## Model Selection:

-Recall ERM:

- Under fitting: The solution is too simple.

The tricing and test error will be high.

-Overfitting: The solution is too complex.

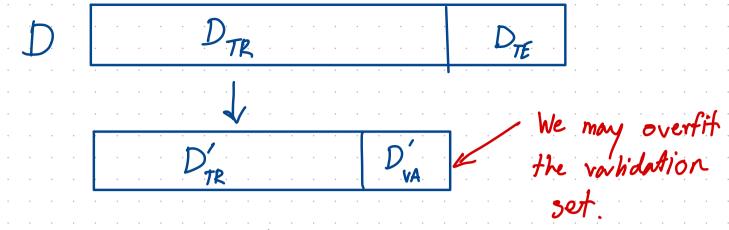
The training error de crease over time, the test error will begin to increase.

ertor will begin to increase.

ertor sweet spot test error transing error

over fitting

-Identifying sweet spot: Divide data into training and validation, portions. Train on the "training" split and evaluate it on the "validation" split, for various value of 71 (10, 10, 10, 10, 10, 10, 10)



## K-fold cross validation:

- Divide your training data into k parts. - Train on k-1 parts and leave one out as validation set. Do this k times and averge the validation error across all runs cideally,

## Telescopic search For A:

- Do two search:
  - . 1 st step: find the best order of magnitude
    for )

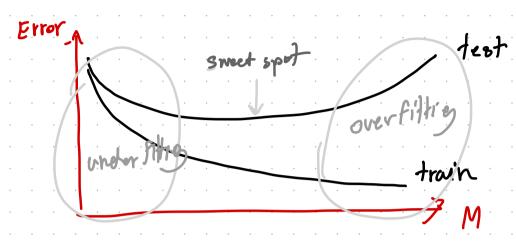
- -For example, first we try 0.01, 0.1, 1 10 100.

  2 nd Step! do a more Fine-grained search around the best N so for
  - Then, we try 5, 10, 15, 29, 25, ..., 95 to test values around 10.

Early Stopping: Stop our optimization after

M > 0 number of gradient steps,

even if optimization has not convend yel



Kernels:

See visualization at: https://www.youtube.com/watch?v=3liCbRZPrZA

- A way to incorporate non-linearities into most linear classifiers.

feature Trans formation:  $\begin{array}{cccc}
x_2 & & & & \\
x_2 & & & & \\
x_3 & & & & \\
x_4 & & & & \\
x_4 & & & & \\
x_1 & & & & \\
x_2 & & & & \\
x_4 & & & & \\
x_5 & &$ 

Extreme case:  $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$  =  $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$   $\in 2^d$   $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$   $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$   $\begin{pmatrix} x_2 \\ x_3 \end{pmatrix}$   $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$   $\begin{pmatrix} x_2 \\ x_4 \end{pmatrix}$   $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$   $\begin{pmatrix} x_2 \\ x_3 \end{pmatrix}$   $\begin{pmatrix} x_1 \\ x_4 \end{pmatrix}$   $\begin{pmatrix} x_2 \\ x_4 \end{pmatrix}$   $\begin{pmatrix} x_3 \\ x_4 \end{pmatrix}$   $\begin{pmatrix} x_4 \\ x_4 \end{pmatrix}$   $\begin{pmatrix}$