



Emne: IELET2106 Industriell instrumentering

Øving: Formeloversikt

Sist oppdatert

24.08.2023

Generelt	
<p>Måleomfang: Målevariabelomfang = $I_{\text{maks}} - I_{\text{min}}$ Målesignalomfang = $O_{\text{maks}} - O_{\text{min}}$</p> <p>Maksimal ulinearitet i % av målesignalomfanget: $N = \frac{\hat{N}}{O_{\text{maks}} - O_{\text{min}}} \cdot 100\%$</p> <p>Maksimal hysteres i % av målesignalomfanget: $H = \frac{\hat{H}}{O_{\text{maks}} - O_{\text{min}}} \cdot 100\%$</p> <p>Avvik i % av målesignalomfanget: $E = \frac{O_{\text{målt}} - O_{\text{ideell}}}{O_{\text{maks}} - O_{\text{min}}} \cdot 100\%$</p> <p>Måleomformermodell: $O(I) = (K + K_M \cdot I_M) \cdot I + K_I \cdot I_I + a + N(I)$</p> <p>Måleomformermodell parametere: $K = \frac{O_{\text{maks}} - O_{\text{min}}}{I_{\text{maks}} - I_{\text{min}}}$ $a = O(I_{\text{min}})$ $K_I = \frac{\Delta O(I_{\text{min}})}{\Delta I_I}$ $K_M = \frac{1}{I_{50\%}} \cdot \frac{\Delta O(I_{50\%})}{\Delta I_M}$ $K_M = \frac{1}{I_{50\%}} \cdot \left(\frac{\Delta O(I_{50\%})}{\Delta I_{M,I}} - K_I \right)$ $I_{50\%} = \frac{I_{\text{maks}} + I_{\text{min}}}{2}$</p> <p>Regresjonsanalyse (minste kvadraters metode): $q = \sum_{i=1}^n (y_i - y(x))^2$ <p>hvis $y(x) = a + b \cdot x$: $a \cdot n + b \cdot \sum_{i=1}^n x_i = \sum_{i=1}^n y_i$ $a \cdot \sum_{i=1}^n x_i + b \cdot \sum_{i=1}^n x_i^2 = \sum_{i=1}^n (x_i \cdot y_i)$</p></p>	<p>Middelverdi: $\bar{X} = \frac{1}{n} \cdot \sum_{i=1}^n X_i$</p> <p>Standardavvik: $S = \sqrt{\frac{1}{n-1} \cdot \sum_{i=1}^n (X_i - \bar{X})^2}$</p> <p>Standardavvik til middelerdien: $S_{\bar{X}} = \frac{S}{\sqrt{n}}$</p> <p>95% - konfidensintervall: $\bar{X} \pm 1,96 \cdot S_{\bar{X}}$</p> <p>GUM (guide to the expression of uncertainty in measurement): $\bar{X} \pm k \cdot S_{\bar{X}}$</p> <p>Normalfordelingsfunksjon: $f(x) = \frac{1}{\sqrt{2 \cdot \pi} \cdot \sigma} \cdot e^{-\frac{(x-\bar{X})^2}{2 \cdot \sigma^2}}$</p> <p>Usikkerhetsanalyse: $U = f(u_1, \dots, u_n)$ $\bar{U} \pm \Delta u = f(\bar{u}_1 \pm \Delta u_1, \dots, \bar{u}_n \pm \Delta u_n)$ $\bar{U} = f(\bar{u}_1, \dots, \bar{u}_n)$ $\Delta u = \sqrt{\sum_{i=1}^n \left(\frac{\partial f}{\partial u_i} \cdot \Delta u_i \right)^2}$ $\Delta u_r = \frac{\Delta u}{U} = \sqrt{\sum_{i=1}^n \left(\frac{\partial f}{\partial u_i} \cdot \frac{\Delta u_i}{U} \right)^2}$</p>

Elektronikk

Ohms lov:

$$V = R \cdot I$$

Aktiv effekt:

$$P = V \cdot I$$

Sinusformede signaler:

$$V(t) = \hat{A} \cdot \sin(\omega \cdot t) \quad \text{der} \quad \hat{A} = \sqrt{2} \cdot V_{\text{RMS}} \quad \text{og} \quad \omega = 2 \cdot \pi \cdot f$$

Serie- og parallellkobling av motstandere:

$$R_s = \sum_{i=1}^n R_n \quad \frac{1}{R_p} = \sum_{i=1}^n \frac{1}{R_n}$$

Kondensatorlikning:

$$i_C = C \cdot \frac{du_C}{dt}$$

Reaktans for kondensatorer:

$$X_C = \frac{1}{j \cdot \omega \cdot C} \quad \text{der} \quad \omega = 2 \cdot \pi \cdot f$$

Spolelikning:

$$u_L = L \cdot \frac{di_L}{dt}$$

Reaktans for spoler:

$$X_L = j \cdot \omega \cdot L \quad \text{der} \quad \omega = 2 \cdot \pi \cdot f$$

Impedans:

$$Z = \text{Resistans} \pm \text{Reaktans} = R \pm X$$

Målebro:

$$V_{ut} = V_{ut+} - V_{ut-} = V_{inn} \cdot \left(\frac{Z_3}{Z_1 + Z_3} - \frac{Z_4}{Z_2 + Z_4} \right) \quad (\text{ved ubelastet krets})$$

Thévenin-ekvivalentskjema:

$$V_{ut} = E_{Th} \quad (\text{ved ubelastet krets})$$

$$V_{ut} = \frac{R_L}{R_{Th} + R_L} \cdot E_{Th} \quad (\text{ved belastet krets})$$

$$R_{Th} = \left(\frac{R_1 \cdot R_3}{R_1 + R_3} + \frac{R_2 \cdot R_4}{R_2 + R_4} \right)$$

Opamp:

$$V_{ut} = A \cdot \left(V_{inn} + \frac{V_{CM}}{CMRR} \right) \quad \text{der} \quad CMRR = \frac{A}{A_{CM}}$$

Instrumenteringsforsterker:

$$V_{ut} = \left(1 + \frac{2 \cdot R}{R_g} \right) \cdot (V_{i+} - V_{i-})$$

Zenerbarriere:

$$E_{\text{total}} = \frac{1}{2} \cdot L \cdot I^2 + \frac{1}{2} \cdot C \cdot V_z^2 \quad \text{der} \quad I = \frac{V_z}{R_z}$$

Strekkklapper

$$R_0 = \frac{\delta \cdot L}{A_C}$$

$$\epsilon_L = \frac{\Delta L}{L}$$

$$\epsilon_D = \frac{\Delta D}{D} = -v_P \cdot \epsilon_L$$

$$\sigma_a = \frac{F_N}{A_C} = E_m \cdot \epsilon_L$$

$$\frac{\Delta R}{R_0} = (1 + 2 \cdot v_P) \cdot \epsilon_L + \frac{\Delta \delta}{\delta} = G_m \cdot \epsilon_L$$

Trykk- og nivåmåling

$$p_{\text{absolutt}} = p_{\text{atmosfære}} + p_{\text{relativt}}$$

$$\Delta p = \rho \cdot g \cdot \Delta h$$

$$\Delta p [\text{Pa}] = \rho_{\text{H}_2\text{O}} \cdot g \cdot \Delta p [\text{mVs}]$$

$$V = A_C \cdot h$$

$$m = \rho \cdot V$$

$$F = m \cdot g$$

$$F = A \cdot p$$

$$C = \frac{\epsilon \cdot A}{d} \quad \text{der} \quad \epsilon = \epsilon_0 \cdot \epsilon_r$$

$$L = \frac{\mu \cdot N^2 \cdot A}{x} \quad \text{der} \quad \mu = \mu_0 \cdot \mu_r$$

$$s = v \cdot t$$

$$h = \frac{c_{\text{lyd}} \cdot t}{2}$$

$$\lambda = c_{\text{lyd}} \cdot T \quad \text{der} \quad T = \frac{1}{f}$$

$$c_{\text{lyd}} = 331,5 \cdot \sqrt{1 + \frac{T}{273,15}}$$

$$t = \frac{T \cdot \Delta f}{f_2 - f_1}$$

$$c' = \sqrt{\frac{c}{\epsilon_r}}$$

$$C = \frac{2 \cdot \pi \cdot \epsilon_0 \cdot (H + h \cdot (\epsilon_r - 1))}{\ln(r_2/r_1)}$$

$$C = \frac{2 \cdot \pi \cdot \epsilon_0 \cdot h}{(1/\epsilon_{r1}) \cdot \ln(D_2/D_1) + (1/\epsilon_{r2}) \cdot \ln(D_3/D_2)}$$

$$G = \frac{1}{R} = \frac{\sigma \cdot A_C}{L} \quad \text{der} \quad \sigma = \frac{1}{\delta}$$

Strømningsmåling (mengdemåling)

$$\tau = \frac{F}{A} = \mu \cdot \frac{dv}{dx}$$

$$\vartheta = \frac{\mu}{\rho}$$

$$Re = \frac{\rho \cdot \bar{v} \cdot D}{\mu}$$

$$q = A \cdot \bar{v}$$

$$\dot{m} = \rho \cdot A \cdot \bar{v}$$

$$\frac{p}{\rho} + \frac{1}{2} \cdot \bar{v}^2 + g \cdot z = \text{konstant}$$

$$E = B \cdot D \cdot \bar{v}$$

$$S = 0,198 \cdot \left(1 - \frac{19,7}{Re}\right)$$

$$f = \frac{S \cdot \bar{v}}{d}$$

$$\Delta t = t_{BA} - t_{AB} \approx \frac{2 \cdot L \cdot \cos \theta \cdot \bar{v}}{c_{lyd}^2}$$

$$\bar{v} = \frac{L}{2 \cdot \cos \theta} \cdot \frac{t_{BA} - t_{AB}}{t_{BA} \cdot t_{AB}}$$

Temperaturmåling

$$t_{\circ C} = \frac{5}{9} \cdot (t_{\circ F} - 32)$$

$$t_K = t_{\circ C} + 273,15$$

$$t_R = t_{\circ F} + 459,6$$

$$R_t = R_0 \cdot (1 + A \cdot t + B \cdot t^2 + \dots)$$

$$R_t = R_0 \cdot (1 + A \cdot t + B \cdot t^2 + C \cdot (t - 100) \cdot t^3) \quad \text{der} \quad C = 0 \text{ når } t > 0^\circ C$$

$$R_T = R_0 \cdot e^{\beta \cdot \left(\frac{1}{T} - \frac{1}{T_0}\right)}$$

$$f_t = f_0 \cdot (1 + A \cdot t + B \cdot t^2 + C \cdot t^3)$$

$$u_A = \int_{t_2}^{t_1} \alpha_A(T) \cdot dT \approx \alpha_A \cdot (t_1 - t_2)$$

$$t = \sum_0^N a_n \cdot E^n$$

$$\mathcal{R}_T = \sigma \cdot T^4$$

$$\mathcal{R}_{T, \text{reell}} = \varepsilon_\lambda \cdot \mathcal{R}_T$$

$$\mathcal{R}_\lambda = \frac{c_1 \cdot \lambda^{-5}}{e^{\frac{c_2}{\lambda \cdot T}} - 1} \approx \frac{c_1 \cdot \lambda^{-5}}{e^{\frac{c_2}{\lambda \cdot T}}}$$

$$\mathcal{R}_{\lambda, \text{reell}} = \varepsilon_\lambda \cdot \mathcal{R}_\lambda$$

$$\lambda_{\text{maks}} \cdot T = 2,898 \cdot 10^{-3} \text{ m} \cdot K$$

$$\frac{T_t}{T_m} = \frac{1}{\varepsilon_\lambda^{1/4}}$$

$$\frac{1}{T_t} - \frac{1}{T_m} = \frac{\lambda \cdot \ln(\varepsilon_\lambda)}{c_2}$$

$$\frac{1}{T_t} - \frac{1}{T_m} = \frac{\ln(\varepsilon_{\lambda 1} / \varepsilon_{\lambda 2})}{c_2 \cdot \left(\frac{1}{\lambda_1} - \frac{1}{\lambda_2}\right)}$$

Posisjonsmåling

$$V_o = \frac{x}{x_{maks}} \cdot V_s$$

$$\Delta\varphi = \frac{360^\circ}{N}$$

$$\Delta\varphi_{4x} = \frac{360^\circ}{4 \cdot N}$$

$$f = \frac{k_T}{T}$$

$$k_m = 60 \cdot f$$

$$n = \frac{k_m}{k_o}$$

$$\Delta n = \frac{60}{k_o \cdot T}$$

$$\Delta\varphi = \frac{360^\circ}{2^N}$$

$$(g_3 g_2 g_1 g_0)_{\text{gray}} \rightarrow (b_3 b_2 b_1 b_0)_{\text{binær}} \quad \text{der} \quad b_3 = g_3, b_2 = g_2 \text{ OR } g_3, b_1 = g_1 \text{ OR } b_2, b_0 = g_0 \text{ OR } b_1$$

Akselerasjonsmåling

$$F = m \cdot a = m \cdot \ddot{x}_m$$

$$F = D \cdot \dot{x}_0$$

$$F = k \cdot x_0$$

$$x_0 = x_i - x_m$$

$$\omega_0 = 2 \cdot \pi \cdot f_0 = \sqrt{\frac{k}{m}}$$

$$\zeta = \frac{D}{2 \cdot \sqrt{k \cdot m}}$$

$$z = \sqrt{(1 - u^2)^2 + (2 \cdot \zeta \cdot u)^2} \quad \text{der} \quad u = \frac{\omega}{\omega_0}$$

$$\left| \frac{x_0}{x_i} \right| = \frac{u^2}{z}$$

$$\left| \frac{\omega_0^2 \cdot x_0}{a_0} \right| = \frac{1}{z} \quad \text{der} \quad a_0 = \omega^2 \cdot x_i$$

Konstanter

Permittivitet for vakuum: $\epsilon_0 = 8,854 \cdot 10^{-12} \text{ F/m}$

Permeabilitet for vakuum: $\mu_0 = 4\pi \cdot 10^{-7} \text{ H/m}$

Tyngdeakselerasjon: $g = 9,81 \text{ m/s}^2$

Lyshastighet: $c = 2,9979 \cdot 10^8 \text{ m/s}$

Stefan – Boltzmanns konstant: $\sigma = 5,6705 \cdot 10^{-8} \text{ W/(m}^2 \cdot \text{K}^4)$

Plancks konstant: $h = 6,6262 \cdot 10^{-34} \text{ J} \cdot \text{s}$

Boltzmanns konstant: $k = 1,3807 \cdot 10^{-23} \text{ J/K}$

$c_1 = 2 \cdot \pi \cdot h \cdot c^2 \approx 3,742 \cdot 10^{-16} \text{ W} \cdot \text{m}^2$

$c_2 = h \cdot c/k \approx 0,0144 \text{ m} \cdot \text{K}$