Constantint Satisfaction Paroblem (CSP)

=> Assumption about the woold: Fr A Single agent Deterministic oction Fully observed state Discrete State Space

Planning: Sequence of cetion > Path to the goal is the imported thing
> Paths have various costs, depths
> Meunistics give problem - specific guidance

Indentification: Assignments to vanidales > The goal itself is impartant, not the path > All paths at the Some depth Ly CSPs are a specialized class of identification problems.

-> State is a black box": arbitrary data structure

-> Goal test can be any Function over states

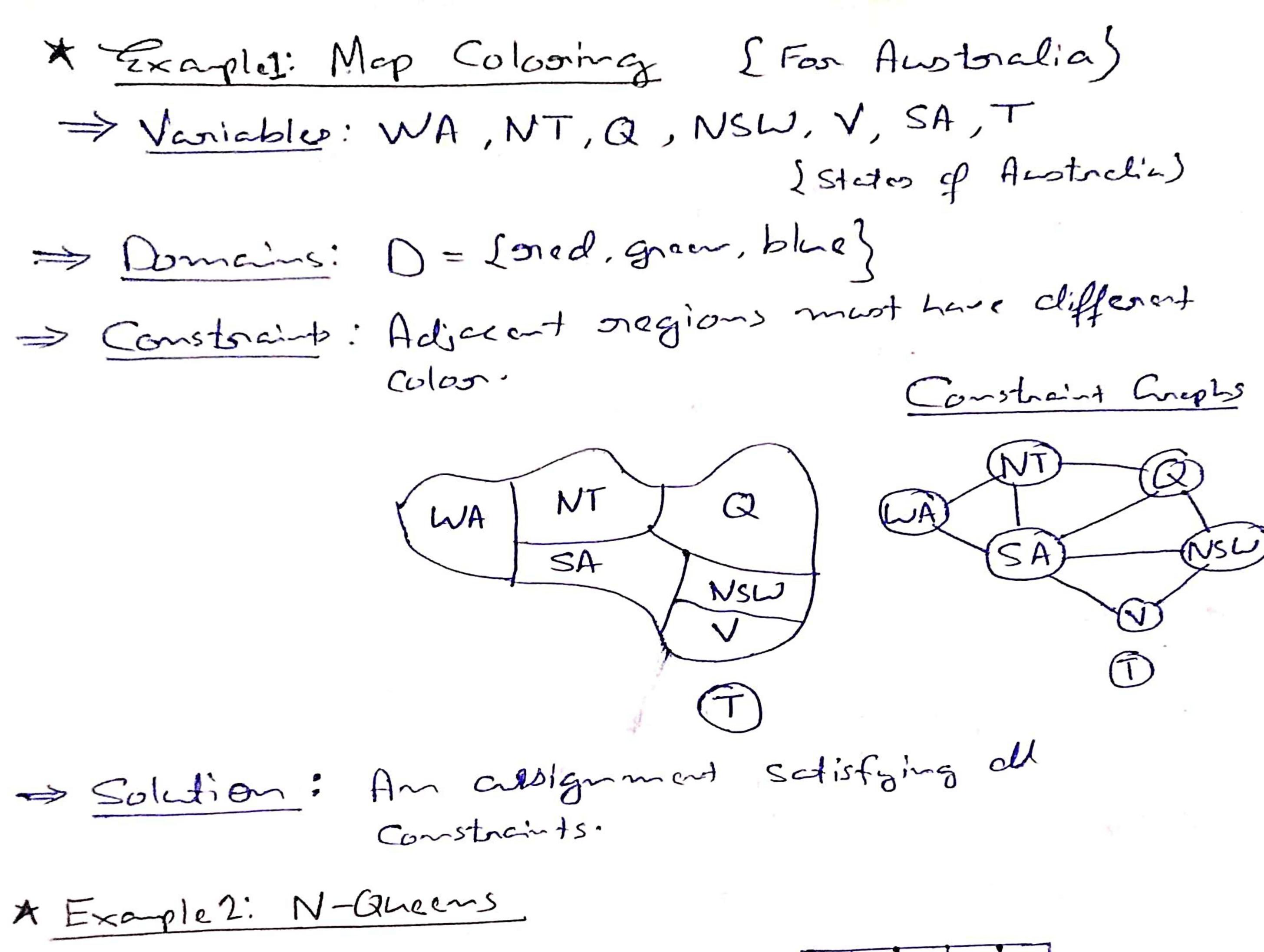
2 Successor function can also be anything.

Standard Search Problem Constraint Satisfaction (BSP)
Problem

-> A Special subset of search Problem

-> Stade is defined by Variable X: with volve from Domain

-> Chock test is a set of constraints
specifying allowable combinations
of values for subset of variables.



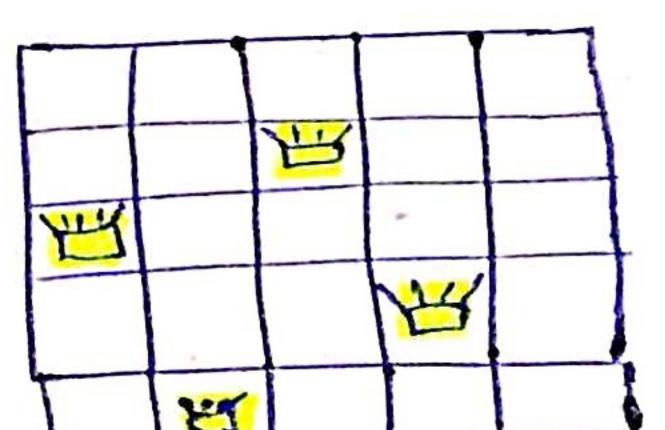
Variables: X:

Domain: [0,1]

Constants:

$$\leq X:$$

n) Queens are non threading



* Constrait anglis

Binary CSP: Each Constraint orelates (atmost)
two variables.

Bimany Constraint graph

Sonocles are variables Sonocs shows constraints

>> Cremend-purpose CSP algorithms use the graph Structure to spend up sameh.

* Example 3: Sudoku

Variables: Each Open Samane

Donain: [1,2,---9]

Comstaints:

> 9-way alldiff for each sou > 9-way alldiff for each snegion > 9-way alldiff for each snegion

* Varieties & CSPs

1 Discrete Variables

OFInite domain Le domains @ O(dn) complete assignments (D) Infinite domain (Integers, strings etc.)

(#) Continuous Vanidal 00

> Unany Constraints involve a Strale variable

> Binary Constraints involve pairs of variables

> Higher-order constraints involve 3 on more
Variables.

* Poreference (Soft Constraints)

> Example: oned is better than green

Often orepresented by a cost for each

variable assignment

Show Constrained optimization problem.