

Question 1

Write down the full set of governing equations (continuity, momentum and energy).

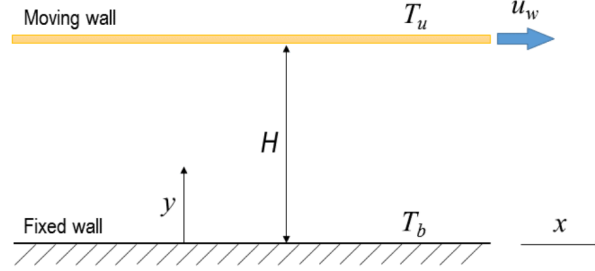


Figure 1: Fluid flow between parallel plates. The bottom plate is fixed, the upper plate is moving horizontally with velocity u_w . The fluid is incompressible and Newtonian.

Solution

We first begin with continuity,

$$\frac{\partial \rho}{\partial t} + \vec{u} \cdot \nabla \rho + \rho(\nabla \cdot \vec{u}) = 0$$

then, the momentum equation,

$$\frac{\partial}{\partial t}(\rho u_i) + \frac{\partial}{\partial x_j}(\rho u_i u_j) = -\frac{\partial P}{\partial x_i} + \frac{\partial}{\partial x_j} \left[\mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right] - \frac{\partial}{\partial x_i} \left(\frac{2}{3} \mu \frac{\partial u_k}{\partial x_k} \right) + \rho b_i$$

lastly, the energy equation,

$$\rho C_p \left(\frac{T}{\partial t} + \vec{v} \cdot \nabla T \right) = k \nabla^2 T + \frac{\mu}{2} \Phi^2$$

where $\Phi_{i,j} = \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$.

Question 2

Write down the momentum conservation equations in Cartesian coordinates. Simplify them using conditions outlined in bullet points.

Table 1: Assumptions and simplifying consequences

Assumption	Consequence
Steady State (S.S.)	$\frac{\partial}{\partial t} = 0$
Incompressible	$\rho = \text{constant}$
Newtonian	$\mu = \text{constant}$
2D Flow	$u_z = \partial_z = 0$
Parallel	$u_y = \partial_y = 0$
Fully developed (F.D.)	$v_x = v_x(y), T = T(y), \partial_x = 0$

We begin with the continuity equation,

$$\overset{\text{S.S.}}{\cancel{\frac{\partial \rho}{\partial t}}} + \vec{u} \cdot \nabla \overset{\text{Incmp.}}{\cancel{\rho}} + \rho(\nabla \cdot \vec{u}) = 0$$

this simplifies to,

$$\frac{\partial}{\partial x} u_x + \frac{\partial}{\partial y} u_y + \frac{\partial}{\partial z} u_z = 0$$

We begin in the x-direction with the momentum equation,

$$\overset{\text{S.S.}}{\cancel{\frac{\partial}{\partial t}}}(\rho u_x) + \frac{\partial}{\partial x_j}(\rho u_x u_j) = \overset{\text{F.D.}}{\cancel{-\frac{\partial P}{\partial x}}} + \frac{\partial}{\partial x_j} \left[\mu \left(\frac{\partial u_x}{\partial x_j} + \frac{\partial u_j}{\partial x_x} \right) \right] - \frac{\partial}{\partial x} \left(\frac{2}{3} \mu \frac{\partial u_k}{\partial x_k} \right) + \rho b_x$$

which simplifies to,

$$\rho \left(\overset{\text{F.D.}}{\cancel{\frac{\partial}{\partial x}}}(u_x^2) + \overset{\text{Par.}}{\cancel{\frac{\partial}{\partial y}}}(u_x u_y) + \overset{\text{2D}}{\cancel{\frac{\partial}{\partial z}}}(u_x u_z) \right) = \mu \left(\overset{\text{Par.}}{\cancel{\frac{\partial^2 u_x}{\partial y^2}}} + \overset{\text{2D}}{\cancel{\frac{\partial^2 u_x}{\partial z^2}}} \right) + \rho b_x$$

0 = b_x

Next, we move to the y-direction,

$$\overset{\text{S.S.}}{\cancel{\frac{\partial}{\partial t}}}(\rho u_y) + \frac{\partial}{\partial x_j}(\rho u_y u_j) = \overset{\text{F.D.}}{\cancel{-\frac{\partial P}{\partial y}}} + \frac{\partial}{\partial x_j} \left[\mu \left(\frac{\partial u_y}{\partial x_j} + \frac{\partial u_j}{\partial x_y} \right) \right] - \frac{\partial}{\partial y} \left(\frac{2}{3} \mu \frac{\partial u_k}{\partial x_k} \right) + \rho b_y$$

which simplifies to,

$$\rho \left(\overset{\text{Par.}}{\cancel{\frac{\partial}{\partial x}}}(u_x u_y) + \overset{\text{F.D.}}{\cancel{\frac{\partial}{\partial y}}}(u_y^2) + \overset{\text{2D}}{\cancel{\frac{\partial}{\partial z}}}(u_y u_z) \right) = \mu \left(\overset{\text{Par.}}{\cancel{\frac{\partial^2 u_y}{\partial x^2}}} + \overset{\text{2D}}{\cancel{\frac{\partial^2 u_y}{\partial z^2}}} \right) + \rho b_y$$

0 = b_y

Question 3

Consider the general form of momentum balance

$$\rho \frac{dv_i}{dt} = \frac{\partial T_{ji}}{\partial x_j} + \rho b_i \quad (1)$$

where d/dt is the total derivative; v_i is the velocity; ρ denotes density; T_{ij} is the stress tensor and b_i is a body force. This equation says that inertial and body forces are balanced by the gradients of the stress tensor.

The general form of the stress tensor reads

$$T_{ij} = -p\delta_{ij} + \mu \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) - \frac{2}{3}\mu \frac{\partial v_k}{\partial x_k} \delta_{ij} + \kappa \left(\frac{\partial v_k}{\partial x_k} \delta_{ij} \right) \quad (2)$$

where p is the pressure, μ is the shear (dynamic) viscosity and κ is the dialation viscocity. For each question assume the viscosities μ and κ are constant.

- Using equations (1) and (2) derive the general form of Navier-Stokes equations for compressible viscous fluid. Note: only index notation can be used. The final form of equations should be presented in operator (vector) form.
- Assuming $\kappa = 0$, write the full set of Navier-Stokes equations in Cartesian coordinates assuming two-dimensional flow (two equations corresponding to x and y directions).

Solution

(a)

First, deal with the stress tensor.

$$T_{ji} = -p\delta_{ji} + \mu \left(\frac{\partial v_j}{\partial x_i} + \frac{\partial v_i}{\partial x_j} \right) - \frac{2}{3}\mu \frac{\partial v_k}{\partial x_k} \delta_{ji} + \kappa \left(\frac{\partial v_k}{\partial x_k} \delta_{ji} \right)$$

Differentiate with respect to x_j ,

$$\frac{\partial T_{ji}}{\partial x_j} = -\frac{\partial p}{\partial x_j} \delta_{ji} + \mu \left(\frac{\partial^2 v_j}{\partial x_j \partial x_i} + \frac{\partial^2 v_i}{\partial x_j^2} - \frac{2}{3} \frac{\partial^2 v_k}{\partial x_j \partial x_k} \delta_{ji} \right) + \kappa \left(\frac{\partial^2 v_k}{\partial x_j \partial x_k} \delta_{ji} \right)$$

Substituting into equation 1,

$$\begin{aligned} \rho \frac{\partial v_i}{\partial t} + \rho v_j \frac{\partial v_i}{\partial x_j} &= -\frac{\partial p}{\partial x_j} \delta_{ji} + \mu \left(\frac{\partial^2 v_j}{\partial x_j \partial x_i} + \frac{\partial^2 v_i}{\partial x_j^2} - \frac{2}{3} \frac{\partial^2 v_k}{\partial x_j \partial x_k} \delta_{ji} \right) + \kappa \left(\frac{\partial^2 v_k}{\partial x_j \partial x_k} \delta_{ji} \right) + \rho b_i \\ &= -\frac{\partial p}{\partial x_i} + \mu \left(\frac{\partial^2 v_j}{\partial x_j \partial x_i} + \frac{\partial^2 v_i}{\partial x_j^2} - \frac{2}{3} \frac{\partial^2 v_k}{\partial x_i \partial x_k} \right) + \kappa \left(\frac{\partial^2 v_k}{\partial x_i \partial x_k} \right) + \rho b_i \end{aligned}$$

Converting the RHS to vector form,

$$\begin{aligned}\text{RHS} &= -\nabla p + \mu \left[\nabla(\nabla \cdot \vec{v}) + \nabla^2 \vec{v} - \frac{2}{3} \nabla(\nabla \cdot \vec{v}) \right] + \kappa \nabla(\nabla \cdot \vec{v}) + \rho \vec{b} \\ &= -\nabla p + \mu \nabla^2 \vec{v} + \left[\frac{\mu}{3} + \kappa \right] \nabla(\nabla \cdot \vec{v}) + \rho \vec{b}\end{aligned}$$

Converting the LHS to vector form,

$$\text{LHS} = \rho \left(\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \nabla) \vec{v} \right)$$

Combining the LHS and RHS,

$$\rho \left(\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \nabla) \vec{v} \right) = -\nabla p + \mu \nabla^2 \vec{v} + \left[\frac{\mu}{3} + \kappa \right] \nabla(\nabla \cdot \vec{v}) + \rho \vec{b}$$

(b)

Assuming $\kappa = 0$, the equation reduces to

$$\rho \left(\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \nabla) \vec{v} \right) = -\nabla p + \mu \nabla^2 \vec{v} + \frac{\mu}{3} \nabla(\nabla \cdot \vec{v}) + \rho \vec{b}$$

In Cartesian coordinates (x, y), assuming $\vec{v} = (u, v)$ and $\vec{b} = (b_x, b_y)$. In the x-direction,

$$\rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} \right) = -\frac{\partial p}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + \frac{\mu}{3} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} \right) + \rho b_x$$

In the y-direction,

$$\rho \left(\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} \right) = -\frac{\partial p}{\partial y} + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) + \frac{\mu}{3} \left(\frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^2 v}{\partial y^2} \right) + \rho b_y$$

Question 4

Consider the heat transfer in incompressible flow of Newtonian fluid. The following form of energy conservation equation holds for this case:

$$\rho C_p \left(\frac{\partial T}{\partial t} + \vec{v} \cdot \nabla T \right) = k \nabla^2 T + \frac{\mu}{2} \Phi^2$$

where T is the temperature, t is time, \vec{v} is the velocity, ρ is density, C_p is the heat capacity, k is the thermal conductivity, μ is the shear (dynamic) viscosity, and Φ_{ij} is the rate of shear tensor defined as

$$\Phi_{ij} = \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i}$$

- What is the physical interpretation of the following terms: $\rho C_p (\vec{v} \cdot \nabla T)$, $k \nabla^2 T$ and $\frac{\mu}{2} \Phi^2$.
- Write equation (3) in Cartesian coordinates assuming three-dimensional flow. Explain all the steps how the term Φ_{ij}^2 unfolds.

Solution

(a)

1. $\rho C_p(\vec{v} \cdot \nabla T)$ is the rate of change of energy due to convection.
2. $k \nabla^2 T$ is the rate of change of energy due to conduction.
3. $\frac{\mu}{2} \Phi^2$ is the rate of change of energy due to viscous dissipation (friction).

(b)

First deal with Φ_{ij}^2 ,

$$\Phi_{ij}^2 = \sum_{i,j}^3 \Phi_{ij} \Phi_{ij}$$

Then,

$$\begin{aligned} \Phi_{ij}^2 &= \Phi_{11}\Phi_{11} + \Phi_{21}\Phi_{21} + \Phi_{31}\Phi_{31} \\ &\quad + \Phi_{12}\Phi_{12} + \Phi_{22}\Phi_{22} + \Phi_{32}\Phi_{32} \\ &\quad + \Phi_{13}\Phi_{13} + \Phi_{23}\Phi_{23} + \Phi_{33}\Phi_{33} \end{aligned}$$

In Cartesian coordinates, assuming $v_i = (u, v, w)$, $x_i = (x, y, z)$,

$$\begin{aligned} \Phi_{ij}^2 &= \left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right)^2 \\ &\quad + \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} + \frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right)^2 \\ &\quad + \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} + \frac{\partial w}{\partial z} \right)^2 \\ &= 4 \left(\frac{\partial u}{\partial x} \right)^2 + 4 \left(\frac{\partial v}{\partial x} \right)^2 + 4 \left(\frac{\partial w}{\partial x} \right)^2 \\ &\quad + 2 \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 + 2 \left(\frac{\partial v}{\partial y} + \frac{\partial v}{\partial y} \right)^2 + 2 \left(\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right)^2 \end{aligned}$$

Now the rest of the terms,

$$\begin{aligned} \rho C_p \left[\frac{\partial T}{\partial t} + \left(u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} + w \frac{\partial T}{\partial z} \right) \right] = & k \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right) \\ & + \frac{\mu}{2} \left[4 \left(\frac{\partial u}{\partial x} \right)^2 + 4 \left(\frac{\partial v}{\partial x} \right)^2 + 4 \left(\frac{\partial w}{\partial x} \right)^2 \right. \\ & + 2 \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 + 2 \left(\frac{\partial v}{\partial y} + \frac{\partial w}{\partial x} \right)^2 \\ & \left. + 2 \left(\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right)^2 \right] \end{aligned}$$