

## Images and Large Array Types

### \* Dynamic and Variable Storage

⇒ `cv::Mat` is considered the epicenter of the entire C++ implementation of the OpenCV library.

⇒ The overwhelming majority of functions in the OpenCV library are:-

- Members of the `cv::Mat` class
- Takes `cv::Mat` as an argument
- Or returns `cv::Mat` as a return value.

⇒ The `cv::Mat` class is used to represent dense arrays of any number of dimensions.

↳ The alternative would be a sparse array.

↳ In the case of a sparse array, only non-zero entries are typically stored.

↳ This can result in a great savings of storage space if many of the entries are in fact zero, but can be very wasteful if the array is relatively dense.

↳ Common usecase of sparse array rather than dense array would be histogram.

↳ `cv::SparseMat`

## \* The cv::Mat Class: N-Dimensional Dense Array

⇒ Each matrix contains:

- flag ⇒ Signaling the contents of the array
- dims ⇒ Indicating the number of dimensions.
- rows ⇒ Indicating number rows & Columns.
- ~~cols~~ <sup>cols</sup> ⇒ Not valid for  $\text{dims} > 2$
- data ⇒ pointer to where the array data is stored.
- refcount ⇒ reference counter analogous to the reference counter used by `cv::Ptr<>`.

⇒ The memory layout in data is described by the array step [3].

⇒ In 2D Case

$$k(\text{mtx}; i, j) = \text{mtx} \cdot \text{data} + \text{mtx} \cdot \text{step}[0] + i + \text{mtx} \cdot \text{step}[1] + j$$

⇒ The data contained in `cv::Mat` is not required to be simple primitives.

## \* Creating an Array

⇒ You can create an array simply by instantiating a variable of type `cv::Mat`.

⇒ An array created in this manner has no size and no data type.

⇒ You can, however, later ask it to allocate data by using a member function such as `create()`.



⇒ One variation of `create()` takes as arguments a number of rows, a number of columns and a type, and configure the array to represent a two-dimensional object.

⇒ The type of an array determines the kind of element it has as well as the number of channels.

`CV_8U, 16S, 16U, 32S, 32F, 64F` `C{1, 2, 3}`

→ Example ⇒ `CV_32FC3`

↓  
{ 32-bit floating point three }  
channel array.

⇒ There are many Constructors for `cv::Mat`, one of which takes the same arguments as `create()` with an optional fourth element to initialize all of the elements in your new array.

`cv::Mat m;`

`m.create(3, 10, CV_32FC3);`

`m.setTo(cv::Scalar(1.0f, 0.0f, 1.0f));`

is equivalent to

`cv::Mat m(3, 10, CV_32FC3, cv::Scalar(1.0f, 0.0f, 1.0f));`

⇒ The data in an array is not attached originally to the array object.

↳ `cv::Mat` object is really a header for a data area, which - in principle - is an entirely separate thing.

⇒ The class `cv::Mat` also provides a number of static member functions to create certain kinds of commonly used arrays.

`cv::Mat::zeros (rows, cols, type);`

`cv::Mat::ones (rows, cols, type);`

`cv::Mat::eye (rows, cols, type);`

### \* Accessing Array Elements Individually

⇒ There are several ways to access a matrix, all of which are designed to be convenient in different contexts.

⇒ The basic means of direct access is the (template) member function `at<>`.

#### Example

`cv::Mat m = cv::Mat::eye(10, 10, 32FC1);`

`m.at<float>(3,3);`

⇒ For a multichannel array:

`cv::Mat m = cv::Mat::eye(10, 10, 32FC2);`

`m.at<cv::Vec2f>(3,3)[0];`

`m.at<cv::Vec2f>(3,3)[1];`

`1.0f));`

⇒ You can also create array of complex numbers.

⇒ OpenCV provides a pair of iterator templates, one for const and one for non-const arrays.

↳ `cv::MatIterator<>`  
↳ `cv::MatConstIterator<>`

Example `cv::Mat m(3, 52, CV_32FC3);`

`cv::MatConstIterator<cv::Vec3f> it = m.begin();`

`while (it != m.end()) {`

`(*it)[0]`

`(*it)[1]`

`(*it)[2]`

`it++`

`}`

★ The N-ary Array Iterator: `NaryMatIterator`

⇒ does not handle discontinuities in the packing of the arrays, but allows us to handle iteration over many arrays at once.

`cv::NaryMatIterator`

↳ Only requirement is that all of the arrays being iterated over be of the same geometry.

{ number of dimension & extent in each dimension }



Instead of returning single elements of the arrays being iterated over, the N-ary iterator operates by returning chunk of those arrays, called planes.

plane

→ Position of the input array in which the data is guaranteed to be contiguous in memory.

### Handling discontinuity

⇒ You are given contiguous chunk one by one.

↳ For each of such plane, you can either operate on it using array operations or iterate trivially over it yourself.

⇒ To initialize the `cv::NaryMatIterator` object, we need to have two things:

① → C-style array containing pointers to all of the `cv::Mats` we wish to iterate over.  
↳ Terminated by 0 or NULL.

② → Another C-style array of `cv::Mats` that can be used to refer to the individual planes as we iterate over them.

TODO

## \* Accessing Array Element by Block

{ Accessing subset of an array  
as another array }

Table 4-7

{ Methods for accessing arrays  
Elements by block }

⇒ When you use `m.row()` or `m.col()`, data in `m` is not copied to the new array.

⇒ Later, we will visit the `copyTo()` method, which actually will copy data.

⇒ The `()` Operator is the only method to access that will allow you to extract a subvolume from a higher-dimensional array.

## \* Matrix Expressions

Table 4.8

$m2 = m1$

→ `m2` will be another reference to data in `m1`

$m2 = m1 + m0$

→ `m2` will have its separate memory.

## \* Saturation Casting

⇒ In OpenCV, you will often do operations that risk overflowing or underflowing the available values in the destination of some computation.

### Example

$V_{xy} = cv::saturate\_cast<uchar>((V_{xy} - 128) * 2 + 128);$

## \* More things an Array Can do

### Table 4-9

## \* The cv::SparseMat Class: Sparse Array

⇒ The cv::SparseMat class is used when an array is likely to be very large compared to number of nonzero entries.

⇒ The disadvantage of sparse representations is that computation with them is slower (on per-element basis).

⇒ The OpenCV sparse matrix class cv::SparseMat functions analogously to the dense matrix class cv::Mat in most ways.

↳ cv::SparseMat uses a hash table to store just the nonzero elements.



## \* Accessing Sparse Array Elements

⇒ The most important difference between Sparse and dense arrays is how elements are accessed.

⇒ Sparse array provides four different access mechanisms:

- cv::SparseMat::ptr()
- cv::SparseMat::ref()
- cv::SparseMat::value()
- cv::SparseMat::find()

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## Array Operations

Table 5-1

→ List of "friend" functions that either takes array type as arguments, have array type as return values or both