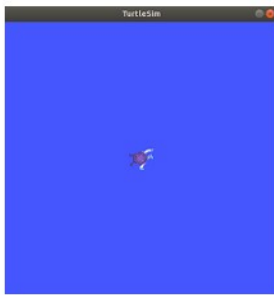


S#1 :: Publisher and Subscriber Nodes

Monday, July 5, 2021 3:22 PM



- Publishing

- Subscribing

Topics
Message Types

Available Nodes

Tele-Operational Keyboard Node

```
"ros2 run demo_nodes_py listener"
```

```
"ros2 run turtlesim turtlesim_node"
```

```
"ros2 run turtlesim turtle_teleop_key"
```

Statically publishing Nodes

```
"ros2 topic list"
```

- Selection of Topic
- Frequency
- Message

```
"ros2 topic pub -1 /topic message_type values"
```

Available Services

- Calling a Service

```
"ros2 service call /service service_type values"
```