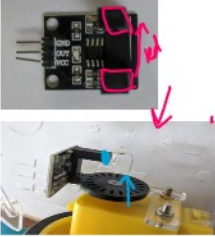


4 - Distance Traveling and Degree Turns

Monday, June 15, 2020 9:45 AM

Encoder Sensor

Hardware



Software

```
Interrupts  
Config  
→ E(1)
```

```
loop() {  
  delay(1);  
  print  
  read  
}
```

```
Counting() {  
  count++;  
}
```

tyre

2 40 100

Let's take a look how good it counts revolutions

Distance Calculations

Basic Geometry of CIRCLES

$$\text{Area} = 2\pi r$$

$$= 2 \times 3.14 \times 33.05 \text{ mm}$$

$$A = 207.5 \text{ mm}$$

Ex 100 cm

$$- 1 \text{ rev} \Rightarrow 20.7 \text{ cm}$$

$$\frac{100}{20.7} = 4.81 \text{ rev}$$

How physically does it look like

dia. VC

$$\frac{66.1}{2} = 33.05$$

Ticks: 49 ticks \rightarrow 1 rev.

$$235.6 \leftarrow 4.81 \text{ rev}$$

Degrees to ticks

$$A = 2\pi r$$

$$A = 2\pi \times 133.1 \text{ mm}$$

$$A = 83.8 \text{ cm}$$

$$360^\circ$$

$$- \frac{83.8 \text{ cm}}{20.7} = 4.04 \text{ rev}$$

49 \rightarrow 198 tick

What is jamming and rotating?

FORMULA: $\frac{\text{Degree rev}}{360} \times 198$

Sol

$$\frac{360}{360} \times 198 \rightarrow 198$$

$$\frac{90}{360} \times 198 \rightarrow \frac{198}{4} = 49.5$$

tick

Going Straight.

$$A = 2\pi r$$

$$= 2 \times 3.14 \times \left(\frac{66.1 \text{ mm}}{2}\right)$$

$$A = 20.7 \text{ cm}$$

Taking Turn

$$A = 2\pi r$$

$$= 2 \times 3.14 \times 133.1 \text{ mm}$$

$$A = 83.8 \text{ cm}$$

$$\frac{A}{20.7} = 4.04 \text{ revolutions}$$

$$4.04 \times 455$$

$$= 1840$$

Turn Travel Sequence

480T → 1840T

- Variables

- One rev = 480
- One rev distance = 20.7cm
- Bool = Moving

- Resetting

- Using While Loop

Efficiency

- Loop is empty
- No serial Printing in interrupts
- No delays in main workflow

Flow chart

