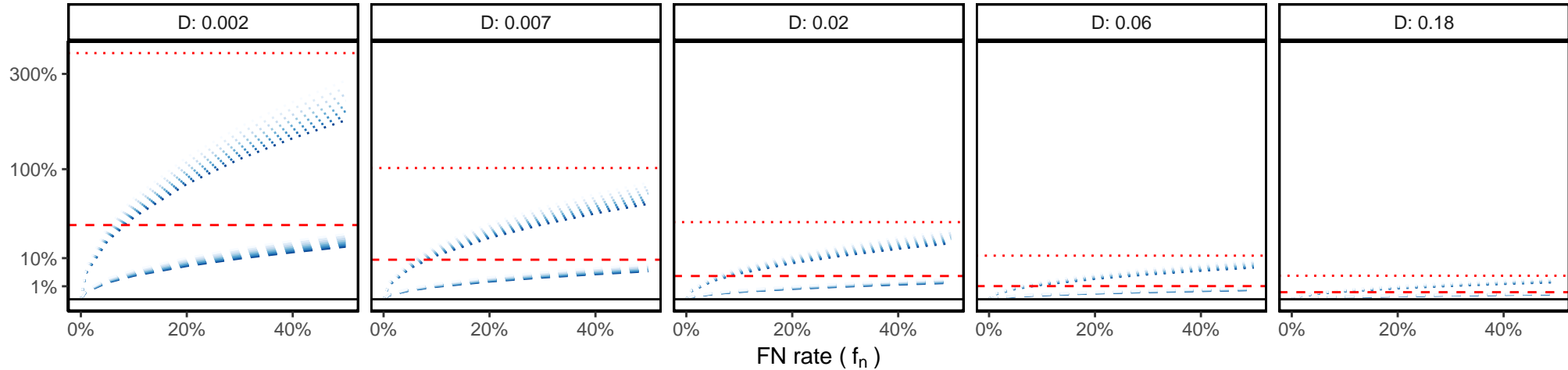
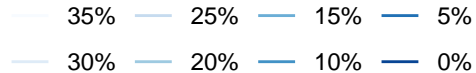


estimated - true
D



FP (f_p)



C_l

