Calculus



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Multiple Integrals

Vector Calculus

Second-Order Differential Equations

Limits and Continuity



Limits

- Limit [%] | Thomas's Calculus^{14th} (2.2-2.4) [■]
- **Limit** $\lim_{x\to c}$: the value of a function (or sequence) approaches as the input (or index) approaches some value (informal definition).
 - Limits are used to define continuity ↓, derivatives ↓, and integrals ↓.

Limits of a Functions and Sequences

- **Limit of a function**: a fundament concept in calculus and analysis concerning the behavior of a function near a particular input *c*, i.e.,

$$\lim_{x \to c} f(x) = L$$

- Reads as "f of x tends to L as x tends to c"
- \circ \mathcal{E} , δ **Limit of function**: a formalized definition, wherein f(x) is defined on an open interval \mathcal{I} , except possibly at c itself, leading to above definition, if and only if:
 - For every real measure of closeness $\mathcal{E} > 0$, there exists a real corresponding $\delta > 0$, such that for all existing further approaches there exist a smaller \mathcal{E} , i.e.,

$$f: \mathbb{R} \to \mathbb{R}, \ c, L \in \mathbb{R} \Rightarrow \lim_{x \to c} f(x) = L$$

$$\updownarrow$$

$$\forall \varepsilon > 0 (\exists \delta > 0 : \forall x \in \mathcal{I} (0 < |x - c| < \delta \Rightarrow |f(x) - L| < \varepsilon))$$

- Functions do not have a limit when the function:
 - has a unit step, i.e., it "jumps" at a point;
 - is not bounded, i.e., it tends towards infinity;
 - or it oscillates, i.e., does not stay close to any single number.
- **Limit of a sequence**: the value that the terms of a sequence (x_n) "tends to" (and not to any other) as n approaches infinity (or some point), i.e.,

$$\lim_{n\to\infty} x_n = x$$

• \mathcal{E} Limit of sequence: for every measure of closeness \mathcal{E} , the sequence's x_n term eventually converge to the limit, i.e.,

$$\forall \varepsilon > 0 \ (\exists N \in \mathbb{N} \ (\forall n \in \mathbb{N} \ (n \geq N \Rightarrow |x_n - x| < \varepsilon)))$$

- Convergent: when a limit of a sequence exists.
- Divergent: a sequence that does not converge.

Properties of Limits

- S List of limits 1 Squeeze theorem 1
- Operations on a single known limit: if $\lim_{x\to c} f(x) = L$ then:
 - $\cdot \lim_{x \to c} [f(x) \pm \alpha] = L \pm \alpha$
 - $\lim_{x \to c} \alpha f(x) = \alpha L$
 - $\lim_{x \to c} f(x)^{-1} = L^{-1}, L \neq 0$
 - $\cdot \lim_{x \to c} f(x)^n = L^n, n \in \mathbb{N}$
 - $\lim_{x \to c} f(x)^{n-1} = L^{n-1}, n \in \mathbb{N}, \text{ if } n \in \mathbb{N}_e \Rightarrow L > 0$
- Operations on two known limits: if $\lim_{x\to c} f(x) = L_1$ and $\lim_{x\to c} g(x) = L_2$
 - $\cdot \lim_{x \to c} [f(x) \pm g(x)] = L_1 \pm L_2$
 - $\cdot \lim_{x \to c} [f(x)g(x)] = L_1 L_2$
 - $-\lim_{x \to c} f(x)g(x)^{-1} = L_1 L_2^{-1}$
- Squeeze theorem: used to confirm the limit of a difficult to compute function via comparison with two other functions whose limits are easily known or computed.
 - Let \mathcal{I} be an interval having the point c as a limit point.
 - Let g, f, and h, be functions defined on \mathcal{I} , except possibly at c itself.
 - Suppose that $\forall x \in \mathcal{I} \land x \neq c \Rightarrow g(x) \leq f(x) \leq h(x)$
 - And suppose that $\lim_{x \to c} g(x) = \lim_{x \to c} h(x) = L$
 - Then, $\lim_{x \to c} f(x) = L$
 - Essentially, the hard to compute limit of the "middle function" is found by finding two other easy functions that "squeeze" the middle function at that point.

One-Sided Limit

- One-Sided Limit %
- **One-sided limit**: one of two limits of f(x) as x approaches a specified point from either the left or from the right.
 - From the left: $\lim_{x \to c^{-}} = L$ From the right: $\lim_{x \to c^{+}} = L$
- o If the left and right limits exist and are equal, then

$$\lim_{x \to c} f(x) = L \Leftrightarrow \lim_{x \to c^{-}} f(x) = L \wedge \lim_{x \to c^{+}} f(x) = L$$

 Limits can still exist, even if the function is defined at a different point, as long as both one-sided limits approach the same value near the given input.

Continuity

- Continuity of functions is one of the core concepts of topology, however, there are definitions in terms of limits that prove useful; the following is only a primer.

Continuous Functions

- o Continuous function: a function that does not have any abrupt changes in value.
 - I.e., a function is continuous if and only if arbitrarily small changes in its output can be assured by restricting to sufficiently small changes in its input.
- **Discontinuous**: when a function is not continuous at a point in its domain, leading to a discontinuity; there are three classifications:
 - **Removable**: when both one-sided limits \uparrow exist, are finite, and are equal, but the actual value of f(x) is not equal to the limit and equal to some other value.
 - · The discontinuity can be removed to regain continuity.
 - · Sometimes the term *removable discontinuity* is mistaken for *removable singularity*, or a "whole" in the function (the point is not defined elsewhere).
 - **Jump**: when a single limit does not exist because the one-sided limits exist and are finite, but not equal.
 - · Points can be defined at the discontinuity, but the function can not be made continuous.
 - **Essential**: when at least one of two one-sided limits doesn't exist; can be the result of oscillating or unbounded functions.

Intermediate Value Theorem

- (2) Intermediate value theorem %
- **Intermediate value theorem**: if f is a continuous function whose domain contains the interval [a, b], then it takes on any given value between f(a) and f(b) at some point within the intervals.
- Relevant deductions, i.e., important corollaries:
 - **Bolzano's theorem**: if a continuous function has values of opposite sign inside an interval, then it has a root in that interval.
 - The image of a continuous function over an interval is itself an interval.
- \circ Thus, the image set $f(\mathcal{I})$ (which has no gaps) is also an interval, and it contains:

$$[\min(f(a), f(b)), \max(f(a), f(b))]$$

Limits Involving Infinity

- Limits involving infinity
 I Thomas's Calculus
 14th (2.6)
 ■
- Let $S \subseteq \mathbb{R}$, $x \in S$ and $f : S \mapsto \mathbb{R}$, then limits of these functions can approach arbitrarily large (\pm) values, providing a connection to asymptotes, and thus, analysis.

Limits at Infinity and Infinite Limits

 \circ Limits at infinity: limits defined as $f(x) \pm infinity$ are defined much like normal limits:

$$\lim_{x \to -\infty} f(x) = L \qquad \lim_{x \to \infty} f(x) = L$$

• Formally, for all measures of closeness \mathcal{E} there exists a point c such that $|f(x) - L| < \mathcal{E}$ whenever $x < c \lor x > c$ (respectively), i.e.,

$$\forall \varepsilon > 0 \left(\exists c \left(\forall x \left\{ <, > \right\} c : |f(x) - L| < \varepsilon \right) \right)$$

- o Basic rules for rational functions $f(x) = p(x)q(x)^{-1}$, where p and q are polynomials, the degree of each is denoted as $\{p,q\}^{\circ}$, and the leading coefficients are denoted as P, Q, then:
 - $p^{\circ} > q^{\circ} \Rightarrow L$ is $\{+, -\}$ depending on the sign of the leading coefficients.
 - $p^{\circ} = q^{\circ} \Rightarrow L = PQ^{-1}$
 - $p^{\circ} < q^{\circ} \Rightarrow L = 0$
- **Infinite limits**: the usual limit does not exist for a limit that grows out of bounds, however, limits with infinite values can be introduced:

$$\lim_{x \to a} f(x) = \infty, \quad \text{i.e.,} \quad \forall n > 0 \ (\exists \delta > 0 : f(x) > n \Leftrightarrow 0 < |x - a| < \delta)$$

Asymptotes of functions

- Asymptotes %
- **Asymptote**: a tangent line of a curve at a point at infinity; the distance between the curve and the line approaches zero as a coordinate tends to infinity.
- There are three kinds of asymptotes: *horizontal, vertical* and *oblique*; nature of the asymptote is dependent on a function's relation to infinity.
 - Horizontal asymptotes: a result of limits at infinity, i.e., when $x \to \pm \infty$
 - **Vertical asymptotes**: a result of infinite limits, i.e., when $x \to \pm a = \pm \infty$
 - **Oblique asymptotes**: when a linear asymptote is not parallel to either axis. f(x) is asymptotic to the straight line $y = mx + n(m \neq 0)$ if:

$$\lim_{x \to \pm \infty} [f(x) - (mx + n)] = 0$$

Derivatives



Derivative Fundamentals

- Operivative
 | Thomas's Calculus 14th (3.2)
 | Thomas's Calculus 14th (3.2)
 | Thomas 14th (3.2)
- **Derivative**: the measure of sensitivity to change of the function value with respect to some change in its in argument.
 - Often described as the instantaneous rate of change of a single variable function, since it is the slope a tangent line at a particular point, when it exists.
 - **Tangent line**: the line through a pair of points on a curve (secant line), except the points are infinitely close, thus, it's the rate of change at that "instant".

Definition, Notation

 \circ Formally, a derivative of the function f(x) with respect to the variable x is the function f' whose value at x is (provided the limit exists)

$$f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$

• Let z = x + h, then $h = z - x \land h \to 0 \Leftrightarrow z \to x$; this leads to an equivalent definition of the derivative (sometimes more convenient):

$$f'(x) = \lim_{z \to x} \frac{f(z) - f(x)}{z - x}$$

• **Notation**: there are many ways to denote the derivative; notations can be useful in various contexts, some common notations (for y = f(x)):

$$f'(x) = y' = \dot{y} = \frac{dy}{dx} = \frac{d}{dx}f(x) = D(f)(x) = D_x f(x)$$

- **Differentiation**: the process of finding a derivative; if f' exists at a particular point, then f is said to be differentiable at that point.
 - If f' exists at every point on an interval, then \overline{f} is differentiable on that interval.
 - f' is differentiable on a closed interval [a, b] if both one-sided limits $^{\uparrow}$ of the function $(h \rightarrow \{0^+:a, 0^-:b\})$ exist at the end points and is differentiable on the interior.
 - Not all continuous functions have a derivative, but functions with a derivative are continuous; functions with any of following do not have derivatives:
 - · corners (one-sided derivatives differ at a point),
 - · cusps (slope approaches alternating $\pm \infty$ on both sides of a point),
 - · discontinuities, or vertical tangent lines.

Differentiation Rules

- Oifferentiation rules
 I Thomas's Calculus 14th (3.3, 3.5, 3.7)
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- Derivatives can be found by computing its limit, but there are several methods that use
 of combinations of simpler functions to make computation easier.

Linear, Product, Chain, Inverse

• **Linear**: differentiation of linear functions consists of the constant and sum (& subtraction) rules, given the following

$$\forall (f \land g) \land \forall (a \land b \in \mathbb{R}) \Rightarrow \frac{d(af + bg)}{dx} = a\frac{df}{dx} + b\frac{dg}{dx}$$
Constant
Constant factor
Sum (Difference)
$$\frac{d}{dx}(c) = 0 \qquad (af)' = af' \qquad (f + f - g)' = f' + f - g'$$

• Product rule: used for the product of two functions; can be generalized \

$$\frac{d(fg)}{dx} = \frac{df}{dx}g + f\frac{dg}{dx}$$

• **Chain rule**: used for the composition of two functions f(g(x)); if z depends on y, which is dependent on x, then z depends on x as well, i.e.,

$$\frac{dz}{dx} = \frac{dz}{dy} \cdot \frac{dy}{dx}$$

The following is used to indicate which points the derivatives have to evaluated at:

$$\left. \frac{dz}{dx} \right|_{x} = \left. \frac{dz}{dy} \right|_{y(x)} \cdot \left. \frac{dy}{dx} \right|_{x}$$

- "Outside-Inside Rule": take the derivative of the "outside" function, leave "inside" alone, and multiply it be the derivative of the "inside."
- This method must be recursively "chained" when there are further compositions in the inside function, hence the name.
- **Inverse function rule**: can be applied if the function f has an inverse function g, i.e., a function that "undoes" the effect of f.

$$\{g(f(x)) = x \land f(g(y)) = y\} \Rightarrow \frac{dx}{dy} = \left(\frac{dy}{dx}\right)^{-1}$$

• Application of the chain rule on $f^{-1}(y) = x$ in terms of x clearly shows the result if the derivatives exist and are reciprocal,

$$\frac{dx}{dv} \cdot \frac{dy}{dx} = \frac{dx}{dx} = 1$$

Powers, Polynomials, Quotients, Reciprocals

Exponential, Logarithmic

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Trigonometric, Hyperbolic

Differentials and Related Concepts

Differentials

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Linearization

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Implicit Differentiation

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Related Rates

Applications of Derivatives



Stationary Point

Maxima and Minima

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Extreme Value Theorem

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Interior Extremum Theorem

Mean Value Theorem

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Symmetric Functions

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Area Between Curves

Applications of Definite Integrals



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Disc Integration

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Shell Integration

Arc Length

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Differential Arc Length

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Revolution about the y-Axis

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Numerical Integration

Trapezoidal Rule

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Simpson's Rule

Improper Integrals

Indirect Evaluation

Infinite Sequences and Series



First-Order Differential Equations



Parametric Equations and Polar Coordinates



Vectors and Vector-Valued Functions



Partial Derivatives



Multiple Integrals



Vector Calculus



Second-Order Differential Equations

