

Mining Big Data Using Parsimonious Factor, Machine Learning, Variable Selection and Shrinkage Methods

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Abstract

A number of recent studies in the economics literature have focused on the usefulness of factor models in the context of prediction using “big data” (see Bai and Ng (2008), Dufour and Stevanovic (2010), Forni et al. (2000, 2005), Kim and Swanson (2014a), Stock and Watson (2002b, 2006, 2012), and the references cited therein). We add to this literature by analyzing whether “big data” are useful for modelling low frequency macroeconomic variables such as unemployment, inflation and GDP. In particular, we analyze the predictive benefits associated with the use of principal component analysis (PCA), independent component analysis (ICA), and sparse principal component analysis (SPCA). We also evaluate machine learning, variable selection and shrinkage methods, including bagging, boosting, ridge regression, least angle regression, the elastic net, and the non-negative garotte. Our approach is to carry out a forecasting “horse-race” using prediction models constructed using a variety of model specification approaches, factor estimation methods, and data windowing methods, in the context of the prediction of 11 macroeconomic variables relevant for monetary policy assessment. In many instances, we find that various of our benchmark models, including autoregressive (AR) models, AR models with exogenous variables, and (Bayesian) model averaging, do not dominate specifications based on factor-type dimension reduction combined with various machine learning, variable selection, and shrinkage methods (called “combination” models). We find that forecast combination methods are mean square forecast error (MSFE) “best” for only 3 of 11 variables when the forecast horizon, $h = 1$, and for 4 variables when $h = 3$ or 12. Additionally, non-PCA type factor estimation methods yield MSFE-best predictions for 9 of 11 variables when $h = 1$, although PCA dominates at longer horizons. Interestingly, we also find evidence of the usefulness of combination models for approximately 1/2 of our variables, when $h > 1$. Most importantly, we present strong new evidence of the usefulness of factor based dimension reduction, when utilizing “big data” for macroeconometric forecasting.

Keywords: prediction, independent component analysis, sparse principal component analysis, bagging, boosting, Bayesian model averaging, ridge regression, least angle regression, elastic net and non-negative garotte.

JEL Classification: C32, C53, G17.

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1 Introduction

In recent years, considerable research has focused on the analysis of “big data” in economics. This in turn has resulted in considerable attention being paid to the rich variety of methods available in the areas of machine learning, data mining, variable selection, dimension reduction, and shrinkage. In this paper, we utilize various of these methods to add to the discussion of the usefulness of “big data” for forecasting macroeconomic variables such as unemployment, inflation and GDP. From the perspective of dimension reduction, we construct of diffusion indices, and add to the discussion of the usefulness of such indices for macroeconomic forecasting.¹ In particular, when constructing diffusion indices, we implement principal component analysis (PCA), independent component analysis (ICA) and sparse principal component analysis (SPCA).² We also evaluate machine learning, variable selection and shrinkage methods, including bagging, boosting, ridge regression, least angle regression, the elastic net, and the non-negative garotte. Finally, we combine various dimension reduction techniques with these machine learning and shrinkage methods and evaluate the usefulness of these approaches for forecasting.

In order to assess all of the above techniques, we carry out a large number of real-time out-of-sample forecasting experiments; and our venue for this "horse-race" is the prediction of 11 key macroeconomic variables relevant for monetary policy assessment. These variables include the unemployment, personal income, the 10 year Treasury-bond yield, the consumer price index, the producer price index, non-farm payroll employment, housing starts, industrial production, M2, the S&P 500 index, and gross domestic product; and as noted in Kim and Swanson (2014a) are discussed on the Federal Reserve Bank of New York’s website, where it is stated that “In formulating the nation’s monetary policy, the Federal Reserve considers a number of factors, including the economic and financial indicators, as well as the anecdotal reports compiled in the Beige Book.”

The notion of a diffusion index is to use appropriately “distilled” latent common factors extracted from a large number of variables as inputs in the specification of subsequent parsimonious (yet “information rich”) models. More specifically, let X be an $T \times N$ -dimensional matrix of observations, and define an $T \times r$ -dimensional matrix of dynamic factors, F . Namely, let

$$X = F\Lambda' + e \quad (1)$$

where e is a disturbance matrix and Λ is an $N \times r$ coefficient matrix. Once F is extracted using one of the estimation methods examined in this paper, we construct the following forecasting

¹A small sample of recent forecasting studies using large-scale datasets and pseudo out-of-sample forecasting includes: Armah and Swanson (2010a,b), Artis et al. (2005), Boivin and Ng (2005, 2006), Forni et al. (2005), and Stock and Watson (1999, 2002a, 2005, 2006, 2012). Stock and Watson (2006) additionally discuss in some detail the literature on the use of diffusion indices for forecasting.

²There is a vast on growing literature in this area. Some few relevant papers, including those addressing both empirical and theoretical issues, includes: For related papers in this area, see Armah and Swanson (2010a,b), Artis et al. (2005), Banerjee and Marcellino (2008), Bai and Ng (2002, 2006b, 2008), Boivin and Ng (2005, 2006), Ding and Hwang (1999), Dufour and Stevanovic (2010), and Stock and Watson (2002a, 2005, 2006, 2012).

The above papers consider PCA. However, there is also a small and growing literature that examines ICA in the context of macroeconomic forecasting (see e.g. Moneta et al. (2013), Tan and Zhang (2012), and Yau (2004)). We were unable to find any papers that hitherto have examined the used of SPCA in our context. However, the method has been applied empirically in other fields. For example, in the context of gene expression genomics, see Carvalho et al. (2008) and Mayrink and Lucas (2013).

model based on Stock and Watson (2002a,b), Bai and Ng (2006a) and Kim and Swanson (2014a):

$$Y_{t+h} = W_t \beta_W + F_t \beta_F + \varepsilon_{t+h}, \quad (2)$$

where Y_t , is the target variable to be predicted, h is the prediction horizon, W_t is a $1 \times s$ vector of “additional” explanatory variables, and F_t is a $1 \times r$ vector of factors, extracted from F . The parameters, β_W and β_F , are defined conformably, and ε_{t+h} is a disturbance term. In empirical contexts such as that considered herein, we first estimate r unobserved (latent) factors, say \hat{F}_t , from the N observable predictors, X . To achieve useful dimension reduction, r is assumed to be much less than N , (i.e. $r \ll N$) Then, parameter estimates, $\hat{\beta}_W$ and $\hat{\beta}_F$ are constructed using an in-sample dataset with Y_{t+h} , W_t , and \hat{F}_t . Finally, ex-ante forecasts based on rolling or recursive estimation schemes are formed.

In Kim and Swanson (2014a), principal component analysis (PCA) is used in obtaining estimates of the latent factors, called principal components. PCA yields “uncorrelated” latent principal components via the use of data projection in the direction of the maximum variance; and principal components (PCs) are naturally ordered in terms of their variance contribution. The first PC defines the direction that captures the maximum variance possible, the second PC defines the direction of maximum variance in the remaining orthogonal subspace, and so forth. Perhaps because derivation of PCs is easily done via use of singular value decompositions, it is the most frequently used method in factor analysis (see e.g. Bai and Ng (2002, 2006b) and Stock and Watson (2002a) for details). As discussed above, in this paper we additionally implement ICA and SPCA for estimating latent factors. These methods are used in the statistics discipline in a variety of contexts. However, economists have yet to explore the usefulness of SPCA in forecasting contexts, and few empirical investigations of the usefulness of ICA have been reported in economics (see above for examples from this small literature). Of note is that ICA (see e.g. Comon (1994) and Lee (1998)) uses so-called “negentropy”, which is a measure of entropy, to construct independent factors. SPCA is designed to uncover *uncorrelated* components and ultimately factors, just like PCA. However, the method also searches for components whose factor loading coefficient matrices are “sparse” (i.e., the matrices can contain zeros). Since PCA yields nonzero loadings for entire set of variables, practical interpretation thereof is more difficult than in contexts where sparsity characterizes the factors. Note that the importance of sparsity has not only been noted in the context of forecasting (see e.g. Bai and Ng (2008)), but has also been recently touted in a number of papers in the financial econometrics literature (see e.g. Fan et al. (2015)). For further discussion of this and related issues, see Vines (2000), Jolliffe et al. (2003), and Zou et al. (2006).

In order to add functional flexibility to our forecasting models, we additionally implement versions of (2) where the numbers and functions of factors used are specified via implementation of a variety of machine learning, variable selection and shrinkage methods, as discussed above. One key feature of many of these methods is that they are used for targeted regressor and factor selection. Related research that focuses on forecast combination methods is discussed in Stock and Watson (2012), Aiolfi and Timmermann (2006), and Bai and Ng (2008); and our discussion is meant to add to the recent work reported in Stock and Watson (2012) and Kim and Swanson (2014a), who survey and analyze several machine learning, variable selection and shrinkage methods that are based on factor augmented autoregression models of the variety given in equation (2). Finally, in our experiments, we also consider various linear benchmark forecasting models including autoregressive (AR) models, AR models with exogenous variables,

and combined autoregressive distributed lag models.

Our main findings can be summarized as follows. First, models specified using factors almost always dominate all other models, in terms of mean square forecast error (MSFE). Additionally, ICA and SPCA are preferred to PCA when estimating the factors in our MSFE-“best” models, when the forecasting horizon is $h = 1$, although the more standard approach of using PCA “wins” at all other forecasting horizons. One reason for this switch between PCA and the other methods may be that the PCA is “more” robust to structural breaks, at the one-step ahead horizon. Stock and Watson (2008) note that factors may, in some cases, play the same “averaging” role as “pooling” forecasts does, particularly in the face of intercept breaks in forecasting models. This argument derives in part from the fact that there all factor loadings are nonzero in principal components. SPCA induces sparseness in factor loadings, and thus may not offer this beneficial feature. Moreover, given the increasing inability of forecast model regression coefficients to swiftly adapt to structural change, as the forecast horizon increases, this feature may account in part for our finding that PCA dominates at longer horizons, but not at the 1-step ahead horizon. Further empirical and theoretical analysis of this finding is left to future research, however.

Second, our benchmark AR type models are never MSFE-best, and model averaging techniques including the use of arithmetic mean forecasts as well Bayesian model averaging only yield MSFE-best models for approximately 1/3 of the 11 variables, regardless of forecast horizon. The reason for this is that pure factor type models, machine learning, variable selection and shrinkage models, and “combination models” that combine dimension reduction via the use of factors with machine learning and shrinkage are the MSFE-best models for most of our variables, across all forecast horizons. In many cases, though, the key to “beating” model averaging methods, involves the use of our combination models.

Third, even though combination models are important, pure machine learning, variable selection, and shrinkage methods almost never deliver MSFE-best models. Rather, they are most useful when combined with factor analysis methods, as discussed above.

Fourth, recursive estimation strategies clearly dominate rolling strategies when constructing 1-step ahead forecasts. However, at longer forecast horizons, rolling estimation methods are preferred to recursive methods. This finding may be due in part to the presence of structural breaks, although further empirical and theoretical investigation is left to future research.

Overall, our findings suggest that dimension reduction associated with the specification and estimation of factors, as well as machine learning and shrinkage methods are very useful for forecasting macroeconomic variables, when analyzing “big data”.

The rest of the paper is organized as follows. In the next section we provide a survey of dynamic factor models, independent component analysis, and sparse principal component analysis. In Section 3, we survey the machine learning, variable selection and shrinkage methods used in our prediction experiments. Data, forecasting methods, and baseline forecasting models are discussed in Section 4, and empirical results are presented in Section 5. Concluding remarks are given in Section 6.

2 Diffusion Index Models

2.1 Principal Component Analysis

In this section, we outline the factor and forecasting models which we use, as well as providing a brief overview of PCA. For a detailed discussion of principal component analysis, see Stock and Watson (1999, 2002a, 2005, 2012), Bai and Ng (2002, 2008, 2009), Kim and Swanson (2014a), and the references cited therein.

Let X_{tj} be the observed datum for the j -th cross-sectional unit at time t , for $t = 1, \dots, T$ and $j = 1, \dots, N$. Recall that we consider the following model:

$$X_{tj} = \Lambda'_j F_t + e_{tj}, \quad (3)$$

where F_t is a $r \times 1$ vector of common factors, Λ_j is an $r \times 1$ vector of factor loadings associated with F_t , and e_{tj} is the idiosyncratic component of X_{tj} .³ The product $\Lambda'_j F_t$ is called the common component of X_{tj} . This is the dimension reducing factor representation of the data. More specifically, with $r < N$, a factor analysis model has the form:

$$\begin{aligned} X_1 &= \lambda_{11} F_1 + \dots + \lambda_{1r} F_r + e_1 \\ X_2 &= \lambda_{21} F_1 + \dots + \lambda_{2r} F_r + e_2 \\ &\vdots \\ X_N &= \lambda_{N1} F_1 + \dots + \lambda_{Nr} F_r + e_N. \end{aligned} \quad (4)$$

Here, F is a vector of $r < N$ underlying latent variables or factors, λ_{ij} is an element of an $N \times r$ matrix, Λ , of factor loadings, and the e are uncorrelated zero-mean disturbances. Many economic analyses fit naturally into the above framework. For example, Stock and Watson (1999) consider inflation forecasting with diffusion indices constructed from a large number of macroeconomic variables. Recall also that our generic forecasting equation is:

$$Y_{t+h} = W_t \beta_W + F_t \beta_F + \varepsilon_{t+h}, \quad (5)$$

where h is the forecast horizon, W_t is a $1 \times s$ vector (possibly including lags of Y), and F_t is a $1 \times r$ vector of factors, extracted from F . The parameters, β_W and β_F are defined conformably, and ε_{t+h} is a disturbance term. Following Bai and Ng (2002, 2006b, 2008, 2009), the whole panel of data $X = (X_1, \dots, X_N)$ can be represented as (3). We then estimate the factors, F_t , using principal components analysis, independent component analysis, or sparse principal component analysis. In particular, forecasts of Y_{t+h} based on (5) involve a two step procedure because both the regressors and the coefficients in the forecasting equation are unknown. The data, X_t , are first used to estimate the factors, yielding \hat{F}_t . With the estimated factors in hand, we obtain the estimators $\hat{\beta}_F$ and $\hat{\beta}_W$ by regressing Y_{t+h} on \hat{F}_t and W_t . Of note is that if $\sqrt{T}/N \rightarrow 0$, then the usual generated regressor problem does not arise, in the sense that least squares estimates of $\hat{\beta}_F$ and $\hat{\beta}_W$ are \sqrt{T} consistent and asymptotically normal (see Bai and Ng (2008)). In this paper, we try different methods for estimating $\hat{\beta}_F$ and then compare the predictive accuracy

³In the sequel, we assume that all variables are standardized, as is customary in this literature.

of the resultant forecasting models.⁴

In the following sections, we provide a brief overview of ICA and SPCA, underscoring the difference between these methods and PCA.

2.2 Independent Component Analysis

Independent Component Analysis (ICA) is predicated on the idea of “opening” the black box in which principal components often reside. A few uses of ICA include mobile phone signal processing, brain imaging, voice signal extraction and stock price modeling. In all cases, there is a large set of observed individual signals, and it is assumed that each signal depends on several factors, which are unobserved.

The starting point for ICA is the very simple assumption that the components, F , are statistically independent in equation (3). The key is the measurement of this independence between components. The method can be graphically depicted as follows:

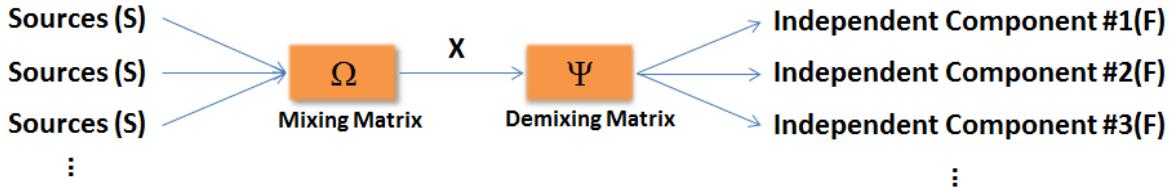


Figure 1: Schematic Representation of ICA

More specifically, ICA begins with statistical independent source data, S , which are mixed according to Ω ; and X , which is observed, is a mixture of S weighted by Ω . For simplicity, we assume that the unknown mixing matrix, Ω , is square, although this assumption can be relaxed (see Hyvärinen and Oja (2000)). Using matrix notation, we have that

$$X = S\Omega \quad (6)$$

We can rewrite (6) as follows,

$$\begin{aligned} X_1 &= \omega_{11}S_1 + \cdots + \omega_{1N}S_N \\ X_2 &= \omega_{21}S_1 + \cdots + \omega_{2N}S_N \\ &\vdots \\ X_N &= \omega_{1N}S_1 + \cdots + \omega_{NN}S_N, \end{aligned} \quad (7)$$

where ω_{ij} is the (i, j) element of Ω . Since Ω and S are unobserved, we have to estimate the demixing matrix Ψ which transforms the observed X into the independent components, F .

⁴We refer the reader to Stock and Watson (1999, 2002a, 2005, 2012) and Bai and Ng (2002, 2008, 2009) for a detailed explanation of this procedure, and to Connor and Korajczyk (1986, 1988, 1993), Forni et al. (2005) and Armah and Swanson (2010b) for further detailed discussion of generic diffusion index models.

That is,

$$F = X\Psi$$

or

$$F = S\Omega\Psi.$$

As we assume that the mixing matrix, Ω is square, Ψ is also square, and $\Psi = \Omega^{-1}$, so that F is exactly the same as S , and perfect separation occurs. In general, it is only possible to find Ψ such that $\Omega\Psi = PD$, where P is a permutation matrix and D is a diagonal scaling matrix. The independent components, F are latent variables, just the same as principal components, meaning that they cannot be directly observed. Also, the mixing matrix, Ω is assumed to be unknown. All we observe is data, X , and we must estimate both Ω and S using it. Only then can we estimate the demixing matrix Ψ , and the independent components, F . However (7) is not identified unless several assumptions are made. The first assumption is that the sources, S , are statistically independent. Since various sources of information (for example, consumer's behavior, political decisions, etc.) may have an impact on the values of macroeconomic variables, this assumption is not strong. The second assumption is that the signals are stationary. For further details, see Tong et al. (1991).

ICA under (7) assumes that N components of F exist. However, we can simply construct factors using up to r ($< N$) components, without loss of generality. In practice, we can construct r independent components by preprocessing with r principal components. See chapter 6 and 10 of Stone (2004) for further details. In general, the above model would be more realistic if there were noise terms added. For simplicity, however, noise terms are omitted; and indeed the estimation of the noise-free model is already computationally difficult (see Hyvärinen and Oja (2000) for a discussion of the noise-free model, and Hyvärinen (1998, 1999) for a discussion of the model with noise added). For a detailed explanation of the estimation algorithm that we use, refer to the working paper version of this paper (i.e., see Kim and Swanson (2014b)).

2.2.1 Comparison with Principal Component Analysis

As is evident from Figure 1, ICA is exactly the same as PCA, if we let the demixing matrix be the factor loading coefficient matrix associated with principal components analysis. The key difference between ICA and PCA is in the properties of the factors obtained. Principal components are uncorrelated and have descending variance so that they can easily be ordered in terms of their variances. Moreover, those components explaining the largest share of the variance are often assumed to be the “relevant” ones for subsequent use in diffusion index forecasting. In particular, the first principal component captures the maximum variance possible, the second component also captures the maximum variance but in an orthogonal subspace, and is thus uncorrelated with the first component, and so on.

For simplicity, consider two observables, $X = (X_1, X_2)$. PCA finds a matrix which transforms X into uncorrelated components $F = (F_1, F_2)$, such that the uncorrelated components have a joint probability density function, $p_F(F)$ with

$$E(F_1F_2) = E(F_1)E(F_2). \quad (8)$$

On the other hand, ICA finds a demixing matrix which transforms the observed $X = (X_1, X_2)$ into independent components $F^* = (F_1^*, F_2^*)$, such that the independent components have a

joint pdf $p_{F^*}(F^*)$ with

$$E[F_1^{*p} F_2^{*q}] = E[F_1^{*p}] E[F_2^{*q}], \quad (9)$$

for every positive integer value of p and q . That is, the condition holds for all moments.

Evidently, PCA estimation is much simpler than ICA, since it just involves finding a linear transformation of components which are uncorrelated. Moreover, PCA ranks components using their variances or correlations, so that components associated with higher variance or correlation are assumed to have more explanatory power than those with lower variance or correlation. On the other hand, ICA is unable to find the variance associated with each independent component since both S and Ω in (6) are unknown, so that any scalar multiplier in one of the sources, S_j , could be cancelled by dividing the corresponding mixing vector, ω_j by the same scalar. Therefore, we can randomly change the order of X in (6) so that we cannot determine the order of the independent components. From the perspective of forecasting, this is probably a good thing, since there is no *a priori* reason to believe that “largest variance” PCA components are the most relevant for predicting any particular target variable. Moreover, this feature of ICA is the reason for using PCA for pre-processing in ICA algorithms. For further details about preprocessing, see Appendix F of Stone (2004).

2.3 Sparse Principal Component Analysis

In the paper in which they develop SPCA, Zou et al. (2006) note that factor loading coefficients under PCA are all typically nonzero, making interpretation of estimated components difficult. They address this issue by proposing a modified PCA method (i.e., SPCA) in which the lasso (elastic net) is used to construct principal components with sparse loadings. This is done this by first reformulating PCA as a regression type optimization problem, and then by using a lasso (elastic net) on the coefficients in a suitably constrained regression model.

Since the seminal paper by Zou et al. (2006), many authors have proposed variants of SPCA. For example, Jolliffe (1995) modifies loadings to be values such as 1, -1 and 0. Another approach is setting thresholds for the absolute value of the loadings, below which loadings are set to zero. Jolliffe et al. (2003) suggest using so-called “SCoTLASS(Simplified Component Technique-LASSO)” to construct modified principal components with possible zero loadings, λ , by solving

$$\max \lambda'(X'X)\lambda, \text{ subject to } \sum_{j=1}^N |\lambda_j| \leq \varphi, \quad \lambda'\lambda = 1,$$

for some tuning parameter, φ . The absolute value threshold results in (various) zero loadings, hence inducing sparseness. However, the SCoTLASS constraint does not ensure convexity, and therefore the approach may be computationally expensive. As an alternative, Zou et al. (2006) develop a regression optimization framework. Namely, they assume that the X are dependent variables, F are explanatory variables, and the loadings are coefficients. They then use the lasso (and elastic net) to derive a sparse loading matrix. Other recent approaches include those discussed in Leng and Wang (2009) and Guo et al. (2010), both of which are based on Zou et al. (2006). We follow the approach of Zou et al. (2006), and readers are referred to Sections 3.3-3.5 of their paper for complete details. As in the case of ICA, we again refer the reader to Kim and Swanson (2014b) for a detailed discussion of the estimation procedures implemented in order to use SPCA in our forecasting experiments.

2.4 Selecting the Number of Factors

Selection of the number of factors when applying PCA in our experiments is an important issue, since the number of factors used in our forecasting models may impact the predictive performance of the models. In some contexts, such as in macroeconomics, factors and numbers of factors can conceivably be chosen based on theoretical arguments. Of course, empirical analysis is also often used for selecting the number of factors. Indeed, there are several empirical approaches for the determination of the appropriate number of factors for PCA. Well known methods include the scree plot and evaluating percentages of cumulative variance. These methods are straightforward, and Neto et al. (2005) contains a nice survey thereof. Cross validation is also feasible, but can be computationally expensive in big data environments. In light of this, Josse and Husson (2012) suggest using general cross validation (GCV) to approximate leave-one-out cross validation based estimation of the number of factors. In the econometrics literature, Bai and Ng (2002) suggest choosing the number of factors using a selection criteria of the form $PC(r) = V\left(r, \hat{F}\right) + rh(N, T)$, where $h(\cdot)$ is a penalty function, $V(\cdot)$ minimizes the Euclidian distance between the variables in the dataset and their factor projection, and r is the number of factors (see Kim and Swanson (2014a) for further details).⁵ With regard to ICA, note that Yo et al. (2007) propose using information criteria for selecting the number of factors in ICA. There is no specific research that we are aware of for selecting the number of factors in SPCA. Our approach is to simply use the number of factors based on Bai and Ng (2002) in all cases. We leave to future research the analysis of trade-offs associated with using alternative estimates of r .

3 Machine Learning, Variable Selection, and Shrinkage Methods

We consider a variety of machine learning, variable selection and shrinkage methods in our forecasting experiments. The methods considered include bagging, boosting, ridge regression, least angle regression, the elastic net, the non-negative garotte and Bayesian model averaging. Here, we briefly summarize a number of these methods, and provide relevant citations to detailed discussions thereof.

Bagging, which was introduced by Breiman (1996), is a machine based learning algorithm whereby outputs from different predictors of bootstrap samples are combined in order to improve overall forecasting accuracy. Bühlmann and Yu (2002) use bagging in order to improve forecast accuracy when data are *iid*. Inoue and Kilian (2008) and Stock and Watson (2012) extend bagging to time series models. Stock and Watson (2012) consider “bagging” as a form of shrinkage, when constructing prediction models. In this paper, we use the same algorithm that they do when constructing bagging estimators. This allows us to avoid time intensive bootstrap computation done elsewhere in the bagging literature. Boosting, a close relative of bagging, is another statistical learning algorithm, was originally designed for classification problems in the context of Probability Approximate Correct (PAC) learning (see Schapire (1990)), and is implemented in Freund and Schapire (1997) using the algorithm called AdaBoost.M1. Hastie

⁵Other recent approaches for selecting the number of factors include Chen et al. (2010), Onatski (2009), and the references cited therein.

et al. (2009) apply it to classification, and argue that “boosting” is one of the most powerful learning algorithms currently available. The method has been extended to regression problems in Ridgeway et al. (1999) and Shrestha and Solomatine (2006). In the economics literature, Bai and Ng (2009) use a boosting for selecting the predictors in factor augmented autoregressions. We implement a boosting algorithm that mirrors that used by these authors.

The other shrinkage methods implemented herein are penalized regression methods. One such method that we consider is called ridge regression, which is a well known linear method in which minimization of the sum of square residuals is modified to include a penalty that is a function of the number parameters. Conveniently, ridge regression uses a quadratic penalty term, and thus has a closed form solution. We also implement the “least absolute shrinkage and selection operator” (lasso), which was introduced by Tibshirani (1996), and is another attractive technique for variable selection using high-dimensional datasets, especially when N is greater than T . This method is similar to ridge, but uses an L_1 penalty function instead of ridge’s L_2 penalty, thus allowing for sparsity. Third, we examine “least angle regression” (LARS), which is introduced in Efron et al. (2004), and can be interpreted as the algorithm which finds a solution path for the lasso. Moreover, LARS is based on a well known model-selection approach known as “forward-selection”, which has been extensively used to examine cross-sectional data (for further details, see Efron et al. (2004)). Bai and Ng (2008) show how to apply LARS and the lasso in the context of time series data, and Gelper and Croux (2008) extend Bai and Ng (2008)’s work to time series forecasting with many predictors. We implement Gelper and Croux (2008)’s algorithm when constructing the LARS estimator. A related method that we consider is called the “elastic net”, which is proposed by Zou and Hastie (2005), and which is also similar to the lasso, as it simultaneously carries out automatic variable selection and continuous shrinkage, via use of penalized regression with both L_1 and L_2 penalty functions. Its name comes from the notion that it is similar in structure to a stretchable fishing net that retains “all the big fish”. Bai and Ng (2008) apply the elastic net method to time series using the approach of Zou and Hastie (2005). We also follow their approach when implementing the elastic net. Finally, we consider the “non-negative garotte”, originally introduced by Breiman (1995). This method is a scaled version of the least square estimator with shrinkage factors. Yuan and Lin (2007) develop an efficient garotte algorithm and prove consistency in variable selection. We follow Yuan and Lin (2007) in the sequel.

In addition to the above machine learning and shrinkage methods, we consider Bayesian model averaging (henceforth, BMA), as it is one of the most attractive methods for model selection currently available (see Fernandez et al. (2001), Koop and Potter (2004) and Ravazzolo et al. (2008)). The concept of Bayesian model averaging can be described with simple probability rules.⁶ If we consider R different models, each model has a parameter vector and is represented by its prior probability, likelihood function and posterior probability. Given this information, using Bayesian inference, we can obtain model averaging weights based on the posterior probabilities of the alternative models. Koop and Potter (2004) consider BMA in the context of many predictors and evaluate its performance. We follow their approach. In the following subsections, we explain the intuition behind the above methods, and how they are used in our forecasting framework.

For a comprehensive discussion of the above methods and estimation algorithms, the reader is referred to Kim and Swanson (2014b).

⁶We also consider simple arithmetic model averaging.

4 Data, Forecasting Methods, and Baseline Forecasting Models

4.1 Data

The data that we use are monthly observations on 144 U.S. macroeconomic time series for the period 1960:01 - 2009:5 ($N = 144, T = 593$)⁷. Forecasts are constructed for eleven variables, including: the unemployment rate, personal income less transfer payments, the 10 year Treasury-bond yield, the consumer price index, the producer price index, non-farm payroll employment, housing starts, industrial production, M2, the S&P 500 index, and gross domestic product.⁸ Table 1 lists the eleven variables. The third row of the table gives the transformation of the variable used in order to induce stationarity. In general, logarithmic differences were taken for all nonnegative series that were not already in rates (see Stock and Watson (2002a, 2012) for complete details). Note that a full list of the 144 predictor variables is provided in an appendix to an earlier version of this paper which is available upon request from the authors.

4.2 Forecasting Methods

Using the transformed dataset, denoted by X , factors are estimated using the techniques discussed above. Thereafter, the estimation methods outlined in the previous section are used to form forecasting models and predictions. In our experiments, we consider three specification types, as follows.

Specification Type 1 (SP1): Factors are first constructed using the large-scale dataset and each of PCA, ICA, and SPCA. Prediction models are then constructed using the machine learning and shrinkage methods of Section 3 to select functions of and weights for the factors to be used in prediction models of the variety given in (5). This specification type is estimated with and without lags of factors.

Specification Type 2 (SP2): Factors are first constructed using subsets of variables from the large-scale dataset and each of PCA, ICA, and SPCA. Variables used in factor calculations are pre-selected via application of the machine learning and shrinkage methods discussed in Section 3. Thereafter, prediction models of the variety given in (5) are estimated. This is different from the above approach of estimating factors using all of the variables. Note that forecasting models are estimated with and without lags of factors.

As stated above, we analyze versions of Specifications 1 and 2 (i.e., SP1 and SP2) both with and without lags of factors. Using the notation of equation (5), SP1 and SP2 include F_t , while the “lags of factors” versions, called SP1L and SP2L, include F_t and F_{t-1} . The reason only one lag was utilized is that no additional forecast improvement was found when more than one lag was included.

Specification Type 3 (SP3): Prediction models are constructed using only the machine and shrinkage methods discussed in Section 3, without use of factor analysis at any stage.

⁷This is an updated and expanded version of the Stock and Watson (2002b, 2012) dataset, although data definitional changes and series discontinuations prevents us from updating the database to a more current date. We leave the discussion of the use of alternative data samples to future research.

⁸Note that gross domestic product is reported quarterly. We interpolate these data to a monthly frequency following Chow and Lin (1971),

Specification Type 4 (SP4): Prediction models are constructed using only machine learning and shrinkage methods, and only with variables which have nonzero coefficients, as specified via pre-selection using SPCA.

In Specification Types 3 and 4, factor augmented autoregressions (FAAR) and pure factor based models (such as principal component regression - see next subsection for complete details) are not used as candidate forecasting models, since models with these specification types do not include factors or any type.

In our prediction experiments, pseudo out-of-sample forecasts are calculated for each variable, model variety, and specification type, for prediction horizons $h = 1, 3$, and 12 . All estimation, including lag selection, machine learning and shrinkage method implementation, and factor selection is done anew, at each point in time, prior to the construction of each new prediction, using both recursive and rolling data window strategies. Note that at each estimation period, the number of factors included will be different, following re-estimation of r . Note also that lags of the target predictor variables are also included in the set of explanatory variables, in all cases. Selection of the number of lags (of both variables and factors) to include is done using the SIC. Out-of-sample forecasts begin after 13 years (e.g. the initial in-sample estimation period is $R = 156$ observations, and the out-of-sample period consists of $P = T - R = 593 - 156 = 437$ observations, for $h = 1$). Moreover, the initial in-sample estimation period is adjusted so that the ex ante prediction sample length, P , remains fixed, regardless of the forecast horizon. For example, when forecasting the unemployment rate, when $h = 1$, the first forecast will be $\hat{Y}_{157}^{h=1} = \hat{\beta}_W W_{156} + \hat{\beta}_F \tilde{F}_{156}$, while in the case where $h = 12$, the first forecast will be $\hat{Y}_{157}^{h=12} = \hat{\beta}_W W_{145} + \hat{\beta}_F \tilde{F}_{145}$. In our rolling estimation scheme, the in-sample estimation period used to calibrate our prediction models is fixed at length 12 years. The recursive estimation scheme begins with the same in-sample period of 12 years (when $h = 12$), but a new observation is added to this sample prior to the re-estimation and construction of each new forecast, as we iterate through the ex-ante prediction period. Note, thus, that the actual observations being predicted as well as the number of predictions in our ex-ante prediction period remains the same, regardless of forecast horizon, in order to facilitate comparison across forecast horizons as well as models.

Forecast performance is evaluated using mean square forecast error (MSFE), defined as:

$$MSFE_{i,h} = \sum_{t=R-h+2}^{T-h+1} \left(Y_{t+h} - \hat{Y}_{i,t+h} \right)^2, \quad (10)$$

where $\hat{Y}_{i,t+h}$ is the forecast for horizon h . Forecast accuracy is evaluated using the above point MSFE measure as well as the predictive accuracy test statistic (called “DM” hereafter) of Diebold and Mariano (1995), which is implemented using quadratic loss, and which has a null hypothesis that the two models being compared have equal predictive accuracy (see Clark and McCracken (2001), McCracken (2000), McCracken (2007), and McCracken (2004) for details describing the importance of accounting for parameter estimation error and nonnestedness in the DM and related predictive accuracy tests).⁹ In the simplest case, the DM test statistic has an asymptotic $N(0, 1)$ limiting distribution, under the assumption that parameter estimation

⁹In the experiments carried out in this paper, we do not consider so-called real-time data. However, it is worth noting that the use of real-time datasets in macroeconomics, and in particular in forecasting and policy analysis, has received considerable attention in the literature in recent years. For a discussion of DM and related tests using real-time data, the reader is referred to Clark and McCracken (2009).

error vanishes (i.e. $P/R \rightarrow 0$, as $T, P, R \rightarrow \infty$), and assuming that each pair of models being compared is nonnested. The null hypothesis of the test is $H_0 : E \left[l \left(\varepsilon_{t+h|t}^1 \right) \right] - E \left[l \left(\varepsilon_{t+h|t}^2 \right) \right] = 0$, where $\varepsilon_{t+h|t}^i$ is i -th model's prediction error and $l(\cdot)$ is the quadratic loss function. The actual statistic in this case is constructed as: $DM = P^{-1} \sum_{i=1}^P d_t / \hat{\sigma}_{\bar{d}}$, where $d_t = \widehat{\left(\varepsilon_{t+h|t}^1 \right)^2} - \widehat{\left(\varepsilon_{t+h|t}^2 \right)^2}$, \bar{d} is the mean of d_t , $\hat{\sigma}_{\bar{d}}$ is a heteroskedasticity and autocorrelation robust estimator of the standard deviation of \bar{d} , and $\widehat{\varepsilon_{t+h|t}^1}$ and $\widehat{\varepsilon_{t+h|t}^2}$ are estimates of the true prediction errors $\varepsilon_{t+h|t}^1$ and $\varepsilon_{t+h|t}^2$. Thus, if the statistic is negative and significantly different from zero, then Model 2 is preferred over Model 1.

4.3 Baseline Forecasting Models

In addition to the various forecast models discussed above (see Specification Types 1-4), we also form predictions using the following benchmark models, all of which are estimated using least squares.

Univariate Autoregression: Forecasts from a univariate AR(p) model are computed as $\hat{Y}_{t+h}^{AR} = \hat{\alpha} + \hat{\phi}(L) Y_t$, with lags $, p$, selected using of the SIC.

Multivariate Autoregression: Forecasts from an ARX(p) model are computed as $\hat{Y}_{t+h}^{ARX} = \hat{\alpha} + \hat{\beta} Z_t + \hat{\phi}(L) Y_t$, where Z_t is a set of lagged predictor variables selected using the SIC.¹⁰ Dependent variable lags are also selected using the SIC. Selection of the exogenous predictors includes choosing up to six variables prior to the construction of each new prediction model, as the recursive or rolling samples iterate forward over time.

Principal Components Regression: Forecasts from principal component regression are computed as $\hat{Y}_{t+h}^{PCR} = \hat{\alpha} + \hat{\gamma} \hat{F}_t$, where \hat{F}_t is estimated via principal components using X , as in equation (5).

Factor Augmented Autoregression: Based on equations (5), forecasts are computed as $\hat{Y}_{t+h}^h = \hat{\alpha} + \hat{\beta}_F \hat{F}_t + \hat{\beta}_W(L) Y_t$. This model combines an AR(p) model, with lags selected using the SIC, and the above principal component regression (PCR) model. PCR and factor augmented autoregressive (FAAR) models are estimated using ordinary least squares. Factors in the above models are constructed using PCA, ICA and SPCA.

Combined Bivariate ADL Model: Following Stock and Watson (2012), we implement a combined bivariate autoregressive distributed lag (ADL) model. Forecasts are constructed by combining individual forecasts computed from bivariate ADL models. The i -th ADL model includes $p_{i,x}$ lags of $X_{i,t}$ and $p_{i,y}$ lags of Y_t , for $i = 1, \dots, N$. The model, thus, is specified as: $\hat{Y}_{t+h}^{ADL} = \hat{\alpha} + \hat{\beta}_i(L) X_{i,t} + \hat{\phi}_i(L) Y_t$. The combined forecast is $\hat{Y}_{T+h|T}^{Comb,h} = \sum_{i=1}^N w_i \hat{Y}_{T+h|T}^{ADL,h}$. Here, we set ($w_i = 1/N$), and $N = 144$. In each model, $p_{i,x}$ is first selected using the SIC, and then $p_{i,y}$ is selected, again using the SIC. There are a number of studies that compare the performance of combining methods in controlled experiments, including: Clemen (1989), Diebold and Lopez (1996), Newbold and Harvey (2002), and Timmermann (2006); and in the literature on factor

¹⁰For this model, autoregressive lags are first selected using the SIC, as in the case of estimation of the AR(p) model. Thereafter, the first lag of each variable in the entire dataset is sequentially added to the model, where we are assuming for simplicity that $h = 1$. If the adjusted R^2 increases by more than 0.01, then the variable is retained, and the search continues, until the first lag of each variable has been tried. This process is repeated until six lags of each variable had been tried.

models, Stock and Watson (2004, 2006, 2012), and the references cited therein. In this literature, combination methods typically outperform individual forecasts. This stylized fact is sometimes called the “forecast combining puzzle.”

Mean Forecast Combination: To further examine the issue of forecast combination, and in addition to the Bayesian model averaging methods discussed previously, we form forecasts as the arithmetic average of the thirteen forecasting models summarized in Table 2, which include those outlined in this and previous sections.

Of final note is that all of the above benchmark models remain unchanged, regardless of specification type, as we define specification types only in the context of dimension reduction, machine learning, variable selection and shrinkage methods. The exception are our mean forecast combinations, since they combine all benchmark forecasts as well as all other models. As stated above, our entire set of models are listed in Table 2.

5 Empirical Results

In this section, we summarize the results of our prediction experiments. The variables (and transformations thereof) that we forecast are listed in Table 1. There are 6 different specification “permutations”. Specification Types 1 and 2 (estimated with and without lags) are estimated via PCA, ICA and SPCA, so that there $4 \times 3 = 12$ permutations of these two specifications. Adding Specification Types 3 and 4, and multiplying by two (for recursive and rolling windowing strategies) yields a total of $(12 + 2) \times 2 = 28$ specification types for each target variable and each forecast horizon. The forecast models that we use in our experiments are summarized in Table 2. For the sake of brevity, we eschew reporting the entirety of our experimental findings, instead focusing on key findings and results. Complete details are available upon request from the authors.

Table 3, Panel A contains the lowest relative MSFEs from amongst all models, for Specification Types 1-4 and for factors estimated using PCA, ICA, and SPCA, where by relative, we mean that MSFEs relative to that of the AR(SIC) benchmark are reported. The models to which each of these MSFEs correspond are given in Panel A of Table 4. Thus, the MSFE value of 0.780 given in the upper right corner of the entries in Panel A of Table 3 is that obtained from use of our FAAR model (see upper right corner of the entries in Panel A of Table 4), under Specification Type 1, with factors estimated using PCA. Panel A of Tables 3 and 4 corresponds to experiments run using recursive estimation. For corresponding results based on rolling estimation, refer to Panel B of Tables 3 and 4. The tables are partitioned into 3 sets of results, corresponding to forecast horizons $h = 1, 3$, and 12. Entries in bold denote the lowest relative MSFEs from amongst all models *for a given model specification* (i.e. Specification Types 1-4). Since the benchmark models, including AR(SIC), ARX, etc., are included as candidate models when selecting the lowest relative MSFEs from amongst all models, for Specification Types 1-4 and for factors estimated using PCA, ICA, and SPCA, MSFE entries in Table 3 might be unity, indicating that the AR(SIC) model was MSFE-“best” for a given specification type and factor estimation method. Additionally, for a given specification type, entries might be the same for multiple factor estimation methods. This occurs because candidate models include those that contain no factors (e.g. the ARX model), and the same ARX model might “win” not only against models estimated using PCA, say, but also against models estimated using SPCA. These cases are made clear by inspection of the model (in Table 4) to

which the MSFE (in Table 3) pertains. For example, in the case of Specification Type 1 and $h = 1$, GDP MSFEs are 0.916 for all three factor estimation methods. This is because ARX, one of benchmark models, yields a lower MSFE than any other model, for Specification Type 1, regardless of whether the models that contain factors are estimated using PCA, ICA, or SPCA. Finally, since Specification Types 3 and 4 do not involve use of factors, there are no bold entries in rows corresponding to these specification types. Namely, there is no “choice” to be made across factor estimation methods for these specification types. A number of clear-cut conclusions emerge upon inspection of Tables 3-4.

First, although there are a limited number of exceptions, most of the entries in Table 3 are less than unity, indicating that our autoregressive model is dominated by other models in virtually all of our experiments. For example, note that the relative MSFE value for IPX, when using Specification Type 1 (SP1) and $h = 1$, is 0.268, under recursive estimation (see the third entry in the column denoted “IPX” in Table 3, Panel A). This entry is clearly less than unity. Additionally, note that this entry is starred, indicating that the model corresponding to the entry (i.e. the FAAR model, with factors estimated using SPCA - see the third entry in the column denoted “IPX” in Table 4, Panel A) statistically significantly different from the AR(SIC) model, at a 90% confidence level, based on application of the DM test discussed above.

Second, the MSFE-best models, from across all specification types and factor estimation methods, are usually specified using Specification Type 1 (i.e., SP1), when $h = 1$. This is seen by inspecting the block of entries in Table 3 (Panel A) associated with $h = 1$, and by noting that for each of the 11 columns of entries in this block of MSFEs, the lowest “bolded” MSFE falls under SP1, with one exception (i.e., CPI and GDP). Furthermore, when comparing all 11 of these so-called “overall winners” for the $h = 1$ case, we see that PCA is the chosen factor estimation method for only 2 variables (i.e., for UR and M2), while SPCA “wins” for 6 variables, and ICA “wins” for 2 variables.¹¹ This supports the use of SPCA and ICA, at the $h = 1$ forecast horizon. Note also that the fact that SP1 “wins” rather than SP1L (recall that SP1 uses no lags of factors, while SP1L is the same as SP1, except that factor lags are included) indicates that additional factor lags, other than the single lag used under SP1 which is needed to ensure that our experiments are *ex ante* are not useful when $h = 1$.

Third, note that the above conclusion with regard to the performance of SPCA and ICA factor estimation methods, for $h = 1$, is based solely upon inspection of results associated with recursive estimation. Interestingly, when the MSFEs associated with the “overall winners” discussed above are compared with the “overall winners” under rolling estimation (see Tables 3 and 4, Panel B), the above conclusion remains largely intact. Indeed, for this case (i.e. $h = 1$), rolling estimation only yields one “overall winner” than is lower than the corresponding “overall winner” for the recursive estimation case. Namely, this is the case for CPI, where rolling estimation under Specification Type 4 yields a lower MSFE than any other method under any other modelling permutation. This finding clearly supports the use of recursive estimation when $h = 1$. To simplify further discussion, let us define the “globally best” MSFE as the lowest “overall winner” when comparing results under both rolling and the recursive estimation strategies. All of our results discussed in the context of our “globally best” models are summarized in Table 5. In particular, for each forecast horizon, one can read, from Table 5, the “globally best” specification type, estimation window type, factor estimation method,

¹¹For CPI, the “overall winner” does not incorporate factors, and hence the sum of these “wins” is only 10.

and model.

Fourth, although recursive estimation yield the “globally best” MSFEs for all 11 variables, when $h = 1$, this is not so for $h = 3$ and $h = 12$. Indeed, for $h = 3$, the lowest MSFEs across specification type, factor estimation method and data windowing choice (i.e., the “globally best” MSFEs) are obtained via rolling estimation for 6 of 11 variables. Moreover, for $h = 12$, the “globally best” MSFEs are obtained via rolling estimation for 9 of 11 variables. When comparing factor estimation methods for these “globally best” models, we see that PCA dominates for 8 of 11 variables when $h = 3$, and for 7 of 11 variables when $h = 12$. Thus, at longer forecast horizons, the choice between using PCA or one of our other factor estimation methods becomes more difficult, and on average it is better to use PCA.

Fifth, as discussed above, entries in the Table 4 show which forecast models (see the list of models in Table 2) have the lowest relative MSFEs, as reported in Table 3, for each target variable, and for each specification type, factor estimation method, and forecast horizon (Panel A summarizes results for recursive estimation, and Panel B does the same for rolling estimation). For example, in the upper-leftmost three entries of Panel A of Table 4, we see that for unemployment, the FAAR, ARX, and FAAR models result in the MSFE-best predictions, under SP1 and for each of PCA, ICA, and SPCA, respectively, given recursive estimation. The corresponding MSFEs for these models, as reported in Table 3 (Panel A) are 0.780, 0.897 and 0.827, respectively. Again as discussed above, bold entries in Panels A and B of Table 4 denote the forecasting models yielding MSFE-best predictions, for a given specification type, forecast horizon, and target variable. When comparing only the “globally best” models across Table 4 (Panels A and B), which we have defined to be the MSFE-best models for each variable across all specification and modeling permutations, we see that for $h = 1$, the FAAR wins 4 times, PCR wins 2 times, Mean or BMA wins 3 times, and Boost wins 2 times. Here, Boost is estimated under Specification Type 1, indicating that it involves the use of estimated factors. In all, then, 10 of 11 “globally best” models are factor based models, since Mean also uses factor type models.¹² Moreover, mean only wins twice. This is strong evidence in favor of using factor models for forecasting macroeconomic variables when $h = 1$, and provides evidence against the oft noted success of using Bayesian averaging and arithmetic mean combinations, since Mean only “wins” twice.

Sixth, when the above model assessment is carried out for $h = 3$ and $h = 12$, we see that the following “wins” obtain. For $h = 3$: PCR (3), Mean (4), Boosting (1), LARS (1), NNG (1), Ridge (1). For $h = 12$: PCR (1), Mean or BMA (4), Boosting (4), LARS (1), Bagging (1). At both of these horizons, 9 of 11 “winning” models incorporate factors, in support of our above conclusion concerning the usefulness of factor models. Interestingly, our machine learning and shrinkage type models fare much better at the higher forecast horizons, and are critical for 4 of 11 variables when $h = 3$, and again for 6 of 11 variables when $h = 12$. This feature of our results might in part be explained by the presence of structural breaks that are more “damaging” to predictions made at longer forecast horizons (see Introduction for further discussion, including a discussion of why ICA and SPCA might be preferred to PCA for $h = 1$ but not for $h > 1$). All of the above results discussed in the context of our “globally best” models are summarized in Table 5. In particular, for each forecast horizon, one can read, from this table, the “globally best” specification type, estimation window type, factor estimation method, and model.

¹²The “winning” CPI model is BMA, estimated under Specification Type 4, and hence factors enter into only 10 of 11 models.

Overall, our findings suggest that dimension reduction associated with the specification and estimation of factors, as well as machine learning and shrinkage methods are very useful for forecasting macroeconomic variables, when analyzing “big data”. Exactly which method and model to use is case specific, as might be expected, although dimension reduction methods seem useful at all forecast horizons, while machine learning and shrinkage methods are more useful at longer forecast horizons. Finally, there is substantial evidence suggesting that SPCA and ICA offer interesting alternatives to the use of PCA when estimating factors, particularly for 1-step ahead prediction.

6 Concluding Remarks

In this paper we outline and discuss a number of interesting new forecasting methods that have recently been developed in the statistics and econometrics literatures. We focus in particular on the examination of a variety of factor estimation methods, including principal components analysis (PCA), independent component analysis (ICA), and sparse principal component analysis (SPCA); as well as hybrid forecasting methods that use these factor estimation methods in conjunction with various types of machine learning, variable selection and shrinkage methods, including bagging, boosting, least angle regression, the elastic net, and the nonnegative garrote, for example. We analyze all models and methods by carrying out a series of real-time prediction experiments, in the context of predicting 11 key macroeconomic indicators at various forecast horizons. We find that simple time series models and model averaging methods do not dominate hybrid methods that couple factor estimation methods with machine learning and shrinkage methods. We also find that SPCA and ICA are useful alternatives to PCA, perhaps due to their sparseness features. Overall, we find strong new evidence of the usefulness dimension reduction associated with the specification and estimation of factors, and find that combining such dimension reduction with learning and shrinkage methods yields promising results, when forecasting macroeconomic variables.

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Table 1: Target Forecast Variables *

Series	Abbreviation	Y_{t+h}
Unemployment Rate	UR	$Z_{t+1} - Z_t$
Personal Income Less transfer payments	PI	$\ln(Z_{t+1}/Z_t)$
10-Year Treasury Bond	TB	$Z_{t+1} - Z_t$
Consumer Price Index	CPI	$\ln(Z_{t+1}/Z_t)$
Producer Price Index	PPI	$\ln(Z_{t+1}/Z_t)$
Nonfarm Payroll Employment	NPE	$\ln(Z_{t+1}/Z_t)$
Housing Starts	HS	$\ln(Z_t)$
Industrial Production	IPX	$\ln(Z_{t+1}/Z_t)$
M2	M2	$\ln(Z_{t+1}/Z_t)$
S&P 500 Index	SNP	$\ln(Z_{t+1}/Z_t)$
Gross Domestic Product	GNP	$\ln(Z_{t+1}/Z_t)$

* Notes: Data used in model estimation and prediction construction are monthly U.S. figures for the period 1960:1-2009:5. Data transformations used in prediction experiments are given in the last column of the table. See Section 4 for further details.

Table 2: Models Used in Forecasting Experiments*

Method	Description
AR(SIC)	Autoregressive model with lags selected by the SIC
ARX	Autoregressive model with exogenous regressors
CADL	Combined autoregressive distributed lag model
FAAR	Factor augmented autoregressive model
PCR	Principal components regression
Bagging	Bagging with shrinkage, $c = 1.96$
Boosting	Component boosting, $M = 50$
BMA1	Bayesian model averaging with g-prior = $1/T$
BMA2	Bayesian model averaging with g-prior = $1/N^2$
Ridge	Ridge regression
LARS	Least angle regression
EN	Elastic net
NNG	Non-negative garrote
Mean	Arithmetic mean

* Notes: This table summarizes the models used in all forecasting experiments. In addition to estimating the above pure linear and factor models (i.e., AR, ARX, CADL, FAAR, PCR), we consider the various above machine learning and shrinkage methods, as well as various combined factor and machine learning / shrinkage methods, when implementing our forecasting experiments. Complete details for all models, other than the pure linear models, are given in Section 4.2, where we discuss Specification Types 1-4, in which the various strategies for factor estimation, machine learning and shrinkage method implementation are outlined. For further details see also Sections 3 and 4.

Table 3: Lowest Point MSFEs by Forecast Estimation and Factor Specification Method*

Panel A: Recursive Window Estimation

Forecast Horizon	Factor Spec. Mtd.	UR	PI	TB10Y	CPI	PPI	NPE	HS	IPX	M2	SNP	GDP	
$h = 1$	SP1	PCA	0.780*	0.870	0.940	0.875	0.943	0.811	0.900	0.800	0.939*	0.976	0.916*
		ICA	0.897	0.920	0.931	0.840*	0.843*	0.802	0.901	0.574	0.965	0.920	0.916*
		SPCA	0.827	0.789*	0.409*	0.870	0.858	0.706*	0.542*	0.268*	0.969	0.897*	0.916*
	SP1L	PCA	0.850*	0.889*	0.955*	0.865*	0.945*	0.879*	0.901*	0.804*	0.930*	0.976*	0.916*
		ICA	0.897	0.966	0.978	0.939	0.960	0.918	0.901*	0.861	0.991	1.002	0.916*
		SPCA	0.897	0.954	0.987	0.939	0.972	0.881	0.901*	0.826	0.954	0.998	0.916*
	SP2	PCA	0.861*	0.950*	0.965*	0.933	0.968	0.854*	0.901*	0.833*	0.942	0.985*	0.871
		ICA	0.897	0.959	0.971	0.939	0.965*	0.861	0.901*	0.874	0.959	0.991	0.867*
		SPCA	0.897	0.959	0.976	0.939	0.966	0.860	0.901*	0.873	0.940*	0.986	0.873
	SP2L	PCA	0.861*	0.950*	0.965*	0.933	0.968	0.854*	0.901*	0.833*	0.942*	0.985*	0.871*
		ICA	0.864	0.957	0.975	0.923*	0.967	0.862	0.901*	0.840	0.961	0.993	0.871*
		SPCA	0.868	0.961	0.974	0.939	0.963*	0.859	0.901*	0.874	0.950	0.991	0.879
	SP3		0.897	0.944	0.987	0.933	0.956	0.826	0.901	0.874	0.977	0.989	0.873
	SP4		0.897	0.964	0.979	0.939	0.962	0.865	0.901	0.829	0.971	0.986	0.916
$h = 3$	SP1	PCA	0.913*	0.866*	0.998	0.929	0.910*	0.819	0.852*	0.850	0.977	0.994*	0.956
		ICA	0.914	0.902	0.975	0.922	0.945	0.819	0.917	0.834	0.969	1.002	0.976
		SPCA	0.916	0.892	0.988	0.895*	0.940	0.775*	0.862	0.816*	0.942*	0.997	0.944*
	SP1L	PCA	0.925*	0.892*	0.988	0.901*	0.929*	0.818*	0.852*	0.838*	0.978*	0.993*	0.963*
		ICA	0.963	0.902	0.998	0.967	0.945	0.927	0.948	0.895	0.997	1.007	0.979
		SPCA	0.951	0.902	0.984	0.968	0.945	0.924	0.912	0.887	0.990	0.997	0.988
	SP2	PCA	0.916*	0.895*	0.992*	0.888	0.945	0.827*	0.783	0.809*	0.967	0.995	0.954*
		ICA	0.941	0.902	0.995	0.959	0.945	0.859	0.824	0.821	0.980	0.997	0.963
		SPCA	0.943	0.902	0.998	0.975	0.945	0.894	0.793	0.873	0.964*	0.993	0.963
	SP2L	PCA	0.916*	0.895*	0.992*	0.888	0.945	0.827*	0.783	0.809*	0.967*	0.995	0.954*
		ICA	0.916*	0.902	0.998	0.903	0.945	0.827*	0.854	0.812	0.979	0.997	0.967
		SPCA	0.950	0.902	0.994	0.972	0.945	0.889	0.803	0.812	0.974	0.993	0.962
	SP3		0.943	0.902	0.998	0.926	0.945	0.860	0.723	0.881	0.939	1.001	0.975
	SP4		0.950	0.902	0.986	0.979	0.945	0.898	0.937	0.872	0.990	0.988	0.978
$h = 12$	SP1	PCA	0.939	0.956	0.997	0.886*	0.939*	0.874	0.818*	0.919*	0.958	1.002	0.999
		ICA	0.948	0.944	0.997	0.960	0.977	0.907	0.844	0.952	0.960	1.001	0.986*
		SPCA	0.933*	0.940*	0.992*	0.928	0.950	0.845*	0.841	0.932	0.950*	0.996	0.993
	SP1L	PCA	0.903*	0.956*	0.988*	0.888*	0.927*	0.860*	0.829*	0.926*	0.942*	0.995*	1.000
		ICA	0.943	0.969	0.997	0.961	0.981	0.912	0.912	0.939	0.964	1.002	0.981
		SPCA	0.912	0.977	0.997	0.945	0.970	0.879	0.832	0.937	0.981	1.001	0.997
	SP2	PCA	0.926	0.949	0.992*	0.891*	0.950*	0.816*	0.749	0.916*	0.930	0.995*	0.982*
		ICA	0.941	0.949	0.997	0.909	0.960	0.843	0.901	0.942	0.933	0.999	0.991
		SPCA	0.916*	0.948*	0.997	0.935	0.957	0.843	0.910	0.919	0.916*	0.997	0.992
	SP2L	PCA	0.926	0.949*	0.992*	0.891*	0.950*	0.816*	0.749	0.916*	0.930*	0.995	0.982*
		ICA	0.933	0.953	0.992	0.894	0.964	0.853	0.883	0.944	0.942	0.998	0.985
		SPCA	0.914*	0.950	0.996	0.958	0.968	0.872	0.880	0.938	0.961	0.994	0.989
	SP3		0.926	0.961	0.997	0.899	0.953	0.862	0.804	0.890	0.910	1.002	0.982
	SP4		0.926	0.963	0.997	0.943	0.962	0.855	0.886	0.927	0.976	1.001	0.990

Panel B: Rolling Window Estimation

Forecast Horizon	Factor Spec. Mtd.	UR	PI	TB10Y	CPI	PPI	NPE	HS	IPX	M2	SNP	GDP	
$h = 1$	SP1	PCA	0.787*	0.909*	0.944*	0.843*	0.971	0.831*	0.841*	0.803*	0.863*	0.998*	0.940*
		ICA	0.871	1.014	0.977	0.876	0.973	0.918	0.841*	0.910	0.918	0.998*	0.948
		SPCA	0.871	1.023	0.977	0.883	0.996	0.877	0.841*	0.875	0.869	1.007	0.945
	SP1L	PCA	0.852*	0.989*	0.954*	0.850*	0.973	0.871*	0.841*	0.845*	0.845*	1.002	0.943
		ICA	0.871	1.004	0.982	0.883	0.985	0.924	0.841*	0.877	0.908	1.008	0.941*
		SPCA	0.871	1.081	0.992	0.883	1.003	0.911	0.841*	0.851	0.880	1.008	0.989
	SP2	PCA	0.871*	1.085	0.963*	0.849	0.936*	0.869*	0.841*	0.858*	0.889	0.998*	0.915*
		ICA	0.871*	1.114	0.977	0.849	0.941	0.884	0.841*	0.858*	0.908	1.006	0.915*
		SPCA	0.871*	1.087	0.979	0.844*	0.949	0.877	0.841*	0.892	0.888*	1.007	0.927
	SP2L	PCA	0.871*	1.088	0.964*	0.850	0.948*	0.865*	0.841*	0.833*	0.886*	0.997*	0.905*
		ICA	0.871*	1.100	0.977	0.843	0.953	0.880	0.841*	0.841	0.909	1.004	0.905*
		SPCA	0.871*	1.095	0.979	0.840*	0.957	0.879	0.841*	0.864	0.910	1.004	0.915
	SP3		0.871	1.114	0.992	0.858	1.000	0.924	0.841	0.841	0.916	1.008	0.930
	SP4		0.871	1.091	0.977	0.828	0.946	0.872	0.841	0.867	0.899	1.008	0.945
$h = 3$	SP1	PCA	0.882*	0.872*	1.002	0.861*	0.937	0.786*	0.769*	0.835*	0.914*	0.997*	0.937
		ICA	0.923	0.925	0.996	0.890	0.941	0.833	0.839	0.854	0.978	1.004	0.957
		SPCA	0.926	0.913	0.993	0.870	0.944	0.847	0.807	0.869	0.941	1.003	0.969
	SP1L	PCA	0.904*	0.889*	0.981*	0.848*	0.920	0.807*	0.744*	0.820*	0.908*	0.988	0.953*
		ICA	0.936	0.925	1.001	0.900	0.951	0.876	0.854	0.877	0.976	1.008	0.957
		SPCA	0.957	0.903	1.002	0.905	0.945	0.905	0.840	0.884	0.981	1.001	0.972
	SP2	PCA	0.895*	0.883*	0.998	0.875	0.941	0.814*	0.740	0.833*	0.912*	0.989	0.929*
		ICA	0.912	0.899	0.995	0.875	0.939	0.838	0.743	0.850	0.915	0.989	0.950
		SPCA	0.919	0.914	0.997	0.863	0.941	0.846	0.785	0.857	0.927	0.989	0.947
	SP2L	PCA	0.889	0.886*	0.988*	0.864	0.942	0.792*	0.738	0.823*	0.911*	0.985*	0.938*
		ICA	0.888*	0.901	0.998	0.865	0.941	0.792*	0.806	0.838	0.921	0.985*	0.947
		SPCA	0.927	0.919	1.002	0.861*	0.936	0.843	0.772	0.858	0.929	0.985*	0.943
	SP3		0.911	0.903	1.002	0.906	0.960	0.839	0.683	0.844	0.950	1.002	0.970
	SP4		0.930	0.903	1.002	0.842	0.925	0.831	0.806	0.858	0.942	0.994	0.960
$h = 12$	SP1	PCA	0.897	0.935*	0.997*	0.812	0.891	0.729	0.723	0.884*	0.896*	1.007	1.010
		ICA	0.930	0.944	0.997*	0.863	0.949	0.779	0.741	0.909	0.937	0.996	0.999
		SPCA	0.879*	0.953	0.997*	0.781	0.920	0.720*	0.715*	0.890	0.904	1.006	0.997*
	SP1L	PCA	0.864*	0.946*	0.997	0.819	0.902	0.737	0.726	0.898*	0.899*	1.000	0.996
		ICA	0.908	0.951	0.997	0.872	0.962	0.730*	0.773	0.902	0.942	1.003	0.987
		SPCA	0.869	0.983	0.992	0.816	0.938	0.759	0.712	0.943	0.960	1.002	0.984*
	SP2	PCA	0.893*	0.929*	0.997*	0.818*	0.912*	0.692	0.637	0.880*	0.884	0.994	0.994
		ICA	0.911	0.932	0.997*	0.833	0.915	0.691*	0.726	0.902	0.888	0.994	0.993
		SPCA	0.901	0.935	0.997*	0.819	0.921	0.692	0.693	0.896	0.879	0.991	0.991*
	SP2L	PCA	0.883*	0.927*	0.997*	0.816*	0.903*	0.714*	0.624	0.888*	0.880*	0.993	0.996
		ICA	0.895	0.929	0.997*	0.835	0.917	0.719	0.695	0.898	0.897	0.994	0.993
		SPCA	0.888	0.935	0.997*	0.836	0.910	0.722	0.768	0.897	0.905	0.994	0.991*
	SP3		0.903	0.971	0.997	0.799	0.947	0.690	0.551	0.940	0.891	1.001	0.998
	SP4		0.882	0.937	0.997	0.804	0.912	0.702	0.616	0.886	0.902	0.997	0.985

Notes: See notes to Tables 1 and 2. Numerical entries in this table are the lowest (relative) mean square forecast errors (MSFEs) based on the use of models estimated used recursive (Panel A) and rolling (Panel B) data windowing methods, and using three different factor estimation methods (PCA, ICA and SPCA - see Section 2 for further discussion), for six different specification types (SP1, SP1L, SP2, SP2L, SP3, and SP4 - see Section 4 for details). Prediction models and target variables are described in Tables 1 and 2. Forecasts are monthly, for the period 1974:3-2009:5. Forecast horizons reported on include $h=1$, 3, and 12. Tabulated relative MSFEs are calculated such that numerical values less than unity constitute cases for which the alternative model has lower point MSFE than the AR(SIC) model. Entries in bold denote point-MSFE “best” models among the three factor estimation methods, for a given specification type, estimation window and forecast horizon. Additionally, bolded entries superscripted with a “” indicate instances for which the AR(SIC) model is statistically inferior that the model yielding the stated “best” MSFE. For a listing of these MSFE “best” models, compare Panel A of Table 3 with Panel A of Table 4. See Section 5 for further details.

Table 4: Forecast Models Corresponding to the Lowest Point MSFEs Reported in Table 3*

Panel A: Recursive Window Estimation

Forecast Horizon	Factor Spec. Mtd.	UR	PI	TB10Y	CPI	PPI	NPE	HS	IPX	M2	SNP	GDP
$h = 1$	SP1	PCA	FAAR	PCR	Ridge	PCR	PCR	FAAR	ARX	PCR	Mean	Mean
		ICA	ARX	FAAR	FAAR	FAAR	FAAR	Ridge	ARX	FAAR	Mean	Boost
		SPCA	FAAR	PCR	PCR	BMA1	BMA2	Mean	FAAR	FAAR	Mean	Boost
	SP1L	PCA	FAAR	PCR	Mean	PCR	Mean	Mean	ARX	BMA1	Mean	ARX
		ICA	ARX	Mean	Mean	ARX	Mean	Mean	ARX	Mean	Mean	ARX
		SPCA	ARX	Mean	CADL	ARX	Mean	Boost	ARX	Mean	Mean	ARX
	SP2	PCA	Boost	Mean	Mean	Boost	Mean	Mean	ARX	BMA1	BMA2	Mean
		ICA	ARX	Mean	Mean	ARX	Mean	Mean	ARX	ARX	EN	Boost
		SPCA	ARX	Mean	Mean	ARX	Mean	Mean	ARX	BMA1	Boost	Mean
	SP2L	PCA	Boost	Mean	Mean	Boost	Mean	Mean	ARX	BMA1	BMA2	Mean
		ICA	Boost	Mean	Mean	Boost	Mean	Mean	ARX	EN	Mean	Boost
		SPCA	Boost	Mean	Mean	ARX	Mean	Mean	ARX	ARX	Boost	Mean
$h = 3$	SP3	ARX	Mean	CADL	Mean	Mean	Mean	ARX	ARX	Mean	Boost	Mean
		SP4	ARX	Mean	Mean	ARX	Mean	Mean	ARX	BMA1	Mean	Mean
		PCA	PCR	PCR	CADL	FAAR	PCR	FAAR	Boost	Mean	LARS	Mean
	SP1	ICA	FAAR	ARX	PCR	FAAR	ARX	FAAR	LARS	Mean	AR	Mean
		SPCA	Mean	PCR	Mean	FAAR	Mean	Ridge	Mean	FAAR	Mean	NNG
		PCA	Mean	Mean	Mean	Mean	Mean	BMA1	Mean	Mean	NNG	Mean
	SP1L	ICA	Mean	ARX	CADL	Mean	ARX	Mean	LARS	ARX	NNG	Mean
		SPCA	Mean	ARX	Mean	Mean	ARX	BMA2	Mean	NNG	NNG	NNG
		PCA	Boost	Mean	EN	Boost	ARX	Boost	Boost	Mean	Mean	Mean
	SP2	ICA	Mean	ARX	LARS	Boost	ARX	Boost	Boost	Mean	Mean	Mean
		SPCA	Mean	ARX	CADL	Mean	ARX	Mean	Boost	Mean	Boost	LARS
		PCA	Boost	Mean	EN	Boost	ARX	Boost	Boost	Mean	Mean	Mean
$h = 12$	SP2L	ICA	Boost	ARX	CADL	Boost	ARX	Boost	Boost	Mean	Mean	Mean
		SPCA	Mean	ARX	BMA2	Mean	ARX	Mean	Boost	LARS	Mean	Mean
		PCA	Mean	Mean	Mean	BMA1	Mean	Boost	Boost	Mean	LARS	LARS
	SP3	ICA	Mean	Mean	CADL	Boost	Mean	EN	EN	Mean	LARS	Mean
		SPCA	Boost	Mean	CADL	Mean	Mean	EN	Boost	Mean	LARS	Mean
		PCA	Mean	Mean	Mean	BMA2	Mean	Boost	Boost	Mean	Mean	LARS
	SP4	ICA	Mean	Mean	Mean	Boost	Mean	Mean	Mean	Mean	AR	EN
		SPCA	Boost	Mean	CADL	Mean	Mean	Mean	Mean	Mean	AR	Mean
		PCA	Mean	Mean	Mean	BMA1	Mean	Boost	Boost	Mean	LARS	LARS

Panel B: Rolling Window Estimation

Forecast Horizon	Factor Spec. Mtd.	UR	PI	TB10Y	CPI	PPI	NPE	HS	IPX	M2	SNP	GDP	
$h = 1$	SP1	PCA ICA SPCA	FAAR ARX ARX	PCR AR AR	Mean Mean Mean	FAAR Mean ARX	Mean Mean LARS	FAAR Mean Mean	ARX ARX ARX	PCR ARX Mean	FAAR Mean Mean	LARS NNG AR	Mean Mean Mean
	SP1L	PCA ICA SPCA	Mean ARX ARX	PCR AR CADL	Mean Mean ARX	Mean Mean ARX	Mean Mean Mean	ARX ARX ARX	Mean Mean Mean	Mean Mean Mean	AR AR AR	Mean Mean LARS	
	SP2	PCA ICA SPCA	ARX ARX ARX	AR AR AR	Mean Mean Mean	LARS LARS LARS	Mean Mean Mean	ARX ARX ARX	Boost Boost Mean	Mean Mean Mean	EN AR AR	EN EN LARS	
	SP2L	PCA ICA SPCA	ARX ARX ARX	AR AR AR	Mean Mean Mean	EN EN Mean	Mean Mean Mean	ARX ARX ARX	BMA2 Boost Boost	Mean Mean Mean	LARS AR AR	LARS LARS LARS	
	SP3		ARX	AR	CADL	Boost	AR	Boost	ARX	Boost	LARS	AR	EN
	SP4		ARX	AR	Boost	BMA2	Mean	Mean	ARX	Mean	Boost	AR	Mean
	SP1	PCA ICA SPCA	Mean Mean Mean	PCR PCR BMA2	AR Mean BMA1	Mean Mean Mean	PCR Mean Mean	Boost Bagg Mean	Mean Mean Mean	FAAR Bagg Mean	LARS AR AR	Boost Mean Mean	
	SP1L	PCA ICA SPCA	Mean Mean Mean	Mean AR AR	LARS BMA2 BMA2	Mean BMA2 NNG	Mean Mean Mean	Boost Boost Mean	Mean Mean Mean	Mean Mean Mean	AR AR AR	Mean Mean LARS	
	SP2	PCA ICA SPCA	Mean Mean Boost	Mean BMA2 BMA1	NNG BMA2 BMA1	Mean Mean Mean	Mean Mean Mean	BMA2 Mean Mean	Boost Boost Mean	Mean Mean Mean	EN EN NNG	NNG NNG Mean	
	SP2L	PCA ICA SPCA	Boost Mean Mean	Mean BMA1 AR	BMA1 BMA2 Mean	Mean Mean Mean	Boost Boost Mean	BMA2 Boost Boost	Mean Mean Mean	Mean Mean Mean	NNG NNG NNG	Mean Mean Mean	
$h = 3$	SP3		Boost	Boost	AR	Boost	NNG	Boost	Boost	Boost	Boost	AR	Boost
	SP4		Mean	Mean	AR	Mean	Mean	Boost	Mean	Boost	Mean	AR	LARS
	SP1	PCA ICA SPCA	Mean Mean Mean	Mean CADL CADL	CADL Ridge BMA2	Mean Mean Mean	PCR FAAR Mean	FAAR Mean Mean	Mean Mean Mean	Mean Mean Mean	AR Bagg AR	AR Mean Mean	
	SP1L	PCA ICA SPCA	Mean Mean Mean	Mean NNG NNG	CADL CADL BMA2	Mean Mean Boost	Mean Mean Mean	Mean Mean Mean	Mean Mean LARS	Mean Mean LARS	AR AR AR	NNG Bagg LARS	
	SP2	PCA ICA SPCA	Mean Mean Mean	Mean CADL CADL	CADL Mean Mean	Mean Mean Mean	EN EN EN	Boost Boost Boost	Mean Mean Mean	Boost Boost Mean	NNG NNG LARS	Mean Mean Mean	
	SP2L	PCA ICA SPCA	Mean Mean Mean	Mean CADL CADL	CADL Mean Mean	Mean Mean LARS	Boost Boost Boost	Boost Boost Mean	Mean Mean Mean	Mean Mean Mean	BMA2 NNG NNG	Mean Mean Mean	
	SP3		Boost	Boost	CADL	EN	EN	Boost	Boost	Boost	Boost	AR	NNG
	SP4		Mean	Mean	CADL	Boost	Mean	Mean	Boost	Mean	Mean	NNG	EN
	SP1	PCA ICA SPCA	Mean Mean Mean	Mean CADL CADL	CADL Ridge BMA2	Mean Mean Mean	PCR FAAR Mean	FAAR Mean Mean	Mean Mean Mean	Mean Mean Mean	AR Bagg AR	AR Mean Mean	
	SP1L	PCA ICA SPCA	Mean Mean Mean	Mean NNG NNG	CADL CADL BMA2	Mean Mean Boost	Mean Mean Mean	Mean Mean Mean	Mean Mean LARS	Mean Mean LARS	AR AR AR	NNG Bagg LARS	
$h = 12$	SP2	PCA ICA SPCA	Mean Mean Mean	Mean CADL CADL	CADL Mean Mean	Mean Mean Mean	EN EN EN	Boost Boost Boost	Mean Mean Mean	Boost Boost Mean	NNG NNG LARS	Mean Mean Mean	
	SP2L	PCA ICA SPCA	Mean Mean Mean	Mean CADL CADL	CADL Mean Mean	Mean Mean LARS	Boost Boost Boost	Boost Boost Mean	Mean Mean Mean	Mean Mean Mean	BMA2 NNG NNG	Mean Mean Mean	
	SP3		Boost	Boost	CADL	EN	EN	Boost	Boost	Boost	Boost	AR	NNG
	SP4		Mean	Mean	CADL	Boost	Mean	Mean	Boost	Mean	Mean	NNG	EN

*Notes: See notes to Tables 1-3. In Panels A and B, MSFE “best” models, based on results reported in Table 3 are reported.

Table 5: Summary of Winning Methods and Models by Forecast Horizon

Forecast Horizon	UR	PI	TB10Y	CPI	PPI	NPE	HS	IPX	M2	SNP	GDP
$h = 1$	SP1	SP1	SP1	SP4	SP1	SP1	SP1	SP1L	SP1	SP2	
	Recur	Recur	Recur	Roll	Recur	Recur	Recur	Recur	Roll	Recur	Recur
	PCA	SPCA	SPCA	N/A	ICA	SPCA	SPCA	SPCA	PCA	SPCA	ICA
	FAAR	PCR	PCR	BMA2	FAAR	Mean	FAAR	FAAR	Mean	Boost	Boost
$h = 3$	SP1	SP1	SP1	SP4	SP1	SP1	SP3	SP2	SP1L	SP2L	SP2
	Roll	Recur	Recur	Roll	Recur	Recur	Roll	Recur	Roll	Roll	Roll
	PCA	PCA	ICA	N/A	PCA	SPCA	N/A	PCA	PCA	PCA	PCA
	Mean	PCR	PCR	Mean	PCR	Ridge	Boost	Mean	Mean	NNG	LARS
$h = 12$	SP1L	SP2L	SP1L	SP1	SP1	SP3	SP3	SP2	SP2	SP1L	
	Roll	Roll	Recur	Roll	Roll	Roll	Roll	Roll	Roll	Roll	Recur
	PCA	PCA	PCA	SPCA	PCA	N/A	N/A	PCA	SPCA	SPCA	ICA
	Mean	Mean	Boost	BMA2	PCR	Boost	Boost	Mean	Boost	LARS	Bagg

* Notes: See notes to Tables 1-4. This table contains details of the winning forecast model/method, for each forecast horizon. Entries correspond to the lowest bolded MSFE entries in Table 3 within each forecast horizon, across all specification types, for each variable. In summary, the “winning” (specification type, estimation windowing method, factor estimation method - when factors enter into the “best” model, and model - as given in Table 2) is summarized, for each forecast horizon and target variable.