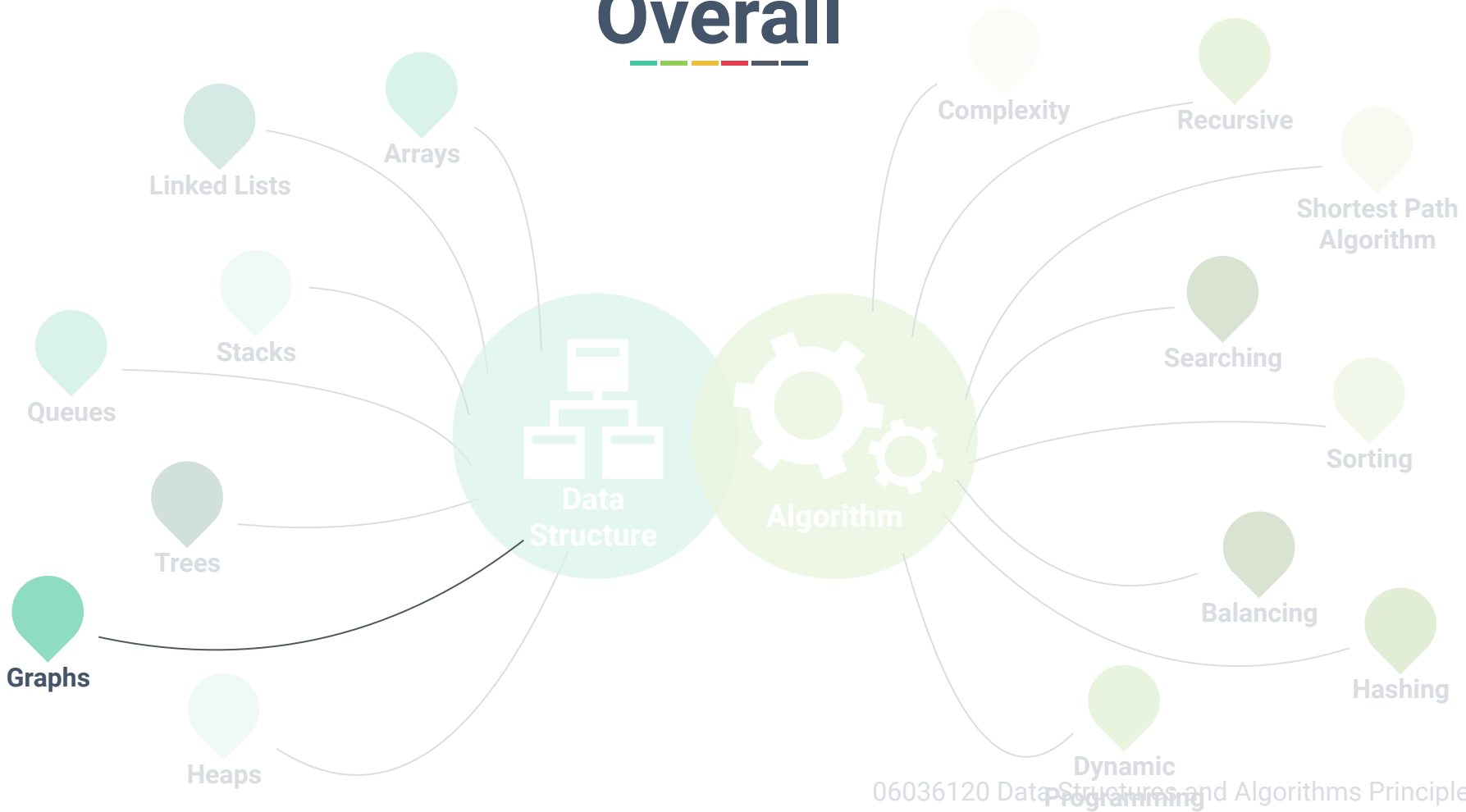


Chapter 11: Graph Algorithms



Dr. Sirasit Lochanachit

Overall



Outline



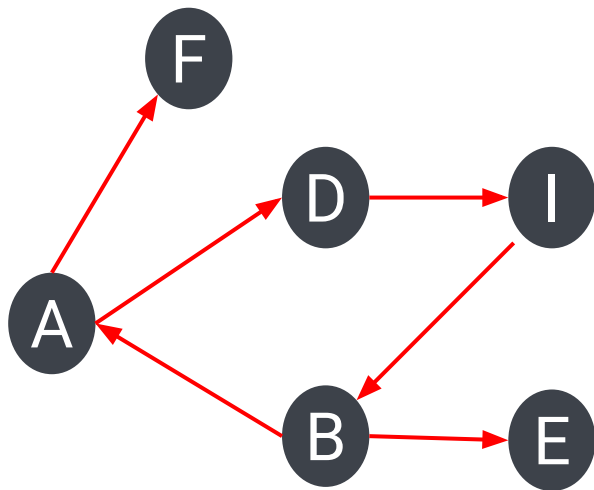
Graphs

- Definition, elements and types
- Graph Representation

Graph Algorithms

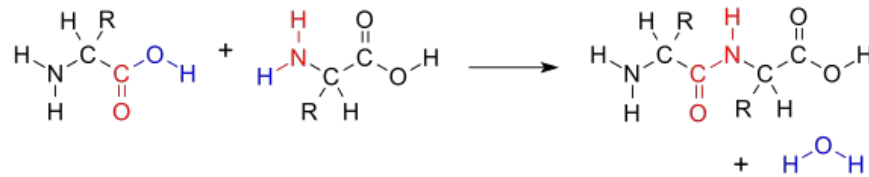
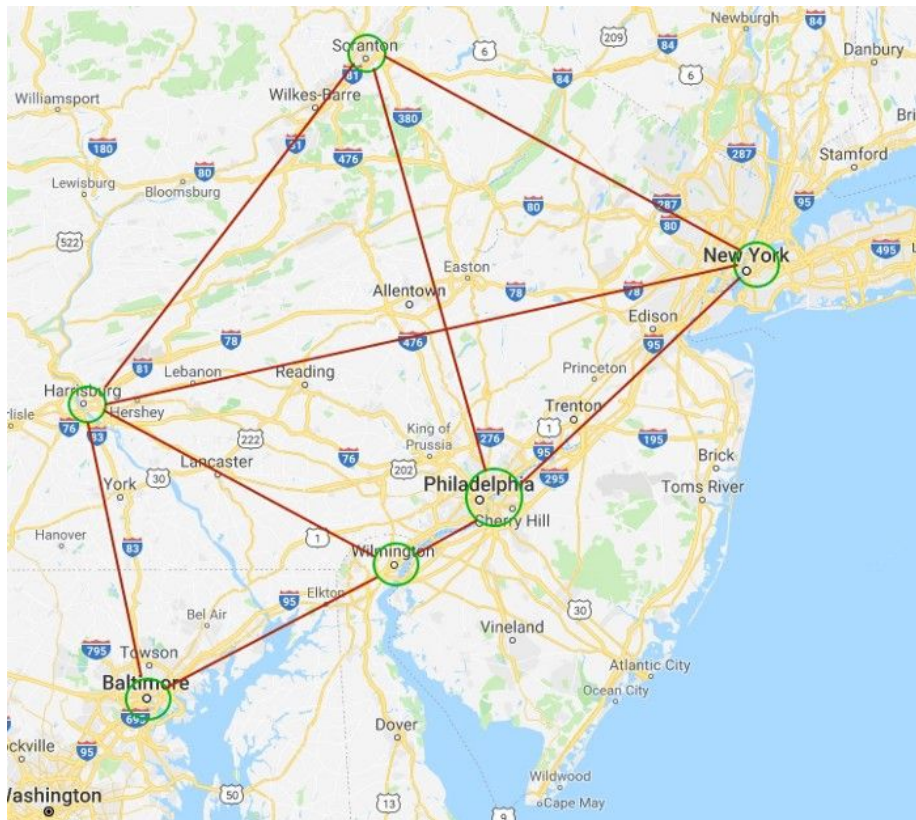
- Traversal
 - Depth-first
 - Breadth-first
- Shortest Path

What is a Graph?

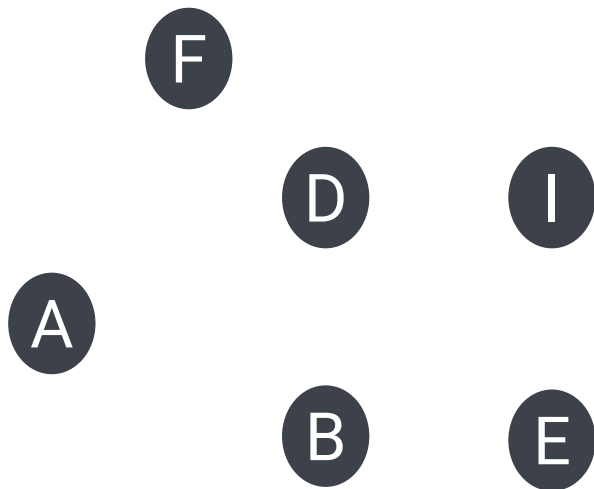


- A **graph** is a set of objects, called vertices or **nodes**, where the actual data is stored and a collection of connections between them, called **edges** or arcs^[1].
- A graph can be used to represent relationships between pairs of objects.

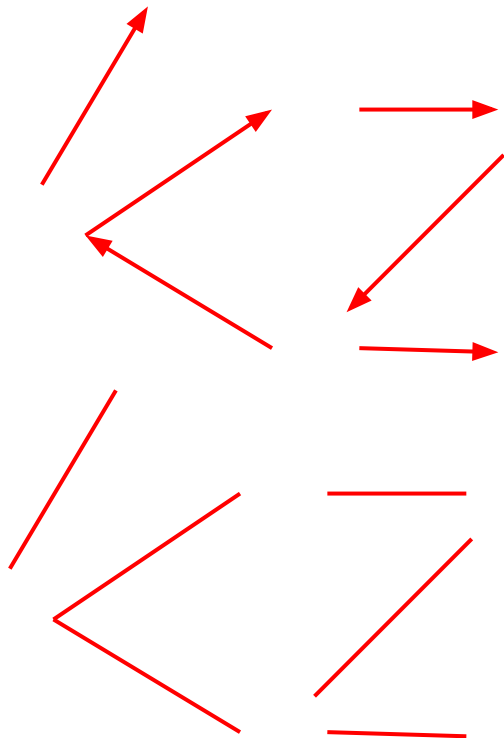
Graphs



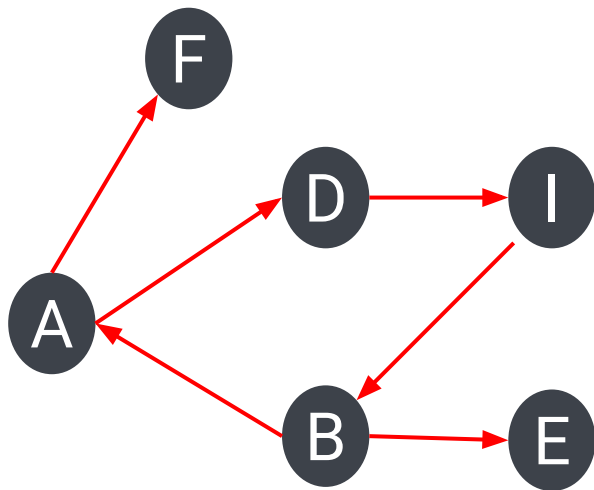
The Basic Elements of Graph



The Basic Elements of Graph



The Basic Elements of Graph

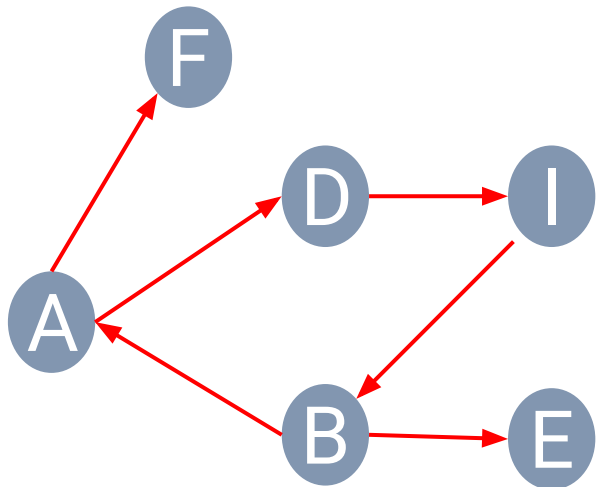


$V = \{A, B, C, D, E, F, I\}$

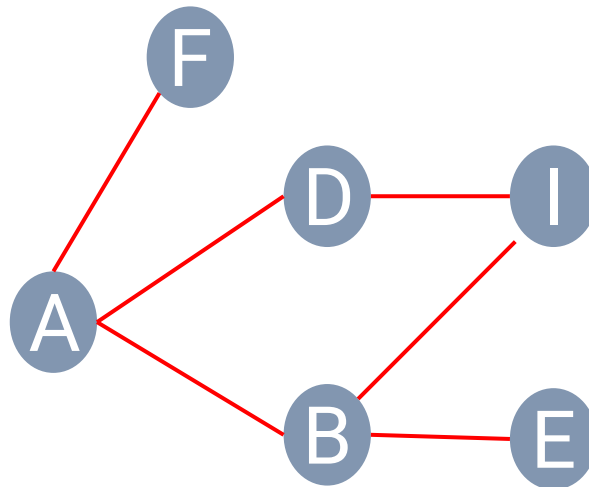
$E = \{(A, F), (A, D), (B, A), (D, I), (I, B), (B, E)\}$

- Formally, a graph G is a set V of vertices and a collection E of pairs of vertices, called edges^[1].

Graph Types



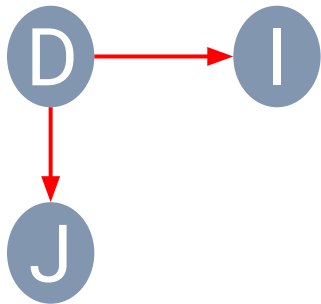
Directed



Undirected

- An edge (u, v) is directed from u to v if the pair (u, v) is ordered.
- An edge (u, v) is undirected if the pair (u, v) is not ordered.

Graph Terminology

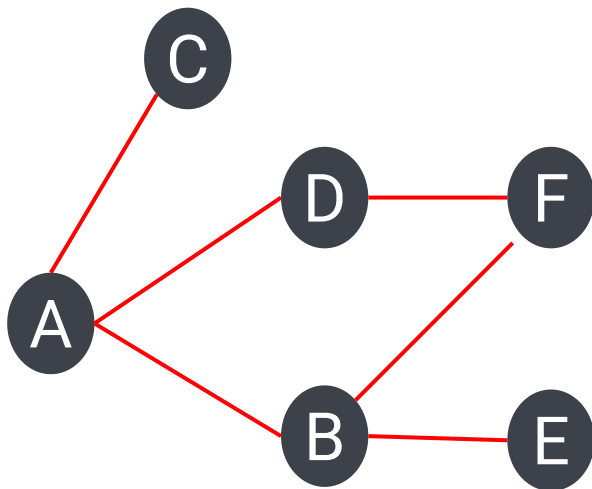


$$V = \{D, I, J\}$$

$$E = \{(D, I), (D, J)\}$$

- **Endpoints:** Two nodes (u, v) that are joined by an edge.
 - These two nodes are **adjacent**.
- **Origin:** First endpoint (u) on a directed edge.
- **Destination:** Second endpoint (v) on a directed edge.

Graph Representation

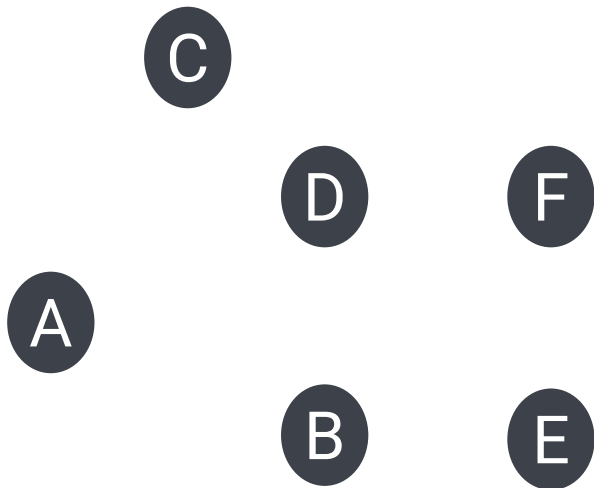


- $V = \{A, B, C, D, E, F\}$
- $E = \{(A, C), (A, D), (A, B), (D, F), (B, E), (B, F)\}$

	A	B	C	D	E	F
A						
B						
C						
D						
E						
F						

Adjacency Matrix

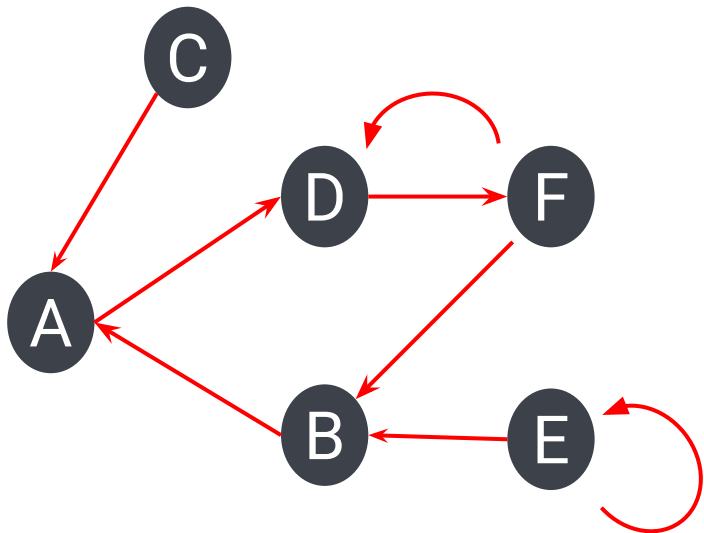
Graph Representation



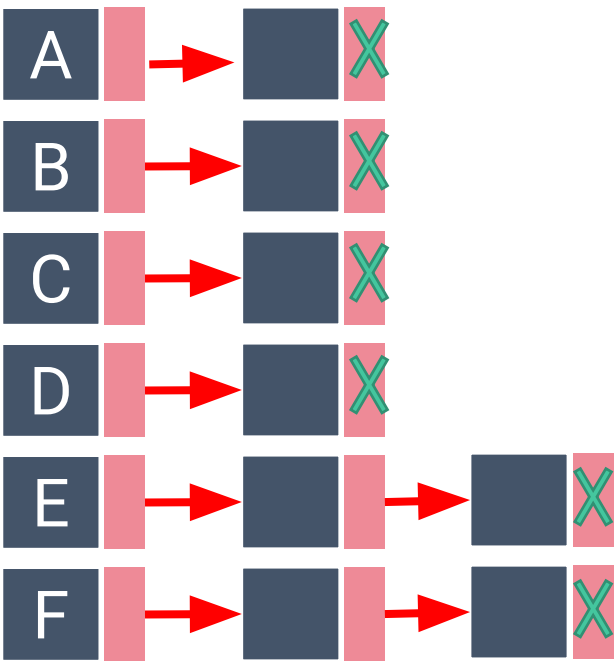
- $V = \{A, B, C, D, E, F\}$
- $E =$

	A	B	C	D	E	F
A	0	0	0	1	0	0
B	1	0	0	0	0	0
C	1	0	0	0	0	0
D	0	0	0	0	0	1
E	0	1	0	0	1	0
F	0	1	0	1	0	0

Adjacency Matrix



- $V = \{A, B, C, D, E, F\}$
- $E = \{(C, A), (A, D), (B, A), (D, F), (F, D), (E, B), (F, B), (E, E)\}$



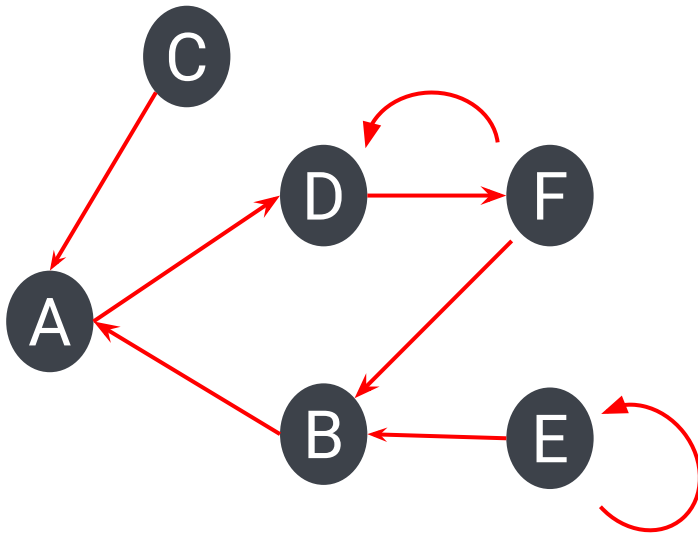
Adjacency List

Graph Representation



Node Representation

Node	Name	Phone
A	Able	
B	Baker	
C	Charlie	
D	Denver	
E	Ethan	
F	Fred	



Edge Representation

	A	B	C	D	E	F
A	0	0	0	1	0	0
B	1	0	0	0	0	0
C	1	0	0	0	0	0
D	0	0	0	0	0	1
E	0	1	0	0	1	0
F	0	1	0	1	0	0

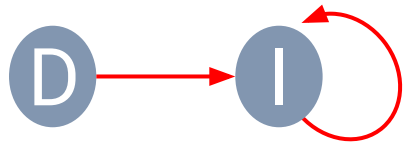
Adjacency Matrix

Graph Terminology



- A **path** is a sequence of nodes and edges that starts at a node and ends at a node such that each node is adjacent to the next one^[2].

- Formally, a path is a sequence of nodes $V_1, V_2, V_3, \dots, V_n$ where $(V_1, V_2), (V_2, V_3), \dots, (V_{n-1}, V_n) \in E$.

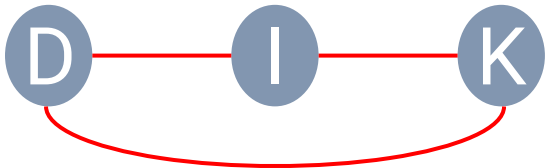


- A **loop** is a special case of path where two endpoints are the same.
 - An edge that starts and ends with the same node.

Graph Properties



- A **cycle** is a path that starts and ends at the same node, having at least one edge.
- A **simple path** is a path that does not contain the same edge more than once.
- A **simple cycle** is a simple path that starts and ends at the same node.

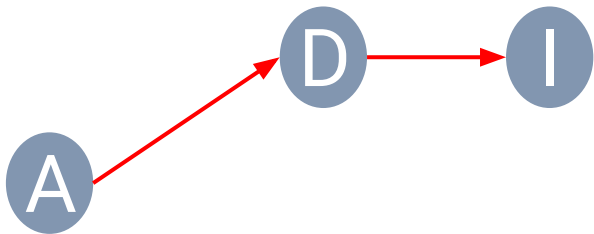


Graph Properties Example



Simple?

Cyclic?



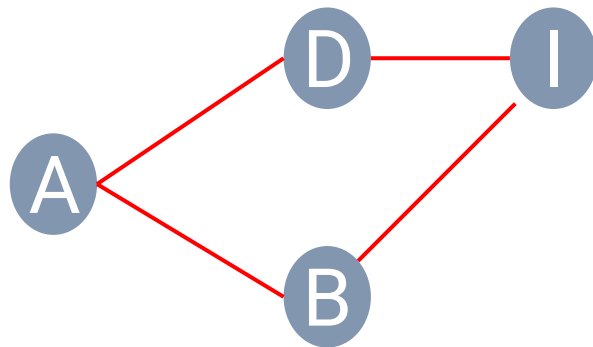
A, D, I

Graph Properties Example



Simple?

Cyclic?



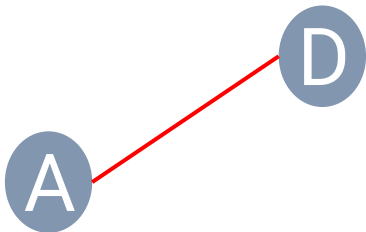
A, D, I, B, A

Graph Properties Example



Simple?

Cyclic?



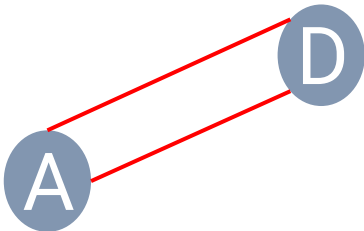
A, B, A

Graph Properties Example



Simple?

Cyclic?



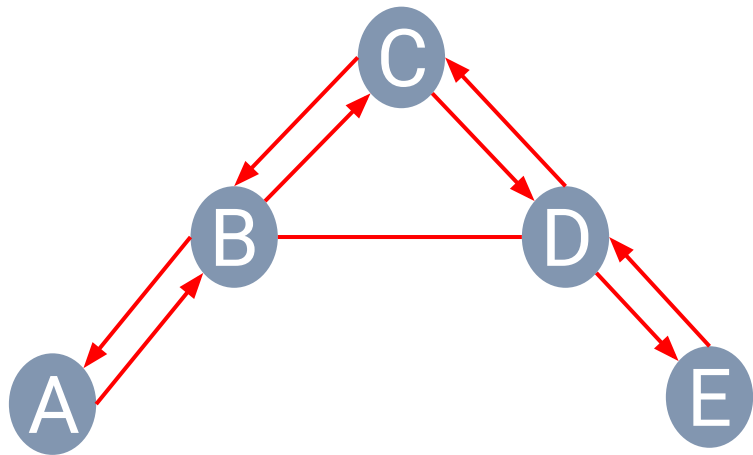
A, D, A

Graph Properties Example



Simple?

Cyclic?



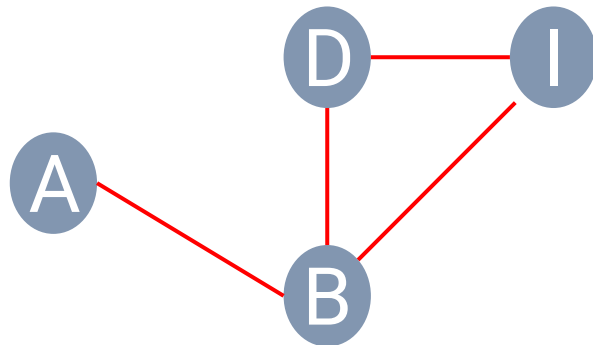
A, B, C, D, E, D, B, A

Graph Properties Example



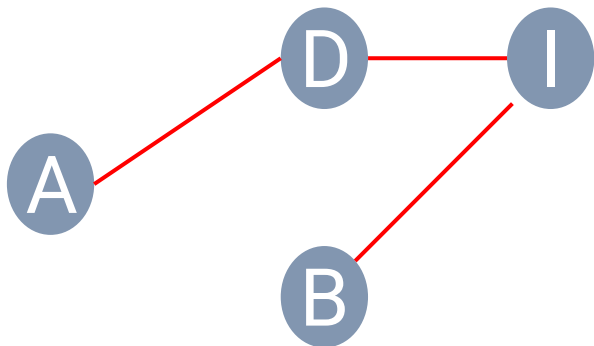
Simple?

Cyclic?

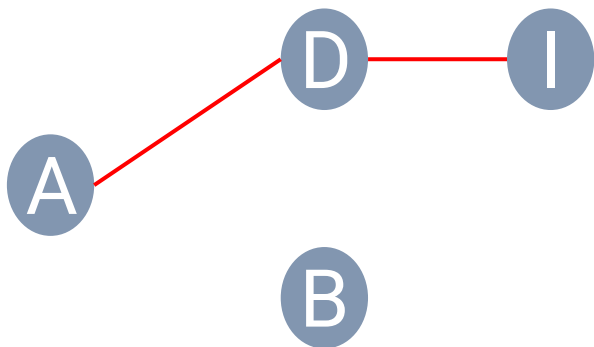


A, B, I, D, B, A

Graph Notations



- A graph is **connected** if, for any two nodes, there is a path between them.
- The **in-degree** of a node v is the number of the incoming edges of v .
- The **out-degree** of a node v is the number of the outgoing edges of v .



Graph Algorithms



- Traversals
 - Depth-first traversal
 - Breadth-first traversal
- Minimum Spanning Tree
 - Prim-Jarnik Algorithm
 - Kruskal's Algorithm
- Shortest Path
 - Dijkstra Algorithm
- Etc.

Graph Traversals



- A **traversal** is a systematic procedure for exploring a graph by examining all of its nodes and edges.
- Graph traversal algorithms are key to answering many fundamental questions about graphs involving the notion of **reachability**, that is, in determining how to travel from one node to another while following paths of a graph^[1].
- Two efficient graph traversal algorithms: **depth-first traversal** and **breadth-first traversal**.

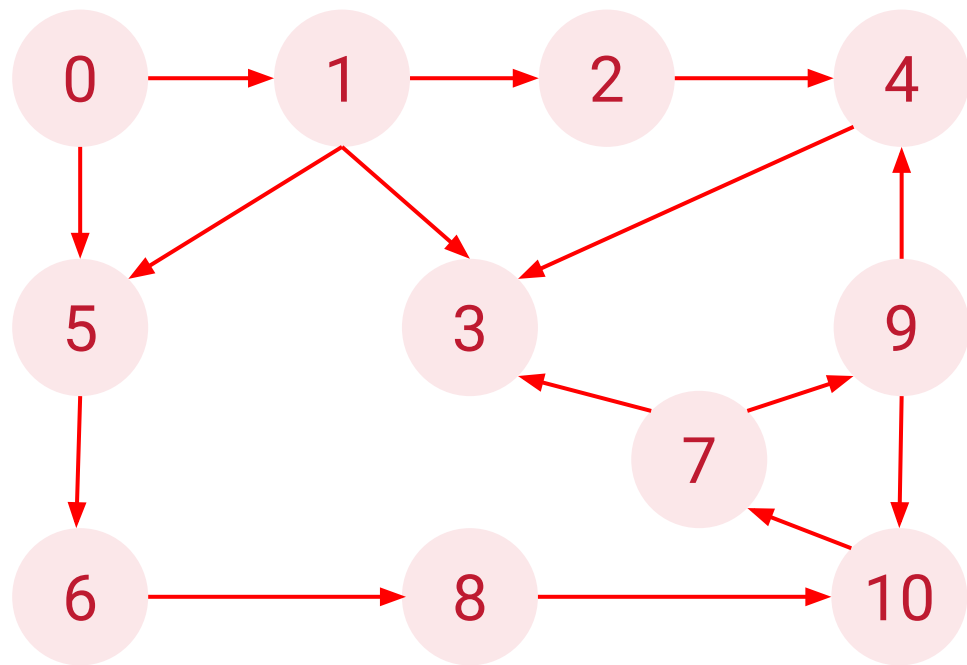
Graph Traversals



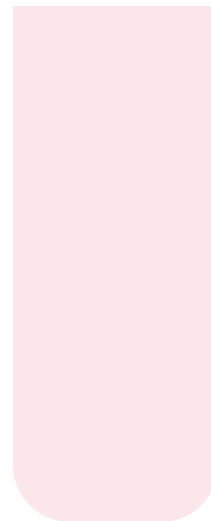
Depth-first traversal

Breadth-first traversal

Depth-First Traversal with Stack



Output :



Stack

Depth-First Traversal with Stack



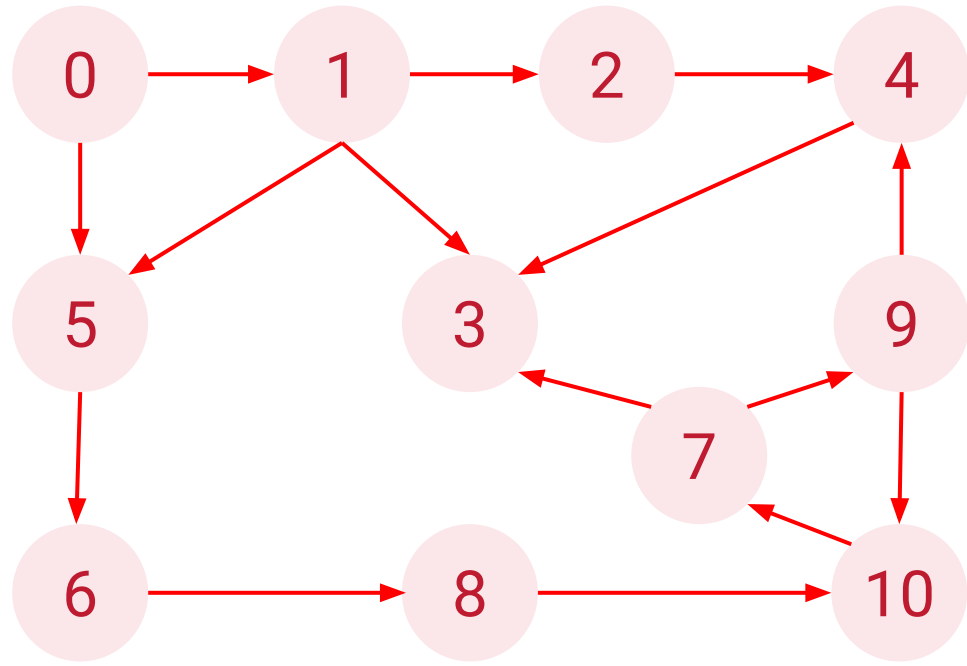
0

0

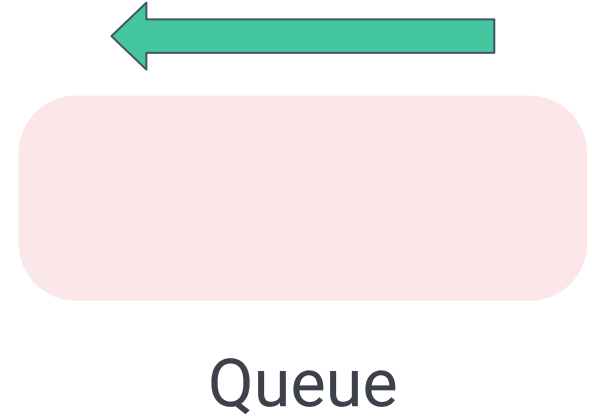
Stack

Output : 0

Breadth-First Traversal with Queue



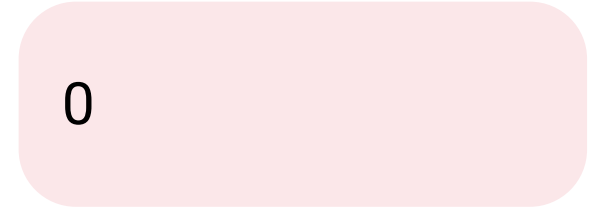
Output :



Breadth-First Traversal with Queue



0



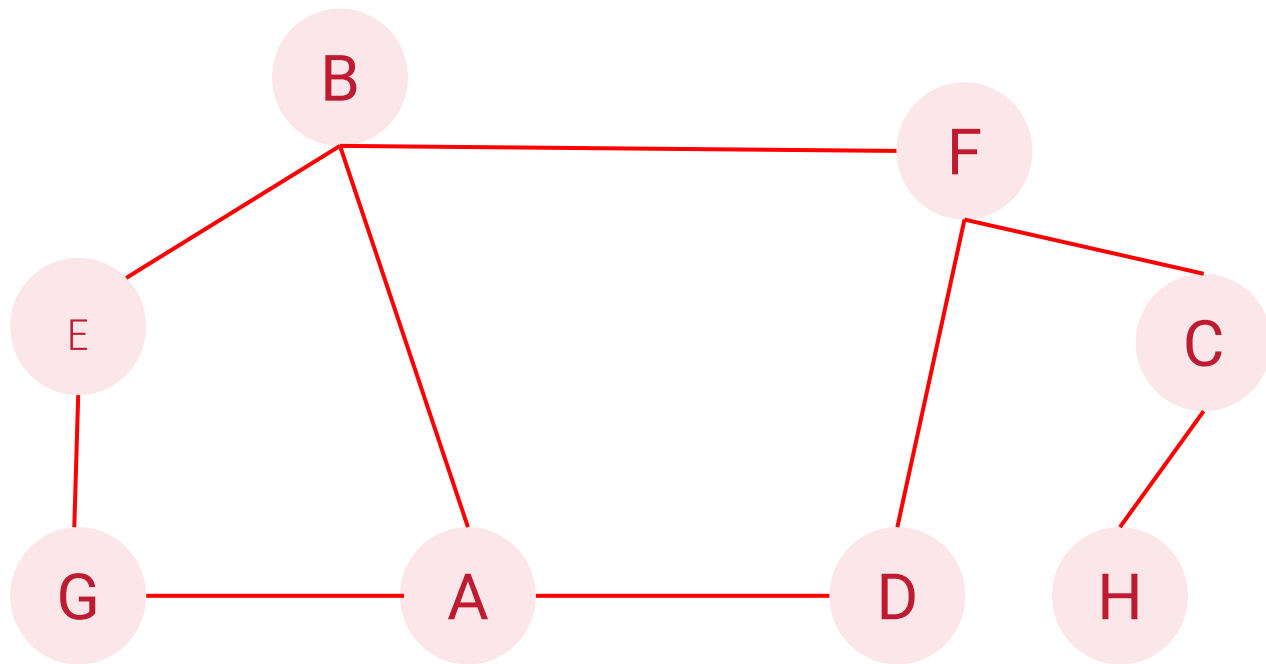
Queue

Output :

Depth-First and Breadth-First Exercise



Rule: Access node in ascending order (A-Z)

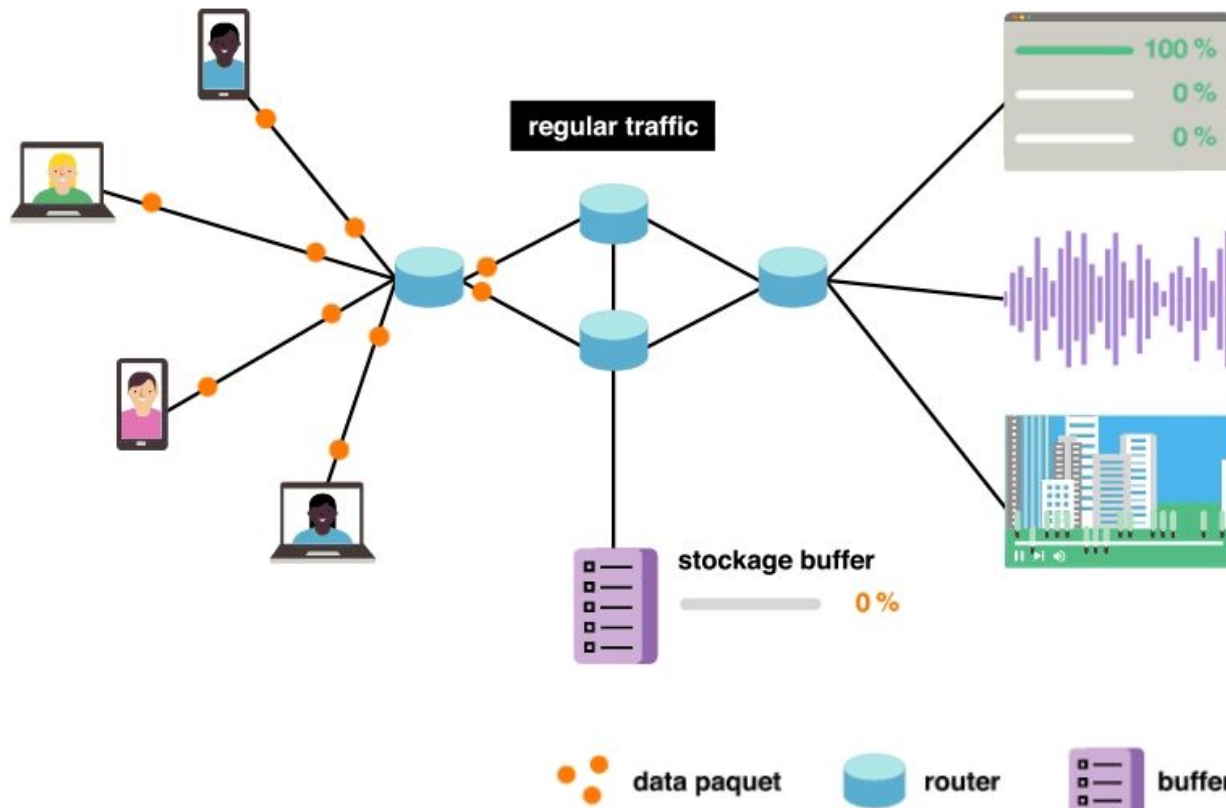


Graph Traversals



- On undirected and directed graph with n nodes and m edges.
 - A DFS traversal can be performed in $O(n + m)$ time.
 - A BFS traversal can be conducted in $O(n + m)$ time

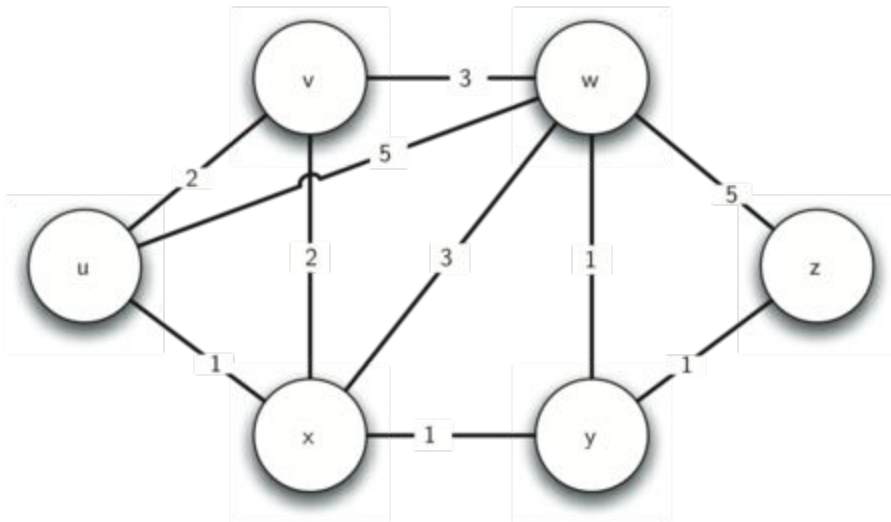
Shortest Path Problem



Shortest Path Problem



- The network of routers can be represented as a graph with weighted edges.



Shortest Path Problem

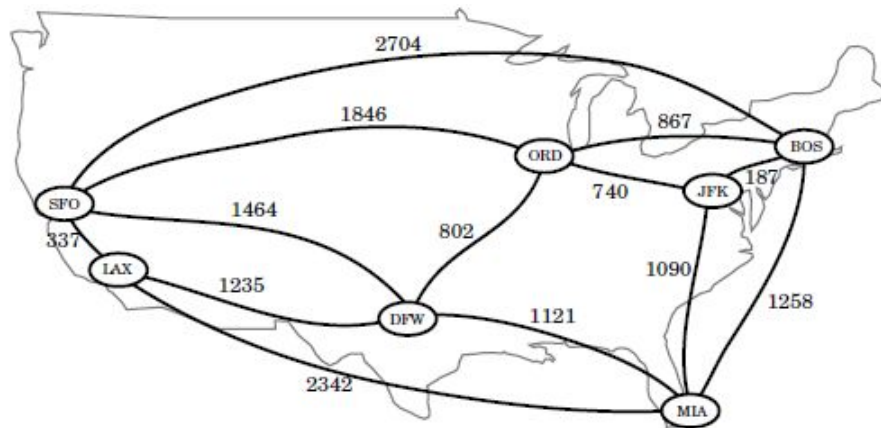


- The breadth first strategy can be used to find a **shortest path** from some starting node to every other node in a connected graph.
 - This approach is suitable in cases where each edge is equal to others.
 - However, for other situations, this approach is not efficient.
- It is natural, therefore, to consider graphs whose edges are not weighted equally.

Weighted Graphs



- A **weight graph** is a graph that has a numeric label $w(e)$ associated with each edge e , called the **weight** of edge e .
- For $e = (u, v)$, $w(u, v) = w(e)$.
- Such weights might represent:
 - Costs
 - Lengths
 - Capacities
 - etc.



Defining Shortest Paths in a Weighted Graph



- Let G be a weighted graph.
- The **length** (or **weight**) of a **path** is the sum of the weights of the edges of P .
 - $P = ((v_0, v_1), (v_1, v_2), \dots, (v_{k-1}, v_k))$
 - Length of P , denoted $w(P)$ is defined as
$$w(P) = \sum_{i=0}^{k-1} w(v_i, v_{i+1}).$$
- The distance from a node u to a node v in G , denoted $d(u, v)$ is the length of a minimum-length path (also called **shortest path**) from u to v .

Shortest Paths Algorithms



- Shortest path in a graph with all equal weights can be solved with breadth-first traversal algorithm.
- Distance cannot be arbitrarily low negative numbers.
 - For instance, the weight of edges represent the cost to travel between cities. If someone pay you to go between the cities, the cost would be negative.
 - Edge weights in G should be nonnegative (that is, $w(e) \geq 0$) for each edge.

Dijkstra's Algorithm



- An iterative algorithm that provides the shortest path from one starting node to all other nodes in the graph^[2].
- Apply **greedy method** to solve the problem by repeatedly selecting the best choice from among those available in each iteration.
 - Useful for optimising cost function over a collection of objects.
- “Weight” breadth-first search starting at the source node s .
- Used in link-state routing protocols in computer network.

Dijkstra's Algorithm Variables



- $\text{dist}[v]$ keeps the shortest/minimum length from the source node s for each node v in the graph.
 - Initially,
 - $\text{dist}[s] = 0$
 - $\text{dist}[v] = \text{Inf}$ for each $v \neq s$
 - In practice, $\text{dist}[v]$ can be set to a very large number than any real distance in the problem.

Dijkstra's Algorithm Variables



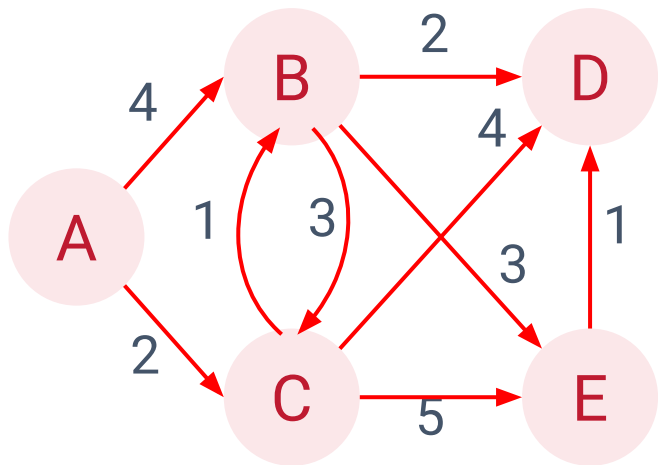
- Q is a set of all the unvisited nodes, called the unvisited set.
- $prev[v]$ is used to keep track of the previous node that provides the shortest path from s .

Dijkstra's Algorithm

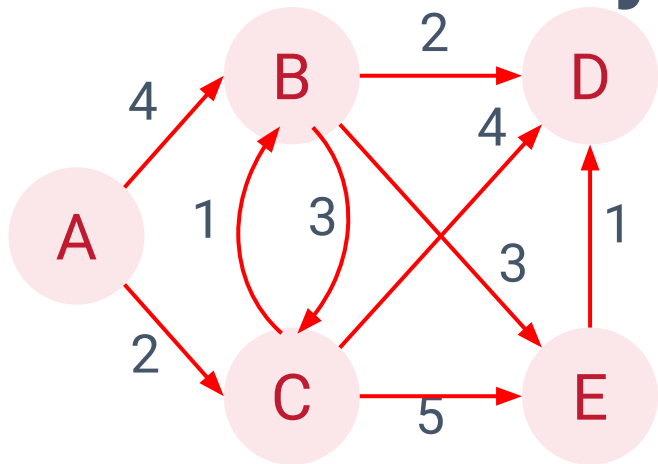


```
1  function Dijkstra(Graph, source):
2
3      create vertex set Q
4
5      for each vertex v in Graph:
6          dist[v] ← INFINITY
7          prev[v] ← UNDEFINED
8          add v to Q
9
10     dist[source] ← 0
11
12     while Q is not empty:
13         u ← vertex in Q with min dist[u]
14
15         remove u from Q
16
17         for each neighbor v of u:           // only v
that are still in Q
18             alt ← dist[u] + length(u, v)
19             if alt < dist[v]:
20                 dist[v] ← alt
21                 prev[v] ← u
22
23     return dist[], prev[]
```

Dijkstra's Algorithm



Dijkstra's Algorithm



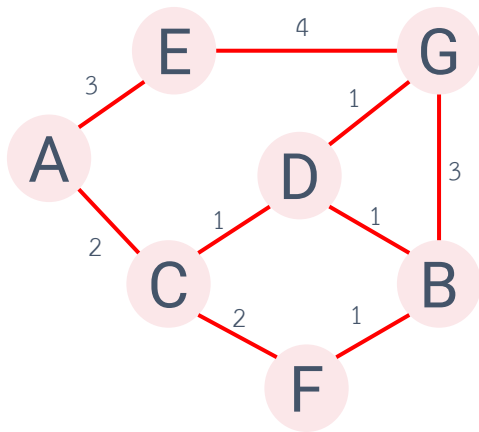
Q = {'A', 'B', 'C', 'D', 'E'}

dist = {'A': 0, 'B': ∞, 'C': ∞, 'D': ∞, 'E': ∞}

prev = {'A': None, 'B': None, 'C': None, 'D': None, 'E': None}

Node	Cumulative weight #1	Cumulative weight #2	Cumulative weight #3	Cumulative weight #4	Route
A					
B					
C					
D					
E					

Dijkstra's Algorithm Exercise



Find the shortest path for each node from node A

Find the distance from A to F

Dijkstra's Algorithm



- Dijkstra's algorithm works only when the weights are all positive.
 - If there is a negative weight on one of the edges in the graph, the algorithm would never exit.
- Another problem is a complete representation of the graph must be presented for the algorithm to run.
 - Every router has a complete map of all the routers: Not practical.
- Other algorithms allow each router to discover the graph as they go.
 - For instance, distance vector routing algorithm (Computer Networks).
 - Each node computes best path without full view of graph, exchanging link information as they go.