

MEC E 301

## Lab 4: Displacement Transducers

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## Question 1

### (a) Quarter Bridge

Table 1: Quarter bridge results for various mass loads

Mass (kg)	$E_{nw}$ (V)	$E_w$ (V)	$\Delta E_w$ (V)	$\Delta E_0$ (V)	$\epsilon$
0.050	0.870	0.886	0.016	5.33E-06	3.09E-06
0.100	0.864	0.912	0.048	1.60E-05	9.28E-06
0.200	0.870	0.941	0.071	2.37E-05	1.37E-05
0.500	0.870	1.073	0.203	6.77E-05	3.92E-05
1.000	0.851	1.270	0.419	1.40E-04	8.10E-05
1.000	0.844	1.257	0.413	1.38E-04	7.98E-05
1.000	0.864	1.276	0.412	1.37E-04	7.96E-05
1.000	0.773	1.192	0.419	1.40E-04	8.10E-05
1.000	0.773	1.196	0.423	1.41E-04	8.18E-05
1.000	0.777	1.202	0.425	1.42E-04	8.22E-05

Sample calculation for  $E_0$  of 0.05 kg load:

$$\begin{aligned}
 E_0 &= \frac{E_w - E_{nw}}{G} \\
 &= \frac{0.886 - 0.870}{3000} \\
 &= \boxed{5.33 \times 10^{-6} \text{ V}}
 \end{aligned}$$

Sample calculation for  $\epsilon$  of 0.05 kg load:

$$E_0 = \frac{1}{4} E_{in} F_g (\epsilon_1 - \epsilon_2 - \epsilon_3 + \epsilon_4) \quad (1)$$

From Fig. 1, we can see that  $\epsilon_2 = \epsilon_3 = \epsilon_4 = 0$  for the quarter bridge configuration. Therefore, the

Table 2: Half bridge results for various mass loads

Mass (kg)	$E_{nw}$ (V)	$E_w$ (V)	$\Delta E_w$ (V)	$\Delta E_0$ (V)	$\epsilon$
0.050	0.400	0.442	0.042	1.40E-05	4.06E-06
0.100	0.396	0.483	0.087	2.90E-05	8.41E-06
0.200	0.403	0.567	0.164	5.47E-05	1.59E-05
0.500	0.400	0.819	0.419	1.40E-04	4.05E-05
1.000	0.396	1.234	0.838	2.79E-04	8.10E-05
1.000	0.393	1.234	0.841	2.80E-04	8.13E-05
1.000	0.396	1.231	0.835	2.78E-04	8.07E-05
1.000	0.390	1.237	0.847	2.82E-04	8.19E-05
1.000	0.390	1.234	0.844	2.81E-04	8.16E-05
1.000	0.396	1.237	0.841	2.80E-04	8.13E-05

equation simplifies to:

$$\begin{aligned}
 E_0 &= \frac{1}{4} E_{in} F_g(\epsilon_1) \\
 \Rightarrow \epsilon &= \frac{4E_0}{E_{in} F_g} \\
 \epsilon &= \frac{4 \times 5.33E-06}{3.30 \times 2.09} \\
 &= \boxed{qt y 3.09E-06}
 \end{aligned}$$

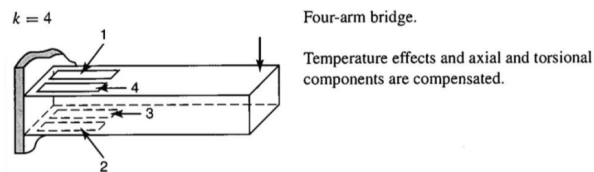


Figure 1: Strain gage configuration

## (b) Half Bridge

Sample calculations for  $E_0$  are identical to those for the quarter bridge configuration.

Sample calculation for  $\epsilon$  of 0.05 load is similar to that of the quarter bridge configuration. From

Eq. (1) and Fig. 1, we can see that  $\epsilon_3 = \epsilon_4 = 0$  for the half bridge configuration. Also,  $\epsilon_1 - \epsilon_2 = 2\epsilon$ . Therefore, the equation simplifies to:

$$\begin{aligned}
 E_0 &= \frac{1}{2} E_{in} F_g(\epsilon) \\
 \Rightarrow \epsilon &= \frac{2E_0}{E_{in} F_g} \\
 \epsilon &= \frac{2 \times 1.40E - 05}{3.30 \times 2.09} \\
 &= \boxed{4.06E - 06}
 \end{aligned}$$

### (c) Full Bridge

Table 3: Full bridge results for various mass loads

Mass (kg)	$E_{nw}$ (V)	$E_w$ (V)	$\Delta E_w$ (V)	$\Delta E_0$ (V)	$\epsilon$
0.050	0.274	0.358	0.084	2.80E-05	4.06E-06
0.100	0.271	0.435	0.164	5.47E-05	7.93E-06
0.200	0.271	0.609	0.338	1.13E-04	1.63E-05
0.500	0.271	1.115	0.844	2.81E-04	4.08E-05
1.000	0.271	1.969	1.698	5.66E-04	8.21E-05
1.000	0.274	1.972	1.698	5.66E-04	8.21E-05
1.000	0.274	1.966	1.692	5.64E-04	8.18E-05
1.000	0.271	1.966	1.695	5.65E-04	8.19E-05
1.000	0.274	1.969	1.695	5.65E-04	8.19E-05
1.000	0.277	1.969	1.692	5.64E-04	8.18E-05

Sample calculations for  $E_0$  are identical to those for the quarter bridge configuration.

Sample calculation for  $\epsilon$  of 0.05 load is similar to that of the quarter bridge configuration. From

Eq. (1) and Fig. 1, we can see that  $\epsilon_1 - \epsilon_2 - \epsilon_3 - \epsilon_4 = 4\epsilon$ . Therefore, the equation simplifies to:

$$\begin{aligned}
 E_0 &= E_{\text{in}} F_g(\epsilon) \\
 \Rightarrow \epsilon &= \frac{E_0}{E_{\text{in}} F_g} \\
 \epsilon &= \frac{1.40E-05}{3.30 \times 2.09} \\
 &= \boxed{4.06 \times 10^{-6}}
 \end{aligned}$$

## Question 2

### (a) Theoretical Strain

The theoretical strains at various loads are given in Table 4.

Table 4: Theoretical strain value at a given loading

Mass	$M$	$\sigma$	$\epsilon$
(kg)	(Nm)	(Pa)	(m/m)
0.050	0.099	2.9E+05	4.2E-06
0.100	0.199	5.75E+05	8.35E-06
0.200	0.398	1.15E+06	1.67E-05
0.500	0.994	2.88E+06	4.17E-05
1.000	1.99	5.75E+06	8.35E-05

### (b) Sample Calculation

The beam measurements are given in Table 5.

The moment of inertia of the beam is calculated as follows:

$$\begin{aligned}
 I &= \frac{bh^3}{12} \\
 &= \frac{(12.8116 \times 10^{-3})(12.7256 \times 10^{-3})^3}{12} \\
 &= 2.20017 \times 10^{-9} \text{ m}^4
 \end{aligned}$$

Table 5: Beam dimension measurements

Dimension	Measurement Number					Nominal Mean
	1	2	3	4	5	
	(mm)	(mm)	(mm)	(mm)	(mm)	
$L$	203.5	202.5	202.5	202.5	202.5	202.7
$b$	12.810	12.813	12.811	12.812	12.812	12.812
$h$	12.726	12.729	12.724	12.724	12.725	12.726

For the 1 kg load, the theoretical strain is calculated as follows:

$$\begin{aligned}
 M &= mgl \\
 &= (1)(9.81)(0.2027) \\
 &= 1.99 \text{ Nm} \\
 \sigma &= \frac{Mh}{2I} \\
 &= \frac{(1.99)(12.726 \times 10^{-3})}{2(2.20017 \times 10^{-9})} \\
 &= 5.75 \text{ MPa} \\
 \epsilon &= \frac{\sigma}{E} \\
 &= \frac{5.75 \times 10^6}{68.9 \times 10^9} \\
 &= \boxed{8.35 \times 10^{-5} \text{ m/m}}
 \end{aligned}$$

### Question 3

#### (a) Plot of Bridge Output Voltage vs Theoretical Strain

The plot of bridge output voltage vs theoretical strain is shown in Figure 2.

#### (b) Sensitivity of Each Bridge

The sensitivity of each bridge is given in Table 6.

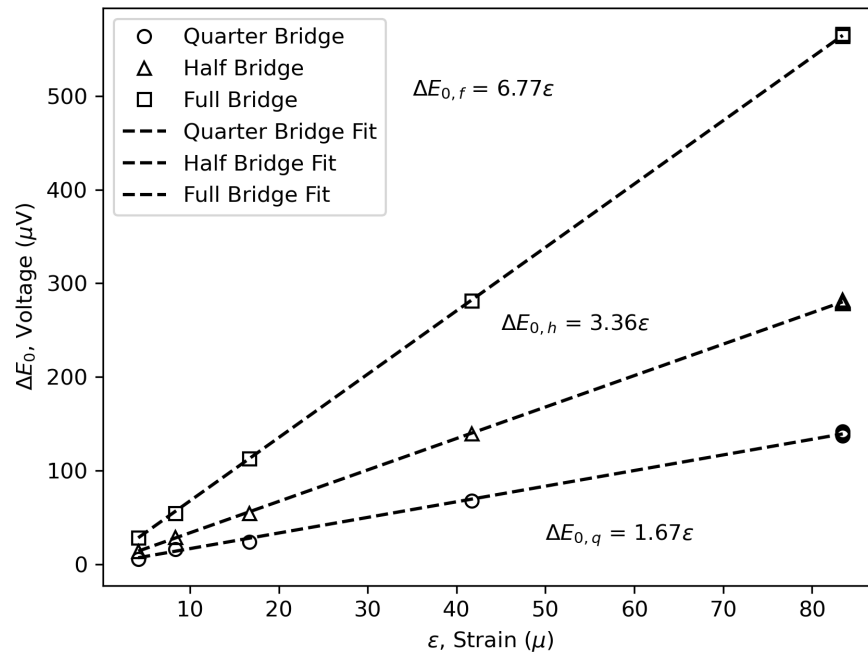


Figure 2: Plot of bridge output voltage vs theoretical strain

Table 6: Sensitivity of each bridge

Bridge	Sensitivity (V)
Quarter Bridge	1.67
Half Bridge	3.36
Full Bridge	6.77

### (c) Discussion

The full bridge has the highest sensitivity because it has the most strain gauges. For example, a displacement on the top will increase the measurement of the strain gauges  $\epsilon_1$  and  $\epsilon_4$ . A displacement on the bottom will increase the measurement of the strain gauges  $\epsilon_2$  and  $\epsilon_3$ . This results in  $\epsilon_1 - \epsilon_2 - \epsilon_3 + \epsilon_4 = 4\epsilon$ .

The least sensitive bridge is the quarter bridge because it only has one strain gauge. A displacement on the top will increase the measurement of the strain gauge  $\epsilon_1$ . None of the other strain gauges will be affected. This results in  $\epsilon_1 = \epsilon$ .

## Question 4

Table 7: Uncertainty in measurements of  $b$ ,  $h$ , and  $L$

Dimension	STDEV (mm)	$T_{\text{INV}}$	$P_x$ (mm)	$B_x$ (mm)	$U_x$ (mm)
$L$	0.4	2.7764	0.5	1	1
$b$	0.001	2.7764	0.001	0.003	0.003
$h$	0.002	2.7764	0.002	0.003	0.004

A sample calculation of the uncertainty in  $L$  is shown below. The uncertainty in  $b$  and  $h$  are calculated in a similar manner.

Using Excel's STDEV.S function applied to Table 5, T.INV function with  $\alpha = 0.05$  and  $n = 5$ , the precision uncertainty  $P_x$  is calculated as:

$$\begin{aligned}
 P_x &= \frac{S_x}{\sqrt{n}} \times t_{\alpha/2, n-1} \\
 &= \frac{0.4}{\sqrt{5}} \times 2.7764 \\
 &= 0.5 \text{ mm}
 \end{aligned}$$

The bias uncertainty  $B_x$  was given to be 1 mm. The total uncertainty  $U_x$  is calculated as:

$$\begin{aligned}
 U_x &= \sqrt{P_x^2 + B_x^2} \\
 &= \sqrt{(0.5)^2 + (1)^2} \\
 &= \boxed{1 \text{ mm}}
 \end{aligned}$$



## Question 5

The relevant equations are:

$$M = mgL$$

$$\sigma = \frac{Mh}{2I}$$

$$I = \frac{bh^3}{12}$$

$$\epsilon = \frac{\sigma}{E}$$

Combining these equations, we get:

$$\epsilon = \frac{6mgL}{bh^2E}$$

Computing the partials,

$$\frac{\partial \epsilon}{\partial m} = \frac{6gL}{bh^2E}$$

$$\frac{\partial \epsilon}{\partial L} = \frac{6mg}{bh^2E}$$

$$\frac{\partial \epsilon}{\partial b} = -\frac{6mgL}{b^2h^2E}$$

$$\frac{\partial \epsilon}{\partial h} = -\frac{12mgL}{bh^3E}$$

$$\frac{\partial \epsilon}{\partial E} = -\frac{6mgL}{bh^2E^2}$$

Evaluating the partials times the uncertainty in each variable,

$$\frac{\partial \epsilon}{\partial m} \delta m = 4.17 \times 10^{-7}$$

$$\frac{\partial \epsilon}{\partial L} \delta L = 4.60 \times 10^{-7}$$

$$\frac{\partial \epsilon}{\partial b} \delta b = 2.12 \times 10^{-8}$$

$$\frac{\partial \epsilon}{\partial h} \delta h = 4.96 \times 10^{-8}$$

$$\frac{\partial \epsilon}{\partial E} \delta E = 1.21 \times 10^{-6}$$

The total uncertainty is the RSS of the partials times the uncertainty in each variable:

$$\begin{aligned} \delta \epsilon &= \sqrt{(4.17 \times 10^{-7})^2 + (4.60 \times 10^{-7})^2 + (2.12 \times 10^{-8})^2 + (4.96 \times 10^{-8})^2 + (1.21 \times 10^{-6})^2} \\ &= \boxed{\pm 1.36 \times 10^{-6}} \end{aligned}$$

The calculations were handled by Matlab, and the code is shown below:

```
clc; clear; close all;
```

```
syms m g L b h E
```

```
epsilon = 6*m*g*L/(b*h^2*E)
```

```
delEdelm = diff(epsilon, m)
```

```
delEdelL = diff(epsilon, L)
```

```
delEdelb = diff(epsilon, b)
```

```
delEdelh = diff(epsilon, h)
```

```
delEdelE = diff(epsilon, E)
```

```
delEdelm_delta_m = double(subs(delEdelm, [m g L b h E], [1 9.81 0.2027  
0.012811 0.0127256 68.9*10^9]) * 0.005)
```

```
delEdelL_delta_L = double(subs(delEdelL, [m g L b h E], [1 9.81 0.2027  
0.012811 0.0127256 68.9*10^9]) * 1.11654678249935/1000)
```

```
delEdelb_delta_b = double(subs(delEdelb, [m g L b h E], [1 9.81 0.2027  
0.012811 0.0127256 68.9*10^9]) * 0.00325628602303491/1000)
```

```
delEdelh_delta_h = double(subs(delEdelh, [m g L b h E], [1 9.81 0.2027
```

```

0.012811 0.0127256 68.9*10^9)) * 0.00378200336150775/1000)
delEdelE_delta_E = double(subs(delEdelE, [m g L b h E], [1 9.81 0.2027
0.012811 0.0127256 68.9*10^9]) * 1*10^9)

delE_delta_E = sqrt(delEdelm_delta_m^2 + delEdelL_delta_L^2 +
delEdelb_delta_b^2 + delEdelh_delta_h^2 + delEdelE_delta_E^2)

```

## Question 6

### (a) Uncertainty in $\Delta E_w$

Table 8: Uncertainty in  $\Delta E_w$

Dimension	STDEV	T-INV	$P_x$	$B_x$	$U_x$
	(V)		(V)	(V)	(V)
$\Delta E_w$	2.683E-03	2.5706	2.8E-03	3.223E-03	4.3E-03

Again, standard deviation is calculated using Excel's `STDEV.S` function. T-INV is calculated using Excel's `T.INV` function with  $\alpha = 0.05$  and  $n = 6$ . The precision uncertainty  $P_x$  is calculated as:

$$\begin{aligned}
 P_x &= \frac{S_x}{\sqrt{n}} \times t_{\alpha/2, n-1} \\
 &= \frac{2.683E-03}{\sqrt{6}} \times 2.5706 \\
 &= 2.8 \times 10^{-3} \text{ V}
 \end{aligned}$$

The bias uncertainty  $B_x$  is the resolution,

$$\begin{aligned}
 B_x &= \frac{3.3}{2^{10}} \\
 &= 3.223 \times 10^{-3} \text{ V}
 \end{aligned}$$

The total uncertainty  $U_x$  is calculated as:

$$\begin{aligned}
 U_x &= \sqrt{P_x^2 + B_x^2} \\
 &= \sqrt{(2.8 \times 10^{-3})^2 + (3.223 \times 10^{-3})^2} \\
 &= \boxed{4.3 \times 10^{-3} \text{ V}}
 \end{aligned}$$

**(b) Uncertainty in  $\Delta E_0$** 

The equation for  $\Delta E_0$  is given by:

$$\begin{aligned}\Delta E_0 &= \frac{\Delta E_w}{G} \\ &= \frac{4.3 \times 10^{-3}}{2.09} \\ &= \boxed{2.06 \times 10^{-3} \text{ V}}\end{aligned}$$

Calculating the partials,

$$\begin{aligned}\frac{\partial \Delta E_0}{\partial \Delta E_w} &= \frac{1}{G} \\ \frac{\partial \Delta E_0}{\partial G} &= -\frac{\Delta E_w}{G^2}\end{aligned}$$

Calculating the partials times the uncertainty (the nominal value for  $\Delta E_w$  is 1.160 V),

$$\begin{aligned}\frac{\partial \Delta E_0}{\partial \Delta E_w} \delta \Delta E_w &= \frac{1}{3000} \times 4.3 \times 10^{-3} \\ &= 1.4 \times 10^{-6} \\ \frac{\partial \Delta E_0}{\partial G} \delta G &= -\frac{1.160}{3000^2} \times 1 \times 3000 \\ &= -3.9 \times 10^{-6}\end{aligned}$$

The total uncertainty is the RSS of the partials times the uncertainty in each variable:

$$\begin{aligned}\delta \Delta E_0 &= \sqrt{(1.4 \times 10^{-6})^2 + (-3.9 \times 10^{-6})^2} \\ &= \boxed{3.6 \times 10^{-5} \text{ V}}\end{aligned}$$

**Question 7**

The equation for strain for the full bridge is:

$$\epsilon = \frac{\Delta E_0}{F_g V_{\text{in}}}$$

The partials are:

$$\begin{aligned}\frac{\partial \epsilon}{\partial \Delta E_0} &= \frac{1}{F_g V_{\text{in}}} \\ \frac{\partial \epsilon}{\partial F_g} &= -\frac{\Delta E_0}{F_g^2 V_{\text{in}}} \\ \frac{\partial \epsilon}{\partial V_{\text{in}}} &= -\frac{\Delta E_0}{F_g V_{\text{in}}^2}\end{aligned}$$

Evaluating the partials times the uncertainty of each variable is shown in Table 9. For example,

$$\begin{aligned}\frac{\partial \epsilon}{\partial \Delta E_0} \delta \Delta E_0 &= \frac{1}{2.09 \times 3.3} \times 5.65 \times 10^{-4} \\ &= 5.21 \times 10^{-6}\end{aligned}$$

Table 9: Partial times uncertainty for variables in  $\epsilon$

Variable	Nominal Value	Uncertainty	$\frac{\partial \epsilon}{\partial x_i} \delta x_i$
$\Delta E_0$	5.65E-04	3.59E-05	5.21E-06
$F_g$	2.09	0.02	-7.83E-07
$V_{\text{in}}$	3.3	0.017	-1.35E-06

The total uncertainty in  $\epsilon$  is the RSS of the partials times the uncertainty in each variable:

$$\begin{aligned}U_x &= \sqrt{\left(\frac{\partial \epsilon}{\partial \Delta E_0} \delta \Delta E_0\right)^2 + \left(\frac{\partial \epsilon}{\partial F_g} \delta F_g\right)^2 + \left(\frac{\partial \epsilon}{\partial V_{\text{in}}} \delta V_{\text{in}}\right)^2} \\ &= \sqrt{(5.21 \times 10^{-6})^2 + (-7.83 \times 10^{-7})^2 + (-1.35 \times 10^{-6})^2} \\ &= \boxed{5.4 \times 10^{-6}}\end{aligned}$$

## A Appendix: Displacement Table of Potentiometer

Table A.10: Displacement table of potentiometer

Caliper Reading (mm)	Up 1 (mm)	Down 1 (mm)	Up 2 (mm)	Down 2 (mm)	Up 3 (mm)
0.00		-0.16		-0.16	
3.64	3.61	3.61	3.61	3.65	3.61
7.64	7.69	7.69	7.69	7.69	7.73
11.64	11.69	11.69	11.69	11.66	11.66
15.64	15.70	15.66	15.66	15.66	15.70
19.64	19.65	19.65	19.61	19.61	19.65
23.64	23.66	23.62	23.66	23.62	23.66
27.64	27.70	27.66	27.66	27.66	27.70
31.64	31.67	31.63	31.67	31.63	31.67
39.10	38.98		38.98		38.98

## B Appendix: Hall Effect Sensor Displacement Table

Table B.11: Hall effect sensor displacement table

Caliper Reading (mm)	Sensor Reading Number				
	1 (mm)	2 (mm)	3 (mm)	4 (mm)	5 (mm)
0.00	-0.01	-0.01	0.00	-0.01	-0.01
0.38	0.40	0.41	0.40	0.40	0.39
0.88	0.86	0.88	0.87	0.86	0.85
1.38	1.36	1.34	1.38	1.37	1.37
1.88	1.92	1.92	1.89	1.89	1.87
2.38	2.40	2.41	2.41	2.41	2.40
2.88	2.83	2.90	2.87	2.83	2.86