Calculus



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Infinite Sequences and Series

First-Order Differential Equations

Parametric Equations and Polar Coordinates

Vectors and Vector-Valued Functions

Partial Derivatives

Multiple Integrals

Vector Calculus

Second-Order Differential Equations

Limits and Continuity



Limits

- Limit [%] | Thomas (2.2-2.4) [■]
- **Limit** $\lim_{x\to c}$: the value of a function (or sequence) as the input (or index) approaches some value (note: an informal definition).
 - Limits are used to define continuity[↓], derivatives[↓], and integrals[↓].

Limits of a Functions and Sequences

- **Limit of a function**: a fundamental concept in calculus and analysis concerning the behavior of a function near a particular input *c*, i.e.,

$$\lim_{x \to c} f(x) = L$$

- Reads as "f of x tends to L as x tends to c"
- \circ ϵ , δ Limit of a function: a formalized definition, wherein f(x) is defined on an open interval \mathcal{I} , except possibly at c itself, leading to the informal definition, if and only if

$$f: \mathbb{R} \to \mathbb{R}, c, L \in \mathbb{R} \Rightarrow \lim_{x \to c} f(x) = L$$

$$\updownarrow$$

$$\forall \varepsilon > 0 (\exists \delta > 0 : \forall x \in \mathcal{I} (0 < |x - c| < \delta \Rightarrow |f(x) - L| < \varepsilon))$$

- Functions do not have a limit when the function:
 - has a unit step, i.e., it "jumps" at a point;
 - is not bounded, i.e., it tends towards infinity;
 - or it oscillate, i.e., it does not stay close to any single number.
- **Limit of a sequence**: the value that the terms of a sequence $(x_n)_{n\in\mathbb{N}}$ "tends to" (and not to any other) as n approaches infinity (or some other point), i.e.,

$$\lim_{n\to\infty} x_n = x$$

• \mathcal{E} Limit of a sequence: for every measure of closeness \mathcal{E} , the sequence's x_n term eventually converges to the limit, i.e.,

$$\forall \varepsilon > 0 \ (\exists N \in \mathbb{N} \ (\forall n \in \mathbb{N} \ (n \geq N \Rightarrow |x_n - x| < \varepsilon)))$$

- · Convergent: when a limit of a sequence exists.
- Divergent: a sequence that does not converge.

Properties of Limits

- S List of limits | Squeeze theorem |
- Operations on a single known limit: if $\lim_{x\to c} f(x) = L$, then:

$$\cdot \lim_{x \to c} [f(x) \pm \alpha] = L \pm \alpha$$

$$\cdot \lim_{x \to c} \alpha f(x) = \alpha L$$

$$\lim_{x \to c} f(x)^{-1} = L^{-1}, L \neq 0$$

$$\cdot \lim_{x \to c} f(x)^n = L^n, n \in \mathbb{N}$$

• Operations on two known limits: if $\lim_{x\to c}$ and $\lim_{x\to c} g(x) = L_2$, then:

$$\cdot \lim_{x \to c} [f(x) \pm g(x)] = L_1 \pm L_2$$

$$\cdot \lim_{x \to c} [f(x)g(x)] = L_1 L_2$$

- **Squeeze theorem**: used to confirm the limit of a difficult to compute function via comparison with two other functions whose limits are easily known or computed.
 - Let \mathcal{I} be an interval having the point c as a limit point.
 - Let g, f, and h be functions defined on \mathcal{I} , except possibly at c itself.

• Suppose that
$$\forall x \in \mathcal{I} \land x \neq \Rightarrow g(x) \leq f(x) \leq h(x)$$

• and
$$\lim_{x \to c} g(x) = \lim_{x \to c} h(x) = L$$

• then,
$$\lim_{x \to c} f(x) = L$$

 Essentially, the hard to compute limit of the "middle function" can be found by finding the limit of two other "easier" functions that that "squeeze" the middle function at a point of interest.

One-Sided Limit

- One-Sided Limit %
- **One-sided limit**: one of two limits of f(x) as x approaches a specified point from either the left or from the right right.

• From the left:
$$\lim_{x\to c^-} = L$$

• From the right:
$$\lim_{x\to c^+} = L$$

o If the left and right limits exist and are equal, then

$$\lim_{x \to c} f(x) = L \Leftrightarrow \lim_{x \to c^{-}} f(x) = L \wedge \lim_{x \to c^{+}} f(x) = L$$

 Limits can still exist, even if the function is defined at a different point, as long as both one-sided limits approach the same value near the given input.

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Continuity

Continuous Functions

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Intermediate Value Theorem

Limits Involving Infinity

Limits at Infinity and Infinite Limits

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Asymptotes of functions

Derivatives



Derivative Fundamentals

Derivative Notation

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Differentiation Rules

Linear, Product, Chain, Inverse

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Powers, Polynomials, Quotients, Reciprocals

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Exponential, Logarithmic

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Trigonometric, Hyperbolic

Differentials and Related Concepts

Differentials

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Linearization

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Implicit Differentiation

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Related Rates

Applications of Derivatives



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Maxima and Minima

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Interior Extremum Theorem

Mean Value Theorem

Rolle's Theorem

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Corollaries of the Mean Value Theorem

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Second-Derivative Test

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Concavity

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Taylor's Theorem

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General Leibniz Rule

Integrals



Integral Fundamentals

Terminology and Notation

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Primer: Formal Definitions

Definite Integrals

Riemann Integral

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Integrability

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Properties of Definite Integrals

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Fundamental Theorem, Part 1

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Fundamental Theorem, Part 2

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The Integral of a Rate

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Total Area

Integration By Substitution

Indefinite Integrals

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Definite Integrals

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Symmetric Functions

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Area Between Curves

Applications of Definite Integrals



Solid of Revolution

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Arc Length

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Transcendental Functions



Inverse Functions

One-to-One Functions

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Derivative Rule for Inverses

Logarithmic Functions

Natural Logarithm

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Properties of Logarithms

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Trigonometric Integrals

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Logarithmic Differentiation

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Euler's Number

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Natural Exponential Function

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Laws of Exponents

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General Exponential Function

Exponential Change

• Separable Differential Equations

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Examples of Exponential Change

Indeterminate Forms

Indeterminate Form 0/0

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L'Hôpital's Rule

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Infinite Indeterminate Forms

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Indeterminate Powers

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Principal Trigonometric Values

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Inverse Trigonometric Tables

Hyperbolic Functions

Hyperbolic Function Tables

Techniques of Integration



Integration by Parts

Definite Integrals by Parts

Trigonometric Integral Methods

Trigonometric Products and Powers

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Trigonometric Square Roots

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Trigonometric Substitutions

Partial Fraction Decomposition

Partial Fraction Principles

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General Statement

Numerical Integration

Trapezoidal Rule

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Simpson's Rule

Improper Integrals

Indirect Evaluation

Infinite Sequences and Series



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