

H16.

$$1. \quad D: S_3 \rightarrow \mathbb{R}^3 \times \mathbb{R}^3$$

$$D(e) = 1_3$$

$$D[(123)] = Q = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$(132) = Q^2 = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} b \\ c \\ a \end{pmatrix} \rightarrow (123)$$

$$(12) = P = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$(13) = QP = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$(23) = PQ = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$2. \quad X = \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix} \in V \subset \mathbb{R}^3 \quad \text{X} \quad \text{invariant subspace} \Leftrightarrow \text{reducible}$$

take $\lambda \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \lambda \in \mathbb{R}$

$$QX = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix} = \begin{pmatrix} x_2 \\ 0 \\ x_1 + x_2 \end{pmatrix} \notin V \rightarrow \text{reducible}$$

$$3. \quad D = E(G) \quad \text{X}$$

$$e=1, \quad Q=1, \quad P=-1$$

$$\begin{aligned} \text{tr}(D(e)) &= 3 \\ \text{tr}(D(Q)) &= 0 = \text{tr}(D(\star\star\star)) \\ \text{tr}(D(P)) &= 1 = \text{tr}(D(\star\star)) \end{aligned}$$

	e	2-cyc	3-cyc
x_S	1	1	1
x_A	1	-1	1
x_m	2	0	-1

$$X = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \text{It can be split into two irreps}$$

what does it look like? $\rightarrow 4$

$$\tilde{R} \xrightarrow{\quad} x_m \quad x_s \xleftarrow{\quad}$$

\tilde{R} acted on only trivial irrep.

$\tilde{\rho}$ and $\tilde{\lambda}$ (forms orthogonal subspace) acted on standard irrep.

$$4. \quad Q \vec{p} = D(Q)_{11} \vec{p} + D(Q)_{21} \vec{\lambda}, \quad Q = (1 \ 2 \ 3) \quad (\text{Typo on the sheet } D_{21} \leftrightarrow D_{12} ?)$$

$$\vec{p} = \frac{1}{\sqrt{2}}(\vec{x}_1 - \vec{x}_2), \quad \vec{\lambda} = \frac{1}{\sqrt{6}}(\vec{x}_1 + \vec{x}_2 - 2\vec{x}_3)$$

$$Q \vec{p} = \frac{1}{\sqrt{2}}(\vec{x}_2 - \vec{x}_3) = D(Q)_{11} \frac{1}{\sqrt{2}}(\vec{x}_1 - \vec{x}_2) + D(Q)_{21} \frac{1}{\sqrt{6}}(\vec{x}_1 + \vec{x}_2 - 2\vec{x}_3)$$

$$D(Q)_{21} = \frac{\sqrt{3}}{2}, \quad D(Q)_{11} = -\frac{1}{2}$$

$$Q \vec{\lambda} = \frac{1}{\sqrt{6}}(\vec{x}_2 + \vec{x}_3 - 2\vec{x}_1) = D(Q)_{12} \frac{1}{\sqrt{2}}(\vec{x}_1 - \vec{x}_2) + D(Q)_{22} \frac{1}{\sqrt{6}}(\vec{x}_1 + \vec{x}_2 - 2\vec{x}_3)$$

$$D(Q)_{12} = -\frac{1}{2} \quad D(Q)_{22} = -\frac{1}{\sqrt{3}} \frac{3}{2} = -\frac{\sqrt{3}}{2}$$

$$\Rightarrow D(Q) = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} \quad \checkmark$$

$$D(e) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$P = (1 \ 2)$$

$$P \vec{p} = \frac{1}{\sqrt{2}}(\vec{x}_2 - \vec{x}_1) = D(P)_{11} \frac{1}{\sqrt{2}}(\vec{x}_1 - \vec{x}_2) + D(P)_{21} \frac{1}{\sqrt{6}}(\vec{x}_1 - \vec{x}_2 - 2\vec{x}_3)$$

$$D(P)_{21} = 0 \quad \text{no } \vec{x}_3 \text{ on LHS}$$

$$D(P)_{11} = -1$$

$$P \vec{\lambda} = \frac{1}{\sqrt{6}}(\vec{x}_1 + \vec{x}_2 - 2\vec{x}_3) = D(P)_{12} \frac{1}{\sqrt{2}}(\vec{x}_1 - \vec{x}_2) + D(P)_{22} \frac{1}{\sqrt{6}}(\dots)$$

$$D(P)_{22} = 1, \quad D(P)_{12} = 0$$

$$\rightarrow D(P) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \quad \checkmark$$

$$Q^2 = (132) : \quad \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix}$$

$$Q^2 \vec{j} = \frac{1}{\sqrt{2}} (\vec{x}_3 - \vec{x}_1) \stackrel{!}{=} D(Q^2)_{11} \frac{1}{\sqrt{2}} (\vec{x}_1 - \vec{x}_2) + D(Q^2)_{21} \frac{1}{\sqrt{6}} (\vec{x}_1 + \vec{x}_2 - 2\vec{x}_3)$$

$$\rightarrow D(Q^2)_{21} = -\frac{\sqrt{3}}{2} \quad D(Q^2)_{11} = -\frac{1}{2}$$

$$Q^2 \vec{\lambda} = \frac{1}{\sqrt{6}} (\vec{x}_3 + \vec{x}_1 - 2\vec{x}_2) \stackrel{!}{=} D(Q^2)_{12} \frac{1}{\sqrt{2}} (\vec{x}_1 - \vec{x}_2) + D(Q^2)_{22} \frac{1}{\sqrt{6}} (\vec{x}_1 + \vec{x}_2 - 2\vec{x}_3)$$

$$D_{22} = -\frac{1}{2} \quad D_{12} = \frac{3}{\sqrt{3}} \cdot \frac{1}{2} = \frac{\sqrt{3}}{2}$$

$$\rightarrow D(Q^2) = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} = [D(Q)]^2$$

$$QP = (13)$$

$$QP \vec{j} = \frac{1}{\sqrt{2}} (\vec{x}_3 - \vec{x}_2) \stackrel{!}{=} D(QP)_{11} \frac{1}{\sqrt{2}} (\vec{x}_1 - \vec{x}_2) + D(QP)_{21} \frac{1}{\sqrt{6}} (\vec{x}_1 + \vec{x}_2 - 2\vec{x}_3)$$

$$D_{21} = -\frac{\sqrt{3}}{2} \quad D_{11} = \frac{1}{2}$$

$$QP \vec{\lambda} = \frac{1}{\sqrt{6}} (\vec{x}_3 + \vec{x}_2 - 2\vec{x}_1) \stackrel{!}{=} D(QP)_{12} \frac{1}{\sqrt{2}} (\vec{x}_1 - \vec{x}_2) + D(QP)_{22} \frac{1}{\sqrt{6}} (\vec{x}_1 + \vec{x}_2 - 2\vec{x}_3)$$

$$D(QP)_{22} = -\frac{1}{2} \quad D(QP)_{12} = -\frac{\sqrt{3}}{2}$$

$$\rightarrow D(QP) = \begin{pmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} = D(Q) \cdot D(P)$$

✓

$$PQ = (23)$$

$$PQ \vec{j} = \frac{1}{\sqrt{2}} (\vec{x}_1 - \vec{x}_3) = D(PQ)_{11} \frac{1}{\sqrt{2}} (\vec{x}_1 - \vec{x}_2) + D(PQ)_{21} \frac{1}{\sqrt{6}} (\vec{x}_1 + \vec{x}_2 - 2\vec{x}_3)$$

$$D(PQ)_{21} = \frac{\sqrt{3}}{2}, \quad D(PQ)_{11} = \frac{1}{2}$$

$$PQ\vec{\lambda} = \frac{1}{\sqrt{6}}(\vec{x}_1 + \vec{x}_3 - 2\vec{x}_2) = D(PQ)_{12} \frac{1}{\sqrt{2}}(\vec{x}_1 - \vec{x}_2) + D(PQ)_{22} \frac{1}{\sqrt{6}}(\vec{x}_1 + \vec{x}_2 - 2\vec{x}_3)$$

$$D_{22} = -\frac{1}{2}, \quad D_{12} = \frac{3}{2} \cdot \frac{1}{\sqrt{3}} = \frac{\sqrt{3}}{2}$$

$$\rightarrow D(PQ) = \begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} = D(P) \cdot D(Q) \quad \checkmark$$

It is a representation!

$$5. \quad \text{tr}[D(P)] = 0, \quad \text{tr}[D(P)D(Q)] = \text{tr}[D(Q)D(P)] = 0$$

$$\text{tr}[D(Q)] = -1 \quad \text{tr}[D(Q^2)] = -1$$

$$\text{tr}[D(e)] = 2$$

\hookrightarrow mixed representation $\rightarrow X_M$

$$6. \quad D_M(\sigma) \Psi(\vec{p}, \vec{\lambda}) = \Psi(\sigma \vec{p}, \sigma \vec{\lambda})$$

$$\Psi_0(\vec{p}, \vec{\lambda}) = \varphi_0(\vec{p}) \varphi_0(\vec{\lambda})$$

$$\varphi_0(\vec{x}) = N_0 \exp(-\frac{1}{2}|\vec{x}|^2/b^2)$$

$$\varphi_0(\vec{p}) \varphi_0(\vec{\lambda}) \propto \exp(-\frac{1}{2}(|\vec{p}|^2 + |\vec{\lambda}|^2))$$

$$P(|\vec{p}|^2 + |\vec{\lambda}|^2) = (|D_{(12)}|\vec{p}|^2 + |D_{(12)}|\vec{\lambda}|^2) = |\vec{p}|^2 + |\vec{\lambda}|^2$$

$$Q(|\vec{p}|^2 + |\vec{\lambda}|^2) = \dots = (|-\frac{1}{2}\vec{p} + \frac{\sqrt{3}}{2}\vec{\lambda}|^2 + |- \frac{1}{2}\sqrt{3}\vec{p} - \frac{1}{2}\vec{\lambda}|^2)$$

$$= |\vec{p}|^2 + |\vec{\lambda}|^2$$

alle other permutations are generated by PQ

$$\rightarrow \sigma \in S_3, \quad \sigma(|\vec{p}|^2 + |\vec{\lambda}|^2) = |\vec{p}|^2 + |\vec{\lambda}|^2$$

\rightarrow trivial rep. \Leftrightarrow symmetric rep.

Ψ_0 is a basis of

$$D_M(\sigma) \Psi_0(\vec{p}, \vec{\lambda}) = \Psi_0(\vec{p}, \vec{\lambda})$$

$$7. \quad \Psi_{io}(\vec{p}, \vec{\lambda}) = \varphi_i(\vec{p}) \varphi_o(\vec{\lambda}) \propto p^i \exp\left[\frac{i}{\hbar}(|\vec{p}|^2 + |\vec{\lambda}|^2)\right]$$
$$\Psi_{oi}(\vec{p}, \vec{\lambda}) = \varphi_o(\vec{p}) \varphi_i(\vec{\lambda}) \propto \lambda^i \exp\left[-\frac{i}{\hbar}(|\vec{p}|^2 + |\vec{\lambda}|^2)\right]$$
$$\rightarrow \begin{pmatrix} \vec{p} \\ \vec{\lambda} \end{pmatrix}, \quad \text{mixed rep.}$$

H17

$$a) \quad \left. \begin{array}{l} K_{Y_A}^2(\sigma) = E^2(\sigma) \\ K_{Y_S}^2(\sigma) = 1^2 \end{array} \right\} = 1 \quad K_{Y_S}(\sigma) K_{Y_A} = E(\sigma) \cdot 1 = K_{Y_A}(\sigma)$$

$$K_{Y_S}(\sigma) K_{Y_M}(\sigma) = 1 \cdot \begin{cases} 2, & \sigma = e \\ -1, & \sigma = Q, Q^2 \\ 0, & \sigma = P_{ik} \end{cases} = K_{Y_M}(\sigma)$$

$$K_{Y_A}(\sigma) K_{Y_M}(\sigma) = E(\sigma) \cdot \begin{cases} 2, & \dots \\ -1, & \dots \\ 0, & \dots \end{cases}$$

$$= \begin{cases} (-1)^0 \cdot 2, & \dots \\ (-1)^1 \cdot (-1), & \dots \\ (-1)^0 \cdot 0, & \dots \end{cases} = \begin{cases} 2, & \dots \\ -1 \\ 0 \end{cases} = K_{Y_M}(\sigma)$$

$$K_{Y_M}^2(\sigma) = \begin{cases} 2^2, & \sigma = e \\ (-1)^2, & \sigma = Q, Q^2 \\ 0^2, & \sigma = P_{ik} \end{cases} = \begin{cases} 2, & \sigma = e \\ 1, & \sigma = Q, Q^2 \\ 1, & \sigma = P_{ik} \end{cases} = K_{Y_S}(e) + K_{Y_A}(e) + K_{Y_M}(e)$$

$$= K_{Y_S}(Q) + K_{Y_A}(Q) + K_{Y_M}(Q) = K_{Y_S}(P_{ik}) + K_{Y_A}(P_{ik}) + K_{Y_M}(P_{ik})$$

$$= K_{Y_S} + K_{Y_A} + K_{Y_M}$$

$$2. \quad \phi \in L^2((R^3)^2, \mathbb{C}_c^3 \otimes \mathbb{C}_S^2 \otimes \mathbb{C}_I^2)$$

$$|\text{baryon}\rangle = |\text{color}\rangle \otimes |\text{space}\rangle \otimes \underbrace{|\text{spin}\rangle \otimes |\text{isospin}\rangle}_{S}$$

$$3. \quad Y = \begin{array}{c|c|c} \square & \cdots & \square \\ \square & \cdots & \square \\ \hline & & l_2 \\ & & l_1 \end{array} \quad l_2 \geq l_1$$

$$\text{To show } D_Y \cong D_j, \quad j = \frac{1}{2}(l_2 - l_1)$$

to show: $l_2 \geq l_1$, irrep. D_j where $j = \frac{1}{2}(l_2 - l_1)$

$$\text{From H.9: } \chi_j = \frac{\lambda^{2j+1} - \bar{\lambda}^{-2j-1}}{\lambda - \bar{\lambda}} = \frac{\sin((j+1)\pi)}{\sin(\pi)}, \quad \lambda = e^{i\pi}$$

$$g \in SU(2), \quad z_2 - z_1 = 2j+1$$

$$z_1 = l_1 + 1 - 1 = l_1, \quad z_2 = l_2 + 2 - 1 = l_2 + 1$$

$$z_2 - z_1 = l_2 + 1 - l_1 = 2j+1 \quad \Rightarrow l_2 - l_1 = 2j$$

$$\text{to show: } V = \mathbb{C}^2 \otimes \mathbb{C}^2 \otimes \mathbb{C}^2, \quad Y = Y_S, j = \frac{3}{2}, \quad Y = Y_M, j = \frac{1}{2}$$

The dim. of the representation is $2j+1$ corresponding to states

$$\text{with spin } j = \frac{1}{2}(l_2 - l_1)$$

↪ Only Yang diag. with 3 boxes and a max. column length of 2

$$\hookrightarrow Y_S = \begin{array}{|c|c|}\hline \square & \square \\ \hline \end{array}$$

$$l_2=3, \quad l_1=0$$

$$\rightarrow j = \frac{3}{2}$$

$$Y_M = \begin{array}{|c|c|}\hline \square & \square \\ \hline \end{array}$$

$$l_2=2, \quad l_1=1$$

$$\rightarrow j = \frac{1}{2}$$

in $SU(2)$:

$$\underbrace{\Delta^-, \Delta^0, \Delta^+, \Delta^{++}}_{16}$$

(consider 2-ways of spin)

$$\underbrace{n, p}_{4}$$

4. $|color\rangle \rightarrow \text{anti-symm.}$

$$|\text{space}\rangle \otimes |\text{spin}\rangle \otimes |\text{isospin}\rangle$$

↑
symm. symm.

→

$$|\text{spin}\rangle: Y_S$$

$$|\text{isospin}\rangle: Y_S$$

$\} \rightarrow \Delta^+$'s

$$|\text{spin}\rangle: Y_M$$

$$|\text{isospin}\rangle: Y_M$$

$\} \rightarrow n, p$

$$\text{Only spin } \frac{1}{2} \quad |\text{spin}\rangle: Y_A$$

not possible

$$|\text{isospin}\rangle: Y_A$$

not possible because of $SU(2)$
only two quarks!

5. $|{\text{space}}\rangle : Y_M \quad (L=1) \quad \text{parity: } (-1)$

$$K_{Y_S} = K_{Y_M} \cdot \underline{K_{Y_A}}$$

$|{\text{spin}}\rangle : Y_M$

Y_S

Y_M

$|{\text{isospin}}\rangle : Y_M, \quad S=\frac{1}{2}, \quad I=\frac{1}{2}$

$Y_M, \quad S=\frac{3}{2}, \quad I=\frac{1}{2}$

$Y_S, \quad S=\frac{1}{2}, \quad I=\frac{3}{2}$

- $S=\frac{3}{2}, \quad I=\frac{1}{2}, \quad J=\frac{1}{2}, \frac{3}{2}, \frac{5}{2}$

$$I(J^\pi) = \frac{1}{2}(\frac{1}{2}^-), \frac{1}{2}(\frac{3}{2}^-), \frac{1}{2}(\frac{5}{2}^-)$$

- $S=\frac{1}{2}, \quad I=\frac{3}{2}, \quad J=\frac{1}{2}, \frac{3}{2}$

$$I(J^\pi) = \frac{3}{2}(\frac{1}{2}^-), \frac{3}{2}(\frac{3}{2}^-)$$

- $S=\frac{1}{2}, \quad I=\frac{1}{2}, \quad J=\frac{1}{2}, \frac{3}{2}$

$$I(J^\pi) = \frac{1}{2}(\frac{1}{2}^-), \frac{1}{2}(\frac{3}{2}^-)$$

symmetric (in spin part) has higher mass.