ???
  storeIndex = left;
  for (i=left; i<right; i++)</pre>
    if (array [i] <= pivotValue) {</pre>
                        = array [i];
      array [i] = array [storeIndex];
      array [storeIndex] = t;
      storeIndex += 1;
                   = array [storeIndex];
  t
 array [storeIndex] = array [right];
 array [right] = t;
  return storeIndex;
```

Type-independent Quicksort, in Java

```
class ComparableInteger<Integer> extends Integer {
  @Override
  int compareTo(Integer i) {
    return intValue() < i.intValue()? -1: intValue == i.intValue()? 0: 1;
  }
}</pre>
```

Type-independent, parameterized Quicksort in C

Using a comparator function pointer

```
int partition (void** array, `... , int (*cmp) (void*, void*)) {
 void* pivotValue, *t;
 int storeIndex, i;
 pivotValue
          = array [pivotIndex];
 array [pivotIndex] = array [right];
 array [right] = pivotValue;
 storeIndex = left;
                                      formerly,
 for (i=left; i<right; i++)</pre>
   +
              = array [i];
     array [i] = array [storeIndex];
     array [storeIndex] = t;
     storeIndex += 1;
 t
                 = array [storeIndex];
 array [storeIndex] = array [right];
            = t;
 array [right]
 return storeIndex;
```

Side note: avoiding void* confusion

```
void sort (void** array, int n, int (*cmp) (void*, void*) ) { ...

int cmpIntegers (void* av, void* bv) {
   int* a = av;
   int* b = bv; ...
int* pa [] = {a, a+1, a+2};
   sort ((void**) pa, 3, cmpIntegers);
```

- It is a pointer type that cannot be dereferenced (directly)
 - "just an address", sometimes called an *opaque* pointer
- in C we used it to represent a pointer to anything
- before using, you must cast it to another pointer type
 - there is no type checking on this type case
 - casting can be done implicitly; explicit cast is not needed
- code with void* can be confusing, especially when encountering void**
- C's typedef statement:
 - creates a new type name for a type expression
 - leads to more readable code
 - common convention: end type names with a "_t"
 - e.g. typedef void* element_t;

Sorting with typedef

Using void*:

```
int partition ( void** array, ..., int (*cmp) (void*, void*)) {
  void* pivotValue, *t;
  ...
}
```

Using new type defined by typedef:

```
typedef void* element_t;
int partition ( element_t* array, ..., int (*cmp) (element_t, element_t)) {
   element_t pivotValue, t;
   ...
}
```

Using the parameterized Quicksort

• To sort integers:

```
int cmpIntegers (void* av, void* bv) {
   int* a = av;
   int* b = bv;
   return *a < *b ? -1: *a == *b ? 0: 1;
}</pre>
```

```
int a[] = {3, 8, 1};
int* pa[] = {a, a+1, a+2}; // addresses of a's elements
sort ((void**) pa, 3, cmpIntegers);
```

• To sort strings (with typedef):

```
int cmpStrings (element_t av, element_t bv) {
  char* a = av;
  char* b = bv;
  return *a < *b ? -1: *a == *b ? 0: 1;
}</pre>
or simply:
return strcmp(a, b);
```

```
char* array[] = {"Psyduck", "Bulbasaur", "Meowth", ..., "Eevee"};
sort ((element_t*) array, sizeof (array) / sizeof (array[0]), cmpStrings);
```

Exercise 1f.3

pair_sort.zip on Canvas

• Sort a list of integer pairs, in ascending order by their product

```
struct pair {
  int x;
  int y;
};
```

```
sort( void** list, int len, int (*cmp)(void*, void*));
```

- Recall A6: value needs the same refcount as the element
 - because value can't automatically be freed otherwise

```
struct element {
 int num;
 char* value;
};
struct element* element_new(int num, char* value) {
  struct element* e = rc malloc(sizeof(*e));
 e->value = rc malloc(strlen(value) + 1);
void element keep ref(struct element* e) {
 rc keep ref(e->value);
  rc keep ref(e);
void element free ref(struct element* e) {
  rc free ref(e->value);
  rc free ref(e);
```

Introducing: finalizers!

• This is better

```
struct element {
  int num;
  char* value;
};
void element finalizer(void* ev) {
                                      But how/when does this finalizer get called?
  struct element* e = ev;
                                      How do we "automate" it?
  free(e->value);
}
struct element* element new(int num, char* value) {
  struct element* e = rc malloc(sizeof(*e));
  e->value = malloc(strlen(value) + 1);
}
void element keep ref(struct element* e) {
  rc_keep_ref(e);
void element_free_ref(struct element* e) {
  rc free ref(e);
```

Fixing the refcount library

```
struct rc_metadata {
  int ref count;
  void (*finalizer) (void* ev); // finalizer associated with each allocation
};
void* rc malloc(int size, void (*ef) (void* ev)) {
  struct rc metadata* md = malloc(size + sizeof(struct rc metadata));
  md->ref count = 1;
  md->finalizer = ef;
  return md + 1; // address of payload
void rc free ref(void* p) { // p is a payload address
  struct rc metadata* md = p;
  md -= 1; // set md to start of metadata
  (md->refcount) -= 1;
  if (md->refcount == 0) {
                                                                     We should actually check
    md->finalizer(p); // call the allocation-specified finalizer
                                                                     that the provided finalizer is
    free (ref count); // free the entire allocation
                                                                     not NULL before calling it
}
```

Usage of the modified rc_malloc, etc.

```
struct element {
  int num;
 char* value;
};
void element finalizer(void* ev) {
  struct element* e = ev;
  free(e->value);
struct element* element new(int num, char* value) {
  struct element* e = rc malloc(sizeof(*e), element finalizer);
  e->value = malloc(strlen(value) + 1);
void element_keep_ref(struct element* e) {
 rc_keep ref(e);
                                               Just use rc keep ref(e) and
                                               rc_free_ref(e), for all allocations
void element_free_ref(struct element* e)
 rc_free_ref(e);
```



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Switch statements

It's super effective!

Switch statement

```
void bar() {
  if (i == 0)
    j = 10;
  else if (i == 1)
    j = 11;
  else if (i == 2)
    j = 12;
  else if (i == 3)
    j = 13;
  else
    j = 14;
}
```

- Semantically, the same as simplified nested/cascading if statements
 - where condition of each **if** tests the same variable
 - unless you leave out the break at the end of a case block
- So, why bother including this language feature?
 - is it for humans, to facilitate ease of writing and reading of code?
 - is it for compilers, permitting a more efficient implementation?
- Implementing switch statements
 - we know how to implement conditionals; is there anything more to consider?

Switch statements

Human vs compiler

- Benefits for humans
 - the syntax models a common idiom: choosing one computation from a set
- But switch statements have interesting restrictions
 - case labels must be *static*, *cardinal* values
 - a cardinal value is a number that specifies a position relative to the beginning of an ordered set
 - for example, integers are cardinal values, but strings are not
 - case labels must be compared for equality to a single dynamic expression
 - some languages permit the expression to be an inequality
- Do these restrictions benefit humans?
 - have you ever wanted to do something like this?

```
switch (pokemonType) {
  case "water": ...
  case "grass": ...
  case "psychic": ...
}
```

```
switch (i, j) {
  case i > 0: ...
  case i == 0 && j > a: ...
  case i < 0 && j == a: ...
}</pre>
```

Why compilers like switch statements

- Notice what we have (in a valid switch statement):
 - switch condition evaluates to a number
 - each case arm has a distinct number
- And so, the implementation has a simplified form

a jump table!

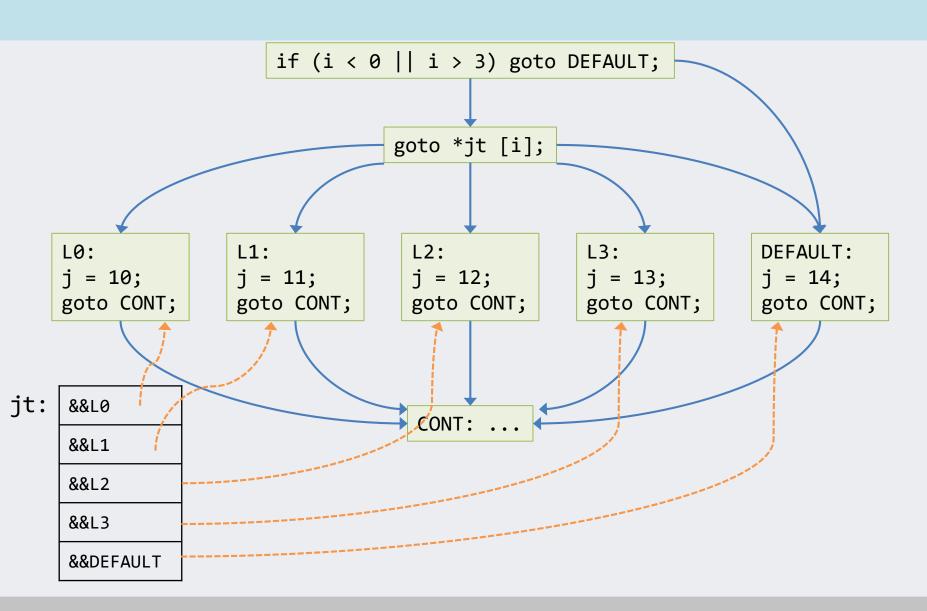
- build a table with the address of every case arm, indexed by case value
- switch by indexing into this table and jumping to matching case arm

• Example:

```
static const
```

```
void* jt[4] = { &&L0, &&L1, &&L2, &&L3 };
    if (i < 0 || i > 3) goto DEFAULT;
    goto *jt [i];
L0: j = 10;
    goto CONT; // "break"
L1: j = 11;
    goto CONT;
L2: j = 12;
    goto CONT;
L3: j = 13;
    goto CONT;
DEFAULT:
    j = 14;
    goto CONT;
Mike Feel CONT:
```

Switch statement control flow with jump table



Happy compilers mean happy people

```
switch (i) {
  case 0:    j = 10; break;
  case 1:    j = 11; break;
  case 2:    j = 12; break;
  case 3:    j = 13; break;
  default:    j = 14; break;
}
```

```
void* jt[4] = { &&L0, &&L1, &&L2, &&L3 };
    if (i < 0 \mid | i > 3) goto DEFAULT;
    goto *jt [i];
L0: j = 10;
    goto CONT; // "break"
L1: j = 11;
    goto CONT;
L2: j = 12;
    goto CONT;
L3: j = 13;
    goto CONT;
                                    if (i == 0)
DFFAULT:
                                      j = 10;
    i = 14;
                                    else if (i == 1)
    goto CONT;
                                      j = 11;
CONT:
                                    else if (i == 2)
                                      j = 12;
```

- Computation can be much more efficient
 - compare the running time to if-based alternative
- Could this all go horribly wrong?
 - construct a switch statement where this implementation technique is a really bad idea

else if (i == 3)

j = 13;

i = 14;

else

The basic implementation strategy

• General form of a switch statement

```
switch (<cond>) {
  case <label_i>: <code_i> repeated 0 or more times
  default: <code_default> optional
}
```

Naïve implementation strategy

```
goto address of code_default if cond > max_label_value
goto address in jumptable [label_i]
statically: jumptable [label_i] = address of code_i forall label_i
```

- But there are two additional considerations:
 - case labels are not always contiguous
 - the lowest case label is not always 0

Refining the implementation strategy

Naïve strategy

```
goto address of code_default if cond > max_label_value
goto address in jumptable [label_i]
statically: jumptable [label_i] = address of code_i forall label_i
```

- Non-contiguous case labels
 - what is the problem?
 - what is the solution?

send over to default

- Case labels not starting at 0 (juny table switch (i) {
 - what is the problem? lorge portions of those table

• what is the solution?

hormalize to 0

```
switch (i) {
em?

indices in range, but

case 0; j = 10; break;

case 0; j = 10; break;

default: j = 14; break;
```

```
2,1-10:00
  case 1000: j = 10; break;
  case 1001: j = 11; break;
 case 1002: j = 12; break;
case 1003: j = 13; break;
  default:
             j = 14; break;
```

Implementing switch statements

- Choose strategy
 - use jump table unless case labels are sparse or there are very few of them
 - use nested if-statements otherwise
- Jump table strategy
 - statically:
 - build jump table for all label values between lowest and highest
 - generate code to:
 - goto default if condition is less than minimum case label or greater than maximum
 - normalize condition value to lowest case label
 - use jump table to go directly to code-selected case arm

```
goto address of code_default if cond < min_label_value
goto address of code_default if cond > max_label_value
goto address in jumptable [cond - min_label_value]

statically: jumptable [i - min_label_value] = address of code_i
    forall i: min_label_value <= i <= max_label_value</pre>
```

Snippet B: in jump table form

```
static const void* jt[4] = { &&L20, &&L21, &&DEFAULT, &&L23 };
    if (i < 20 || i > 23) goto DEFAULT;
    goto *jt [i-20];
L20: j = 10;
    goto CONT; // "break"
L21: j = 11;
    goto CONT;
L23: j = 13;
    goto CONT;
DEFAULT:
    j = 14;
    goto CONT;
```

Snippet B: in assembly form

```
foo:
         ld
             $i, r0
                    # r0 = &i
        ld 0x0(r0), r0  # r0 = i
ld $0xffffffed, r1 # r1 = -19
             r0, r1
                     # r0 = i-19
         add
                   # goto 10 if i>19
         bgt r1, 10
             default
                      # goto default if i<20
         br
10:
             $0xffffffe9, r1 # r1 = -23
         ld
                    # r1 = i-23
         add r0, r1
         bgt r1, default # goto default if i>23
             $0xffffffec, r1 # r1 = -20
         ld
                    # r0 = i-20
         add r1, r0
             $jmptable, r1 # r1 = &jmptable
                                                  r); jump table address
         ld
             *(r1, r0, 4)
                         # goto jmptable[i-20]
                      # r1 = 10
case20:
         ld
             $0xa, r1
             done
                           # goto done
         br
default:
        ld $0xe, r1 # r1 = 14
                        # goto done
         br
             done
                        # r0 = &j
done:
         ld
             $j, r0
             r1, 0x0(r0) # j = r1
         st
                           # goto cont
         br
             cont
jmptable: .long case20
                           # & (case 20)
         .long case21
                           # & (case 21)
         .long default
                           # & (case 22)
         .long case23
                           # & (case 23)
```

Review: static and dynamic control flow

• Jump instructions

- specify a target address and a jump-taken condition
- target address can be static or dynamic
- jump-target condition can be static (unconditional) or dynamic (conditional)
- Static jumps
 - jump target address is static
 - compiler hard-codes this address into instruction

Name	Semantics	Assembly	Machine
branch	pc ← a (or pc + p*2)	br a	8-pp
branch if equal	$pc \leftarrow a (or pc + p*2) if r[c] == 0$	beq rc, a	9срр
branch if greater	$pc \leftarrow a (or pc + p*2) if r[c] > 0$	bgt rc, a	асрр
jump	pc ← a	j a	b aaaaaaaa

- Dynamic jumps
 - jump target address is dynamic

Review: dynamic jumps

plus a new double-indirect jump

- Indirect jump
 - jump target address stored in a register
 - already introduced, but we used it for static procedure calls

Name	Semantics	Assembly	Machine
indirect jump	$pc \leftarrow r[t] + o (or r[t] + p*2)$	j o(rt)	ctpp

- Double indirect jumps
 - jump target address stored in memory
 - base-plus-displacement and indexed modes for memory access

Name	Semantics	Assembly	Machine
dbl-ind jump b+o	$pc \leftarrow m[r[t] + o] (or m[r[t] + pp*2])$	j *o(rt)	dtpp
dbl-ind jump indexed	$pc \leftarrow m[r[t] + r[i]*4]$	j *(rt, ri, 4)	eti-

What happens when this code is compiled and run?

```
void foo (int i) {printf ("foo %d\n", i);}
void bar (int i) {printf ("bar %d\n", i);}
void bat (int i) {printf ("bat %d\n", i);}

void (*proc[3])(void) = {foo, bar, bat};

int main (int argc, char* argv) {
   int input;
   if (argc == 2) {
      input = atoi (argv [1]);
      if (input>=0 && input <=2)
        proc[input] (input+1);
   }
}</pre>
```

- A. It does not compile
- B.) For any value of input, it generates a runtime error
- C. If input is 1, it prints "bat 2" and it does other things for other values
- D. If input is 1, it prints "bar 2" and it does other things for other values

• What happens when this code is compiled and run?

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void foo (int i) {printf ("foo %d\n", i);}
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void (*proc[3])(int) = {foo, bar, bat};

int main (int argc, char* argv[]) {
   int input;
   if (argc == 2) {
      input = atoi (argv [1]);
      if (input>=0 && input <=2)
        proc[input] (input+1);
   }
}</pre>
```

```
0 | foo
1 | bar
2 | bat
```

- A. It does not compile
- B. For any value of input, it generates a runtime error
- C. If input is 1, it prints "bat 2" and it does other things for other values
- D. If input is 1, it prints "bar 2" and it does other things for other values

• Which implements proc[input] (input + 1); ?

```
(r5), r0
    1d
       $proc, r1 wop table
    1d
    deca
         r5
         r0, r2
    mov
                 input +)
    inc r2
    st r2, (r5)
    gpc $2, r6
          *(r1, r0, 4)
    ld (r5), r0
В.
    deca r5
```

```
void foo (int i) {printf ("foo %d\n", i);}
void bar (int i) {printf ("bar %d\n", i);}
void bat (int i) {printf ("bat %d\n", i);}

void (*proc[3])(int) = {foo, bar, bat};

int main (int argc, char* argv[]) {
   int input; ← local variable of main
   if (argc == 2) {
      input = atoi (argv [1]);
      if (input>=0 && input <=2)
          proc[input] (input+1);
   }
}</pre>
```

```
mov r0, r2
inc r2
st r2, (r5)
gpc $6, r6
j bar
```

- C. I think I understand this, but I can't really read the assembly code
- D. Are you serious? I have no idea.