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JDLA E E2024#2

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- GPT5 SOTA

1

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Part I

1. (Mach Basics)

2 1. (Statistics)

2.0.1 1

KL $D_{KL}(P||Q)$ $H(P,Q)$

$$D_{KL}(P||Q) = H(P,Q) - H(P)$$

- P Q $H(P)$ P
- A. Q P
- B. P $H(P)$ KL
- C. KL $P=Q$ 0
- D. KL $D_{KL}(P||Q) = D_{KL}(Q||P)$

Part II

2. (Machine Learning)

3 1. (Machine Learning Basics)

3.0.1 1

MAP

MAP Maximum A Posteriori Estimation MLE Maximum Likelihood Estimation

I.

A. MLE MAP

B. MLE MAP

C. MLE MAP

D. MAP

MAP θ_{MAP} θ_{MAP}

$$\theta_{\text{MAP}} = \arg \max_{\theta} P(\theta | X) =$$

II.

A. $\arg \max_{\theta} P(X | \theta)$

B. $\arg \max_{\theta} \frac{P(\theta)}{P(X)}$

C. $\arg \max_{\theta} P(X | \theta) P(\theta)$

D. $\arg \max_{\theta} \log P(X)$

Part III

3. (Basic Deep-learning)

4 1. (Feedforward Neural Network)

4.0.1 1

2

```
import numpy as np

def binary_crossentropy(y_true, y_pred):
    """
    y_true:      [batch_size] (0 or 1)
    y_pred:      [batch_size] (0~1 )
    """
    #
    epsilon = 1e-15
    y_pred =

    #
    loss = -np.mean(y_true * np.log(y_pred) + (1 - y_true) * np.log(1 - y_pred))
    return loss
```

- A. np.clip(y_pred, epsilon, 1.0)
- B. np.clip(y_pred, 0.0, 1 - epsilon)
- C. np.clip(y_pred, epsilon, 1 - epsilon)
- D. np.maximum(y_pred, epsilon)

4.0.2 2

```
import numpy as np

def softmax(x):
    """
    x:      [batch_size, num_classes]
    """
```

```
#
x_max =
x_shifted = x - x_max

#
exp_x = np.exp(x_shifted)
sum_exp =

return exp_x / sum_exp
```

- A. : np.max(x, axis=1, keepdims=True), : np.sum(exp_x, axis=1, keepdims=True)
- B. : np.max(x, axis=0, keepdims=True), : np.sum(exp_x, axis=0, keepdims=True)
- C. : np.max(x, axis=1), : np.sum(exp_x, axis=1)
- D. : np.maximum(x, 0), : np.sum(exp_x)

4.0.3 3

tanh

```
import numpy as np

def tanh(x):
    y =
    return y
```

- A. (np.exp(x) + np.exp(-x)) / (np.exp(x) + np.exp(-x))
- B. (np.exp(x) + np.exp(-x)) / (np.exp(x) - np.exp(-x))
- C. (np.exp(x) - np.exp(-x)) / (np.exp(x) - np.exp(-x))
- D. (np.exp(x) - np.exp(-x)) / (np.exp(x) + np.exp(-x))

4.0.4 4.

- () \sim () ReLU () $\sigma(x)$ () $\sigma(x)$ ()
- () :
- A. $\frac{1}{1+e^{-x}}$
 - B. $\frac{e^x}{1+e^x}$
 - C. $\frac{1}{1+e^x}$
 - D. $\frac{1}{1-e^x}$

() :

- A. $1 - \sigma(x)$
- B. $\sigma(x)(1 - \sigma(x))$
- C. $x(1 - x)$
- D. e^{-x}

() :

- A.
- B.
- C.
- D.

() :

- A.
- B. $(0, 1)$
- C. ReLU
- D. ReLU $- 1$

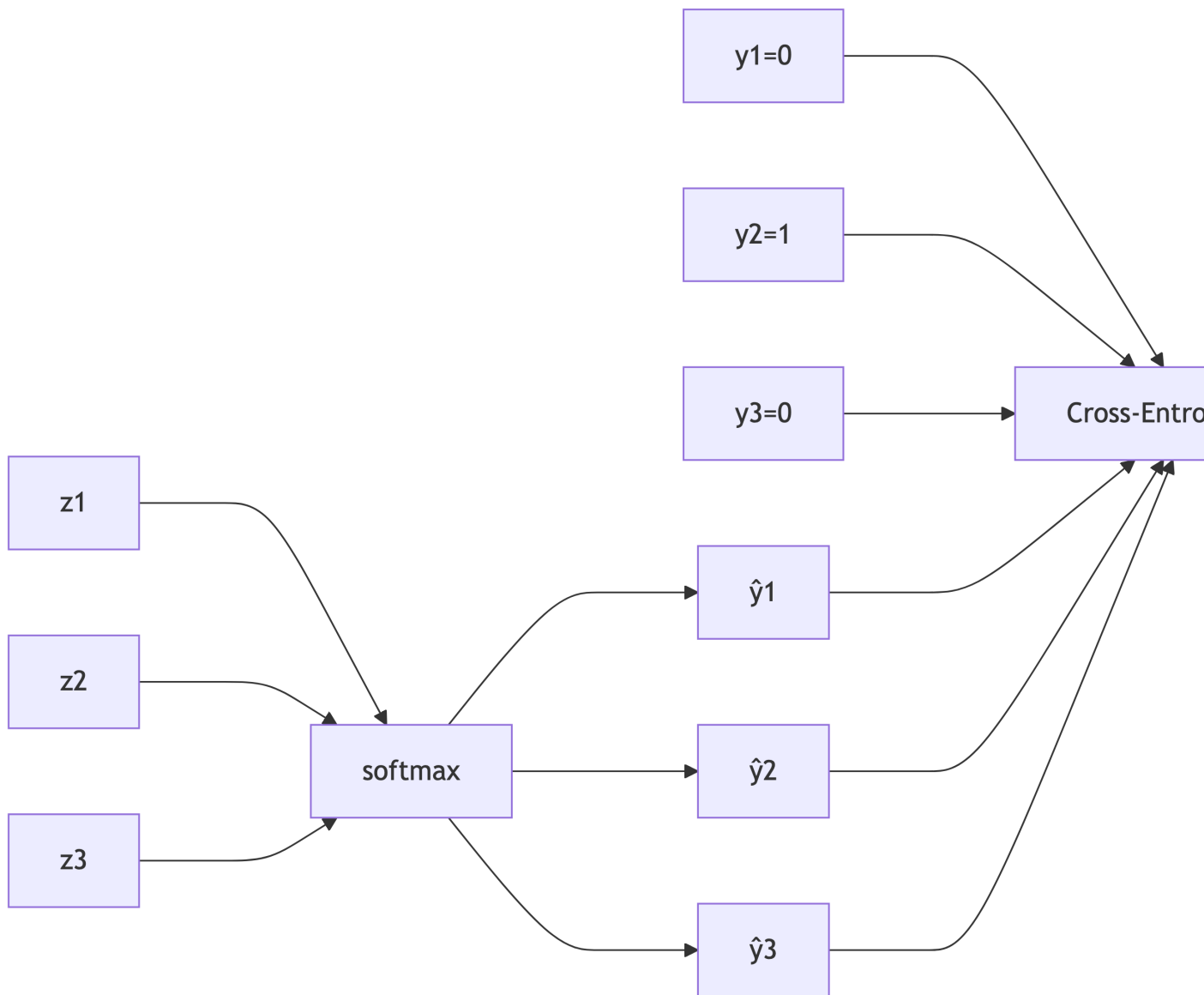
() () :

- A. ResNet
- B. Word2Vec Negative Sampling
- C. GAN Discriminator
- D. Transformer Multi-Head Attention

5.2. (Optimization)

5.0.1 1

$$(z = [z_1, z_2, z_3]) \quad (L)$$



I. $\frac{\partial L}{\partial z_j}$

$$\hat{y}_i = \frac{\exp(z_i)}{\sum_k \exp(z_k)}$$

$$L = - \sum_i y_i \log(\hat{y}_i)$$

- A. $y_j - \hat{y}_j$
- B. $\hat{y}_j - y_j$
- C. $\frac{-y_j}{\hat{y}_j}$
- D. $\hat{y}_j(1 - y_j)$

- II.3 $y = [0, 1, 0]$ $\hat{y} = [0.2, 0.3, 0.5]$ $\frac{\partial L}{\partial z_2}$
- A. -0.7
 - B. 0.7
 - C. -0.3
 - D. 0.3

5.0.2 2

AdaGrad

$$h_t = h_{t-1} + \nabla E(W_t) \odot \nabla E(W_t) \alpha_t = \alpha_0 \times (1/\sqrt{(h_t + \varepsilon)}) W_{t+1} = W_t - \alpha_t \odot \nabla E(W_t)$$

- A. h_t
- B. _t
- C.
- D. h_t

5.0.3 3

1 train_flag True False dropout_ratio

```

1  import numpy as np
2
3  class Dropout:
4      def __init__(self, dropout_ratio=0.5):
5          self.dropout_ratio = dropout_ratio
6          self.mask = None
7
8      def forward(self, x, train_flg=True):
9          if train_flg:
10             self.mask = ( ) self.dropout_ratio
11             return ( )
12         else:
13             return ( )

```

```
14
15     def backward(self, dout):
16         return ( )
```

- A. `np.random.rand(*x.shape) >`
- B. `np.random.rand(*x.shape) >`
- C. `np.random.randn(*x.shape) <`
- D. `np.random.rand(*x.shape) <`

- A. `x * self.mask`
- B. `x * (1.0 + self.mask)`
- C. `x - self.mask`
- D. `x * (1.0 - self.mask)`

- A. `x * self.mask`
- B. `x * (1.0 - self.mask)`
- C. `x * self.dropout_ratio`
- D. `x * (1.0 - self.dropout_ratio)`

- A. `dout * self.mask`
- B. `dout * (1.0 - self.mask)`
- C. `dout * self.dropout_ratio`
- D. `dout * (1.0 - self.dropout_ratio)`

6.3. (Convolutional Neural)

6.0.1 1.

1 1 im2col
5×5
3×3
1
0

I.

- A. (2, 2)
- B. (3, 3)
- C. (4, 4)
- D. (5, 5)

II. im2col im_col.shape 1 1

- A. (3, 3)
- B. (9, 9)
- C. (9, 25)
- D. (3, 9)

Part IV

4 . (Advanced Deep-learning)

7 1. (Image Recognition)

7.0.1 1

- A.
- B.
- C.
- D.

7.0.2 2

$$\begin{array}{lll} C_{in} = 64 & C_{out} = 256 & H = W = 32 \\ 3 \times 3 & \text{ResNet50} & \end{array}$$

MAC

1×1 conv : $64 \rightarrow 64$
 3×3 conv : $64 \rightarrow 64$
 1×1 conv : $64 \rightarrow 256$

- A. $1/2$
- B. $1/4$
- C. $1/8$
- D. $1/16$

7.0.3 3

Vision Transformer ViT 1

- A. 1 CNN
- B. Transformer
- C. CNN
- D.

8 2. (Object Detection)

8.0.1 1

- FCOS
- A. FCOS
 - B. FCOS Feature Pyramid Network(FPN)
 - C. FCOS
 - D. FCOS Center-ness

8.0.2 2

R-CNN (A) ROI ROI (B) R-CNN (C)

8.0.3 3

SSD Single Shot MultiBox Detector

- A. Single Shot 2 MultiBox 1 1
- B. Single Shot 1 MultiBox
- C. Single Shot 1 MultiBox GPU
- D. Single Shot YOLO MultiBox

9 3. Semantic Segmentation (Semantic Segmentation)

9.0.1 1

FCN Fully Convolutional Network
 ResNet
 FCN

FCN-32s FCN-16s FCN-8s

CNN VGG

$$L = - \sum_{x \in \Omega} \sum_{c \in C} y_c(x) \log P_c(x)$$

$y_c(x)$ x one-hot $P_c(x)$ c

- A. ☐ ☐ Transposed Conv ☐ ☐
- B. ☐ ☐ Interpolation ☐ ☐ ReLU
- C. ☐ ☐ Transposed Conv ☐ ☐
- D. ☐ ☐ ☐ ☐

10 4. (Natural Language Processing)

10.0.1 1

Seq2Seq

- A. $+\log P(y \mid x)$
- B. $-\log P(y \mid x)$
- C. $+\log P(y \mid x)$
- D. $-\log P(y \mid x)$

10.0.2 2

Word2Vec

- A. CBOW
- B. Skip-gram
- C. GloVe
- D. LSI

10.0.3 3

GPT

- A. GPT-2
- B. GPT-3
- C. GPT-2 Masked Language Modeling
- D. GPT-3 Few-shot Learning Fine-tuning

10.0.4 4

Word2Vec Skip-gram

softmax

A. softmax

B.

C.

D. skip-gram CBOW

11 5. Recurrent Neural Network (Recurrent Neural Network)

11.0.1 1

LSTM t LSTM RNN

3

```
n_input = 100
n_hidden = 256

w =
b = np.zeros(n_hidden * 4)

# x
# h, c
def lstm(x, h, c):
    # Wx + Uh + b
    inputs = np.concatenate((x, h), axis=1)
    inputs = np.matmul(inputs, w) + b
    z, i, f, o = np.hsplit(inputs, 4)
    ...
```

()

- A. np.random.randn(n_input * n_hidden, n_hidden * 3)
- B. np.random.randn(n_input * n_hidden, n_hidden * 4)
- C. np.random.randn(n_input + n_hidden, n_hidden * 3)
- D. np.random.randn(n_input + n_hidden, n_hidden * 4)

11.0.2 2

LSTM GRU(Gated Recurrent Unit)

12 6. (Generative Model)

12.0.1 1

1

- A. VAE Reparameterization Trick
- B. Denoising Autoencoder
- C.
- D. GAN VAE

13.7. (Reinforcement Learning)

13.0.1 1

MDP

$\gamma = 0.5$			
s_0	a_0	$r_0 = 2$	s_1
s_1		$r_1 = 4$	0

- I. $V^\pi(s_1)$
- II. $Q^\pi(s_0, a_0)$

13.0.2 2

DQN Q TD

$$TD = \text{ } - Q(s, a)$$

- A. $Q(s', a')$
- B. $\text{ } - Q(s, a)$
- C. $\gamma * Q(s, a)$
- D. $R(s, a) + \gamma * \max_{a'} Q(s', a')$

13.0.3 3

$V(s_0)$

$\nabla_{\theta} J(\theta)$

$Q(s,a)$

$\pi_{\theta}(a|s)$

$\nabla_{\theta} J(\theta) = \mathbb{E}_{\pi_{\theta}}[()]$

$- (|)$

$()$

- A. $\nabla_{\theta} \log \pi_{\theta}(a|s) Q^{\pi}(s,a)$
- B. $\nabla_{\theta} \pi_{\theta}(a|s) Q^{\pi}(s,a)$
- C. $\frac{\nabla_{\theta} \pi_{\theta}(a|s)}{Q^{\pi}(s,a)}$
- D. $\frac{Q^{\pi}(s,a)}{\nabla_{\theta} \pi_{\theta}(a|s)}$

14 8. (Various Learning Methods)

14.0.1 1

Triplet Network Triplet Network Siamese Network
 Network 2 Triplet Network 3 3 Siamese
 triplet loss L d_p
 L

- A. $\max(d_p - d_n + m, 0)$
- B. $\max(d_p - d_n, m)$
- C. $\max(-d_p + d_n, m)$
- D. $\max(d_p - d_n - m, 0)$

14.0.2 2

- A. Triplet Network
- B. Siamese Network 2
- C. Siamese Network 2 Triplet Network 2
- D. Triplet Network

15 9. (Explainability of Deep-learning)

15.0.1 1

Grad-CAM Gradient-weighted Class Activation Mapping

- A. AlexNet CNN
- B. Grad-CAM
- C. Guided Grad-CAM Grad-CAM Guided Backpropagation
- D. CNN

15.0.2 2

1

- A. CAM Global Average Pooling
- B. Grad-CAM Global Average Pooling
- C. GoogLeNet Flatten→ CAM
- D. VGG Global Average Pooling CAM

15.0.3 3

Shapley Shapley

- A. 1
- B. Permutation
- C.
- D.

Part V

5 . (Infrastructure)

16 4. (Accelerator)

16.0.1 1

	AI			Google	TPU	Tensor	Processing
Unit	TPU	GPU	GPU				
A.							
B.							
C.							
D.	8bit	16bit					

17

18 1 . (Mach Basics)

18.1 1. (Statistics)

1. D

19 2 . (Machine Learning)

19.1 1. (Machine Learning Basics)

1. I: A II: C

20 3 . (Basic Deep-learning)

20.1 1. (Feedforward Neural Network)

1. C
2. A
3. D
4. ():A
- ():B

i

$$\frac{d}{dx} \frac{1}{f(x)} = -\frac{f'(x)}{f(x)^2}$$

$$f(x) = 1 + e^{-x}$$

$$f(x) = 1 + e^{-x}, \quad f'(x) = -e^{-x}$$

$$\frac{d\sigma(x)}{dx} = \frac{d}{dx} \frac{1}{f(x)} = -\frac{f'(x)}{f(x)^2} = -\frac{-e^{-x}}{(1 + e^{-x})^2} = \frac{e^{-x}}{(1 + e^{-x})^2}$$

(x)

$$\sigma(x) = \frac{1}{1 + e^{-x}} \implies 1 - \sigma(x) = \frac{e^{-x}}{1 + e^{-x}}$$

$$\frac{d}{dx} \sigma(x) = \frac{e^{-x}}{(1 + e^{-x})^2} = \sigma(x)(1 - \sigma(x))$$

- ():D
- ():B
- () ():B,C

i

(D) Transformer Multi-Head Attention

20.2 2. (Optimization)

1. I: B II: A
2. D

i
0

20.3 3. (Convolutional Neural)

1. I: B II: B

21 4 . (Advanced Deep-learning)

21.1 1. (Image Recognition)

1. B

21.2 2. (Object Detection)

1. A
2. A: Region-based Convolutional Neural Network
B: Region Proposal()
C: Selective Search
3. B

21.3 3. Semantic Segmentation (Semantic Segmentation)

1. C

21.4 4. (Natural Language Processing)

1. B
2. C
3. B
2. C

21.5 5. Recurrent Neural Network (Recurrent Neural Network)

1. D
2. LSTM: (Forget Gate) (Input Gate) (Output Gate) (Memory Cell)
GRU: (Reset Gate) (Update Gate)

21.6 6. (Generative Model)

1. C

21.7 7. (Reinforcement Learning)

1. I: 4 II: 4
2. D
3. A

21.8 8. (Various Learning Methods)

1. A
2. A

21.9 9. (Explainability of Deep-learning)

1. A
2. B
3. B

22 5 . (Infrastructure)

22.1 4. (Accelerator)

1. A

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- [Transformer - Multi-Head Attention](#) [vol.28](#)
- [KL](#)
- [E](#)
- [E](#)
- [e](#)