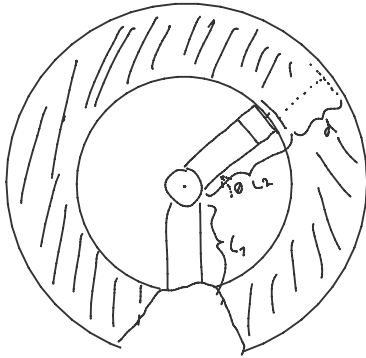
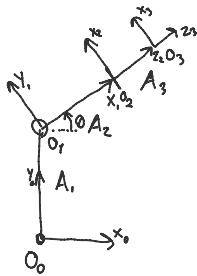


c)



b)



$$T_3^0 = A_1 A_2 A_3$$

$$A_1 = \begin{bmatrix} 1 & 0 & 0 & l_1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$d = l_1, \theta = 0$

$$A_2 = \begin{bmatrix} c_{\theta_2} & -s_{\theta_2} & 0 & l_2 c_{\theta_2} \\ s_{\theta_2} & c_{\theta_2} & 0 & l_2 s_{\theta_2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$d = l_2, \theta = \theta_2$

$$A_3 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & d_3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$d = d_3, \theta = 0$

$$A_1 A_2 = \begin{bmatrix} 1 & 0 & 0 & l_1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c & -s & 0 & l_2 c \\ s & c & 0 & l_2 s \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} c & -s & 0 & l_2 c + l_1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T_3^0 = A_1 A_2 A_3 = \begin{bmatrix} c & -s & 0 & l_2 c + l_1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & d_3 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} c & -s & 0 & l_2 c + l_1 + d_3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\hat{a)} \quad \frac{2\pi \text{ rad}}{1024 \text{ revs}} = 6.136 \cdot 10^{-3} \text{ rad/revs}$$

$$= \underline{\underline{0.0061 \text{ rad/revs}}}$$

$$b) \quad \begin{array}{c} \text{d} \\ \text{L}_2 \end{array} \quad \text{r} \cdot \Delta\theta = \underline{\underline{(L_2 + d) \Delta\theta}}$$


$$a) \quad R_3^2 = (R_2^3)^{-1} \quad R_2^1 = R_0^1 R_2^0 = (R_0^1)^{-1} R_2^0$$

$$\underline{R_3^0 = R_2^0 R_3^2 = R_2^0 (R_2^3)^{-1}}$$

$$b) \quad R = R_{\psi, \phi} R_{z, \theta} R_{\chi, \psi} R_{\alpha, \beta} R_{\gamma, \beta}$$

$$c) \quad R_2^0 = R_1^0 R_2^1 = R_{z, \frac{\pi}{6}} R_{x, \frac{\pi}{4}} = \begin{bmatrix} \cos \frac{\pi}{6} & -\sin \frac{\pi}{6} & 0 \\ \sin \frac{\pi}{6} & \cos \frac{\pi}{6} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \frac{\pi}{4} & -\sin \frac{\pi}{4} \\ 0 & \sin \frac{\pi}{4} & \cos \frac{\pi}{4} \end{bmatrix}$$

$$R_2^0 = \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 \\ \frac{1}{2} & \frac{\sqrt{3}}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ 0 & \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{bmatrix}$$

$$R_2^0 = \begin{pmatrix} \frac{\sqrt{3}}{2} & \frac{-1}{2} & 0 \\ \frac{1}{2} & \frac{\sqrt{3}}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{\sqrt{2}}{2} & \frac{-\sqrt{2}}{2} \\ 0 & \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{2} & \frac{-\sqrt{2}}{4} & \frac{\sqrt{2}}{4} \\ \frac{1}{2} & \frac{\sqrt{6}}{4} & \frac{-\sqrt{6}}{4} \\ 0 & \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix}$$

$$p_0 = R_2^0 p^2 =$$

$$\begin{pmatrix} \frac{3^{0,5}}{2} & \frac{-2^{0,5}}{4} & \frac{2^{0,5}}{4} \\ \frac{1}{2} & \frac{6^{0,5}}{4} & \frac{-6^{0,5}}{4} \\ 0 & \frac{2^{0,5}}{2} & \frac{2^{0,5}}{2} \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{2} & 0 & 0 \\ \frac{1}{2} & 0 & 0 \\ \sqrt{2} & 0 & 0 \end{pmatrix}$$