



"emc
pps-internal" — 2021/4/6 — 2:56 — page ii — #2







Chapter 1

Safe Features

sec-safe-cpp11 Intro text should be here.







Chapter 1 Safe Features

sec-safe-cpp14





Chapter 2

Conditionally Safe Features

sec-conditional Intro text should be here.



Variadic Templates

Chapter 2 Conditionally Safe Features

Variable-Argument-Count Templates

vavaadadicemphaaee

By Andrei Alexandrescu

Variadic templates provide language-level support for specifying templates that accept an arbitrary number of template arguments.

Description

std::string

description-variadic

Experience with C++03 revealed a recurring need to specify a class or function that accepts an arbitrary number of arguments. The C++03 workarounds often require considerable boilerplate and hardcoded limitations that impede usability. Consider, for example, a function concat taking zero or more const std::string&, const char*, or char arguments and returning an std::string that is the concatenation of that argument sequence:

One advantage of using a variadic function, such as **concat**, instead of repeatedly using the + operator is that the **concat** function can build the destination string exactly once, whereas each invocation of + creates and returns a new **std::string** object.

A simpler example is a variadic function, add, that calculates the sum of zero or more integer values supplied to it:

Historically, variadic functions, such as concat and add (above), were implemented as a suite of related non-variadic functions accepting progressively more arguments, up to some arbitrary limit (e.g., 20) chosen by the implementer:

```
int add();
int add(int);
int add(int, int);
int add(int, int, int);
// ...
// ... declarations from 4 to 19 int parameters elided
// ...
int add(int, int, int, /* 16 more int parameters elided, */ int);
```

4

Given the existence of an identity value (zero for addition), an alternative approach would be to have a single add function but with each of the parameters defaulted:

```
int add(int=0, int=0, /* 17 more defaulted parameters omitted */ int=0);
```

However, concat cannot use the same approach because each of its arguments may be a ${\tt char}$, a ${\tt const char^*}$, or an ${\tt std::string}$ (or types convertible thereto), and no single type accommodates all of these possibilities. To accept an arbitrary mix of arguments of the allowed types with maximal efficiency, the brute-force approach would require the definition of an exponential number of overloads taking any combination of ${\tt char}$, ${\tt const char^*}$, and ${\tt const std::string\&}$, again up to some implementation-chosen maximum number of parameters, N.

With such an approach, the number of required overloads is $O(3^N)$, which means that accommodating a maximum of just 5 arguments would require 283 overloads and 10 arguments would require 88,573 overloads! Defining a suite of N function templates instead is one approach to avoiding this combinatorial explosion of overloads:

Using conventional function templates, we can drastically reduce the volume of source code required, albeit with some manageable increase in implementation complexity.

Each of the N+1 templates can be written to accept any combination of its M arguments $(0 \le M \le N)$ such that each parameter will independently bind to a **const char***, an $\mathsf{std}::\mathsf{string}$, or a **char** with no unnecessary conversions or extra copies at run time. Of the exponentially many possible **concat** template instantiations, the compiler generates — on demand — only those overloads that are actually invoked.

With the introduction of variadic templates in C++11, we are now able to represent variadic functions such as add or concat with just a single template that expands automatically to accept any number of arguments of any appropriate types — all by, say, const lvalue reference:

¹The std::string_view standard library type introduced with C++17 would help here because it accepts conversion from both const char* and std::string and incurs no significant overhead. However, std::string_view cannot be initialized from a single char, so we'd be looking at $O(2^N)$ instead of $O(3^N)$ — not a dramatic improvement.



```
std::string

template <class... Ts>
std::string concat(const Ts&...);
    // Return a string that is the concatenation of a sequence of zero or
    // more character or string arguments --- each of potentially distinct
    // C++ type and passed by const lvalue reference.
```

A variadic function template will typically be implemented with **recursion** to the same function with fewer parameters. Such function templates will typically be accompanied by an overload (templated or not) that implements the lower limit, in our case, the overload having exactly zero parameters:

```
std::string concat();
   // Return an empty string ("") of length 0.
```

The non-template overload above declares **concat** taking no parameters. Importantly, this overload will be preferred for calls of **concat** with no arguments because it's a better match than the variadic declaration, even though the variadic declaration would also accept zero arguments.

Having to write just two overloads to support any number of arguments has clear advantages over writing dozens of overloaded templates: (1) there is no hard-coded limit on argument count, and (2) the source is dramatically smaller, more regular, and easier to maintain and extend — e.g., it would be easy to add support for efficiently passing by forwarding reference (see Section 2.1."??" on page ??). A second-order effect should be noted as well. The costs of defining variadic functions with C++03 technology are large enough to discourage such an approach in the first place, unless overwhelming efficiency motivation exists; with C++11, the low cost of defining variadics often makes them the simpler, better, and more efficient choice altogether.

Variadic class templates are another important motivating use case for this language feature.

A tuple is a generalization of std::pair that, instead of comprising just two objects, can store an arbitrary number of objects of heterogeneous types:

```
std::string
Tuple<int, double, std::string> tup1(1, 2.0, "three");
   // tup1 holds an int, a double, and an std::string
Tuple<int, int> tup2(42, 69);
   // tup2 holds two ints
```

Tuple provides a container for a specified set of types, in a manner similar to a **struct**, but without the inconvenience of needing to introduce a new **struct** definition with its own name. As shown in the example above, the tuples are also initialized correctly according to the specified types (e.g., tup2 contains two integers initialized, respectively, with 42 and 69).

In C++03, an approximation to a tuple could be improvised by composing an $\mathtt{std}:\mathtt{pair}$ with itself:

```
#include <utility> // std::pair
```

```
std::pair<int, std::pair<double, long>> v;
   // Define a holder of an int, a double, and an long, accessed as
   // v.first, v.second.first, and v.second.second, respectively.
```

Composite use of std:pair types could, in theory, be scaled to arbitrary depth; defining, initializing, and using such types, however, is not always practical. Another approach commonly used in C++03 and similar to the one suggested for the add function template above is to define a template class, e.g., Cpp03Tuple, having many parameters (e.g., 9), each defaulted to a special marker type (e.g., None), indicating that the parameter is not used:

Cpp03Tuple may be used to store, access, and modify up to 9 values together, e.g., Cpp03Tuple<int, int, std::string> would consist of two ints and an std::string.

Cpp03Tuple's implementation uses a variety of metaprogramming tricks to detect which of the 9 type slots are used. This is the approach taken by boost::tuple,² an industrial-strength tuple implemented using C++03-era technology. In contrast, the variadic-template-based declaration (and definition) of a modern C++ tuple is much simpler:

```
template <typename... Ts>
class Cpp11Tuple; // class template storing an arbitrary sequence of objects
```

C++11 introduced the standard library class template std::tuple, declared in a manner similar to Cpp11Tuple.

An std::tuple can be used, for example, to return multiple values from a function. Suppose we want to define a function, minAverageMax, that — given a range of double values — returns, along with its cardinality, its minimum, average, and maximum values. The interface for such a function in C++03 might have involved multiple output parameters passed, e.g., by non**const** lvalue reference:

Alternatively, one could have define a separate **struct** (e.g., MinAverageMaxRes) and incorporate that into the interface of the minAverageMax function:

 $^{^2} https://github.com/boostorg/tuple/blob/develop/include/boost/tuple/tuple.hpp\\$



```
#include <cstddef> // std::size_t

struct MinAverageMaxRes // used in conjunction with minAverageMax (below)
{
    std::size_t count; // number of input values
    double min; // minimum value
    double average; // average value
    double max; // maximum value
};

template <typename Iterator>
MinAverageMaxRes minAverageMax(Iterator b, Iterator e);
```

Adding a helper **aggregate** such as **MinAverageMax** (above) works but demands a fair amount of boilerplate coding that might not be reusable or otherwise worth naming. The C++11 library abstraction **std::tuple** allows code to define such simple aggregates "on the fly" (as needed):

We can now use our minAverageMax function to extract the relevant fields from a vector of double values:

Note that elements in a tuple are accessed in a numerically indexed manner (beginning with slot 0) using the standard function template std::get for both reading and writing.

There are other motivating uses of variadic templates, such as allowing generic code to forward arguments to other functions, notably constructors, without the need to know in advance the number of arguments required. Related artifacts added to the C++ standard library include std::make_shared, std::make_unique, and the emplace_back member

function of std::vector (see *Use Cases* — ?? on page ?? [AUs: There is no subsection called "Factory functions." Did you mean the Object factories section?]).

There is a lot to unpack here. We will begin our journey by understanding variadic class templates as **generic types** that provide a solid basis for understanding variadic function templates. In practice, however, variadic function templates are arguably more frequently applicable outside of advanced metaprogramming; see Variadic function templates on page 18.

Variadic-class-templates

Suppose we want to create a class template C that can take zero or more template type arguments. C++11 introduces new syntax — based on the ellipsis (...) token — that supports such variadic parameter lists:

```
template <typename... Ts> class C;
  // The class template C can be instantiated with a sequence of zero or
  // more template arguments of arbitrary type. Because this is only a
  // declaration, the parameter name, Ts (for "types"), isn't used.
```

The declaration above introduces a class template C that can accept an arbitrary sequence of type parameters optionally represented here (for documentation purposes) by the identifier Ts (for "Types").

First we point out that the ellipsis (...), just like ++ or ==, is parsed as a separate token; hence, any whitespace around the ellipsis is optional. The common style, and the one used in the C++ Standard documents, follows the typographic convention in written prose: ... abuts to the left and is followed by a single space as in the declaration of C above.

Whether we use **typename** (as we do throughout this book) or **class** to introduce a **template type parameter** is entirely a matter of style:

```
template <typename... Ts> class C;  // style used throughout this book
template <class... Ts> class C;  // style used in the C++ Standard
```

Note that, as with non-variadic template parameters, providing a name to represent the supplied template "parameters" (a.k.a. template parameter pack, see below) is optional:

When an ellipsis token (...) appears *after* **typename** or **class** and before the optional type-parameter name (e.g., Ts), it introduces a template parameter pack:

```
template <typename... Ts> // Ts names a template parameter pack.
class C;
```

We call entities such as Ts template parameter packs (as opposed to parameter packs) to distinguish them from function parameter packs (see Variadic function templates on page 18), non-type parameter packs (see ?? on page ?? [AUs: There is no section called "Non-type parameter packs"]), and template template parameter packs (see ?? on page ?? [AUs: There is no section called "Template template parameter packs"]). The phrase parameter pack is a conflation of the four and also a casual reference to either of them whenever there is no ambiguity.

Variadic Templates

Chapter 2 Conditionally Safe Features

This syntactic form of . . . is used primarily in **declarations** (including those associated with **definitions**):

```
template <typename... Ts>
class C { /*...*/ }; // definition of class C
```

The same ... token, when it appears to the right of an existing template parameter pack (e.g., Ts), is used to unpack it:

In the example above, the *unpacking* results in a comma-separated list of the types with which C was instantiated. The . . . token is used after the template parameter pack name Ts to recreate the sequence of arguments originally passed to the instantiation of C. Referring to our example above, we might choose to create an object, X, of type C < int > :

```
C<int> x; // has data member, d_data, of type std::vector<int>
```

We might, instead, consider creating an object, y, that also passes std::allocator<char> to C's instantiation:

```
C<char, std::allocator<char>> y;
    // y.d_data has type std::vector<char, std::allocator<char>>.
```

And so on. That is, **class** C can be instantiated with any sequence of types that is supported by the d_data member variable.

An instantiation such as C<float, double> would correspondingly attempt to instantiate std::vector<float, double>, which is in error and would cause the instantiation of C to fail. Several other cases and patterns of *unpacking* of template parameter packs exist and are described in detail in *Template parameter packs* on page 32.

Continuing our pedagogical discussion, let's **define** an empty variadic class template, D:

```
template <typename...> class D { }; // empty variadic-class-template definition
```

We can now create explicit instantiations of class template D by providing it with any number of type arguments:

```
D<> d0; // instantiation of D with no type arguments
D<int> d1; // instantiation of D with a single int argument
D<int, int> d2; // instantiation of D with two int arguments
D<int, const int> d3; // Note that d3 is a distinct type from d2.
D<double, char> d4; // instantiation of D with a double and char
D<char, double> d5; // Note that d5 is a distinct type from d4.
D<D<>>, D<int>> d6; // instantiation of D with two UDT arguments
```

The number and order of arguments are part of the instantiated type, so each of the objects $d\theta$ through $d\theta$ above has a distinct C++ type:

The sections that follow examine in full detail how to

- declare variadic *class* and *function* templates using parameter packs
- make use of variadic argument lists in the implementation of class definitions and function bodies

Template parameter packs

emplate-parameter-packs

A template parameter pack is the name representing a list of zero or more parameters following class... or typename... within a variadic template declaration.

Let's take a closer look at just the *declaration* of a variadic class template, C:

```
template <typename... Ts> class C { };
```

Here, the identifier Ts names a template parameter pack, which — as we saw previously — can bind to any sequence of explicitly supplied types including the empty sequence:

```
C<> c0; // OK, instantiation of C with no type arguments C<int> c1; // OK, instantiation of C with a single int argument C<float, bool> c2; // OK, instantiation of C with two type arguments
```

Passing an argument to C that is not a type, however, is not permitted:

Template parameter packs can appear together with simple template parameters, with one restriction: Primary class template declarations allow at most one variadic parameter pack at the end of the template parameter list. (Recall that in standard C++ terminology, the primary declaration of a class template is the first declaration introducing the template's name; all specializations and partial specializations of a class template require the presence of a primary declaration.)

```
template <typename... Ts>
class C0 { };  // OK

template <typename T, typename... Ts>
class C1 { };  // OK

template <typename T, typename U, typename... Ts>
class C2 { };  // OK
```



```
template <typename... Ts, typename... Us>
class Cx0 { }; // Error, more than one parameter pack

template <typename... Ts, typename T>
class Cx1 { }; // Error, parameter pack must be the last template parameter
```

There is no way to specify a default for a parameter pack; however a parameter pack can follow a defaulted parameter:

What can we do with a template parameter pack? Template parameter packs are of a so-called kind distinct from other C++ entities. They are not types, values, or anything else found in C++03. As such, parameter packs are not subject to any of the usual operations one might expect:

There is no way to use a parameter pack in unexpanded form. Once introduced, the name of a parameter pack can occur only as part of a **pack expansion**. We've already encountered the simple **pack expansion** Ts..., which expands to the list of types to which Ts is bound. That expansion is only allowed in certain contexts where multiple values would be allowed:

12

Note that the code above remains invalid even if Ts contains a single type, e.g., in the instantiation C<int>. Pack expansion is not textual and not allowed everywhere; it is allowed only in certain well-defined contexts. The first such context, as showcased with the member variable next in the code example above, is inside a template argument list. Note how the pattern may be surrounded by other parameters or expansions:

```
#include <map> // std::map
template <typename... Ts>
class C
    void arbitraryMemberFunction()
                                       // for illustration purposes
                                  v0; // OK, same type as *this
        C<Ts...>
        C<int, Ts...>
                                  v1; // OK, expand after another argument
        C<Ts..., char>
                                  v2; // OK, expand before another argument
        C<char, Ts..., int>
                                  v3; // OK, expand in between
        C<void, Ts..., Ts...>
                                  v4; // OK, two expansions
        C<char, Ts..., int, Ts...> v5; // OK, no need for them to be adjacent
                                  v6; // OK, expansion nested within
        C<void, C<Ts...>, int>
        C<Ts..., C<Ts...>, Ts...> v7; // OK, mix of expansions
        std::map<Ts...>
                                  v8; // OK, works with non-variadic template
    }
};
```

The examples above illustrate how pack expansion is not done textually, like a macro expanded by the C preprocessor. A simple textual expansion of C<char, Ts..., int> would be C<char, int> if Ts were empty (i.e., inside the instantiation C<>). Parameter pack expansion is syntactic and "knows" to eliminate any spurious commas, caused by the expansion of empty parameter packs.

Within the context of a template argument list, Ts... is not the only pattern that can be expanded; any template instantiation using Ts (e.g. C<Ts>...) can be expanded as a unit. The result is a list of template instantiations using each of the types in Ts, in turn. Note that, in the example below, the expansions C<Ts...> and C<Ts>... are both valid but produce different results:



The second important parameter pack expansion context for type parameter packs is in a base specifier list. All patterns that form a valid base specifier are allowed:

```
template <typename... Ts>  // zero or more arguments
class D1 : public Ts...  // publicly inherit T0, T1, ...
{ /*...*/ };

template <typename... Ts>
class D2 : public D<Ts>...  // publicly inherit D<T0>, D<T1>, ...
{ /*...*/ };

template <typename... Ts>
class D3 : public D<Ts...>  // publicly inherit D<T0, T1, ...>
{ /*...*/ };
```

The access control specifiers — public, protected, and private — can be applied as usual, though, within a single expansion pattern, the access specifier must be the same for all expanded elements:

```
template <typename... Ts>
class D4 : private Ts... // privately inherit T0, T1, ...
{ /*...*/ };

template <typename... Ts>
class D5 : public Ts..., private D<int, Ts>...
    // publicly inherit T0, T1, ...
    // and privately inherit D<int, T0>, D<int, T1>, ...
{ /*...*/ };
```

Pack expansions can be freely mixed with simple base specifiers:

```
class AClass1 { /*...*/ }; // arbitrary class definition
class AClass2 { /*...*/ }; // arbitrary class definition

template <typename... Ts>
class D6 : protected AClass1, public Ts... // OK
{ /*...*/ };

template <typename... Ts>
class D7 : protected AClass1, private Ts..., public AClass2 // OK
{ /*...*/ };
```

If the parameter pack being expanded (e.g., Ts, in the code snippet above) is empty, the expansion does not introduce any base class. Notice, again, how the expansion mechanism is semantic, not textual, e.g., in the instantiation D7<> the fragment private Ts..., disappears entirely, leaving D7<> with AClass1 as a protected base and AClass2 as a public base.

To recap, the two essential parameter expansion contexts for template parameter packs are inside a template argument list and in a base specifier list.

او

Specialization of variadic class templates

Recall from prior to C++11 that after a class template is introduced by a primary class template declaration, it is possible to create specializations and partial specializations of that class template. We can declare specializations of a variadic class template by supplying zero or more arguments to its parameter pack:

```
template <typename... Ts> class C0; // primary class template declaration

template <> class C0<>; // specialize C0 for Ts=<>
template <> class C0<int>; // specialize C0 for Ts=<int>
template <> class C0<int, void>; // specialize C0 for Ts=<int, void>
```

Similar specializations can be applied to class templates that have other template parameters preceding the template parameter pack. The nonpack template parameters must be matched exactly by the arguments, followed by zero or more arguments for the parameter pack:

Partial specializations of a class template may take multiple parameter packs because some of the types involved in the partial specialization may themselves use parameter packs. Consider, for example, a variadic class template, Tuple, defined as having exactly one parameter pack:

```
template <typename... Ts> class Tuple // variadic class template \{ \ /^* \dots */ \ \};
```

Further assume a primary declaration of a variadic class template , C2, also having one type parameter pack. We also introduce definitions in addition to declarations so we can instantiate C2 later:

```
template <typename... Ts> class C2
    // (0) primary declaration of variadic class template C2
{ /*...*/ };
```

This simple setup allows a variety of partial specializations. First, we can partially specialize C2 for exactly two Tuples instantiated with the same exact types:

```
template <typename... Ts>
class C2<Tuple<Ts...>, Tuple<Ts...>> // (1) two identical Tuples
{ /*...*/ };
```

We can also partially specialize C2 for exactly two Tuples but with potentially different type arguments:

```
template <typename... Ts, typename... Us> class C2<Tuple<Ts...>, Tuple<Us...>> // (2) any two Tuples { /*...*/ };
```



Furthermore, we can partially specialize C2 for any Tuple followed by zero or more types:

```
template <typename... Ts, typename... Us> class C2<Tuple<Ts...>, Us...> // (3) any Tuple followed by 0 or more types \{\ /^*...^*/\ \};
```

The possibilities are endless; let us show one more partial specialization of C2 with three template parameter packs that will match two arbitrary Tuples followed by zero or more arguments:

```
template <typename... Ts, typename... Us, typename... Vs>
class C2<Tuple<Ts...>, Tuple<Us...>, Vs...>
    // (4) Specialize C2 for Tuple<Ts...> in the first position,
    // Tuple<Us...> in the second position, followed by zero or more
    // arguments.
{ /*...*/ };
```

Now that we have definitions for the primary template C2 and four partial specializations of it, let's take a look at a few variable definitions that instantiate C2. Partial ordering of class template specializations³ will decide the best match for each instantiation and also deduce the appropriate template parameters:

Notice how partial ordering chooses (2) instead of (4) for the definition of c2c, although both (2) and (4) are a match; a matching non-variadic template is always a better match than one involving deduction of a parameter pack.

Even in a partial specialization, if a template argument of the specialization is a pack expansion, it must be in the last position:

```
template <typename... Ts>
class C2<Ts..., int>;
    // Error, template argument int can't follow pack expansion Ts....

template <typename... Ts>
class C2<Tuple<Ts>..., int>;
    // Error, template argument int can't follow pack expansion Tuple<Ts>....

template <typename... Ts>
class C2<Tuple<Ts...>, int>;
    // OK, pack expansion Ts... is inside another template.
```

Parameter packs are a terse and very flexible placeholder for defining partial specialization — a "zero or more types fit here" wildcard. The primary class template does not even need to be variadic. Consider, for example, a non-variadic class template, Map, fashioned after the std::map class template:

³?, section 14.5.5.2, "Partial ordering of class template specializations," [temp.class.order], pp. 339–340.

```
template <class Key, class Value> class Map; // similar to std::map
```

We would then want to partially specialize another non-variadic class template, C3, for all maps, regardless of keys and values:

```
template <typename T> class C3; // (1) primary declaration; C3 not variadic
template <typename K, typename V>
class C3<Map<K, V>>;
    // (2a) Specialize C3 for all Maps, C++03 style.
```

Variadics offer a terser, more flexible alternative:

```
template <typename... Ts>
class C3<Map<Ts...>>;
    // (2b) Specialize C3 for all Maps, variadic style.
    // Note: Map works with pack expansion even though it's not variadic.
```

The most important advantage of (2b) over (2a) is flexibility. In maintenance, Map may acquire additional template parameters, such as a predicate and an allocator. This requires surgery on C3's specialization (2a), whereas (2b) will continue to work unchanged because Map<Ts...> will accommodate any additional template parameters Map may have.

An application must use either the non-variadic (2a) or the variadic (2b) partial specialization but not both. If both are present, (2a) is always preferred because an exact match is always more specialized than one that deduces a parameter pack.

Variadic alias templates

Alias templates (since C++11) are a new way to associate a name with a family of types without needing to define forwarding glue code. For full details on the topic, see Section 1.1."??" on page ??. Here, we focus on the applicability of template parameter packs to alias templates.

Consider, for example, the Tuple artifact — briefly discussed in Description — that can store an arbitrary number of objects of heterogeneous types:

```
template <typename... Ts> class Tuple; // declare Tuple
```

Suppose we want to build a simple abstraction on top of Tuple — a "named tuple" that has an std::string as its first element, followed by anything a Tuple may store:

```
#include <string> // std::string

template <typename... Ts>
using NamedTuple = Tuple<std::string, Ts...>;
    // introduce alias for Tuple of std::string and anything
```

In general, alias templates take template parameter packs following the same rules as primary class template declaration: An alias template may be defined to take at most one template parameter pack in the last position. Alias templates do not support specialization or partial specialization.

ariadic-alias-templates

17

Variadic Templates

Chapter 2 Conditionally Safe Features

ic-function-templates

Variadic function templates

The simplest example of a variadic function template accepts a template parameter pack in its template parameters list but does not use any of its template parameters in its parameter declaration:

```
template <class... Ts>
int f0a();    // does not use Ts in parameter list

template <class... Ts>
int f0b(int);    // uses int but not Ts in parameter list

template <class T, class... Ts>
int f0c();    // does not use T or Ts in parameter list
```

The only way to call the functions shown in the code snippet above is by passing them template argument lists explicitly:

```
int a1 = f0a<int, char, int>();  // Ts=<int, char, int>
int a2 = f0b<double, void>(42);  // Ts=<double, void>
int a3 = f0c<int, void, int>();  // T=int, Ts=<void, int>
int e1 = f0a();  // Error, cannot deduce Ts
int e2 = f0b(42);  // Error, cannot deduce Ts
int e3 = f0c();  // Error, cannot deduce T and Ts
```

The notation f0a<int, char, int>() means to explicitly instantiate template function f0a with the specified type arguments and to call that instantiation.

Invoking any of the instantiations shown above will, of course, require that the corresponding definition of the function template exists somewhere within the program:

```
template <typename...> void f0a() { /*...*/ } // variadic template definition
```

This definition will typically be part of or reside alongside its declaration in the same header or source file, but see Section 2.1."??" on page ??.

Such functions are rarely encountered in practice; most of the time a template function would use its template parameters in the function parameter list. They have only pedagogical value; as the joke goes, the keys were lost in the living room but we're looking for them in the hallway because the light is better. To take a look in the living room, let's now consider a different kind of variadic function template — one that not only accepts an arbitrary number of template arguments, but also accepts an arbitrary number of function arguments working in tandem with the template arguments.

ction-parameter-packs

Function parameter packs

The syntax for declaring a variadic function template that accepts an arbitrary number of function arguments makes two distinct uses of the ellipsis (...) token. The first use is to introduce the template parameter pack Ts, as already shown. Then, to make the argument list of a function template variadic, we introduce a function parameter pack by placing the ... to the left of the function parameter name:

```
template <typename... Ts> // template parameter pack Ts
```

```
int f1a(Ts... values);  // function parameter pack values
  // f1a is a variadic function template taking an arbitrary sequence of
  // function arguments by value (explanation follows), each independently of
  // arbitrary heterogeneous type.
```

A function parameter pack is a function parameter that accepts zero or more function arguments. Syntactically, a function parameter pack is similar to a regular function parameter declaration, with two distinctions:

- The type in the declaration contains at least one template parameter pack
- The ellipsis . . . is inserted right before the function parameter name, if present, or replaces the parameter name, if absent

Therefore, the declaration of fla above has a template parameter pack Ts and a function parameter pack values. The function parameter declaration Ts... values indicates that values may accept zero or more arguments of various types, all by value. Replacing the parameter declaration with const Ts&... values would result in pass by const reference. Just as with non-variadic function templates, variadic template parameter lists are permitted to include any legal combination of qualifiers (const and volatile) and declarator operators (i.e. pointer *, reference &, forwarding reference &&, and array []):

```
template <typename... Ts> void f1b(Ts&...);
  // accepts any number and types of arguments by reference

template <typename... Ts> void f1c(const Ts&...);
  // accepts any number and types of arguments by reference to const

template <typename... Ts> void f1d(Ts* const*...);
  // accepts any number and types of arguments by pointer to const
  // pointer to nonconst object

template <typename... Ts> void f1e(Ts&&...);
  // accepts any number and types of arguments by forwarding reference

template <typename... Ts> void f1f(const volatile Ts*&...);
  // accepts any number and types of arguments by reference to pointer to
  // const volatile objects
```

To best understand the syntax of variadic template declarations, it is important to distinguish the distinct — and indeed complementary — roles of the two occurrences of the . . . token. First, as discussed in *Template parameter packs* on page 32, **typename**... Ts introduces a template parameter pack called Ts that matches an arbitrary sequence of types. The second use of . . . is, instead, a pack expansion that transforms the pattern — whether it's Ts..., const Ts&..., Ts* const*... etc, — into a comma-separated parameter list for the function, where the C++ type of each successive parameter is determined by the corresponding type in Ts. The resulting construct is a function parameter pack.

Conceptually, a single variadic template function declaration can be thought of as a multitude of similar declarations with zero, one,... parameters fashioned after the variadic declaration:



```
template <typename... Ts> void f1c(const Ts&...);
    // variadic, any number of arguments, any types, all by const &
void f1c();
    // pseudo-equivalent for variadic f1c called with 0 arguments

template <typename T0> void f1c(const T0&);
    // pseudo-equivalent for variadic f1c called with 1 argument

template <typename T0, typename T1>
void f1c(const T0&, const T1&);
    // pseudo-equivalent for variadic f1c called with 2 arguments

template <typename T0, typename T1, typename T2>
void f1c(const T0&, const T1&, const T2&);
    // pseudo-equivalent for variadic f1c called with 3 arguments

/* ... and so on ad infinitum ... */
```

A good intuitive model would be that the pack expansion in the function parameter list is like an "elastic" list of parameter declarations that expands or shrinks appropriately. Note that the types in a parameter pack may all be different from one another, but their qualifiers (const and/or volatile) and declarator operators (i.e. pointer *, reference &, rvalue reference &&, and array []) are the same.

The name of the pack may be missing from the declaration, which, combined with the parameter declaration syntax coming all the way from C, does allow for some obscure constructs:

```
template<typename... Ts> void fpf(Ts (*...)(int));
    // mystery declaration
```

To read such a declaration, add a name, keeping in mind that the . . . in a function parameter pack always comes immediately to the left of where the name would be:

```
template <typename... Ts> void fpf(Ts (*...pFunctions)(int));
   // Aha, the function parameter pack is pFunctions!
   // The function fpf takes zero or more pointers to functions taking one
   // int, each returning some arbitrary type.
```

A variadic function template may take additional template parameters as well as additional function parameters:

```
template <typename... Ts> void f2a(int, Ts...);
    // one int followed by zero or more arbitrary arguments by const &

template <typename T, typename... Ts> void f2b(T, const Ts&...);
    // first by value, zero or more by const &

template <typename T, typename U, typename... Ts> void f2c(T, const U&, Ts...);
    // first by value, second by const &, zero or more by value
```

There are restrictions on such declarations; see *The Rule of Greedy Matching* on page 25 and *The Rule of Fair Matching* on page 27.

Note that inside the function parameters declaration, . . . can be used only in conjunction with a template parameter pack. Attempting to use . . . where there's no parameter pack to expand could lead to inadvertent use of the old C-style variadics:

Such a mistake may be caused by a simple typo in the declaration of oops, leading to a variety of puzzling compile-time or link-time errors; see *Potential Pitfalls* — *Accidental use* of *C-style ellipsis* on page 73.

It is possible to use the parameter pack name (e.g., Ts) as a parameter to a user-defined type:

```
template <typename> struct S1; // declaration only

template <typename... Ts> // parameter pack named Ts
int fs1(S1<Ts>...);
    // **Pack expansion** for explicit instantiation of S1 accepts any number of
    // independent explicit instantiations of S1 by value.
```

The parameter pack name Ts acts as though it were a separate type parameter for each function argument, thereby allowing a different instantiation for S1 at each parameter position. To invoke fs1 on arguments of user-defined type S1, however, S1 will need to be a **complete type** — i.e., its definition must precede the point of invocation of the function in the current translation unit:

More complex setups are possible as well. For example, we can write a variadic function template that operates on instantiations of user-defined-type templates that take two independent type parameters:

Variadic Templates

Chapter 2 Conditionally Safe Features

Calls to fs2 work only if we supply instantiations of S2 having the same type for both template parameters:

The problem with the last two calls above is that the instantiations S2<char, int> and S2<char, const char> violate the requirement that the two types in the instantiation of S2 are identical, so there is no way to provide or deduce some Ts in a way that would make the call work.

adic-member-functions

Variadic member functions

Member functions may be variadic in two orthogonal ways: The class they are part of may be variadic, and they may be variadic themselves. The simplest case features a variadic member function of a non-template class:

Expectedly, a non-variadic class template may declare variadic member functions as well:

A variadic class template may define regular member functions, member functions that take their own template parameters, and variadic member function templates:

```
template <class... Us>
  int f3(Us...); // variadic template member function of variadic class
};

int s5a = S5<int, char>().f1();
  // Ts=<int, char>

int s5b = S5<char, int>().f2(2.2);
  // Ts=<int, char>, T=double

int s5c = S5<int, char>().f3(1, 2.2);
  // Ts=<int, char>, Us=<int, double>
```

Although in a sense all member functions of a variadic class template (e.g., \$5, above) are variadic, the class's template parameter pack (e.g., Ts, above) is fixed at the time the class is instantiated. The only truly variadic function is f3 because it takes its own template parameter pack, Us.

A member function of a variadic class may use the template parameter pack of the class in which it is defined:

```
template <class... Ts>
struct S6
                           // variadic class template
{
    int f1(const Ts&...); // OK, not truly variadic; Ts is fixed
    template <class T>
    int f2(T, Ts...);
                          // OK, also not truly variadic; Ts is fixed
    template <class... Us>
    int f3(Ts..., Us...); // OK, variadic template member function
};
int s6a = S6<int, char>().f1(1, 'a');
    // Ts=<int, char>
int s6b = S6<char, int>().f2(true, 'b', 2);
    // Ts=<int, char>, T=bool
int s6c = S6<int, char>().f3(1, 2.2, "asd", 123.456);
    // Ts=<int, char>, Us=<const char*, int, double>
```

Notice how, in the initialization of s6c, the type arguments Ts of class template S6 must be chosen explicitly, whereas the variadic template f3 need not have Us specified because they are deduced from the argument types. This takes us to the important topic of template argument deduction.

Template argument deduction

Late-argument-deduction

A popular feature of C++ ever since templates were incorporated into the language prestandardization has been the ability of function templates to determine their template argu-



ments from the types of arguments provided. Consider, for example, designing and using a function, print, that outputs its argument to the console. In most cases, just letting print deduce its template argument from the function argument's type has brevity, correctness, and efficiency advantages:

```
#include <string> // std::string

template <class T> void print(const T& value); // prints x to stdout

void testPrint0(const std::string& s)
{
    print<const char*>("Hi");
        // verbose: specifies template argument *and* function argument
        // redundant: function argument's type *is* the template argument

print<int>(3.14);
        // Error-prone: Mismatch may cause incorrect results (prints 3).

print<std::string>("Oops");
        // inefficient: may incur additional expensive implicit conversions

print("Hi");
    print(3.14);
    print(s);
        // all good: let print deduce template argument from function argument
}
```

What makes the shorter form of the call work is the magic of C++ template argument deduction, which, unsurprisingly, works with variadic template parameters as well. A detailed description of all rules for template argument deduction, including those inherited from C++03, is outside the scope of this book.⁴ Here, we focus on the additions to the rules brought about by variadic function templates.

With that in mind, imagine we set out to redesign the API of print (in the code example above) to output any number of arguments to the console:

⁴Please insert a cite to Scott Meyers' "Effective Modern C++" (which is already in your bib file), with the addition: Chapter 1: "Deducing Types", pages 9–35. [AUs: We have several editions of the Meyers book in our bib; which one did you intend?]

The compiler will independently deduce each type in Ts from the respective types of the function's argument values:

As shown in the first line of test2 (above), a template parameter pack may be specified in its entirety when instantiating a function template:

Interestingly, we can specify only the first few types of the template parameter pack and let the others be deduced, mixing together explicit template argument specification and template argument deduction:

Such a mix of explicit and implicit may be interesting but is not new; it has been the case for function templates since C++ was first standardized. The new element here is that we get to specify a fragment of a template parameter pack.

In the general case, a function may mix template parameter packs with other template parameters in a variety of ways. It may also mix function parameter packs with other function parameters in a variety of ways.

The Rule of Greedy Matching

The Rule of Greedy Matching for template parameter packs (but not function parameter packs) states that once a template parameter pack starts matching one explicitly specified template argument, it also matches all template arguments following it. There's no way to tell a template parameter pack it matched enough. Template parameter packs are greedy.

Consequently, there is no syntactic way to explicitly specify any template argument following one that matches a template parameter pack; the first pack gobbles all remaining

rule-of-greedy-matching

25



arguments up. Put succinctly: all template parameters following a template parameter pack can *never* be explicitly specified as template arguments.

Notice that the rule applies only once a pack starts matching, i.e., it has matched at least one item; indeed there are a few legitimate cases in which a parameter list makes no match at all, which we'll discuss soon.

Using the Rule of Greedy Matching allows us to navigate with relative ease a variety of combinations of pack and nonpack template parameters.

In the simplest and overwhelmingly most frequently encountered situation, the function takes one template parameter pack and one function parameter pack, both in the last position:

```
template <typename T1, typename T2, typename... Ts> // ... in last position int f1(T1, T2, const Ts&...); // ... in last position
```

In such cases, the Rule of Greedy Matching doesn't need to kick in because there are no parameters following a pack. Template argument deduction can be used for all of T1, T2, and Ts or for only for a subset. In the simplest case, no template parameters are specified and template argument deduction is used for all:

```
int x1a = f1(42, 2.2, 'a', true);
    // T1=int, T2=double, Ts=<char, bool> (all deduced)
```

Explicitly specified template arguments, if any, will match template parameters in the order in which they are declared. Therefore, if we specify one type, it binds to T1:

```
int x1b = f1<double>(42, 2.2, 'a', true);
    // T1=double (explicitly), T2=double (deduced), Ts=<char, bool> (deduced)
```

If we specify two types, they will bind to T1 and T2 in that order:

```
int x1c = f1<double, char>(42, 65, "abc", true);
    // T1=double (explicitly), T2=char (explicitly),
    // Ts=<const char*, bool> (deduced)
```

Note how, in the two examples above, we also have implicit conversions going on, i.e., 42 is converted to **double** and 65 is converted to **char**. Furthermore, a call may specify T1, T2, and the entirety of Ts:

```
int x1d = f1<const char*, char, bool, double>("abc", 'a', true, 42U);
   // T1=const char* (explicitly), T2=char (explicitly),
   // Ts=<bool, unsigned> (explicitly)
```

Last but not least, as mentioned, a call may specify T1, T2, and only the first few types in Ts:

```
int x1e = f1<const char*, char, bool, double>("abc", 'a', true, 42, 'a', 0);
    // T1=const char* (explicitly), T2=char (explicitly),
    // Ts=<bool, int, char, int> (first two explicit, others deduced)
```

Let us now look at a function having a template parameter pack not in the last position. However, in the argument list, the function parameter pack is still in the last position:

```
template <typename T, typename... Ts, typename U> // ... not last int f2(T, U, const Ts&...);
```

In such cases, by the Rule of Greedy Matching, there is no way to specify U explicitly, so the only way to call f1 is to let U be deduced:

```
int x2a = f2(1, 2);
    // T=int (deduced), U=int (deduced), Ts=<> (by arity)

int x2b = f2<long>(1, 2, 3);
    // T=long (explicit), U=int (deduced), Ts=<int> (deduced)
```

The first template argument passed to f2, if any, is matched by T. Note that inferring the empty template parameter pack in the initialization of x2a does not involve deduction; the empty length is inferred by the arity of the call. In contrast, in the initialization of x2b, a pack of length 1 is deduced.

Any subsequent template arguments will be matched *en masse* by Ts in concordance with the Rule of Greedy Matching:

```
int x2c = f2<long, double, char>(1, 2, 3, 4);
    // T1=long (explicit), T2=int (deduced), Ts=<double, char> (explicit)
int x2d = f2<int, double>(1, 2, 3.0, "four");
    // T1=int (explicit), T2=int (deduced), Ts=<double, const char*> (partially specified)
int x2e = f2<int, char, double>(1, 3.0, 'a');
    // Error, no viable function for T1=int and Ts=<char, double>
```

In all cases, T2 must be deduced for the call to f2 to go through.

Another way to make a template parameter work even if it's positioned after a parameter pack is by assigning it a default argument:

```
template <typename... Ts, typename T = int>
T f3(Ts... values);
```

Due to the way f3 is defined, there is no way to either deduce or specify T, so it will always be int:

```
int x3a = f3("one", 2);
    // Ts=<const char*, int> (deduced), T=int (default)

int x3b = f3<const char*>("one", 2);
    // Ts=<const char*, int> (partially deduced), T=int (default)

int x3c = f3<const char*, int>("one", 2);
    // Ts=<const char*, int> (explicit), T=int (default)
```

____The Rule of Fair Matching

To further explore the varied ways in which parameter packs may interact with the rest of C++, let's take a look at a function that has a type following a template parameter pack and also a value following a function parameter pack:

```
template <typename... Ts, typename T>
int f4(Ts... values, T value);
```

27



Here, a new rule applies, the Rule of Fair Matching, which is to a good extent the converse of the Rule of Greedy Matching. When a function parameter pack (e.g., values in the code snippet above) is *not* at the end of a function's parameter list, its corresponding type parameter pack (e.g., Ts above) cannot be deduced ever.

This rule makes the function parameter pack values fair because function parameters following a function parameter pack have a chance to match function arguments.

Let's take a look at how the rule applies to f4. In calls with one argument, Ts is not deduced, so it forcibly matches the empty list, and T matches the type of the argument:

```
int x4a = f4(123);  // Ts=<> (forced non-deduced), T=int
int x4b = f4('a');  // Ts=<> (forced non-deduced), T=char
int x4c = f4('a', 2);  // Error, cannot deduce Ts
```

Calls with more than one argument can be made if and only if we provide Ts to the compiler explicitly:

```
int x4d = f4<int, char>(1, '2', "three");
    // Ts=<int, char> (explicit), T=const char*
```

Incidentally, for f4 there is no way to specify T explicitly because of the Rule of Greedy Matching:

```
int x4e = f4<int, char, const char*>(1, '2', "three");
   // Error, Ts=<int, char, const char*> (explicit), no argument for T value
```

Note that the two rules may work simultaneously on the same function call; they do not compete because they apply in different places; the Rule of Greedy Matching applies to template parameter packs, and the Rule of Fair Matching applies to function parameter packs.

Let's now consider declaring a function with two consecutive parameter packs and see how the rules work together in calls:

```
template <typename... Ts, typename... Us> // two template parameter packs
int f5(Ts... ts, Us... us); // two function parameter packs
```

By the Rule of Greedy Matching, we cannot specify Us explicitly so us will rely on deduction exclusively. By the Rule of Fair Matching, Ts cannot be deduced. First, let's analyze a call with no template arguments:

```
int x5a = f5(1);
    // Ts=<> (forcibly), Us=<int>

int x5b = f5(1, '2');
    // Ts=<> (forcibly), Us=<int, char>

int x5c = f5(1, '2', "three");
    // Ts=<> (forcibly), Us=<int, char, const char*>
```

Whenever a call specifies no **template arguments**, Ts cannot be deduced so it can at best match the empty list. That leaves all of the arguments to us, and deduction will work as expected for Us. This right-to-left matching may surprise at first and requires close reading of different parts of the C++ Standard but is easy to explain by using the two rules.

Let's now issue a call that does specify template arguments:

```
int x5d = f5<int, char>(1, '2');
    // Ts=<int, char> (explicitly), Us=<const char*>
int x5e = f5<int, char>(1, '2', "three");
    // Ts=<int, char> (explicitly), Us=<const char*>
int x5f = f5<int, char>(1, '2', "three", 4.0);
    // Ts=<int, char> (explicitly), Us=<const char*, double>
```

By the Rule of Greedy Matching, all explicit template arguments go to Ts, and, by the Rule of Fair Matching, there's no deduction for Ts, so, even before looking at the function arguments, we know that Ts is exactly <int, char>. From here on, it's easy: The first two arguments go to ts, and all others, if any, will go to us.

Corner cases of function template argument matching

There are cases in which a template function could be written that can never be called, whether with explicit template parameters or by relying on template argument deduction:

```
template <typename... Ts, typename T>
void odd1(Ts... values);
```

late-argument-matching

By the Rule of Greedy Matching applied to Ts, T can never be specified explicitly. Moreover, T cannot be deduced either because it's not part of the function's parameter list. Hence, odd1 is impossible to call. According to standard C++, such function declarations are ill formed, no diagnostic required (IFNDR). Current compilers do allow such functions to be defined without a warning. However, any conforming compiler will disallow any attempt to call such an ill-fated function.

Another scenario is one whereby a variadic function can be instantiated, but one or more of its parameter packs must always have length zero:

```
template <typename... Ts, typename... Us, class T>
int odd2(Ts..., Us..., T); // specious
```

Any attempt to call odd2 by relying on only template argument deduction will force both Ts and Us to the empty list because, by the Rule of Fair Matching, neither Ts nor Us can benefit from template argument deduction. So calls with two, three, or more arguments fail:

```
int x2a = odd2(1, 2.5); // Error, Ts=<>, Us=<>, too many arguments int x2a = odd2(1, 2.5, "three"); // Error, Ts=<>, Us=<>, too many arguments
```

However, there seem to be ways to invoke odd2, at least on contemporary compilers. First, calls using deduction with exactly one argument will merrily go:

```
int x2c = odd2(42); // Ts=<>, Us=<>, T=42
```

Better yet, functions that pass an explicit argument list for Ts also seem to work:

```
int x2d = odd2<int, double>(1, 2.0, "three");
    // Ts=<int, double>, Us=<>, T=const char*
```

The call above passes Ts explicitly as <int, double>. Then, as always, Us is forced to the empty list, and T is deduced as const char* for the last argument. That way, the call goes through!



Variadic Templates

Chapter 2 Conditionally Safe Features

Or does it? Alas, the declaration of odd2 is IFNDR. By the C++ Standard, if all valid instantiations of a variadic function template require a specific template parameter pack argument to be empty, the declaration is IFNDR. Although such a rule sounds arbitrary, it does have a good motivation: If all possible calls to odd2 require Us to be the empty list, why is Us present in the first place? Such code is more indicative of a bug than of a meaningful intent. Also, diagnosing such cases may be quite difficult in the general case, so no diagnostic is required. As it turns out, today's compilers do not issue such a diagnostic, so the onus is on the template writer to make sure the code does what it's supposed to do.

A simple fix for odd2 is to just eliminate the Us template parameter, in which case odd2 has the same signature as f4 discussed in *The Rule of Fair Matching* on page 27. Another possibility to "legalize" odd2 is to drop the nonpack parameter, in which case it has the same signature as f5 in the same section.

A function that has three parameter packs in a row would also be IFNDR:

```
template <typename... Ts, typename... Us, typename... Vs>
void odd3(Ts..., Us..., Vs...); // impossible to instantiate
```

The reason odd3 cannot work is purely bureaucratic: Neither Ts nor Us may benefit from deduction, and then there is no way to specify Us explicitly because Ts is greedy. Consequently, Us is forced to be always of length zero.

It may seem there is no way to define a function template taking more than two parameter packs. However, recall that deducing variadic function template parameters from the (object) arguments passed to the function uses the full power of C++'s template argument deduction. Defining functions with any number of template parameter packs is entirely possible provided the parameter packs are themselves part of other template instantiations:

```
template <typename...> class Vct { }; // variadic class template definition

template <class T, typename... Ts, typename... Us, typename... Vs>
int fvct(const T&, Vct<Ts...>, Vct<Us...>, Vct<Vs...>);
    // The first parameter matches any type by const&, followed by three
    // not necessarily related instantiations of Vct.
```

The function template fvct takes a fixed number of parameters (four), the last three of which are independent instantiations of a variadic class template Vct. For each of them, fvct takes a template parameter pack that it passes along to Vct. For each call to fvct, template argument deduction figures out whether the call is viable and also binds Ts, Us, and Vs to the packs that make the call work:

```
int x = fvct(5, Vct<>(), Vct<char, int, long>(), Vct<bool>());
    // OK, T=int, Ts=<>, Us=<char, int, long>, Vs=<bool>
```

For each argument in the call above, the compiler matches the type of the argument with the pattern required by the template parameter; the matching process deduces the types that would make the match work. The general algorithm for matching a concrete type against a type pattern is called **unification**.⁵

emplate-parameter-packs

Non-type template parameter packs

Defining a variadic template that take arguments other than types is also possible. Just as C++03 template parameters can be *types*, *values*, or *templates*, so can template parameter packs. We used type template parameter packs up until now to simplify exposition, but non-type template parameter packs apply to class templates and function templates as well.

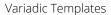
To clarify terminology, the C++ Standard refers to template parameters that accept values as **non-type template parameters** and to template parameters that accept names of templates as **template template parameters** (to be discussed in subsection *Template parameter packs* on page 32).

Non-type template parameter packs are defined analogously with non-type template parameters:

The type specifier of the template non-type parameter pack need not only be **int**; the same rules as for **non-type** parameters apply, restricting the types of non-type parameters to

- integral
- enumerated
- pointer to function or object
- lvalue reference to function or object
- pointer to member
- std::nullptr_t

These types are the value types allowed for C++03 non-type template parameters. In short, value parameter packs obey the same restrictions as the C++03 non-type template parameters:



```
template <Enum... es>
                                           // OK, enumerated
                               class Ce:
                                          // OK, reference
template <int&... is>
                               class Cri;
template <std::string*... ss> class Csp;
                                          // OK, pointer
template <void (*... fs)(int)> class Cf;
                                          // OK, pointer to function
template <int AClass::*... >
                              class Cpm; // OK, pointer to member
template <std::nullptr_t>
                              class Cnl; // OK, std::nullptr_t
                                           // Error, cannot be user-defined
template <Ci<>... cis>
                               class Cu;
template <double... ds>
                                           // Error, cannot be floating-point
                               class Cd;
template <float... fs>
                               class Cf;
                                           // Error, cannot be floating-point
```

In the example above, the declaration of class template Cu is not permitted because Ci<> is a *user-defined* type, whereas the declarations of both Cd and Cf are disallowed because **double** and **float** are floating-point types.⁶

Template parameter packs

olate-parameter-packs

Template parameter packs are the variadic generalization of C++03's template template parameters. Classes and functions may be designed to take template parameter packs as parameters in addition to type parameter packs.

A template template parameter is a template parameter that names an argument that is itself a template. Consider, for example, two arbitrary class templates, A1 and A2:

```
template <typename> class A1 \{/* \dots */ \}; // some arbitrary class template template <typename> class A2 \{/* \dots */ \}; // another arbitrary class template
```

Now suppose that we have a *class* template, (e.g., C1) that takes, as its template parameter, a *class template*:

```
template <template<typename> class X> // X is a template template parameter.
struct C1 : X<int>, X<double> // inherit X<int> and X<double>
{ };
```

We can now create instances of class C1 where the bases are obtained by instantiating whatever argument we pass to C1 with int and double, respectively:

```
C1<A1> c1a; // inherits A1<int> and A1<double> C1<A2> c1b; // inherits A2<int> and A2<double>
```

In the code snippet above, X is a template template parameter that takes one type parameter. The template classes A1 and A2 match X because each of these templates, in turn, takes one type parameter as well.

If an instantiation is attempted with a class template that does not take the same number of template parameters, the instantiation fails, even when there is no doubt as to what the intent might be:

```
template <typename, typename = char> class A3 { /*...*/ }; // OK, two-parameter template, with second one defaulted
```

⁶C++20 does allow *floating point* non-type template parameters, which enable the definition and use of non-type parameter packs using **float**, **double**, or **long double** (making, e.g., the final entry — Ci<4.0> ci4; — in the previous example above valid as well).

```
C1<A3> c1c; // Error, parameters of A3 are different from parameters of X.
```

Although A3 could be instantiated with a single template argument (due to its second template parameter having a default argument) and A3<int> is valid, C1<A3> will not compile. The compiler complains that A3 has two parameters, whereas X has a single parameter.

The same limitation is at work when the argument to C1 is a variadic template:

```
template <typename...>
class A4 { /*...*/ };  // OK, arbitrary variadic template

C1<A4> c1d;  // Error, parameters of A4 are different from parameters of X.
```

Let's define a class C2 that is a variadic generalization of C1 in such a way that it allows instantiation with A3 and A4:

```
template <template<typename...> class X> // template template parameter
struct C2 : X<int>, X<double> // inherit X<int>, X<double>
{ };
```

Note that, although one may use **typename** and **class** interchangeably inside the template parameters of X above, one must always must use **class** for X itself.⁷

The difference between C2 and C1 is literally one token: C2 adds one ... after typename inside the parameter list of X. That one token makes all the difference: by using it, C2 signals to the compiler that it accepts templates with any number of parameters, be they fixed in number, defaulted, or variadic. In particular, it works just fine with A1 and A2 as well as A3 and A4:

```
C2<A1> c2a;
    // inherits A1<int> and A1<double> in that order

C2<A2> c2b;
    // inherits A2<int> and A2<double> in that order

C2<A3> c2c;
    // C2<A3> inherits A3<int, char> and A3<double, char> in that order.
    // char is the default argument for A3's second type parameter.

C2<A4> c2d;
    // inherits A4<int> and A4<double> in that order
```

When C3 instantiates A3<int> or A3<double>, A3's default argument for its second parameter kicks in. A4 will be instantiated with the type parameter pack <int> and separately with the type parameter pack <double>.

In contrast with template template parameters that require exact matching with their arguments, variadic template template parameters specifying **typename...** work in a more "do what I mean" manner by matching templates with default arguments and variadic templates. Applications may need either style of matching depending on context.

There is an orthogonal other direction in which we can generalize C2: We can define a template, C3, that accepts zero or more template template arguments:

 $^{^{7}}$ Since C++17, code may use either **typename** or **class** for template template parameters and for template parameter packs.

Variadic Templates

Chapter 2 Conditionally Safe Features

```
template <template<typename> class... Xs> // Xs is a template parameter pack.
struct C3
   : Xs<int>... // inherit X0<int>, X1<int>, ...
   , Xs<double>... // inherit X0<double>, X1<double>, ...
{ };
```

We get to instantiate C3 with zero or more template classes, each of which takes exactly one type parameter:

Note that C3, just like C1, cannot be instantiated with A3, again due to mismatched template parameters:

```
C3<A3> c3f;
   // Error, parameters of A3 are different from parameters of Xs.
C3<A4> c3g;
   // Error, parameters of A4 are different from parameters of Xs.
```

If we want to make instantiations with A3 and A4 possible, we can combine the two generalization directions by placing the \dots inside the Xs parameter declaration and on Xs as well:

C4 combines the characteristics of C2 and C3. It accepts zero or more arguments, which in turn are accepted in a "do what I mean" manner:

```
C4<> c4a;
// no base classes at all; Xs=<>, all base specifiers vanish

C4<A1> c4b;
// inherits A1<int> and A1<double> in that order

C4<A1, A2> c4c;
```

34

Quite a few other templates match C4's template argument, even though they will fail to instantiate with a single parameter:

```
template <typename, typename> class A5 { /*...*/ };
template <typename, typename, typename...> class A6 { /*...*/ };

C4<A5> err1; // Error, matches, but A5<int> and A5<double> are invalid.
C4<A6> err2; // Error, matches, but A6<int> and A6<double> are invalid.
```

Templates that do not take type template parameters, however, will not match C4 or, for that matter, any of C1 through C4:

In short, class templates that do not take specifically *types* as their template parameters cannot be used in instantiations of C4.

In the general case, template parameter packs may appear together with other template parameters and follow the rules and restrictions discussed so far in the context of type parameter packs. Any number of subtle but nevertheless perfectly meaningful matching cases may be defined involving combinations of fixed and variadic template parameters. Suppose, for example, we want to define a class ${\tt C5}$ that accepts a template that takes ${\tt at}$ ${\tt least}$ two parameters and possibly more:

```
template <template<typename, typename, typename...> class X>
class C5
    // *class* template definition having one *template* template parameter
    // for which the *template* template accepts two or more type
    // arguments
{ /*...*/ };

// A few templates that match C5.

template <typename, typename> class B1;
template <typename, typename = int> class B2;
```



Chapter 2 Conditionally Safe Features

```
template <typename, typename = int, typename = int> class B3;
template <typename, typename...> class B4;

C5<B1> c5a; // OK
C5<B2> c5b; // OK
C5<B3> c5c; // OK
```

However, templates that don't have two fixed type parameters in the first two position will not match C5:

```
template <typename> class B5;
template <int, typename, typename...> class B6;
template <typename, typename, int, typename...> class B7;
template <typename, typename...> class B8;

C5<B5> c5d; // Error, argument mismatch
C5<B6> c5e; // Error, argument mismatch
C5<B7> c5f; // Error, argument mismatch
C5<B8> c5g; // Error, argument mismatch
```

To match C5's template parameter, a template must take types for its first two parameters, followed by zero or more type parameters (with default values or not). B5 does not match because it takes only one parameter. B7 does not match because it takes an <code>int</code> in the first position, as opposed to a type, as required. B7 fails to match because it takes an <code>int</code> in the third position instead of a type. Finally, B7 is not a match because its second argument is not fixed.

To summarize our findings, template parameter packs generalize template template parameters in two distinct, orthogonal ways.

- The ... at the template template parameter level allows zero or more template arguments to match.
- The ... inside the parameter list of the template template parameter allows loose matching of templates with default arguments or variadic; however, type vs. value vs. template parameters are still checked, as in the example involving A7, A68, and A9.

pack-expansion

Pack expansion

Now that we have a solid command of using parameter packs in type and function declarations, it is time to explore how to use parameter packs in function implementations.

As briefly mentioned in *Variadic class templates* on page 9, parameter packs belong to a *kind* distinct from any other C++ entity; they are not types, values, template names, and so on. As far as learning parameter packs goes, they cannot be related to existing entities, so they may as well come from another language with its own syntax and semantics.

Literally the only way to use a parameter pack is to make it part of a so-called pack expansion. A pack expansion consists of a fragment of code (a "pattern") followed by The code fragment must contain at least a pack name; otherwise, it does not qualify as an expansion. Exactly what patterns are allowed depends on the place where the expansion

occurs. Depending on context, the pattern is syntactically a simple identifier, a parameter declaration, an expression, or a type.

The dual use of ... — to both introduce a pack and expand it — may seem confusing at first, but distinguishing between the two uses of ... is easy: When the ellipsis occurs *before* a previously undefined identifier, it is meant to introduce it as the name of a parameter pack; in all other cases, the ellipsis is an expansion operator.

We've already seen pack expansion at work in *Variadic function templates* on page 18. In a variadic function template declaration, the function argument list (e.g., Ts... values) is an expansion resulting in zero or more by-value parameters.

To introduce a simple example of pack expansion in an actual computation, recall the add example in *Description* on page 4, in which a variadic function adds together an arbitrary number of integers. The full implementation shown below uses **double** instead of **int** for better usability. The important part is the expansion that keeps the computation going:

The key to understanding how add works is to model the expansion <code>rest...</code> as a comma-separated list of <code>doubles</code>, always invoking add with fewer arguments than it currently received; when <code>rest</code> becomes the empty pack, the expansion expands to nothing and <code>add()</code> is called, which terminates the recursion by providing the neutral value 0.

Consider the call:

```
int x1 = add(1.5, 2.5, 3.5);
```

Computation proceeds in a typical recursive manner.

- 1. The top-level call goes to the variadic function template add.
- 2. add binds T to double and Ts to <double, double>.
- 3. The expression add(rest...) expands into the recursive call add(2.5, 3.5).
- 4. That call binds T to **double** and Ts to **double**>.
- 5. The second expansion of add(rest...) leads to the recursive call add(3.5).
- 6. Finally, the last expansion will recurse to add(), which returns 0.

The result is constructed as the recursion unwinds.⁸

 $^{^8\}mathrm{C}++17$ adds fold expressions — return lhs + ... + rest; — that allow a more succinct implementation of add.



Chapter 2 Conditionally Safe Features

From an efficiency perspective, it should be noted that add is not recursive in a traditional Computer Science sense. It does not call itself. Each seemingly recursive call is a call to an entirely new function with a different arity generated from the same template. After inlining and other common optimizations, the code is as efficient as writing the statements by hand.

A few rules apply to all parameter-pack expansions irrespective of their kind or the context in which they are used.

First, any pattern must contain at least one parameter pack. Therefore, expansions such as C<int...> or f(5...) are invalid. This requirement can be problematic in function declarations because a typo in a name may switch the meaning of ... from parameter pack expansion to an old-style C variadic function declaration; see *Potential Pitfalls* — *Accidental use of C-style ellipsis* on page 73.

A single pack expansion may contain two or more parameter packs. In that case, expansion of multiple parameter packs within the same expansion is always carried *in lockstep*, i.e., all packs are expanded concomitantly. For example, consider a function modeled after a slightly modified add, and note how, instead of expanding just rest, we expand a slightly more complex pattern in which rest appears twice:

```
template <typename... Ts>
double add2(const Ts&... xs)    // accepts 0 or more arguments
{
    return add((xs * xs)...);    // expand xs * xs in call to add
}
```

This time add2 calls add with the expansion (xs * xs)..., not just xs..., so we're looking at two parameter packs (the two instances of xs) expanded in lockstep. The call add2(1.5, 2.5, 3.5) will forward to add(1.5 * 1.5, 2.5 * 2.5, 3.5 * 3.5), revealing that add2 computes the sum of squares of its arguments.

The parentheses around the pattern in the expansion (xs * xs)... are not needed; the expansion comprehends the full expression to the left of ..., so the call could have been written as add(xs * xs...).

For expansion to work, all parameter packs in one expansion must be of the same length; otherwise, an error will be diagnosed at compile time. Suppose we define a function f1 that takes two parameter packs and passes an expansion involving both to add2:

```
template <typename... Ts, typename... Us>
double f1(const Ts&... ts, const Us&... us)
{
    return add2((ts - us)...);
}
```

Here, the only valid invocations are those with equal number of arguments for ts and us:

```
double x1a = f1<double, double>(1, 2, 3, 4);
    // OK, Ts=<double, double> (explicit), Us=<int, int> (deduced)

double x1b = f1<double, double>(1, 2, 3, 4, 5);
    // Error, parameter packs ts and us have different lengths.
    // Ts=<double, double> (explicit), Us=<int, int, int> (deduced)
```

Every form of pack expansion produces a comma-separated list consisting of copies of the pattern with the parameter packs suitably expanded. Expansion is semantic, not textual — that is, the compiler is "smarter" than a typical text-oriented preprocessor. If the pack expansion is within a larger comma-separated list and the parameter packs being expanded have zero elements, the commas surrounding the expansion are adjusted appropriately to avoid syntax errors. For example, if ts is empty, the expansion add(1, ts..., 2) becomes add(1, 2), not add(1, 2).

Expansion constructs may be nested. Each nesting level must operate on at least one parameter pack:

```
template <typename... Ts>
double f2(const Ts&... ts)
{
    return add2((add2(ts...) + ts)...);
}
```

Expansion always proceeds "inside out," with the innermost expansion carried first. In the call f2(2, 3), the expression returned after the first, innermost ts is expanded is add2((add2(2, 3) + ts)...). The second expansion results in the considerably heftier expression add2(add2(2, 3) + 2, add2(2, 3) + 3). Nested expansions grow in a combinatorial manner, so care is to be exercised.

What forms of pattern... are allowed, and where in the source code is the construct allowed? Parameter pack expansions are defined for a variety of well-defined contexts, each of which is separately described in the following subsections. Not all potentially useful contexts are supported, however; see ?? — ?? on page ??[AUs: There is no section called "Expansion at the statement level is not permitted."] Expansion is allowed in:

- a function parameter pack
- a function call argument list or a braced initializer list
- a template argument list
- a base specifier list
- a member initializer list
- a lambda capture list
- an alignment specifier
- an attribute list
- a **sizeof**... expression
- a template parameter pack that is a pack expansion

Chapter 2 Conditionally Safe Features

nction-parameter-pack

Expansion in a function parameter pack

An ellipsis in a function declaration's parameter list expands to a list of parameter declarations. The pattern being expanded is a parameter declaration.

We discussed this expansion at length in the preceding subsections, so let's quickly recap by means of a few examples:

```
template<typename... Ts>
void f1(Ts...);
                               // expands to T0, T1, T2,...
template<typename... Ts>
void f2(const Ts&...);
                               // const T0&, const T1&,...
template<typename... Ts>
void f3(const C<Ts>&...);
                               // Complex use, e.g., in templates, is allowed.
template<typename... Ts, typename... Us>
void f4(const C<Ts, Us>&...); // const C<T0, U0>&, const C<T1, U1>&,...
```

aced-initializer-list

Expansion in a function call argument list or a braced initializer list

Expansion may occur in the argument list of a function call or in an initializer list — either parenthesized or brace-enclosed (see Section 2.1."??" on page ??). In these cases, the pattern is the largest expression or braced initialization list to the left of the ellipsis.

This expansion is the only one that expands into expressions (all others are declarative), so in a way it is the most important because it relates directly to runtime work getting done.

Let's look at a few examples of expansion. Suppose we have a library that comprises three variadic function templates, f, g, and h, and an ordinary class, C, having a variadic value constructor:

```
template <typename... Ts> int f(Ts...); // variadic function template
template <typename... Ts> int g(Ts...); // "
template <typename... Ts> int h(Ts...); //
struct C
                                        // ordinary class
   template <typename... Ts> C(Ts...); // variadic value constructor
```

Let's now suppose that we another variadic function template, client1, that intends to make use of this library by expanding its own parameter pack, xs, in various contexts:

```
template <typename... Ts>
void client1(Ts... xs)
{
    f(xs...);
                                // (1) f(x0, x1, ...);
   f(C(xs...));
                                // (2) f(C(x0, x1, ...));
                                // (3) f(C(x0), C(x1), ...);
   f(C(xs)...);
                               // (4) f(3.14, x0 + 1, x1 + 1, ...);
   f(3.14, xs + 1 ...);
   f(3.14, xs * 2. ...);
                                // (5) f(3.14, x0 * 2., x1 * 2., ...);
}
```

In comments, we informally denote with x0, x1, ..., the elements of the pack xs. The first call, f(xs...), illustrates the simplest expansion; the pattern being expanded, xs, is simply the name of a function parameter pack. The expansion results in a comma-separated list of the arguments received by client1.

The other examples illustrate a few subtleties. Examples (2) and (3) show how the positioning of ... determines how expansion unfolds. In (2), the expansion is carried inside the call to C's constructor, so f is called with exactly one object of type C. In (3), the ellipsis occurs outside the constructor call, so f gets called with zero or more C objects, each constructed with exactly one argument.

Examples (4) and (5) show how whitespace may be important. If the space before ... were missing, the C++ parser would encounter 1... and 2..., both of which are incorrect floating-point literals.

Let's now look at a few more complex examples in another function, client2:

Examples (6) and (7) feature simultaneous expansion of two packs. In (6), xs is expanded twice. In (7), template parameter pack Ts and value parameter pack xs are both expanded. In all cases of simultaneous expansion, the two or more packs are expanded in lockstep, i.e., the first element in Ts together with the first element in vs form the first element in the expansion, and so on. Attempting to expand packs of unequal lengths results in a compile-time error. Example (6) also shows how an expansion may be somewhere in the middle of a function's argument list.

Example (8) shows two sequential expansions that look similar but are quite different. The two expansions are independent and can be analyzed separately. In g(xs)..., the pattern being expanded is g(xs) and results in the list g(x0), g(x1), In contrast, in the expansion h(xs...), the expansion is carried inside the call to h - h(x0, x1, ...).

Example (9) shows that expansion is allowed inside special functions as well. The expansion C(*xs...) results in C's constructor called with *x0, *x1, and so on.

Last but not least, examples (10) and (11) illustrates expansion inside a braced-initialization list. Example (10) calls the same constructor as (9), and example (11) initializes an array of **int** with the content of **xs** followed by a **0**.

For each of these examples to compile, the code resulting from pack expansions needs to pass the usual semantic checks; for example, the **int** array initialization in (11) would fail to compile if **xs** contained a value with a type not convertible to **int**. As is always the case with templates, some instantiations work, whereas some don't.

In the examples above, the functions involved are all variadic. However, a function doesn't need to be variadic — or template for that matter — to be called with an expansion. The

41

Chapter 2 Conditionally Safe Features

expansion is carried in the function call expression, and then the usual lookup rules apply to decide whether the call is valid:

Expansion in a template argument list emplate-argument-list

We have already encountered pack expansion in the argument list of a template instantiation; if C is a class template and Ts is a template parameter pack, C<Ts...> instantiates C with the contents of Ts. There is no need for the template C to accept a variadic list of parameters. The resulting expansion must be appropriate for the template instantiated.

For example, suppose we define a variadic class Lexicon that uses its parameter pack in an instantiation of std::map:

```
#include <map>
                   // std::map
#include <string> // std::string
template <typename... Ts>
                                        // template parameter pack
class Lexicon
                                        // variadic class template
{
    std::map<Ts...> d_data;
                                        // Use Ts to instantiate std::map.
    // ...
};
Lexicon<std::string, int> c1;
                                        // (1) OK, std::map<std::string, int>
                                        // (2) Error, std::map<int> invalid
Lexicon<int> c2;
Lexicon<int, long, std::less<int>> c3; // (3) OK
Lexicon<long, int, 42> c4;
                                        // (4) Error, 42 instead of functor
```

Given that Lexicon forwards all of its template arguments to std::map, the only viable template arguments for Lexicon are those that would be viable for std::map as well. Therefore, (1) is valid because it instantiates std::map<std::string, int>. As usual, std::map's default arguments for its third and fourth parameters kick in; the pack expansion does not affect default template arguments. To wit, (3) passes three template arguments to std::map and leaves the last one (the allocator) to be filled with the default. Instantiations (2) and (4) of Lexicon are not valid because they would attempt to instantiate std::map with incompatible template arguments.

Expansion in a base specifier list

n-a-base-specifier-list

Suppose we set out to define a variadic template, MB1, that inherits all of its template arguments. This scheme is useful in applying design patterns such as Visitor⁹ or Observer¹⁰. To enable such designs, expansion is allowed in a base specifier list. The pattern under expansion is a base specifier, which includes an optional protection specifier (public, protected, or private) and an optional virtual base specifier. Let us define MB1 to inherit all of its template arguments using public inheritance:

```
template <typename... Ts> // template parameter pack
class MB1 : public Ts... // multibase class, publicly inherit each of Ts
{
    // ...
};
```

The pattern **public** Ts... expands into **public** T0, **public** T1, and so on for each type in Ts. All bases resulting from the expansion have the same protection level. If Ts is empty, MB1<> has no base class.

```
class S1 { /*...*/ }; // arbitrary class
class S2 { /*...*/ }; // arbitrary class
MB1<>
                m1a;
                         // OK, no base class at all
MB1<S1>
                m1b;
                         // OK, instantiate with S1 as only base
MB1<S1, S2>
                m1c;
                         // OK, instantiate with S1 and S2 as bases.
                         // Error, cannot inherit S1 twice
MB1<S1, S2, S1> m1d;
MB1<S1, int>
                         // Error, cannot inherit from scalar type int
                m1e;
```

After expansion, the usual rules and restrictions apply; a class cannot inherit another one twice and cannot inherit types such as **int**.

Other bases may be specified before and/or after the pack. The other bases may specify other protection levels (and if they don't, the default protection level applies):

```
template <typename... Ts>
                               // parameter pack Ts
class MB2
    : virtual private S1
                               // S1 virtual private base
    , public Ts...
                               // inherit each of Ts publicly
{ /*...*/ };
template <typename... Ts>
                               // parameter pack Ts
class MB3
    : public S1
                               // S1 public base
    , virtual protected Ts...
                              // each type in Ts a virtual protected base
    , S2
                               // S2 private base (uses default protection)
{ /*...*/ };
MB2<>
        m2a;
                               // (1) virtual private base S1
MB2<S2> m2b;
                               // (2) virtual private base S1, public base S2
MB3<>
        m3a:
                               // public base S1, private base S2
```

⁹?, Chapter 10, "Visitor," pp.!235–262

¹⁰?, Chapter 5, section "Observer," pp. 293–303



Chapter 2 Conditionally Safe Features

```
MB3<S2> m3b; // Error, cannot inherit S2 twice
```

Expansions are not limited to simple pack names. The general pattern allowed in a base specifier list is that of a full-fledged base specifier. For example, the parameter pack can be used to instantiate another template:

```
template <typename T>
                                // arbitrary class template
class Act
{ /*...*/ };
template <typename... Ts>
                                // template parameter pack Ts
class MB4
    : public Act<Ts>...
                                // bases Act<T0>, Act<T1>, ...
{ /*...*/ };
MB4<>
                          m4a; // no base class
MB4<int, double>
                          m4b; // bases Act<int>, Act<double>
MB4<MB4<int>, int>
                          m4c; // bases Act<MB4<int>>, Act<int>
```

Arbitrarily complex instantiations can be specified in an base specifier pack expansion, which opens to opportunity for a variety of expansion patterns. Depending on where the ellipsis is placed, different expansion patterns can be created.

Although the two expansions featured above are similar in syntax, they are semantically very different. First, **public** Avct<Ts>... expands into multiple bases for MB5: **public** Avct<T0>, **public** Avct<T1>, and so on. The second expansion is completely different; in fact, it's not even an expansion in a base specifier list. Its context is a template's argument list; see *Expansion in a template argument list* on page 42. The result of that expansion is a single class Avct<T0, T1, ...> that is an additional private base of MB5:

```
MB5<int, double> mb5a;
    // inherits publicly Avct<int>, Avct<double>
    // inherits privately Avct<int, double>

MB5<Avct<int, char>, double> mb5b;
    // inherits publicly Avct<Avct<int, char>, Avct<double>,
    // inherits privately Avct<Avct<int, char>, double>

MB5<int> mb5c;
    // Error, cannot inherit Avct<int> twice
```

Expansion in a member initializer list

nember-initializer-list

This feature is a "forced move" of sorts. Allowing variadic bases on a class naturally creates the necessity of being able to initialize those bases accordingly. Consequently, parameter pack expansion is allowed in a base initializer list. The pattern is a base initializer, i.e., the name of a base followed by a parenthesized list of arguments for its constructor:

The default constructor (1) calls all bases' constructors, passing 0 to each. The second constructor (2) passes its one **int** argument to each base. The last constructor (3) of S implements the copy constructor and is rather interesting because it expands in turn to a call to the copy constructor for each member, passing it the result of a **static_cast** (which, in fact, is implicit) to the appropriate base type. Similar syntax can be used for defining the move constructor (see Section 2.1."??" on page ??) and other constructors.

Let's embark on a more complex example. Suppose we want to define a class S2 with a constructor that accepts any arguments and forwards them to all of its base classes. To do so, that constructor itself needs to be variadic with a distinct parameter pack:

The code above has at least one ellipse on every significant line, and all are needed. Let's take a closer look.

Chapter 2 Conditionally Safe Features

the outer ... into a base initialization list: TO(x0, x1, ...), T1(x0, x1, ...),

What if pass by reference to **const** is too constraining, and we would want to define a more general constructor that can forward modifiable values as well? In that case, we need to use forwarding references (see Section 2.1."??" on page ??) and the Standard Library function std::forward:

S3's variadic constructor makes use of **forwarding references**, which automatically adapt to the type of the arguments passed. The library function std::forward ensures that each argument is forwarded with the appropriate type, qualifier, and *lvalueness* to the constructors of each base class. The expansion process is similar to that in S2's constructor previously discussed, with the additional detail that std::forward<Us>(xs)... expands in lockstep Us and xs.

Expansion in a lambda capture list

A C++ lambda expression, introduced with C++11 (see "??" on page ??[AUs: you have here "Lambda Expressions"; do you mean lambdas, generic lambda, or lambda capture feature?]), is an unnamed function object. A lambda can store internally some of the local variables present at the point of creation by a mechanism known as lambda capture. This important capability distinguishes lambdas from simple functions. Let's put it to use in defining a tracer lambda that is able to print a given variable to the console:

```
#include <iostream> // std::cout, std::endl

template <typename T> // single-parameter template
auto tracer(T& x) // returns a lambda that, when invoked, prints x
{
   auto result = [&x]() { std::cout << x << std::endl; };
   // [&x] means the function object captures x by reference.
   // tracer must use auto to initialize the function object.
   return result;
}</pre>
```

Lambdas have a type chosen by the compiler, so we need **auto** to pass lambda objects around; see Section 2.1."??" on page ??.

This may seem like a lot if you're new to lambdas, in which case reading locationc."??" on page ?? along with Section 3.2."??" on page ?? before continuing may be in order. The underlying idea is simple: A call such as tracer(x) saves a reference to x in a function

46

object, which it then returns. Subsequent calls to that function object output the current value of x. It's important to save x by reference (hence the & in the capture), lest the lambda store x by value and uninterestingly print the same thing on each call.

Let's see tracer at work, tracing some variable in a function:

What is the connection with variadics? Variadics are all about generalization, which applies here as well. Suppose we now set out to trace several variables at once. Instead of a one-argument function, tracer would then need to be variadic. Also, crucially, the lambda returned needs to store references to all arguments received in order to print them later. That means an expansion must be allowed inside a lambda capture list.

First, let's assume a function, print, exists that prints any number of arguments to the console (*Use Cases — Generic variadic functions* on page 52 features an implementation of print):

The definition of multitracer uses print in a lambda with variadic capture:

The entire API is enabled by the ability to expand xs inside the capture list. Expanding with [&xs...] captures by reference, whereas [xs...] captures the pack by value. Inside the lambda, print expands the pack as usual with x....

Expansions in captures can be combined with all other captures:

```
template <typename... Ts>  // variadic template
auto test(Ts&... xs)  // for illustration purposes
{
   int a = 0, b = 0;
   auto f1 = [&a, xs...]() { /*...*/ };
   // Capture a by reference and all of xs by value.
```

Chapter 2 Conditionally Safe Features

```
auto f2 = [xs..., &a]() { /*...*/ };
    // same capture as f1

auto f3 = [a, &xs..., &b]() { /*...*/ };
    // Capture a by value, all of xs by reference, and b by reference.

auto f4 = [&, xs...]() { /*...*/ };
    // Capture all of xs by value and everything else by reference.

auto f5 = [=, &xs..., &a]() { /*...*/ };
    // Capture a and all of xs by reference, and everything else by value.
}
```

The pattern must be that of a simple capture; complex capture patterns are not allowed as of C++14.¹¹

Expansion in an alignment specifier

The **alignas** specifier is a feature new to C++11 that allows specifying the alignment requirement of a type or object; see Section 2.1."??" on page ??:

```
alignas(8) float x2; // Align x1 at an address multiple of 8. alignas(double) float x1; // Align x2 with the same alignment as a double.
```

Pack expansion inside the **alignas** specifier is allowed. The meaning in the presence of the pack is to specify the largest alignment of all types in the pack:

```
template <typename... Ts>
                             // variadic template
                           // for illustration purposes
int test1(Ts... xs)
{
    struct alignas(Ts...) S { };
        // Align S at the largest alignment of all types in Ts.
        // If Ts is empty, the alignas directive ignored.
    alignas(Ts...) float x1;
        // Align x1 at the largest alignment of all types in Ts.
        // If Ts is empty, the alignas directive ignored.
    alignas(Ts...) alignas(float) float x2;
        // Align x2 at the largest alignment of double and all types in Ts.
    alignas(float) alignas(Ts...) float x3;
        // same alignment as x2; order does not matter
    return 0;
}
```

As always with **alignas**, requesting an alignment smaller than the minimum alignment required by the declaration is an error:

n-alignment-specifier

 $^{^{11}\}mathrm{C}++20$ introduces pack expansion in lambda initialization captures (see ?) that allows capturing variadics with a syntax such as [...us = vs] or [...us = std::move(vs)].

An idiom that avoids such errors is to use two **alignas** for a given declaration, one of which is the natural alignment of the declaration. This is the idiom followed by the declarations of x2 and x3 in the definition of function template test1.

Using handwritten, comma-separated lists inside an **alignas** specifier is, however, not allowed. Expansion *outside* the specifier is also disallowed:

To conclude, pack expansion in an **alignas** specifier allows choosing without contortions the largest alignment of a parameter pack. Combining two or more **alignas** specifiers facilitates a simple idiom for avoiding errors and corner cases.

Expansion in an attribute list

on-in-an-attribute-list

Attributes, introduced with C++11, are a mechanism for adding built-in or user-defined information about declarations; see Section 1.1."??" on page ??.

Attributes are added to declaration using the syntax [[attribute]]. For example, [[noreturn]] is a standard attribute indicating that a function will not return:

```
[[noreturn]] void abort(); // Once called, it won't return.
```

Two or more attributes can be applied to a declaration either independently or as a commaseparated list inside the square brackets:

```
[[noreturn]] [[deprecated]] void finish(); // won't return, also deprecated
[[deprecated, noreturn]] void finish(); // same
```

For completeness and future extensibility, pack expansion is allowed inside an attribute specifier as in [[attribute...]]. However, this feature is not currently usable with any current attribute, standard or user-defined:

```
template <class... Ts>
[[Ts()...]] void functionFromTheFuture();
    // NONWORKING CODE
    // Receive a number of types; instantiate them as attributes.
```

The ability to expand packs inside attribute specifiers is reserved for future use and good to keep in mind for future additions to the language.

Chapter 2 Conditionally Safe Features

-sizeof...-expression

Expansion in a sizeof... expression

The **sizeof**... expression is an oddity in three ways. First, it has nothing to do with classical **sizeof** in the sense that **sizeof**... does not yield the extent occupied in memory by an object. Second, it is the only parameter pack expansion that does *not* use the (by now familiar) pack... syntax. And third, although it is considered an expansion, it does not expand a pack into its constituents.

For any parameter pack P, sizeof...(P) yields to a compile-time constant of type $size_t$ equal to the number of elements of P:

```
std::size_t
 template <typename... Ts>
 std::size_t countArgs(Ts... xs)
 {
                                             // x1 is the number of parameters
     std::size_t x1 = sizeof...(Ts);
     std::size_t x2 = sizeof...(xs);
                                            // same value as x1
     static_assert(sizeof...(Ts) >= 0,""); // sizeof...(Ts) is a constant.
     static_assert(sizeof...(xs) >= 0,""); // sizeof...(xs) is a constant.
     return sizeof ... (Ts);
                                            // whitespace around ... allowed
 }
Let's see countArgs in action:
 std::size_t a0 = countArgs();
                                          // initialized to 0
 std::size_t a1 = countArgs(42);
                                         // initialized to 1
 std::size_t a2 = countArgs("ab", 'c'); // initialized to 2
```

Whitespace is allowed around the ..., but parentheses are not optional. Also, expansion is disallowed inside **sizeof** and **sizeof**... alike:

mplate-parameter-list

Expansion inside a template parameter list

Not to be confused with the case discussed in *Expansion in a template argument list* on page 42, pack expansion may occur in a template *parameter* (not argument) list. This is different from all other expansion cases because it involves two distinct parameter packs: a type parameter pack and a non-type parameter pack. To set things up, suppose we define a class template, C1, that has a type parameter pack, Ts. Inside, we define a secondary class template, C2, that does *not* take any type parameters. Instead, it takes a non-type template parameter pack with types derived from Ts:

Once C1 is instantiated with some types, the inner class C2 will accept *values* of the types used in the instantiation of C1. For example, if C1 is instantiated with **int** and **char**, its inner class template C2 will accept an **int** value and a **char** value:

```
C1<int, char>::C2<1, 'a'> x1; // OK, C2 takes an int and a char.
C1<int, char>::C2<1> x2; // Error, too few arguments for C2
C1<int, char>::C2<1, 'a', 'b'> x3; // Error, too many arguments for C2
```

Only instantiations of C1 that lead to valid declarations of C2 are allowed. For example, user-defined types are not allowed as non-type template parameters, and consequently C1 cannot be instantiated with a user-defined type:

```
class AClass { };  // simple user-defined class

C1<int, AClass>::C2<1, AClass()> x1;
    // Error, a non-type template parameter cannot have type AClass.
```

No other expansion contexts

her-expansion-contexts

-contexts-and-patterns

Note that what's missing is as important as what's present. Parameter pack expansion is explicitly disallowed in any other context, even if it would make sense syntactically and semantically:

```
template <typename... Ts>
void bumpAll(Ts&... xs)
{
    ++xs...; // Error, cannot expand xs in an expression-statement context
}
```

Annoyances — ?? on page ??[AUs: There is no subsection called "Expansion at the statement level is not permitted"] discusses this context further. Also recall that it is illegal to use pack names anywhere without expanding them, so they don't enjoy first-class status; see Annoyances — Parameter packs cannot be used unexpanded on page 76.

Summary of expansion contexts and patterns

To recap, expansion is allowed in only the following places:

51

Chapter 2 Conditionally Safe Features

Context	Pattern
function parameter pack	parameter declaration
function call argument list or a braced initializer list	function argument
template argument list	template argument
base specifier list	base specifier
member initializer list	base initializer
lambda capture list	capture
alignment specifier	alignment specifier
attribute list	attribute
'sizeof' expression	identifier
template parameter pack that is a pack expansion	parameter declaration

use-cases-variadic

ic-variadic-functions

Use Cases

Generic variadic functions

A variety of functions of general utility are naturally variadic, either mathematically (min, max, sum) or as a programmer's convenience. Suppose, for example, we want to define a function, print, that writes its arguments to std::cout in turn followed by a newline 12:

```
#include <iostream> // std::cout, std::endl
std::ostream& print()
                                     // parameterless overload
    return std::cout << std::endl; // only advances to next line</pre>
template <class T, typename... Ts>
                                                   // one or more types
std::ostream& print(const T& x, const Ts&... xs) // one or more args
    std::cout << x;
                                                   // output first argument
    return print(xs...);
                                                   // recurse to print rest
}
void test()
{
    print("Pi is about ", 3.14159265);
                                                   // "Pi is about 3.14159"
```

The implementation follows a head-and-tail recursion that is typically used for C++ variadic function templates. The first overload of print has no parameters and simply outputs a newline to the console. The second overload does the bulk of the work. It takes one or more arguments, prints the first, and recursively calls print to print the rest. In the limit, print is called with no arguments, and the first definition kicks in, outputting the line terminator and also ending the recursion.

A variadic function's smallest number of allowed arguments does not have to be zero, and it is free to follow many other recursion patterns. For example, suppose we want to define a variadic function <code>isOneOf</code> that returns <code>true</code> if and only if its first argument is

¹²C++20 introduces std::format, a facility for general text formatting.

equal to one of the subsequent arguments. Calls to such a function are sensible for two or more arguments:

Again, the implementation uses two definitions in a pseudo-recursive setup but in a slightly different stance. The first definition handles two items and also stops recursion. The second version takes three or more arguments, handles the first two, and issues the recursive call only if the comparison yields **false**.

Let's take a look at a few uses of isOneOf:

```
#include <string> // std::string

int a = 42;
bool b1 = isOneOf(a, 1, 42, 4); // b1 is true.
bool b2 = isOneOf(a, 1, 2, 3); // b2 is false.
bool b3 = isOneOf(a, 1, "two"); // Error, can't compare int with const char*
std::string s = "Hi";
bool b4 = isOneOf(s, "Hi", "a"); // b4 is true.
```

object-factories

Object factories

Suppose we want to define a generic factory function — a function able to create an instance of any given type by calling one of its constructors. Object factories^{13,14} allow libraries and applications to centrally control object creation for a variety of reasons: using special memory allocation, tracing and logging, benchmarking, object pooling, late binding, deserialization, interning, and more.

The challenge in defining a generic object factory is that the type to be created (and therefore its constructors) is not known at the time of writing the factory. That's why C++03 object factories typically offer only default object constructions, forcing clients to awkwardly use two-phase initialization, first to create an empty object and then to put it in a meaningful state.

Writing a generic function that can transparently forward calls to another function ("perfect forwarding") has been a long-standing challenge in C++03. An important part of the puzzle is making the forwarding function generic in the number of arguments, which is where variadic templates help in conjunction with forwarding references (see Section 2.1."??" on page ??):

 $^{^{13}}$?, Chapter 1-5, section "Factory Method," pp. 107–115 14 ?, Chapter 8, "Object Factories," pp. 197–218

Chapter 2 Conditionally Safe Features

Ts&&... xs introduces xs, a function parameter pack that represents zero or more forwarding references. As we know, the construct std::forward<Ts>(xs)... is a pack expansion that expands to a comma-separated list std::forward<T0>(x0), std::forward<T1>(x1), and so on. The Standard Library function template std::forward passes accurate type information from the forwarding references x0, x1, ... to Product's constructor.

To use the function, we must always provide the **Product** type explicitly; it is not a function parameter, so it cannot be deduced. The others are at best left to template argument deduction. In the simplest case, **factory** is usable with primitive types:

```
int i1 = factory<int>();
                                         // Initialize i1 to 0.
 int i2 = factory<int>(42);
                                         // Initialize i2 to 42.
It also works correctly with overloaded constructors:
 struct Widget
     Widget(double);
                             // constructor taking a double
     Widget(int&, double); // constructor taking an int& and a double
 };
 int g = 0;
 Widget w1 = factory<Widget>(g, 2.4);
                                         // calls ctor with int& and double
 Widget w2 = factory<Widget>(20);
                                         // calls ctor with double
 Widget w3 = factory<Widget>(20, 2.0); // Error, cannot bind rvalue to int&
```

The last line introducing w3 fails to compile because the *rvalue* 20 cannot convert to the non-const int& required by Widget's constructor — an illustration of perfect forwarding doing its job.

Many variations of object factories (e.g., using dynamic allocation, custom memory allocators, and special exceptions treatment) can be built on the skeleton of factory shown. In fact, Standard Library factory functions, such as std::make_shared and std::make_unique, use variadics and perfect forwarding in this same manner.

Hooking function calls

Forwarding is not limited to object construction. We can use it to intercept function calls in a generic manner and add processing such as tracing, logging, and so on. Suppose, for example, writing a function that calls another function and logs any exception it may throw:

```
#include <exception> // std::exception
```

54

ooking-function-calls

```
#include <utility>
                      // std::forward
void log(const char* msg);
                                               // Log a message.
template <typename Callable, typename... Ts>
auto logExceptions(Callable&& fun, Ts&&... xs)
    -> decltype(fun(std::forward<Ts>(xs)...))
    try
    {
        return fun(std::forward<Ts>(xs)...); // perfect forwarding to fun
    catch (const std::exception& e)
                                               // log exception information
        log(e.what());
                                               // Rethrow the same exception.
        throw;
    catch (...)
        log("Nonstandard exception thrown."); // log exception information
        throw;
                                               // Rethrow the same exception.
    }
}
```

Here, we enlist not only the help of std::forward but also that of the auto -> decltype idiom; see Section 1.1."??" on page ?? and Section 1.1."??" on page ??. By using auto instead of the return type of logExceptions and following with -> and the trailing type decltype(fun(std::forward<Ts>(xs)...)), we state that the return type of logExceptions is the same as the type of the call fun(std::forward<Ts>(xs)...), which matches perfectly the expression that the function will actually return.

In case the call to fun throws an exception, logExceptions catches, logs, and rethrows that exception. So logExceptions is entirely transparent other than for logging the passing exceptions. Let's see it in action. First, we define a function, assumeIntegral, that is likely to throw an exception:

Chapter 2 Conditionally Safe Features

```
long b = logExceptions(assumeIntegral, 4.4); // throws and logs
}
```

_Tuples

tuples

A tuple or a record is a type that groups together a fixed number of values of unrelated types. The C++03 Standard Library template std::pair is a tuple with two elements. The standard library template std::tuple, introduced in C++11, implements a tuple with the help of variadic templates. For example, std::tuple<int, int, float> holds two ints and a float.

There are many possible ways to implement a tuple in C++. C++03 implementations typically define a hardcoded limit on the number of values the tuple can hold and use considerable amounts of scaffolding, as described in *Description* on page 4:

Variadics are a key ingredient in a scalable, manageable tuple implementation. We discuss a few possibilities in approaching the core definition of a tuple, with an emphasis on data layout.

The definition of Tuple1 (in the code snippet below) uses specialization and recursion to accommodate any number of types:

```
std::size_tstd::stringassertstd::runtime_error
template <typename... Ts>
                             // (0) incomplete declaration
class Tuple1;
template <>
class Tuple1<>
                             // (1) specialization for zero elements
{ /*...*/ };
template <typename T, typename... Ts>
class Tuple1<T, Ts...>
                          // (2) specialization for one or more elements
{
    T first;
                             // first element
    Tuple1<Ts...> rest;
                             // all other elements
    // ...
};
```

Tuple1 uses composition and recursion to create its data layout. As discussed in *Expansion* in a base specifier list on page 43, the expansion Tuple1<Ts...> results in Tuple1<T0, T1, ..., Tn>. The specialization Tuple1<> ends the recursion.

The only awkward detail is that Tuple1<int> has member rest of type Tuple1<>, which is empty but is required to have nonzero size, so it ends up occupying space in the

tuple. 15 This is an important issue if the tuple is to be used at scale.

A solution to avoid this issue is to partially specialize **Tuple1** for one element in addition to the two existing specializations:

With this addition, Tuple1<> uses the total specialization (1), Tuple1<int> uses the partial specialization (3), and all instantiations with two or more types use the partial specialization (2). For example, Tuple1<int, long, double> instantiates specialization (2), which uses Tuple1<long, double> as a member, which in turn uses the partial specialization (3) for member rest of type Tuple1<double>.

The disadvantage of the design above is that it requires similar code in the Tuple1<T> partial specialization and the general definition, leading to a subtle form of code duplication. This may not seem very problematic, but a good tuple API has a considerable amount of scaffolding; for example, std::tuple has 25 member functions.

Let's address Tuple1's problem by using inheritance instead of composition, thus benefitting from an old and well-implemented C++ layout optimization known as the empty base optimization. When a base of a class has no state, that base is allowed, under certain circumstances, to occupy no room at all in the derived class. Let's design a Tuple2 variadic class template that takes advantage of the empty base optimization:

If we assess the size of Tuple2<int> with virtually any contemporary compiler, it is the same as sizeof(int), so the base does not, in fact, add to the size of the complete object. One awkwardness with Tuple2 is that with most compilers the types specified appear in the memory layout in reverse order; for example, in an object of type Tuple1<int, int, float, std::string>, the string would be the first member in the layout, followed by the float and then by the two ints. (Compilers do have some freedom

¹⁵On Clang 11.0 and GCC 7.5, sizeof(T1) is 8, twice the size of an int.



Chapter 2 Conditionally Safe Features

in defining layout, but most of today's compilers simply place bases first in their order, followed by members in the order of their declarations.)

To ensure a more intuitive layout, let's define Tuple3 that uses an additional **struct** to hold individual elements, which Tuple3 inherits (by means of the seldom-used **protected** inheritance) before recursing:

```
template <typename T>
struct Element3
                    // element holder
{
    T value;
                     // no other data or member functions
};
template <typename... Ts>
class Tuple3;
                    // declaration to introduce the class template
template <>
                    // specialization for zero elements
class Tuple3<>
{ /*...*/ };
template <typename T, typename... Ts> // one or more types
class Tuple3<T, Ts...>
                                  // one or more elements
    : public Element3<T>
                                      // first in layout
    , public Tuple3<Ts...>
                                     // recurse to complete layout
{ /*...*/ };
```

This is close to what we need, but there is one additional problem to address: The instantiation <code>Tuple3<int</code>, <code>int></code> will attempt to inherit <code>Element<int></code> twice, which is not allowed. One way to address this issue is by passing a so-called cookie to <code>Element</code>, an additional template parameter that uniquely tags each <code>Element</code> differently. We choose <code>size_t</code> for the cookie type:

The Tuple4 class instantiates Element with a decreasing value of cookie for each successive element:

```
, public Tuple4<Ts...> // recurse to complete layout { /*...*/ };
```

To see how it all works, consider the instantiation Tuple4<int, int, char>, which matches specialization (2) with T=int and Ts=<int, char>. Consequently sizeof...(Ts) — the number of elements in Ts — is 2. The specialization first inherits Element<2, int> and then Tuple4<int, char>. The latter, in turn, also uses specialization (2) with T=int and Ts=<char>, which inherits Element<int, 1> and Tuple4<char>. Finally, Tuple4<char> inherits Element<char, 0> and Tuple4<>>, which kicks the first specialization into gear to terminate the recursion.

It follows that Tuple4<int, int, char> ultimately inherits (in this order) Element<int, 2>, Element<int, 1>, and Element<char, 0>. Most implementations of std::tuple are variations of the patterns illustrated by Tuple1 through Tuple4. 16

If Element didn't take a distinct number for each member of the product type, Tuple4<int, int> would not work because it would inherit Element<int> twice, which is illegal. With cookie, the instantiation works because it inherits the distinct types Element<int, 1> and Element<int, 2>.

The expanded templates for the above code example might look like this invalid but illustrative code:

```
class Tuple4<>
{ /*...*/ };
class Tuple4<char> : public Element<char, 0>, public Tuple4<>
{ /*...*/ };
class Tuple4<int, char> : public Element<int, 1>, public Tuple4<char>
{ /*...*/ };
class Tuple4<int, int, char> : public Element<int, 2>, public Tuple4<int, char>
{ /*...*/ };
```

The complete implementation of a tuple type would contain the usual constructors and assignment operators as well as a *projection function* that takes an index **i** as a compile-time parameter and returns a reference to the **i**th element of the tuple. Let's see how to implement this rather subtle function. To get it done, we first need a helper template that returns the **n**th type in a template parameter pack.

¹⁶libstdc++, the GNU C++ Standard Library, uses an inheritance-based scheme with increasing indexes (as opposed to Tuple4 in which cookie values are decreasing). libc++, the LLVM Standard Library that ships with Clang, does not use inheritance for std::tuple, but its state implementation uses inheritance in conjunction with an increasing integral sequence. Microsoft's open-source STL (?) uses, at time of this writing, the approach taken by Tuple2.

Chapter 2 Conditionally Safe Features

```
{
    typedef T type;
};
```

NthType follows the now familiar pattern of recursive parameter pack handling. The first declaration introduces the recursive case. The specialization that follows handles the limit case n == 0 to stop the recursion. It is easy to follow that, for example, NthType<1, short, int, long>::type is int.

We are now ready to define the function get such that get<0>(x) returns a reference to the first element of a Tuple4 object called x.

Calculating the cookie ${\tt sizeof...}(Ts)$ - n - 1 requires some finesse. Recall that the elements in a tuple come with cookies in the reverse order of their natural order, so the first element in a Tuple4<Ts...> has cookie ${\tt sizeof}(Ts...)$ - 1 and the last element has cookie 0. Therefore, when we compute the cookie of the nth element in the cookie, we use elementary algebra to get to the expression shown.

After all typing has been sorted out, the implementation itself is trivial; it fetches the appropriate Element base by means of an implicit cast and then returns its value. Let's put the code to test:

```
void test()
{
    Tuple4<int, double, std::string> value;
    get<0>(value) = 3;
    get<1>(value) = 2.718;
    get<2>(value) = "hello";
    assert(get<2>(value) == "hello");
}
```

The example also illustrates why get is best defined as a nonmember function: A member function would have been forced to use the awkward syntax value.template get<0>() = 3 to disambiguate the use of < as a template instantiation as opposed to the less-than operator.

_Variant types

variant-types

A variant type, sometimes called a discriminated union, is similar to a C++ union that keeps track of which of its elements is currently active and protects client code against unsafe uses. Variadic templates support a natural interface to express this design as a generic

library feature.¹⁷ For example, a variant type such as Variant<int, float, std::string> would be able to hold exactly one int or one float or one std::string value. Client code can change the current type by assigning to the variant object an int, a float, or an std::string respectively.

To define a variant type, we need it to have enough storage to keep any of its possible values, plus a *discriminator* — typically a small integral that keeps the index of the currently stored type. For Variant<int, float, std::string>, the discriminator could be by convention 0 for int, 1 for float, and 2 for std::string.

We saw in the previous sections how to define data structures recursively for parameter packs, so let's try our hand at a variant layout in the Variant1 design:

```
template <class... Ts>
                                             // parameter pack
class Variant1
                                             // can hold any in parameter pack
    template <typename...>
                                             // union of all types in Ts
    union Store {};
    template <class U, typename... Us>
                                             // Specialize for >=1 types.
    union Store<U, Us...>
    {
        U head;
                                             // Lay out a U object.
        Store<Us...> tail;
                                             // all others at same address
    };
                                             // Store for current datum.
    Store<Ts...> d_data;
    unsigned int d_active;
                                             // index of active type in Ts
public:
    // ... (API goes here)
};
```

C-style **union**s can be templates, too, and variadic ones at that. We take advantage of this feature in **Variant1** to recursively define **Store<Ts...>** that stores each of the types in the parameter pack **Ts** at the same address. One important C++11 feature that conveys flexibility to the design above is the relaxation on the restrictions on types that can be stored in **union**s. In C++03, **union** members were not allowed to have non-trivial constructors or destructors. Starting with C++11, any type can be a member in a **union**; see Section 3.1."??" on page ??. Therefore, types such as **Variant1<std::string**, **std::map<int</code>, int>>** work fine.

It is possible to define d_data in a more succinct manner as a fixed-size array of **char**. There are two challenges to address. First, the size of the array needs to be computed during compilation as the maximum of the sizes of all types in Ts. Second, the array needs to have sufficient alignment to store any of the types in Ts. Fortunately, both problems have simple solutions in idiomatic modern C++:

```
#include <algorithm> // std::max
```

 $^{^{17}\}mathrm{C}++17$'s Standard Library type $\mathtt{std}::$ variant provides a robust and comprehensive implementation of a variant type.



Chapter 2 Conditionally Safe Features

```
template <class... Ts> class Variant2; // introducing declaration
template <> class Variant2<>
                                 // specialization for empty Ts
{ /*...*/ };
template <class T, class... Ts>
class Variant2<T,Ts...>
                                 // specialization for one or more types
    enum : std::size_t { size = std::max({sizeof(T), sizeof(Ts)...}) };
        // std::max takes std::initializer_list and is constexpr in C++14
    alignas(T) alignas(Ts...)
                                 // payload
    char d_data[size];
                                 // index of active type in Ts
    unsigned int d_active;
public:
    // ... (API goes here)
};
```

The code above uses a new use of std::max — overload introduced in C++14 that takes an initializer list as parameter; see Section 2.1."??" on page ??. Another novelty is the use of std::max during compilation; see Section 2.1."??" on page ??. We apply std::max to sizeof(T) and the sizeof(Ts)... expansion, which results in a comma-separated list sizeof(T), sizeof(T0), sizeof(T1), (Note it is not the same expansion as sizeof...(Ts), which would just return the number of elements in Ts).

In brief, d_data is an array of **char** as large as the maximum of the sizes of all of the types passed to Variant2. In addition, the **alignas** directives instructs the compiler to align d_data at the largest alignment of all types among T and all of Ts; see *Description* — *Expansion in an alignment specifier* on page 48 and Section 2.1."??" on page ??.

It is worth noting that both Variant1 and Variant2 are equally good from a layout perspective; in fact, even the implementation of their respective APIs are identical. The only use of d_data is to take its address and use it as a pointer to void, which the API casts appropriately.

The public interface ensures that when an element is stored in d_data, d_active will have the value of the index into the parameter pack Ts... that corresponds to that type. Hence, when a user attempts to retrieve a value from the variant, if the wrong type is requested, a runtime error will be reported.

Let's take a look at defining some relevant API functions — the default constructor, a value constructor, and the destructor:

```
std::size_tstd::stringassertstd::runtime_error

#include <algorithm> // std::max

template <typename... Ts> // introducing declaration
class Variant;

template <> class Variant<> // specialization for empty Ts
```

```
{ /*...*/ };
template <typename T, typename... Ts> // specialization for 1 or more
class Variant<T,Ts...>
    enum : std::size_t { size = std::max({sizeof(T), sizeof(Ts)...}) };
        // compute payload size
    alignas(T) alignas(Ts...)
    char d_data[size];
                                       // approach in Variant1 fine too
                                       // index of active type in Ts
    unsigned int d_active;
    template <class U, class... Us>
    friend U& get(Variant<Us...>& v); // `friend` accessor
public:
   Variant();
                                       // default constructor
    template <typename U>
                                       // value constructor
    Variant(U&&);
                                       // U must be among T, Ts.
    ~Variant();
                                       // destroy the current object
    // ...
};
```

The default constructor should put the object in a simple, meaningful state. A reasonable decision is to create (by default construction) the *first* object in Ts:

```
template <typename T, typename... Ts>
Variant<T, Ts...>::Variant()
{
    ::new(&d_data) T(); // default-constructed T at address of d_data
    d_active = 0; // Set the active type to T, first in the list.
}
```

The default constructor uses **placement new** to create a default-constructed object at the address of d_data . The first element in the parameter pack is selected by means of partial specialization.

The value constructor is a bit more challenging because it needs to compute the appropriate index for d_active during compilation, for example as an **enum** value. To implement it, first we need a support metafunction that reports the index of a type in a template parameter pack. The first type is the sought type, followed by the types to be searched. If the first type is not among the others, an error is produced:



Chapter 2 Conditionally Safe Features

The: size_t syntax, new to C++11, specifies that the introduced anonymous **enum** has type size_t as a base; see Section 2.1."??" on page ??. The class template IndexOf follows a simple recursive pattern. In the general case, the type X is different from the first type T, and value is computed recursively as a search through the tail of the list.

If the sought type is identical to the first in the list, partial specialization 1 kicks in; if the sought type is a **const** variant of the second, partial specialization 2 matches. (A complete implementation would also add a similar specialization for the **volatile** qualifier.) In either case, the recursion ends and the value 0 is popped up the compile-time recursion stack:

If the type is not found in the pack at all, then the recursion will come to an end when Ts is empty and the recursion cannot find a specialization for only one type T, resulting in a compile-time error.

It is worth noting that IndexOf has an alternative implementation that uses std::integral_constant, a Standard Library facility introduced in C++11 that automates part of the value definition:

The type std::integral_constant<size_t, n> defines a constant member named value of type size_t with value n, which simplifies to some extent the definition of IndexOf and clarifies its intent.

With this template in our toolbox, we are ready to implement Variant's value constructor, using perfect forwarding to create a Variant holding an object of the given type, with a compile-time error if the specified type is not found in the parameter pack Ts.

There is one more detail to handle. By design, we require Ts to contain only unqualified (no **const** or **volatile**), nonreference types, but the value constructor may deduce its type parameter as a reference type (such as int&). In such cases, we need to extract int from int&. The Standard Library template std::remove_reference_t was designed exactly for this task — both std::remove_reference_t<int> and std::remove_reference_t<int&> are aliases for **int**:

```
template <typename T, typename... Ts> // definition for partial specialization
template <typename UARG>
                                       // value constructor
Variant<T, Ts...>::Variant(UARG&& xs) // uses perfect forwarding
    typedef std::remove_reference_t<UARG> U;
        // Remove reference from UARG if any, e.g. transform int& into int.
    ::new(&d_data) U(std::forward<UARG>(xs)); // Construct object at address.
    d_active = IndexOf<U, T, Ts...>::value;
                                              // This code fails if U not in Ts.
}
```

Now we get to construct a Variant given any value of one of its possible types:

```
Variant<float, double> v1(1.0F); // v1 has type float and value 1.
Variant<float, double> v2(2.0);
                                  // v2 has type double and value 2.
                                  // Error, int is not among allowed types.
Variant<float, double> v3(1);
```

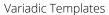
A more advanced Variant implementation could support implicit conversions during construction as long as there is no ambiguity. Such functionality is supported by std::variant.

Now that Variant knows the index of the active type in Ts, we can implement an accessor function that retrieves a reference to the active element, by a client that knows the type. For example, given a Variant<short, int, long> object named v, int& get<int>(v) should return a reference to the stored int if and only if the current value in v has indeed type **int**; otherwise, it throws an exception:

```
// T is the assumed type.
template <class T, class... Ts>
T& get(Variant<Ts...>& v)
                                                 // Variant<Ts...> by ref
    if (v.d_active != IndexOf<T, Ts...>::value) // Is the index correct?
        throw std::runtime_error("wrong type"); // If not, throw.
                                                 // If so, take store address
    void* p = &v.d_data;
    return *static_cast<T*>(p);
                                                 // and convert.
}
```

A overload of **get** that takes and returns **const** is defined analogously.

In spite of its simplicity, the get function (which needs to be a friend of Variant because it needs access to its **private** members) is safe and robust. If given a type not present in the Variant's parameter pack, IndexOf fails to compile, and, consequently, get does not compile either. If the type is present in the pack but is not the current type stored in the Variant, an exception is thrown. If everything works well, the address of data is converted to a reference to the target type, in full confidence that the cast is safe to perform:



Chapter 2 Conditionally Safe Features

Writing Variant's destructor is more difficult because, in that case, we need to produce the compile-time type of the active element from the *runtime* index, d_active. The language offers no built-in support for such an operation, so we must produce a library solution instead.

One idea is to use a linear search approach: Starting with the active index d_active and the entire parameter pack Ts, we reduce both successively until d_active becomes zero. At that point, we know that the dynamic type of the variant is the head of what's left of Ts, and we call the appropriate destructor. To implement such an algorithm, we define two overloaded functions, destroyLinear, that are friends of Variant:

The second overload employs the idiom (used in several places in this feature section) of stripping the first element from the parameter pack on each call using a named type parameter. If the runtime index is 0, then the destructor of T, the first type in the pack, is called against the pointer received. Otherwise, destroyLinear "recursively" calls a version of itself with the parameter pack reduced by 1 and the compile-time counter i correspondingly bumped. Note that "recursion" is not quite the correct term because the template instantiates a different function for each call.

The first overload simply terminates the recursion. It is never called in a correct program, but the compiler doesn't know that, so we need to provide a body for it.

Variant's destructor ensures that the variant object is not corrupt and then calls destroyLinear, passing the entire pack Ts... as template argument and the current index and pointer to state as runtime arguments:

```
template <class T, class... Ts> // definition for partial specialization
Variant<T, Ts...>::~Variant() // linear lookup destructor
```

When presented with a linear complexity algorithm, the natural reaction is to look for a similar solution with lower complexity, especially considering that the linear search will be performed at run time, not during compilation. In this case, we might try a binary search through the type parameter pack. In common usage, a variant does not have that many types, so this may be considered overkill, but there are two reasons why this problem deserves our attention. First, there are variant types in common use that have a large number of alternatives, such as the VARIANT type in the Windows operating system with around 50 options in its union, and some data exchange formats that can have hundreds of types. Second, destructors are of particular importance because they tend to be called intensively, so destructors' size and speed can often affect performance of programs using them.

Defining a binary search that is a mix of compile-time and runtime computations is challenging, particularly because parameter packs do not have indexed access. However, we can implement destroyLog with relative ease if we design the algorithm in a hybrid manner—linear search during compilation and binary search at runtime. We do so by defining destroyLog to take two integral template parameters, skip and total, that instruct the template which types in the pack it must look at. If skip is greater than 0, the algorithm does a linear search during compilation in the parameter pack. When skip is zero, we know we need to search total elements in the parameter pack, and we do so in a textbook binary search manner:

```
template <unsigned int, unsigned int>
void destroyLog(unsigned int n, void*) // no-op terminal function
{ }
template <unsigned int skip, unsigned int total, typename T, typename... Us>
void destroyLog(unsigned int n, void* p)
{
    enum : std::size_t { mid = total / 2 };
    if (skip > 0)
        destroyLog<skip - 1, total - 1, Us...>(n, p);
    else if (n == 0)
        static_cast<T*>(p)->~T();
    else if (n < mid)</pre>
        destroyLog<0, mid, T, Us...>(n, p);
    else
        destroyLog<mid, total, T, Us...>(n - mid, p);
}
```

There are quite a few moving parts in destroyLog, so let's take a look at each in turn. The first overload is simple: Its role, just like before, is to stop the recursion. It takes two unsigned int parameters, both of which it ignores. The first overload will never be called or even linked.

The bulk of the work is carried by the second overload. First, it computes half of the total in constant mid.



Chapter 2 Conditionally Safe Features

Now, to understand how the four branches of the if/else cascade work, it's important to distinguish the first condition from all others; the skip > 0 test is essentially a compiletime test and does no computation at run time. All instantiations with a nonzero skip will simply recurse to a different instantiation and do nothing else. The compiler will in all likelihood inline the call and eliminate all other code in the function.

Why do we subtract (skip > 0) from skip and total instead of simply subtracting 1? If we used skip - 1, when skip reaches 0, the compiler would attempt to instantiate destroyLog with -1 (even if it never calls that instantiation), which translates into a very large unsigned, causing a runaway of further instantiations. The way the condition is written avoids this situation.

All other tests are performed during run time. The second test n=0 checks for a match, and, if the test passes, the appropriate destructor is called manually. This is in keeping with how destroyLinear works.

The rest of the function is the engine that accelerates <code>destroyLog</code> in comparison to <code>destroyLinear</code>. If n is less than <code>mid</code>, then there's no need to consider the upper elements of the pack at all; therefore, <code>destroyLog</code> is instantiated with <code>mid</code> as the total elements to search. All other arguments — both of the template and runtime kind — are the same. Otherwise, on the contrary, there's no need to look at the first <code>mid</code> elements of the pack, so <code>destroyLog</code> is instantiated accordingly.

All in all, the ${\tt destroyLog}$ template compactly encodes a linear search during compilation and simultaneously a binary search during run time. As expected, contemporary compilers eliminate dead code entirely and generate code virtually identical to code competently handwritten in a hardcoded approach. 18

Of course, once we have a logarithmic implementation, we immediately wonder if we can do better, perhaps even a constant time lookup. That brings us to an application of variadic templates in a braced initialization, as described in *Description — Expansion in a function call argument list or a braced initializer list* on page 40. We use braced initialization to generate a table of function pointers, each pointing to a different instantiation of the same function template. For the table to work, each function must have exactly the same signature. For the case of invoking a destructor, we will want to supply the object to be destroyed by using <code>void*</code> just like we did with <code>destroyLinear</code> and <code>destroyLog</code>. We can then write a function template taking a non-deduced type parameter to carry the necessary type information for the function implementation to cast the <code>void*</code> pointer to the necessary type:

```
template <class T>
static void destroyElement(void *p)
{
    static_cast<T*>(p)->~T();
}
```

With this simple function template, we can populate a static array of function pointers by initializing an array of unknown bound (that will implicitly deduce the correct size) with a braced list produced by a pack expansion, taking the address of the destroyElement function template instantiated with the types in the pack. Once we have the array of de-

 $^{^{18}\}mathrm{The}$ corresponding code has been tested with Clang 11.0.1 and GCC 10.2 at optimization level -03.

structor functions, matching the expected order of the runtime index d_active, we can simply invoke the function pointer at the current index to invoke the correct destructor for the currently active element.

Note that this constant-time lookup is also the simplest of the three forms presented since it leans more heavily on integrating variadic pack expansion with other language features, in this case braced array initialization.

It may appear that <code>destroyCtTime</code> is the best of the lot: It runs in constant time, it's small, it's simple, and it's easy to understand. However, upon a closer look, <code>destroyCtTime</code> has serious performance disadvantages. First, each destructor call entails an indirect call, which is notoriously difficult to inline and optimize except for the most trivial cases. ¹⁹

Second, it is often the case that many types involved in a Variant have trivial destructors that do not perform any work at all. The functions destroyLinear and destroyLog have a white-box approach that naturally leads to the inlining and subsequent elimination of such destructors, leading to a massive simplification of the ultimately generated code. In contrast, destroyCtTime cannot take advantage of such opportunities; even if some destructors do no work, they will still be hidden beyond an indirect call, which is paid in all cases.

There is, however, a way to combine the advantages of destroyCtTime, destroyLinear, and destroyLog by using a meta-algorithmic strategy called algorithm selection²⁰: Choose the appropriate algorithm depending on the Variant instantiation. The characteristics of instantiation can be inferred by using compile-time introspection. The criteria for selecting the best of three algorithms can be fairly complex. For instantiations with only a few types, most of which have trivial destructors, destroyLinear is likely to work best; for moderately large parameter pack sizes, destroyLog will be the algorithm of choice; finally, for very large parameter pack sizes, destroyCtTime is best.

For a simple example, we can use the parameter pack size as a simple heuristic:

```
template <class T, class... Ts> // definition for partial specialization
Variant<T, Ts...>::~Variant() // improved destructor implementation
{
    assert((d_active < Variant<T,Ts...>::size)); // check invariant of variant
    void* p = &d_data; // `d_data` as `void*`
    if (Variant<T,Ts...>::size <= 4)
        destroyLinear<0u, T, Ts...>(d_active, p); // choose linear algorithm
    else if (Variant<T,Ts...>::size <= 64)</pre>
```

 $^{^{19}\}mathrm{GCC}$ 10.2 generates tables and indirect calls even for the most trivial uses. Clang 11.0.1 is able to optimize away indirect calls for locally defined Variant objects only if the function has no control flow affecting Variant values. Both compilers were tested at optimization level -03.

Chapter 2 Conditionally Safe Features

The constants 4 and 64 deciding the thresholds for choosing between algorithms are called **metaparameters** and are to be chosen experimentally. As mentioned, a more sophisticated implementation would eliminate from Ts... all types that have trivial destructors and focus only on the types that require destructor calls. Distinguishing between trivial and non-trivial destructors is possible with the help of the Standard Library introspection primitive $std::is_trivially_destructible$ introduced in C++11.

advanced-traits

Advanced traits

The use of **template template** parameters with variadic arguments allows us to create partial template specializations that match template instances with an arbitrary number of type parameters. This allows the definition of traits that were not possible with prevariadics technology.

For example, consider the family of **smart pointer** templates. A smart pointer type virtually always is instantiated from a template having the pointed-to type as its first parameter:

```
template <typename T>
struct SmartPtr1
{
    typedef T value_type;
    T& operator*() const;
    T* operator->() const;
    // ...
};
```

A more sophisticated smart pointer might take one or more additional template parameters, such as a deletion policy:

```
template <class T, class Deleter>
struct SmartPtr2
{
    T& operator*() const;
    T* operator->() const;
    // ...
};
```

SmartPtr2 still takes a value type as its first template parameter but also takes a Deleter functor for destroying the pointed-to object. (The Standard Library smart pointer std::unique_ptr added with C++11 also takes a deleter parameter). Note that the author of SmartPtr2 did not add a nested value_type, yet the human reader can easily deduce that SmartPtr2's value type is T.

Now, we aim to define a traits class template that, given an arbitrary pointer-like type such as SmartPtr1<int> or SmartPtr2<double, MyDeleter>, can deduce the value type

pointed-to by the pointer (in our examples, as **int** and **double**, respectively). Additionally, our traits class should allow us to "rebind" the pointer-like type, yielding a new pointer-like type with a different value type. Such an operation is useful, for example, when we want to use the same smart pointer facility as another library, but with our own types.

Suppose, for example, a library defines a type Widget:

```
class Widget // third-party class definition \{ \ /^* \dots^* / \};
```

Furthermore, the same library defines type WidgetPtr that behaves like a pointer to a Widget type but could be (depending on the library version, debug versus release builds, and so on) either SmartPtr1 or SmartPtr2:

```
class FastDeleter
                      // policy for performing minimal checking on SmartPtr2
{ /*...*/ };
class CheckedDeleter
                            // policy for performing maximal checking on SmartPtr2
{ /*...*/ };
#if !defined(DBG_LEVEL)
typedef SmartPtr1<Widget>
   WidgetPtr;
                                            // release mode, fastest
#elif DBG LEVEL >= 2
typedef SmartPtr2<Widget, CheckedDeleter>
                                            // safe smart pointer for debugging
   WidgetPtr;
#else
typedef SmartPtr2<Widget, FastDeleter>
   WidgetPtr;
                                            // safety/speed compromise
#endif
```

In debug mode (DBG_LEVEL defined), the library uses a SmartPtr2 smart pointer that does additional checking around, for example, dereference and deallocation. There are two possible debugging levels, one with stringent checks and one that cuts a trade-off between safety and speed. In release mode, the library wants to run at full speed so it uses SmartPtr1. User code simply uses WidgetPtr transparently because the interfaces of the types are very similar.

On the client side, we'd like to define a GadgetPtr type that behaves like a pointer to our own type Gadget but automatically adjusts to use the same smart pointer underpinnings, if any, that WidgetPtr is using. However, we don't have control over DBG_LEVEL or over the code introducing WidgetPtr. The strategies used by the definition of WidgetPtr may change across releases. How can we robustly figure out what kind of pointer — smart or not — WidgetPtr is representing?

Let's begin by declaring a primary class template with no body, and then specializing it for native pointer types:



Chapter 2 Conditionally Safe Features

```
{
    typedef T value_type; // normalized alias for T
    template <class U>
    using rebind = U*; // rebind<U> is an alias for U*
};
```

The new **using** syntax has been introduced in C++11 as a generalized **typedef**; see Section 1.1."??" on page ??. PointerTraits provides a basic traits API. For any built-in pointer type, P, PointerTraits<P>::value_type resolves to whatever type P points to. Moreover, for some other type, X, PointerTraits<P>::rebind<X> is an alias for X*, i.e., it propagates the information that P is a built-in pointer to X:

PointerTraits has a nested type, value_type, and a nested alias template, rebind. The first static_assert shows that, when Ptr is int*, value_type is int. The second static_assert shows that, when Ptr is int*, rebind<double> is double*. In other words, PointerTraits can determine the pointed-to type for a raw pointer and provides a facility for generating a raw pointer type pointing to a different value type.

For now, however, PointerTraits is not defined for any type that is not a builtin pointer. For PointerTraits to work with an arbitrary smart pointer class (such as
SmartPtr1 and SmartPtr2 above but also std::shared_ptr, std::unique_ptr, and std::weak_ptr),
we must partially specialize it for a template instantiation, PtrLike<T, X...>, where T is
assumed to be the value type and X... is a parameter pack of zero or more additional type
parameters to PtrLike:

This partial specialization will produce the correct result for any pointer-like class template that takes one or more type template parameters, where the first parameter is the value type of the pointer. First, it correctly deduces the value_type from the first argument to the template:

```
typedef SmartPtr2<Widget, CheckedDeleter> WP1; // fully checked
typedef SmartPtr2<Widget, FastDeleter> WP2; // minimally checked
static_assert(std::is_same<
    PointerTraits<WP1>::value_type, // Fetch the pointee type of WP1.
```

```
Widget>::value, "");  // should be Widget

static_assert(std::is_same<
    PointerTraits<WP1>::value_type,  // Fetch the pointee type of WP2.
    Widget>::value, "");  // should also be Widget
```

Second, rebind is able to reinstantiate the original template, SmartPtr2, with another first argument but the same second argument:

The Standard Library facility std::pointer_traits, introduced with C++11, is a superset of our PointerTraits example.

ntial-pitfalls-variadic Potential Pitfalls

use-of-c-style-ellipsis

Accidental use of C-style ellipsis

Inside the function parameters declaration, ... can be used only in conjunction with a template parameter pack. However, there is an ancient use of ... in conjunction with C-style variadic functions such as printf. That use can cause confusion. Say we set out to declare a simple variadic function, process, that takes any number of arguments by pointer:

The author meant to declare process as a variadic function taking any number of pointers to objects. However, instead of Widgets*..., the author mistakenly typed Widget*.... This typo took the declaration into a completely different place: It is now a C-style variadic function in the same category as printf. Recall the printf declaration in the C Standard Library:

```
int printf(const char* format, ...);
```

The comma and the parameter name are optional in C and C++, so omitting both leads to an equivalent declaration:

```
int printf(const char*...);
```

Comparing process (with the typo in tow) with printf makes it clear that process is a C-style variadic function. Runtime errors of any consequence are quite rare because the

Variadic Templates

Chapter 2 Conditionally Safe Features

expansion mechanisms are very different across the two kinds of variadics. However, the compile- and link-time diagnostics can be puzzling. In addition, if the variadic function ignores the arguments passed to it, calling it may even compile, but the call will use a different calling convention than that intended and assumed.

As an anecdote, a similar situation occurred during the review stage of this feature section. A simple misunderstanding caused a function to be declared inadvertently as a C-style variadic instead of C++ variadic template, leading to numerous indecipherable compile-time and link-time errors in testing that took many emails to figure out.

undiagnosed-errors

Undiagnosed errors

Description — Corner cases of function template argument matching on page 29 shows definitions of variadic template functions that are in error according to the C++ Standard yet pass compilation on contemporary compilers — that is, IFNDR. In certain cases, they can even be called. Such situations are most assuredly latent bugs:

```
template <typename... Ts, typename... Us, class T>
int process(Ts..., Us..., T);
    // ill-formed declaration - Us must be empty in every possible call
int x = process<int, double>(1, 2.5, 3);
    // Ts=<int, double>, Us=<>, T=int
```

In virtually all cases, such code reflects a misplaced expectation; an always-empty parameter pack has no reason to exist in the first place.

number-of-arguments

Compiler limits on the number of arguments

The C++ Standard recommends that compilers support at least 1024 arguments in a variadic template instantiation. Although this limit seems very generous, real-world code may push against it, especially in conjunction with generated code or combinatorial uses.

This limit may lead to a lack of portability in production — for example, code that works with one compiler but fails with another. Suppose, for example, we define Variant that carries all possible types that can be serialized in a large application:

```
typedef Variant<
    char,
    signed char,
    unsigned char,
    short,
    unsigned short
    // ... (more built-in and user-defined types)
>
WireData;
```

We release this code to production and then, at some later date, clients find it fails to build on some platforms, leading to a need to reengineer the entire solution to provide full cross-platform support.

74

Annoyances

annoyances-variadic unusable-functions

Unusable functions

Before variadics, any properly defined template function could be called by using explicit template argument specification, type deduction, or a combination thereof. Now it is possible to define variadic function templates that pass compilation but are impossible to call (either by using explicit instantiation, argument deduction, or both). This may cause confusion and frustration. Consider, for example, a few function templates, none of which take any function parameters:

The first four functions can be called by explicitly specifying their template arguments:

However, there is no way to call f5 because there is no way to specify T:

Recall that by the Rule of Greedy Matching (see *Description — The Rule of Greedy Matching* on page 25), Ts will match all of the template arguments passed to f5, so T is starved. Such uncallable functions are IFNDR. There are several other variations that render variadic function templates uncallable and therefore IFNDR. However, most contemporary compilers do allow compilation of f5.²¹ If other overloads of such an uncallable function are present, the matter may be interpreted as the wrong overload being called.

Limitations on expansion contexts

As discussed in Description — Pack expansion on page 36 and in the sections that follow it, expansion contexts are prescriptive. The standard enumerates all expansion contexts

²¹The corresponding code has been tested with Clang 11.0 and GCC 7.5.

Variadic Templates

Chapter 2 Conditionally Safe Features

exhaustively: There is no other place in a C++ program where a parameter pack is allowed to occur, even if it seems syntactically and semantically correct.

For example, consider a variadic function template, bump1, that attempts to expand and increment each of the arguments in its parameter pack:

Attempting to expand a parameter pack at the statement level is simply not among the allowed expansion contexts; hence, the example function body above fails to compile.

Such limitations can be worked around by artificially creating an expansion context. For example, we can achieve our goal by replacing the erroneous line in bump1 (above) with one in bump2 (below) that, say, creates a local class with a constructor that takes Ts&... as parameters:

The code above creates a local **struct** called **Local** with a constructor and immediately constructs an object of that type called **local**. Expansion is allowed inside the argument list for the constructor call, which makes the code work.

A possibility to achieve the same effect with terser code is to create a lambda expression, [](Ts&...){} and then immediately call it with the expansion ++vs... as its arguments:

The function above works, albeit awkwardly, by making use of another feature of C++11 that essentially allows us to define an anonymous function *in situ* and then invoke it; see "??" on page ?? [AUs: You have "lambda expressions" here. Do you mean the lambda, lambda capture, or generic lambda feature?]²²

Parameter packs cannot be used unexpanded

As discussed in *Description* — *Pack expansion* on page 36, the name of a parameter pack cannot appear on its own in a correct C++ program; the only way to use a parameter pack

ot-be-used-unexpanded

 $^{^{22}\}text{C}++17$ adds fold expressions that allow easy pack expansion at expression and statement level. The semantics desired for the example shown would be achieved with the syntax (...++vs);.

is as part of an expansion by using ... or **sizeof**. Such behavior is unlike types, template names, or values.

It is impossible to pass parameter packs around or to give them alternative names (as is possible with types by means of **typedef** and **using** and with values by means of references). Consequently, it is also impossible to define them as "return" values for metafunctions following conventions such as ::type and ::value that are commonly used in the <type_traits> standard header.

Consider, for example, sorting a type parameter pack by size. This simple task is not possible without a few helper types because there is no way to return the sorted pack. One necessary helper would be a typelist:

```
template <typename...> struct Typelist { };
```

With this helper type in hand, it is possible to encapsulate parameter packs, give them alternate names, and so on — in short, give parameter packs the same maneuverability that C++ types have:

```
typedef Typelist<short, int, long, float, double, long double> Numbers;
   // can be used to give a pack an alternate name

typedef SortBySize<Numbers>::type SortedNumbers;
   // can be used to "return" a pack from a metafunction
```

Currently no Typelist facility has been standardized. An active proposal²³ introduces parameter_pack along the same lines as Typelist above. Meanwhile compiler vendors have attempted to work around the problem in nonstandard ways.²⁴ A related proposal²⁵ defines std::bases and std::direct_bases but has, at the time of writing, been rejected.

Expansion is rigid and requires verbose support code

There are only two syntactic constructs that apply to parameter packs: **sizeof...** and expansion via The latter underlies virtually all treatment of variadics and, as discussed, requires handwritten support classes or functions as scaffolding toward building a somewhat involved recursion-based pattern.

There is no expansion in an expression context, so it is not possible to write functions such as print in a concise, single-definition manner; see *Use Cases — Generic variadic functions* on page 52. In particular, expressions are not expansion contexts so the following code would not work:

```
template <class T, typename... Ts>
std::ostream& print(const T& v, const Ts&... vs)
{
    std::cout << vs...;
    return std::cout << std::endl;</pre>
```

²⁵[AUs: url please, so I can cite this.

s-verbose-support-code

77

²⁴GNU defines the nonstandard primitives std::tr2::__direct_bases and std::tr2::__bases. The first yields a list of all direct bases of a given class, and the second yields the transitive closure of all bases of a class, including the indirect ones. To make these artifacts possible, GNU defines and uses a helper __reflection_typelist class template similar to Typelist above.



Variadic Templates

Chapter 2 Conditionally Safe Features

}

search-for-everything

Linear search for everything

One common issue with parameter packs is the difficulty of accessing elements in an indexed manner. Getting to the nth element of a pack is a linear search operation by necessity, which makes certain uses awkward and potentially time-consuming during compilation. Refer to the implementation of destroyLog in *Use Cases* — *Variant types* on page 60 as an example.

see-also

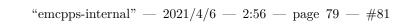
See Also

- "??" (§2.1, p. ??) ♦ illustrates one of the expansion contexts for function parameter packs.
- "??" (§2.1, p. ??) ♦ describes a feature used in conjunction with variadics to achieve perfect forwarding.
- "??" (, p. ??) ♦ [AUs: By "Lambda Expressions," do you mean lambda, generic lambda, or lambda capture?]describes a feature that allows expansion both in capture list and in the arguments list.

Further Reading

further-reading

- "F.21: To return multiple"out" values, prefer returning a struct or tuple," ?
- ?



 \oplus

C++14

Variadic Templates

sec-conditional-cpp14



"emcpps-internal" — 2021/4/6 — 2:56 — page 80 — #82









Chapter 3

Unsafe Features

sec-unsafe-cpp11 Intro text should be here.





Chapter 3 Unsafe Features

sec-unsafe-cpp14