Calculus



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Infinite Sequences and Series

First-Order Differential Equations

Parametric Equations and Polar Coordinates

Vectors and Vector-Valued Functions

Partial Derivatives

Multiple Integrals

Vector Calculus

Second-Order Differential Equations

Limits and Continuity



Limits

- Limit $\lim_{x\to c}$: the value of a function (or sequence) as the input (or index) approaches some value (note: an informal definition).
 - Limits are used to define continuity[↓], derivatives[↓], and integrals[↓].

Limits of a Functions and Sequences

- Limit of a function [%] | Limit of a sequence [%] | Essence of Calculus, Ea
- **Limit of a function**: a fundamental concept in calculus and analysis concerning the behavior of a function near a particular input *c*, i.e.,

$$\lim_{x \to c} f(x) = L$$

- Reads as "f of x tends to L as x tends to c"
- \circ ϵ , δ Limit of a function: a formalized definition, wherein f(x) is defined on an open interval \mathcal{I} , except possibly at c itself, leading to the informal definition, if and only if

$$f: \mathbb{R} \to \mathbb{R}, c, L \in \mathbb{R} \Rightarrow \lim_{x \to c} f(x) = L$$

$$\updownarrow$$

$$\forall \varepsilon > 0 (\exists \delta > 0 : \forall x \in \mathcal{I} (0 < |x - c| < \delta \Rightarrow |f(x) - L| < \varepsilon))$$

- Functions do not have a limit when the function:
 - has a unit step, i.e., it "jumps" at a point;
 - is not bounded, i.e., it tends towards infinity;
 - or it oscillate, i.e., it does not stay close to any single number.
- **Limit of a sequence**: the value that the terms of a sequence $(x_n)_{n\in\mathbb{N}}$ "tends to" (and not to any other) as n approaches infinity (or some other point), i.e.,

$$\lim_{n\to\infty} x_n = x$$

• \mathcal{E} Limit of a sequence: for every measure of closeness \mathcal{E} , the sequence's x_n term eventually converges to the limit, i.e.,

$$\forall \varepsilon > 0 \ (\exists N \in \mathbb{N} \ (\forall n \in \mathbb{N} \ (n \geq N \Rightarrow |x_n - x| < \varepsilon)))$$

- Convergent: when a limit of a sequence exists.
- Divergent: a sequence that does not converge.

Properties of Limits

- S List of limits 1 Squeeze theorem 1
- Operations on a single known limit: if $\lim_{x\to c} f(x) = L$, then:

$$\cdot \lim_{x \to c} [f(x) \pm \alpha] = L \pm \alpha$$

$$\cdot \lim_{x \to c} \alpha f(x) = \alpha L$$

$$\lim_{x \to c} f(x)^{-1} = L^{-1}, L \neq 0$$

$$\cdot \lim_{x \to c} f(x)^n = L^n, n \in \mathbb{N}$$

• Operations on two known limits: if $\lim_{x\to c}$ and $\lim_{x\to c} g(x) = L_2$, then:

$$\cdot \lim_{x \to c} [f(x) \pm g(x)] = L_1 \pm L_2$$

$$\cdot \lim_{x \to c} [f(x)g(x)] = L_1 L_2$$

- **Squeeze theorem**: used to confirm the limit of a difficult to compute function via comparison with two other functions whose limits are easily known or computed.
 - Let \mathcal{I} be an interval having the point c as a limit point.
 - Let g, f, and h be functions defined on \mathcal{I} , except possibly at c itself.

• Suppose that
$$\forall x \in \mathcal{I} \land x \neq \Rightarrow g(x) \leq f(x) \leq h(x)$$

• and
$$\lim_{x \to c} g(x) = \lim_{x \to c} h(x) = L$$

• then,
$$\lim_{x \to c} f(x) = L$$

 Essentially, the hard to compute limit of the "middle function" can be found by finding the limit of two other "easier" functions that that "squeeze" the middle function at a point of interest.

One-Sided Limit

- One-Sided Limit %
- **One-sided limit**: one of two limits of f(x) as x approaches a specified point from either the left or from the right right.

• From the left:
$$\lim_{x\to c^-} = L$$

• From the right:
$$\lim_{x\to c^+} = L$$

o If the left and right limits exist and are equal, then

$$\lim_{x \to c} f(x) = L \Leftrightarrow \lim_{x \to c^{-}} f(x) = L \wedge \lim_{x \to c^{+}} f(x) = L$$

 Limits can still exist, even if the function is defined at a different point, as long as both one-sided limits approach the same value near the given input.

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Continuity

- Thomas (2.5)
 ■
- Continuity of functions is one of the core concepts of topology, however, there are definitions in terms of limits that prove useful; the following is only a primer.

Continuous Functions

- Continuous function Discontinuities
- Continuous function: a function that does not have any abrupt changes in value.
 - I.e., a function is continuous if and only if arbitrarily small changes in its output can be assured by restricting to sufficiently small changes in its input.
- **Discontinuous**: when a function is not continuous at a point in its domain, leading to a discontinuity; there are three classifications:
 - **Removable**: when both one-sided limits \uparrow exist, are finite, and are equal, but the actual value of f(x) is not equal to the limit and instead equal to some other value.
 - · The discontinuity can be removed to regain continuity.
 - · Sometimes the term *removable discontinuity* is mistaken for a *removable singularity*, or a "whole" in the function (the point is not defined elsewhere).
 - **Jump**: when a single limit does not exist because the one-sided limits exist and are finite, but not equal.
 - · Points can be defined at the discontinuity, but the function can not be made continuous.
 - **Essential**: when at least one of the two one-sided limits do not exist; can be the result of oscillating or unbounded functions.

Intermediate Value Theorem

- Intermediate value theorem %
- **Intermediate value theorem**: if f is a continuous function whose domain contains the interval [a, b], then it takes on any given value between f(a) and f(b) at some point within the intervals.
- Relevant deductions, i.e., important corollaries:
 - **Bolzano's theorem**: if a continuous function has values of opposite sign inside an interval, then it has a root in that interval.
 - The image of a continuous function over an interval is itself an interval.
- \circ Thus, the image set $f(\mathcal{I})$ (which has no gaps) is also an interval, and it contains:

$$[\min(f(a), f(b)), \max(f(a), f(b))]$$

Limits Involving Infinity

- Thomas (2.6)
 ■
- Let $S \subset \mathbb{R}$, $x \in S$ and $f : S \mapsto \mathbb{R}$, then limits of these functions can approach arbitrarily large (\pm) values, providing a connection to asymptotes, and thus, analysis.

Limits at Infinity and Infinite Limits

- Limits involving infinity %
- **Limits at infinity**: limits defined as $f(x)\pm$ infinity are defined much like normal limits:

$$\lim_{x \to -\infty} f(x) = L \qquad \lim_{x \to \infty} f(x) = L$$

• Formally, for all measures of closeness \mathcal{E} there exists a point c such that $|f(x) - L| < \mathcal{E}$ whenever $x < c \lor x > c$ (respectively), i.e.,

$$\forall \varepsilon > 0 (\exists c (\forall x \{ < \lor > \}c : |f(x) - L| < \varepsilon))$$

- Basic rules for rational functions $f(x) = p(x)q(x)^{-1}$, where p and q are polynomials, where the degree of each is denoted as $\{p \lor q\}^{\circ}$, and where the leading coefficients are denoted as P, Q, then:
 - $p^{\circ} > q^{\circ} \Rightarrow \pm L$, depending on the sign of the leading coefficient.
 - $p^{\circ} = q^{\circ} \Rightarrow L = PQ^{-1}$
 - $p^{\circ} < q^{\circ} \Rightarrow L = 0$
- **Infinite limits**: the usual limit does not exist for a limit that grows out of bounds, however, limits with infinite values can be introduced:

$$\lim_{x \to c} f(x) = \infty$$
, i.e., $\forall n > 0 \ (\exists \delta > 0 : f(x) > n \Leftrightarrow 0 < |x - c| < \delta)$

Asymptotes of functions

- Asymptotes %
- **Asymptote**: a tangent line of a curve at a point at infinity; the distance between the curve and the line approaches zero as a coordinate tends to infinity.
- There are three kinds of asymptotes: *horizontal, vertical* and *oblique*; the nature of the asymptote is dependent on a function's relation to infinity.
 - Horizontal asymptote: a result of limits at infinity, i.e., when $x \to \pm \infty$.
 - Vertical asymptote: a result of infinite limits, i.e., when $x \to \pm c = \pm \infty$
 - Oblique asymptote: when a linear asymptote is not parallel to either axis; f(x) is asymptotic to the straight line $y = mx + n \ (m \neq 0)$ if:

$$\lim_{x \to \pm \infty} [f(x) - (mx + n)] = 0$$

Derivatives



Derivative Fundamentals

- O Derivative \(\) | Thomas (3.2, 3.4)
- **Derivative**: the measure of sensitivity to change of the function value with respect to some change in its in argument.
 - Often descried as the instantaneous rate of change of a single variable function, since it is the slope of a tangent line at a particular point, when it exists.
 - **Tangent line**: the line through a pair of points on a curve (secant line), except the points are infinitely close, hence, it is the rate of change at that "instant".

Derivative Notation

• Formally, a derivative of the function f(x), with respect to the variable x, is the function f' whose value at x is (provided the limit exists):

$$f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$

• Let z=x+h, then $h=z-x\wedge h\to 0\Leftrightarrow z\to x$; this leads to an equivalent definition of the derivative (sometimes more convenient):

$$f'(x) = \lim_{z \to x} \frac{f(z) - f(x)}{z - x}$$

• **Notation**: there are many ways to denote the derivative; different notation can be useful in various contexts, some common notations (for y = f(x)):

$$f'(x) = y' = \dot{y} = \frac{dy}{dx} = \frac{d}{dx}f(x) = D(f)(x) = D_x f(x)$$

- **Differentiation**: the process of finding a derivative; if f' exists at a particular point, then f is said to be differentiable at that point.
 - If f' exists at every point on an interval, then f is differentiable on that interval.
 - f' is differentiable on a closed interval [a, b] if both one-sided limits \uparrow of the function $(h \rightarrow \{0^+:a, 0^-:b\})$ exist at the end points, and it is differentiable on the interior.
 - Not all continuous functions have a derivative, but functions with a derivative are continuous; functions with any of the following do not have derivatives:
 - · corners (one-sided derivatives differ at a point),
 - · cusps (slope approaches alternating $\pm \infty$ on both sides of a point),
 - · discontinuities, or vertical tangent lines.

Differentiation Rules

- Opinion Properties Differentiation rules Dif
- Derivatives can be found by computing the limit, but there are several methods that use combinations of simpler functions to make computation easier.

Linear, Product, Chain, Inverse

- Product % | Chain % | Inverse %
- **Linear**: differentiation of linear functions consists of the constant and sum rules, given the following:

$$\forall (f \land g) \land \forall (a \land b \in \mathbb{R}) \Rightarrow \frac{d(af + bg)}{dx} = a\frac{df}{dx} + b\frac{dg}{dx}$$

Constant $\frac{d}{dx}(c) = 0$ Constant factor (af)' = af'

Sum / Difference

$$(f+g)'=f'+g'$$

• **Product rule**: used for the product of two functions; can be generalized \(\psi

$$\frac{d(fg)}{dx} = g\frac{df}{dx} + f\frac{dg}{dx}$$

• Chain rule: used for the composition of two functions f(g(x)); if z depends on y, which is dependent on x, then z depends on x as well, i.e.,

$$\frac{dz}{dx} = \frac{dz}{dy} \cdot \frac{dy}{dx}$$

• The following is used to indicate points of evaluation:

$$\left. \frac{dz}{dx} \right|_{x} = \left. \frac{dz}{dy} \right|_{y(x)} \cdot \left. \frac{dy}{dx} \right|_{x}$$

- Outside-Inside rule: take the derivative of the "outside" function, leave the "inside" alone, and multiply it by the derivative of the "inside."
- · This method must be recursively "chained" when there are further compositions in the inside function, hence the name.
- Inverse function rule: can be applied if the function f has an inverse function g, i.e., "undoes" the effect of f.

$$\{g(f(x)) = x \land f(g(y)) = y\} \Rightarrow \frac{dx}{dy} = \left(\frac{dy}{dx}\right)^{-1}$$

• Application of the chain rule on $f^{-1}(y) = x$ in terms of x clearly shows the result, if the derivatives exist and are reciprocal,

$$\frac{dx}{dy} \cdot \frac{dy}{dx} = \frac{dx}{dx} = 1$$

Power, Polynomial, Reciprocal, Quotient

- Power % | Reciprocal % | Quotient %
- **Power rule**: used to differentiate functions in the form of $f(x) = x^r$; can be applied to polynomials since differentiation is linear.
 - Let $f: \mathbb{R} \mapsto \mathbb{R}$ be a function satisfying

$$f(x) = x^r$$
, $\forall x (r \in \mathbb{R}) \Rightarrow \frac{d}{dx} = rx^{r-1}$

- **Reciprocal rule**: yields the derivative of the reciprocal (multiplicative inverse) of a function f in terms of the derivative of f.
 - · Can be used to show that the power rule holds for negative exponents.
 - The product and reciprocal rules can be used to deduce the quotient rule.
 - Let f be differentiable at x and $f(x) \neq 0$, then $g(x) = f(x)^{-1}$ is also differentiable and

$$\frac{d(f^{-1})}{dx} = -f^{-2}\frac{df}{dx}$$
 i.e., $g' = -\frac{f'}{f^2}$

- **Quotient rule**: used to find the derivative of a function that is a ratio of two differentiable functions.
 - Let f and g be differentiable and $g(x) \neq 0$, then

$$\left(\frac{f}{g}\right)' = \frac{f'g - fg'}{g^2}$$

Trigonometric Differentiation

- Trigonometric functions
- All derivatives of circular trigonometric functions can be found from those of sin(x) and cos(x) by means of the quotient rule.

$$\sin(x) \rightarrow \cos(x) \qquad \arcsin(x) \rightarrow \left(\sqrt{1-x^2}\right)^{-1}$$

$$\cos(x) \rightarrow -\sin(x) \qquad \arccos(x) \rightarrow -\left(\sqrt{1-x^2}\right)^{-1}$$

$$\tan(x) \rightarrow \sec^2(x) \qquad \arctan(x) \rightarrow \left(x^2+1\right)^{-1}$$

$$\cot(x) \rightarrow -\csc^2(x) \qquad \arccos(x) \rightarrow -\left(x^2+1\right)^{-1}$$

$$\sec(x) \rightarrow \sec(x) \tan(x) \qquad \arccos(x) \rightarrow \left(|x|\sqrt{x^2-1}\right)^{-1}$$

$$\csc(x) \rightarrow -\csc(x) \cot(x) \qquad \arccos(x) \rightarrow -\left(|x|\sqrt{x^2-1}\right)^{-1}$$

 \circ Inverse trigonometric functions are found using implicit differentiation $^{\downarrow}$.

Differentiation Concepts

Thomas (3.7, 3.8)

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Implicit Differentiation

Implicit differentiation %

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Logarithmic Differentiation

Logarithmic differentiation %

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Higher Order Derivatives

Second derivative %

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Related Rates

Related rates %

Applications of Derivatives



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Maxima and Minima

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Interior Extremum Theorem

Mean Value Theorem

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The Integral of a Rate

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Simpson's Rule

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Indirect Evaluation

Infinite Sequences and Series



First-Order Differential Equations



Parametric Equations and Polar Coordinates



Vectors and Vector-Valued Functions



Partial Derivatives



Multiple Integrals



Vector Calculus



Second-Order Differential Equations

