

H.4

Chernoff Way

a) A symmetric, positive definite $\rightarrow \exists A^{-1}$

$$\begin{aligned}
 & (\vec{x} - A^{-1} \vec{j})^T A (\vec{x} - A^{-1} \vec{j}) \leftarrow \text{note it is just a "translation"} \\
 &= \vec{x}^T A \vec{x} + (A^{-1} \vec{j})^T \underbrace{A}_{\text{1}} A^{-1} \vec{j} - \underbrace{(A^{-1} \vec{j})^T A \vec{x} - \vec{x}^T A A^{-1} \vec{j}}_{= -2 \vec{x}^T A A^{-1} \vec{j}} \\
 &= -2 \vec{x}^T \vec{j} \\
 &= -2 \vec{j} \cdot \vec{x} \\
 & \text{Thus we can rewrite the integral as } \checkmark \quad \leftarrow A^T = A
 \end{aligned}$$

$$\begin{aligned}
 & \frac{1}{(2\pi)^{n/2}} \int_{i=1}^n dx_i \exp(-\frac{1}{2} \vec{x}^T A \vec{x} + \vec{j} \cdot \vec{x}) \\
 &= \frac{1}{(2\pi)^{n/2}} \int_{i=1}^n dx_i (-\frac{1}{2} (\vec{x} - A^{-1} \vec{j})^T A (\vec{x} - A^{-1} \vec{j}) + \frac{1}{2} \vec{j}^T A^{-1} \vec{j}) \\
 &= \frac{1}{(2\pi)^{n/2}} \exp(\frac{1}{2} \vec{j}^T A^{-1} \vec{j}) \underbrace{\int_{i=1}^n dx_i \exp(-\frac{1}{2} (\vec{x} - A^{-1} \vec{j})^T A (\vec{x} - A^{-1} \vec{j}))}_{= \int_{i=1}^n dx_i \exp(-\frac{1}{2} \vec{x}^T A \vec{x})} \\
 & \quad \text{since } A^{-1} \vec{j} \text{ is just a constant } \checkmark
 \end{aligned}$$

Introduce the similarity transformation

$$U^T A U = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix}, \quad \det(U)$$

it bring A to its diagonal form and $\det(\text{Jac}) = 1$

$$\begin{aligned}
 &= \int_{i=1}^n dx_i \exp(-\frac{1}{2} \vec{x}^T U U^T A U U^T \vec{x}) \\
 &= \int_{i=1}^n dy_i \exp(-\frac{1}{2} \vec{y}^T (U A U^{-1}) \vec{y}) \checkmark
 \end{aligned}$$

$$\begin{aligned}
&= \int \prod_{i=1}^n dy_i \exp(-\frac{1}{2}(y_1^2 \lambda_1 + \dots + y_n^2 \lambda_n)) \\
&= \int dy_1 \exp(-\frac{1}{2}\lambda_1 y_1^2) \cdot \dots \cdot \int dy_n \exp(-\frac{1}{2}\lambda_n y_n^2) \\
&= (2\pi)^{\frac{n}{2}} \prod_{i=1}^n \lambda_i^{-\frac{1}{2}} \\
&= (2\pi)^{\frac{n}{2}} \sqrt{\det(U^{-1}AU)}^{-1} \\
&= (2\pi)^{\frac{n}{2}} (\det(A))^{-\frac{1}{2}} \\
\Rightarrow & \frac{1}{(2\pi)^{\frac{n}{2}}} \int \prod_{i=1}^n dx_i \exp(-\frac{1}{2} \vec{x}^\top A \vec{x} + \vec{j} \cdot \vec{x}) \\
&= \frac{1}{\sqrt{\det A}} \exp(\frac{1}{2} \vec{j}^\top A^{-1} \vec{j}) \quad \checkmark
\end{aligned}$$

b) Complex gain integral with scalar

$$\begin{aligned}
\int \frac{dz dz^*}{2\pi i} \exp(-z^* a z) &= \int \frac{dx dy}{\pi} e^{-ax^2 + y^2} \\
&\quad | \\
z &= x + iy \\
z^* &= x - iy \\
x &= r \cos \varphi \\
y &= r \sin \varphi &= \frac{1}{\pi} \int_0^\infty \int_0^{2\pi} dr d\varphi e^{-ar^2} \\
&= 2 \int_0^\infty dr e^{-ar^2} \\
&= \frac{1}{a} \quad \checkmark
\end{aligned}$$

$$\begin{aligned}
&\frac{1}{(2\pi i)^n} \int \prod_{i=1}^n dz_i^* dz_i \exp(-\vec{z}^\top H \vec{z} + \vec{j}^* \cdot \vec{z} + \vec{j} \cdot \vec{z}^*) \\
&= \frac{1}{\pi^n} \int \prod_{i=1}^n dx_i dy_i \exp(-\vec{x}^\top H \vec{x} - \vec{y}^\top H \vec{y} + \vec{j}^* \cdot (\vec{x} + i\vec{y}) + \vec{j} \cdot (\vec{x} - i\vec{y})) \\
&= \frac{1}{\pi^n} \int \prod_{i=1}^n dx_i dy_i \exp(-\vec{x}^\top H \vec{x} + (\vec{j}^* + \vec{j}) \cdot \vec{x}) \exp(-\vec{y}^\top H \vec{y} + i(\vec{j}^* - \vec{j}) \vec{y}) \\
&= \frac{1}{\pi^n} \frac{(2\pi)^{\frac{n}{2}}}{\sqrt{\det(2H)}} \exp\left(\frac{1}{2} (\vec{j}^* + \vec{j})^\top (2H)^{-1} (\vec{j}^* + \vec{j})\right) \cdot \frac{(2\pi)^{\frac{n}{2}}}{\sqrt{\det(2H)}} \exp\left(-\frac{1}{2} (\vec{j}^* - \vec{j})^\top (2H)^{-1} (\vec{j}^* - \vec{j})\right)
\end{aligned}$$

$$\begin{aligned}
\det(2H) &= \det(H) \cdot 2^n \\
&= \frac{1}{\pi^n} (2\pi)^n \cdot \frac{1}{2^n} \underbrace{\frac{1}{\det H} \exp\left(\frac{1}{4}\left[\left(\vec{J}^* + \vec{J}\right)^T H \left(\vec{J}^* + \vec{J}\right) - \left(\vec{J}^* - \vec{J}\right)^T H \left(\vec{J}^* - \vec{J}\right)\right]\right)}_{= \vec{J}^T H \vec{J}^* + \vec{J}^* H \vec{J} + \vec{J}^{*T} H \vec{J}} \\
&\quad + \vec{J}^T H \vec{J}^* \\
&= \frac{1}{\det H} \exp\left(\vec{J}^T H^{-1} \vec{J}\right) \quad \checkmark
\end{aligned}$$

$$\frac{1}{(2\pi i)^n} \int_{i=1}^n d\vec{z}_i^* d\vec{z}_i \exp(-\vec{z}_k^* H_{kk} \vec{z}_k + J_k^* \vec{z}_k + J_k \vec{z}_k^*)$$

$$\vec{z}^T H \vec{z} + J^T \vec{z} + J \vec{z}^T = -w^T \Delta w + J^T H^{-1} J$$

$$UHU^{-1} = \Delta, \quad U^T = U^{-1}, \quad \det U = 1$$

$$W = U(\vec{z} - H^{-1} J)$$

$$d\vec{z}^* d\vec{z} = dw^* dw \underbrace{\det U}_{=1}$$

$$= 2i dx dy$$

$$\Rightarrow \int_{i=1}^n d\vec{x}_i d\vec{y}_i \exp(-x^T \Delta x - y^T \Delta y)$$

\uparrow
 use (a)

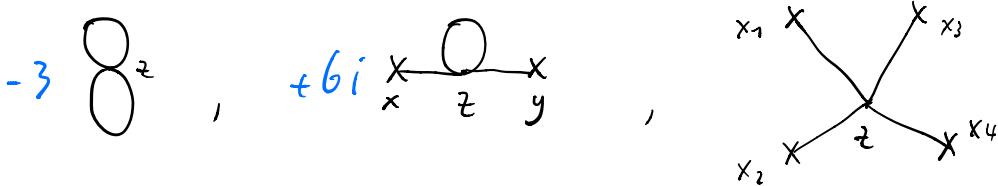
H.5

a) At $\partial(\lambda^0)$. $W_0[\lambda] = \exp(-\frac{i}{2} \int d^4x d^4y j(x) D(x-y) j(y))$

At $\partial(\lambda^1)$:

$$\begin{aligned}
 & \exp\left(-i \frac{\lambda}{4!} \int d^4z \left(\frac{1}{i} \frac{\delta}{\delta j(z)}\right)^4\right) \exp\left(-\frac{i}{2} \int d^4x d^4y j(x) D_F(x-y) j(y)\right) \\
 &= \left[1 - i \frac{\lambda}{4!} \int d^4z \left(\frac{1}{i} \frac{\delta}{\delta j(z)}\right)^4 + \partial(\lambda^1)\right] \exp\left(-\frac{i}{2} \int d^4x d^4y j(x) D_F(x-y) j(y)\right) \\
 & \quad \left(\frac{\delta}{\delta j(z)}\right)^4 \exp\left(-\frac{i}{2} \int d^4x d^4y j(x) D_F(x-y) j(y)\right) \\
 &= \left(\frac{\delta}{\delta j(z)}\right)^3 \left(-i \int d^4y D_F(z-y) j(y)\right) \exp\left(-\underbrace{\left(\int d^4x D_F(z-x) j(x)\right)^2}_{\sim}\right) \\
 &= \left(\frac{\delta}{\delta j(z)}\right)^2 \left(-i D_F(z-z) + (i) \underbrace{\int d^4y d^4x D_F(z-y) j(y) D(z-x) j(x)}_{\sim}\right) \exp\left(\sim\right) \\
 &= \left(\frac{\delta}{\delta j(z)}\right) \left(-i D_F(0) \underbrace{\int d^4x D_F(z-x) j(x)}_{\sim} - 2 D_F(0) \int d^4x j(z) D(z-x) j(x)\right. \\
 & \quad \left.+ i \underbrace{\int d^4y \int d^4x D_F(z-y) j(y) D(z-x) j(x) \int d^4x D_F(z-x) j(x)}_{\sim}\right) \exp\left(\sim\right) \\
 &= \left[\int dx D(x-z) j(x)\right]^3 \\
 &= \left(-3 D_F(0) + 3i D_F(0) \underbrace{\int d^4x D_F(z-x) j(x)}_{\sim} \int d^4y D_F(z-y) j(y)\right) \\
 & \quad + \underbrace{\prod_{i=1}^4 \int d^4x_i D_F(z-x_i) j(x_i)}_{\sim} \exp\left(\sim\right) \\
 &= \left[\int dx D_F(z-x) j(x)\right]^4 \\
 &\rightarrow 3 \text{ come from } -3 D_F(0) \int d^4x D_F(z-x) j(x) \frac{\delta}{\delta j(z)} \exp\left(\sim\right) \\
 &\text{another 3 come from } \frac{\delta}{\delta j(z)} \left(\int dx D_F(z-x) j(x)\right)^3
 \end{aligned}$$

$$= \left[-3 D_F^2(0) + \frac{6}{i} i D_F(0) \int d^4y \int d^4x D_F(z-y) j(y) D(z-x) j(x) \right. \\ \left. + \frac{4}{\pi} \int_{i=1}^4 d^4x_i D_F(z-x_i) j(x_i) \right] \exp(-\dots)$$



$$\Rightarrow W[j] = \frac{1}{N_0} \left[\left(1 - i \frac{\lambda}{4!} \int d^4z (-3 D_F^2(0)) - 3i D_F(0) \int d^4y d^4x D_F(z-y) j(y) D(z-x) j(x) \right. \right. \\ \left. \left. + \frac{4}{\pi} \int_{i=1}^4 d^4x_i D_F(z-x_i) j(x_i) \right) \right] e^{-\frac{i}{2} \int d^4x d^4y j(x) D_{xy} j(y)}$$

$$N_0 = \left(1 - i \frac{\lambda}{4!} \int d^4z (-3 D_F^2(0)) \right)$$

$$\frac{1}{z-x} = 1 + x + \partial(x^2) \Rightarrow \text{no vacuum bubbles}$$

b) $\frac{\delta^4}{\delta j(x_1) \delta j(x_2) \delta j(x_3) \delta j(x_4)} e^{-\frac{i}{2} \int d^4x d^4y j(x) D_{xy} j(y)}$

$$= \frac{\delta^3}{\delta_1 \delta_2 \delta_3} (-i D_{4x} j_x) e^{\dots}, \quad \text{Integration over repeated indices}$$

$$= \frac{\delta^2}{\delta_1 \delta_2} (-i D_{43} - i D_{4x} j_x D_{3y} j_y) e^{\dots}$$

$$= \frac{\delta}{\delta_1} (-i D_{43} D_{2x} j_x - i D_{42} D_{3y} j_y - i D_{4x} j_x D_{3z} - i D_{4x} j_x D_{3y} j_y D_{2z} j_z) e^{\dots}$$

$$= (-i D_{43} D_{21} - i D_{42} D_{31} - i D_{41} D_{32} + \dots) e^{\dots}$$

— + | | + X No effect after setting $j=0$

$$\frac{\delta^2}{\delta j(a) \delta j(b)} D_{2y} j_y D_{2x} j_x$$

$$= \frac{\delta}{\delta j(a)} (D_{zb} D_{zx} j_x + D_{zy} j_y D_{zb})$$

$$= 2 \frac{\delta}{\delta j(a)} D_{z6} D_{z2} j_x$$

$$= 2 D_{z6} D_{za}$$

In the 4-point function a, b can be any two of x_1, x_2, x_3, x_4 . The two differentiations left are applied to the exponential.

$$\equiv \boxed{1} = X$$

$$\begin{aligned}
 & \langle 0 | T \phi(x_1) \phi(x_2) \phi(x_3) \phi(x_4) | 0 \rangle \\
 &= \frac{\delta^4 w[j]}{\delta j(x_1) \delta j(x_2) \delta j(x_3) \delta j(x_4)} \Big|_{j=0} \\
 &= \frac{1}{N_b} \left[\left(1 - i \frac{\lambda}{4!} \int d^4 z \cancel{-3i D_F^2(0)} \right) \cdot (-i D_{z1} D_{z4} - i D_{z3} D_{z4} - i D_{z4} D_{z3}) \right. \\
 &\quad \left. - 3i \lambda \boxed{2} \left\{ -i \frac{\lambda}{4!} \cancel{(-3i) D_F(0)} \int d^4 z \left(2 D_{z1} D_{z2} D_{z3} + 2 D_{z1} D_{z3} D_{z4} + 2 D_{z1} D_{z4} D_{z3} \right. \right. \right. \\
 &\quad \left. \left. \left. + 2 D_{z2} D_{z3} D_{z4} + 2 D_{z2} D_{z4} D_{z3} + 2 D_{z3} D_{z4} D_{z3} \right) \right\} \right] \\
 &\quad - i \frac{\lambda}{4!} \cancel{4!} \int d^4 z \underbrace{D_{z1} D_{z2} D_{z3} D_{z4}}_{\text{permutation}} \\
 &= -3 (\equiv) - 3i \lambda (\boxed{0}) - i \lambda (X)
 \end{aligned}$$

\rightarrow Ryder ch 6.5