

Map-Server

⇒ Offers map data as a ROS Service. ⇒

* Map format

⇒ Map is stored in a pair of files. ⇒

→ YAML file describes the map meta-data, and names the image file. ⇒

→ The Image file encodes the occupancy data. =

→ Whiter ⇒ free

→ blacker ⇒ occupied

→ Pixels color in between ⇒ Unknown

`roscpp map-server map-server map_name.yaml`

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