

Integrating Latent Cause Inference into Actor-Critic Algorithms for Continual Learning

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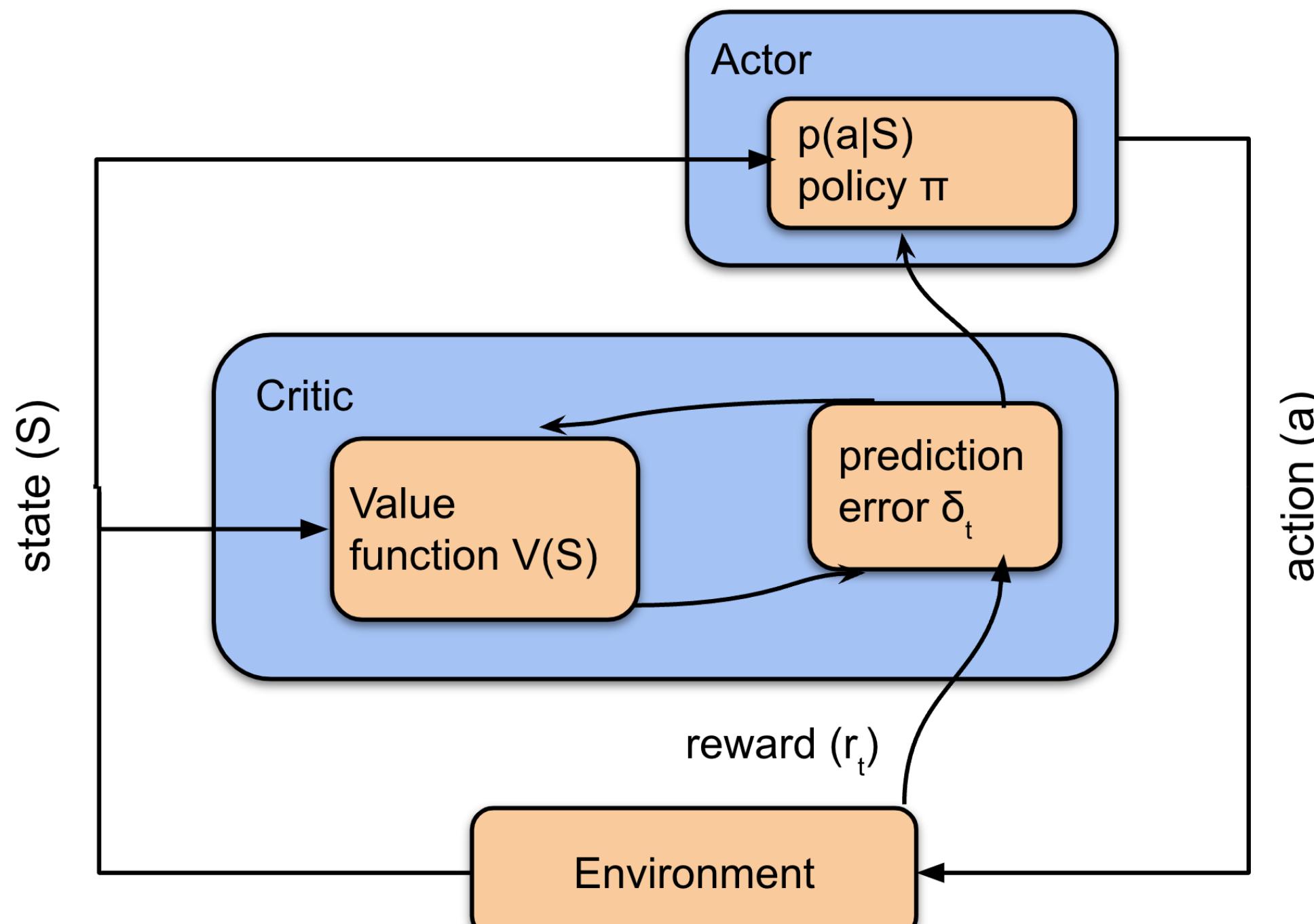
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Background

- ★ Reinforcement learning in the real world is often faced with changing environments that nevertheless have recurring, hidden structures.
- ★ The challenge of “continual learning” in such situations involves adapting quickly to change while being able to retain and reuse old knowledge.
- ★ One strategy for effective learning in such environments is for agents to discover useful state representations, by extracting **latent causal structure** and using it to control generalization and segregation across learning experiences.

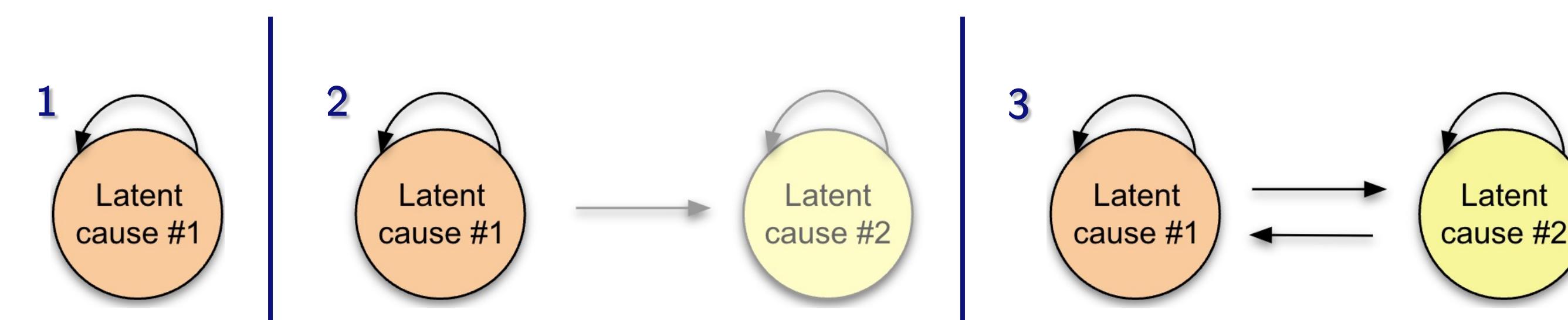
Actor-Critic Model

- ★ Our methods involve an actor-critic algorithm connected to a latent cause inference module.



Reinforcement Learning Agents

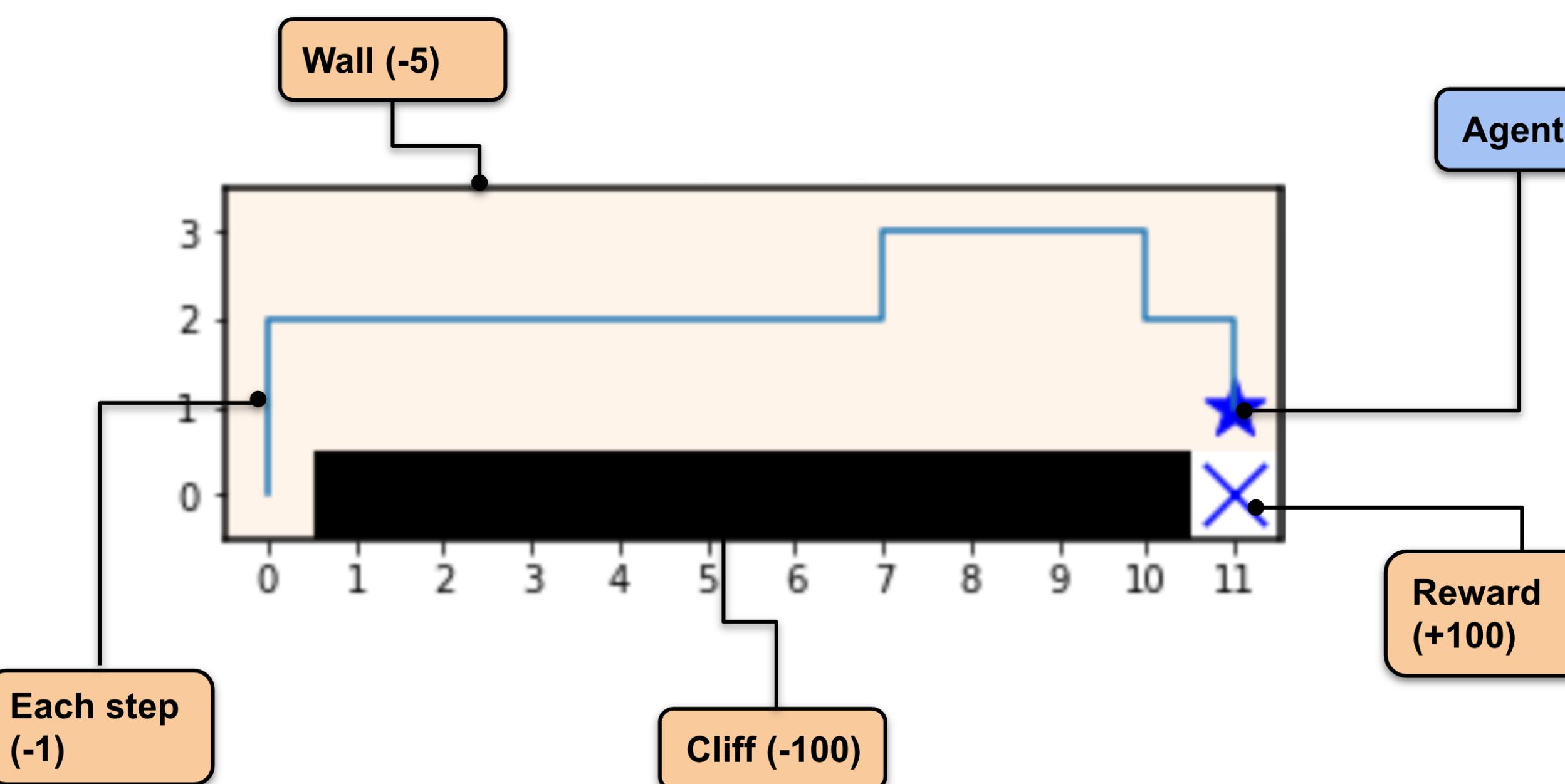
- ★ We investigated the learning dynamics of **three** different reinforcement learning agents, with varying degrees of access to **latent cause representations**.



1. Assumed that the **same** latent cause was active throughout training, leading it to incorrectly apply old knowledge even if the reward location changed, and **overwrite previous knowledge** through subsequent learning.
2. Only had access to changes in latent causes, leading it to adapt quickly to **change-points** but requiring it to **re-learn** every time, even if it had seen a latent cause before.
3. Had access to all past latent causes, enabling it to segregate learning when the task changed abruptly, but also **“remember”** and apply previous knowledge to tasks it had already seen.

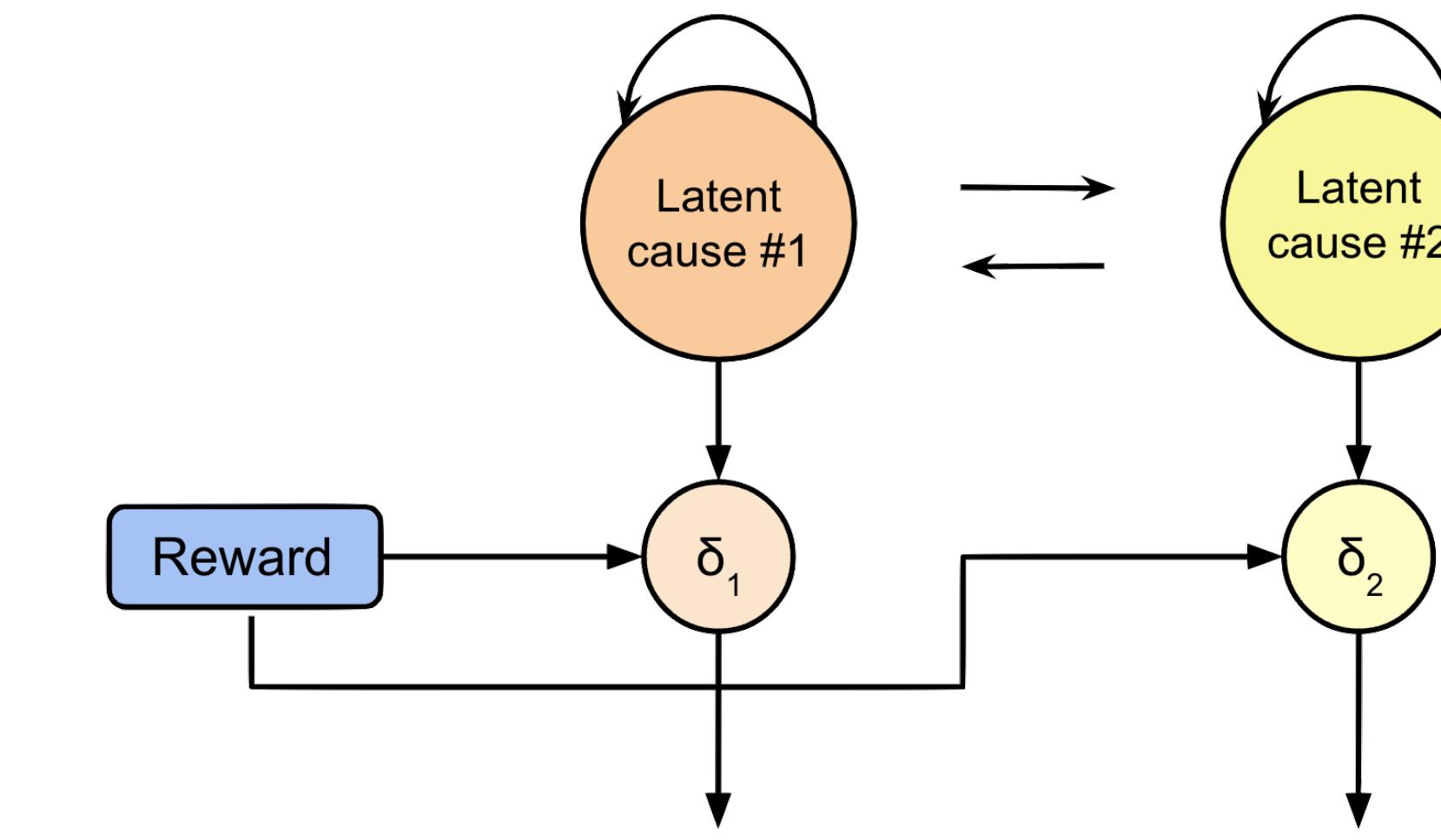
Grid-world Setting

- ★ The agent’s objective is to find the **optimal path to a reward** in a simulated grid-world setting.
- ★ The reward location is determined by a **hidden cause** that could change and recur throughout training.



Ongoing Work

- ★ Tighter coupling between the latent cause and actor-critic modules.

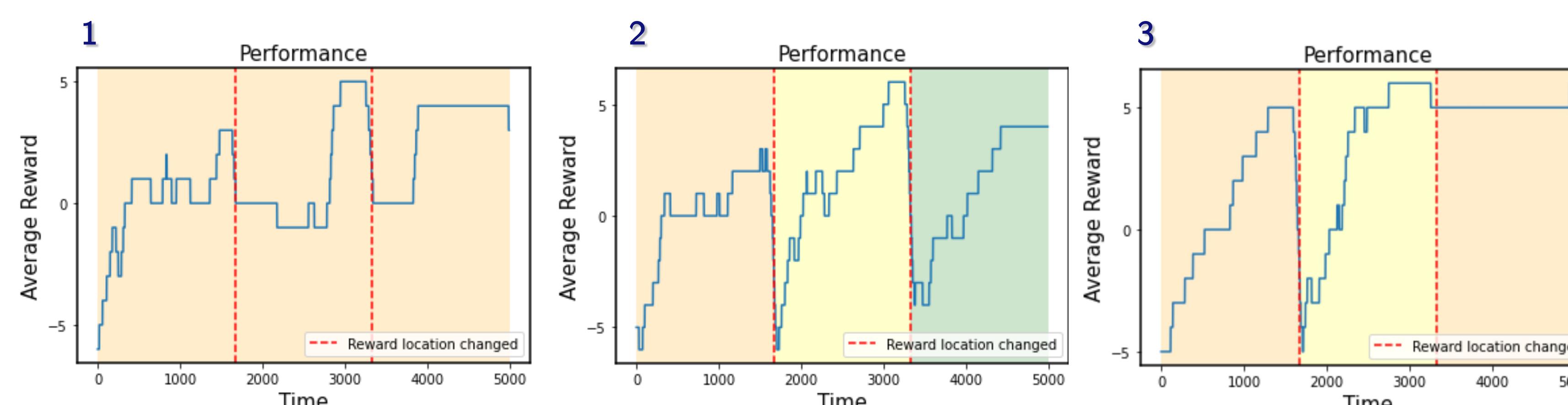


RL in the Brain

- ★ The brain discovers latent causes by interacting with its environment. (1)
- ★ Failures of under-segregation or over-segregation of old and new learning in the brain may underlie **psychiatric conditions** such as PTSD and anxiety. (3)

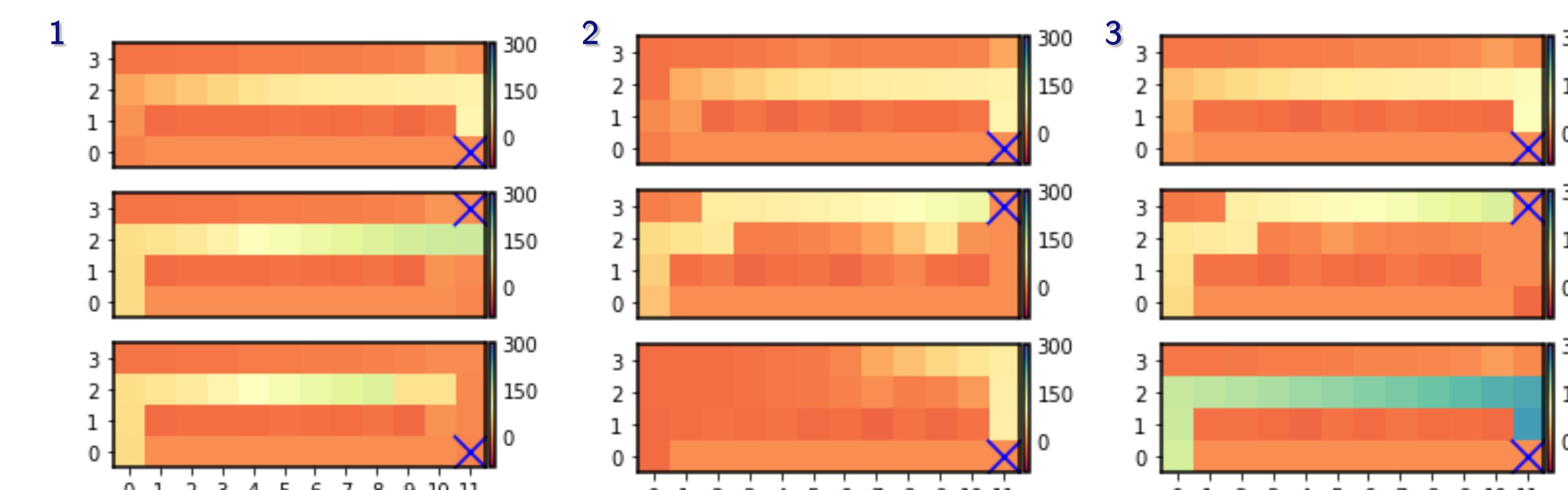
Performance Curves

- ★ The average reward received during training across 5000 timesteps was plotted for each of the 3 agents.
- ★ A difference in shading between each third of each plot represents a change in what the **agent “thinks” the latent cause is**.



State Value Functions

- ★ Heatmaps of the state value functions for each of the 3 reward locations for each agent.



Acknowledgments

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