

## Lecture 8

### Least-norm solutions of undetermined equations

#### ★ Undetermined linear equations

⇒ We consider

$$y = Ax$$

where  $A \in \mathbb{R}^{m \times n}$  is fat ( $m < n$ )

→ there are more variables than equations.

→  $x$  is underspecified  
(i.e. many choices of  $x$  lead to the same  $y$ )

⇒ We'll assume that  $A$  is full rank( $m$ ), so for each  $y \in \mathbb{R}^m$ , there is a solution set of all solutions has form

$$\{x \mid Ax = y\} = \{x_p + z \mid z \in N(A)\}$$

where  $x_p$  is any ('Particular') solution

(i.e.  $Ax_p = y$ )

⇒ Solution has  $\dim N(A) = n - m \Rightarrow$  degree of freedom

→ Can choose  $z$  to satisfy other specs or optimize among solutions.

### ★ Least-norm Solution

⇒ One particular solution is

$$x_m = A^T(AA^T)^{-1}y$$

{ $AA^T$  is invertible since  $A$  is full rank}

⇒  $x_m$  is solution of optimization problem

Minimize  $\|x\|$   
Subject to  $Ax = y$

 where  $x \in \mathbb{R}^n$

### Proof

⇒ Suppose  $Ax = y$ , so  $A(x - x_m) = 0$

$$\Rightarrow (x - x_m)^T x_m = (x - x_m)^T A^T (AA^T)^{-1} y$$

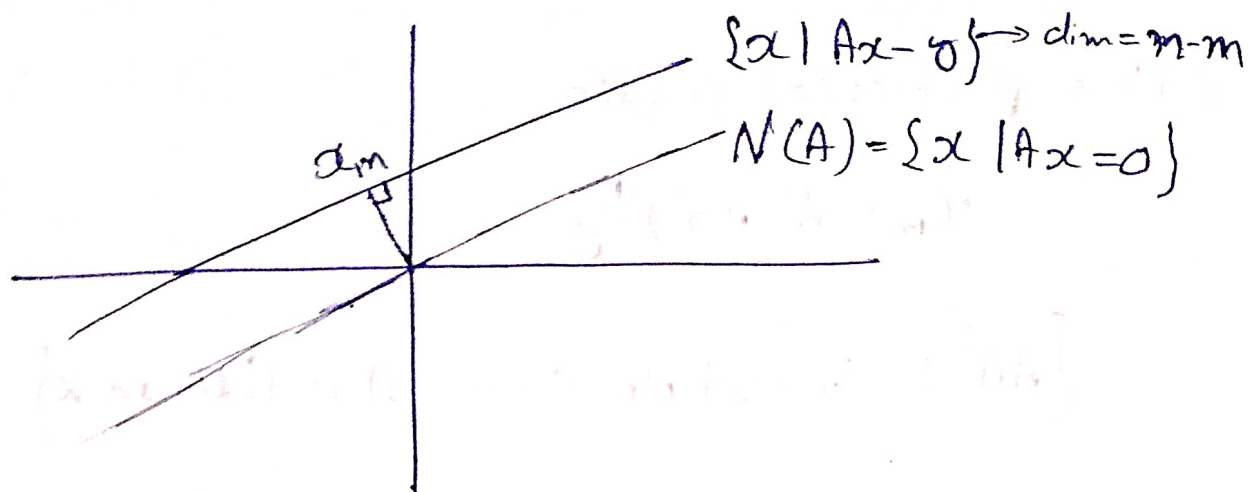
$$= (A(x - x_m))^T (AA^T)^{-1} y$$

$$= 0$$

$$\Rightarrow (x - x_m) \perp x_m$$

$$\Rightarrow \text{So, } \|x\|^2 = \|x_m + x - x_m\|^2 = \|x_m\|^2 + \|x - x_m\|^2 \geq \|x_m\|^2$$

$$\|x_m\|^2 \leq \|x\| \quad \left\{ x_m \text{ has smallest norm of any solution} \right\}$$



- Orthogonality Condition:  $x_m \perp N(A)$
- Projection interpretation:  $x_m$  is projection of 0 on solution set  $\{x | Ax = y\}$

$\Rightarrow A^+ = A^T(AA^T)^{-1}$  is called the pseudo-inverse of full rank, fat  $A$ .

$\Rightarrow A^T(AA^T)^{-1}$  is a right inverse of  $A$ .

$\Rightarrow I - A^T(AA^T)^{-1}A$  gives projection onto  $N(A)$ .

★ Least-norm solution via QR factorization

$\Rightarrow$  find QR factorization of  $A^T$  i.e.  $A^T = QR$  with

$\rightarrow Q \in \mathbb{R}^{n \times m}$ ,  $Q^T Q = I_m$

$\rightarrow R \in \mathbb{R}^{m \times m}$ , upper triangular, non singular

$\Rightarrow$  then

$$x_m = A^T(AA^T)^{-1}y = QR^{-1}y$$

$$\|x_m\| = \|R^{-1}y\|$$



## ★ Derivation via Lagrange multipliers

⇒ least-norm solution solves optimization problem

$$\text{minimize } x^T x$$

$$\text{subject to } Ax = y$$

⇒ Introduce Lagrange multipliers:

$$L(x, \lambda) = x^T x + \lambda^T (Ax - y)$$

Objective

Lagrange multipliers

Constraints

⇒ Optimality conditions are

$$\nabla_x L = 2x + A^T \lambda = 0 \Rightarrow x = -A^T \lambda / 2$$

$$\nabla_\lambda L = Ax - y = 0$$

$$\lambda = -2(AA^T)^{-1}y$$

⇒ hence

$$\boxed{x = A^T (AA^T)^{-1} y}$$

$$\|x\|_\infty = \max_i |x_i| \quad \{\text{infinity norm}\}$$

$$\|x\|_1 = \sum_i |x_i| \quad \{\text{Manhattan norm}\}$$

$$\|x\|_2 = \sqrt{\sum_i |x_i|^2} \quad \{\text{Euclidean norm}\}$$

## ★ Relation to regularized least-squares

⇒ Suppose  $A \in \mathbb{R}^{m \times n}$  is fat, full rank.

⇒ define  $J_1 = \|Ax - y\|^2$ ,  $J_2 = \|x\|^2$

⇒ least-norm solution minimizes  $J_2$  with  $J_1 = 0$

⇒ minimizer of weighted-sum objective

$$J_1 + \mu J_2 = \|Ax - y\|^2 + \mu \|x\|^2 \text{ is}$$

$$x_\mu = (A^T A + \mu I)^{-1} A^T y$$

⇒ fat:  $x_\mu \rightarrow x_{\text{in}}$  as  $\mu \rightarrow 0$

$\left\{ \begin{array}{l} \text{regularized solution converges to} \\ \text{least-norm solution as } \mu \rightarrow 0 \end{array} \right\}$

⇒ In matrix terms as  $\mu \rightarrow 0$

$$(A^T A + \mu I)^{-1} A^T \rightarrow A^T (A A^T)^{-1}$$

$\left\{ \text{for full rank, fat } A \right\}$

## \* General norm minimization with equality constraints

⇒ Consider problem,

$$\text{minimize } \|Ax - b\|$$

$$\text{Subject to } Cx = d$$

with variable  $x$

⇒ Includes least-square and least-norm problems  
as special case.

⇒ Equivalent to

$$\text{minimize } \frac{1}{2} \|Ax - b\|^2$$

$$\text{Subject to } Cx = d$$

⇒ Lagrangian is

$$L(x, \lambda) = \frac{1}{2} \|Ax - b\|^2 + \lambda^T (Cx - d)$$

$$= \frac{1}{2} x^T A^T A x - b^T A x + \frac{1}{2} b^T b + \lambda^T C x - \lambda^T d$$

$$\nabla_x L = A^T A x - A^T b + C^T \lambda = 0 \quad | \quad \nabla_\lambda L = Cx - d = 0$$

⇒ Write in block matrix form as:

$$\begin{bmatrix} A^T A & C^T \\ C & 0 \end{bmatrix} \begin{bmatrix} x \\ \lambda \end{bmatrix} = \begin{bmatrix} A^T b \\ d \end{bmatrix}$$

$$\begin{bmatrix} x \\ \lambda \end{bmatrix} = \begin{bmatrix} A^T A & C^T \\ C & 0 \end{bmatrix}^{-1} \begin{bmatrix} A^T b \\ d \end{bmatrix} \quad \left\{ \text{If invertible} \right\}$$

⇒ If  $A^T A$  is invertible, we can derive a more explicit (and complicated) formula for  $x$

$$x = (A^T A)^{-1} (A^T b - C^T \lambda)$$

⇒ Substitute into  $Cx = d$  we get

$$C(A^T A)^{-1} (A^T b - C^T \lambda) = d$$

$$\Rightarrow \lambda = (C(A^T A)^{-1} C^T)^{-1} (C(A^T A)^{-1} A^T b - d)$$

⇒ recover  $x$  from equation above:

$$x = (A^T A)^{-1} \left( A^T b - C^T (C(A^T A)^{-1} C^T)^{-1} (C(A^T A)^{-1} A^T b - d) \right)$$

