

Lecture 5 Transfer Functions

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Student Notebooks

★ Exponential Input

⇒ Let us choose as elementary input $u(t) = e^{st}$, where $s \in \mathbb{C}$ is a complex number.

⇒ If s is real, then u is a simple exponential.

⇒ If $s = j\omega$ is imaginary, then the elementary input must be accompanied by the "conjugate"

$$u^*(t) + u(t) = e^{j\omega t} + e^{-j\omega t} = 2 \cos(\omega t)$$

↳ If s is imaginary, then $u(t) = e^{st}$ must be understood as a "half" of a sinusoidal signal.

⇒ If $s = \sigma + j\omega$ then

$$u(t) + u^*(t) = 2e^{\sigma t} \cos(\omega t)$$

↳ Input u is a half of a sinusoid with exponentially-changing amplitude.

⇒ For unit step input $u(t) = e^{st}$, set $s = 0$.

$$\text{So } u(t) = 1 \quad \forall t \geq 0$$

★ Output response to elementary inputs

$$\Rightarrow y(t) = C e^{At} x(0) + C \int_0^t e^{A(t-\tau)} B u(\tau) d\tau + D u(t)$$

\Rightarrow Plug in $u(t) = e^{st}$

$$\Rightarrow y(t) = \quad \text{II} \quad + C \int_0^t e^{A(t-\tau)} B e^{s\tau} d\tau + D e^{st}$$

$$C \int_0^t e^{A(t-\tau)} B e^{s\tau} d\tau$$

$$C e^{At} \left[\int_0^t e^{(SI-A)\tau} d\tau \right] B$$

\Rightarrow If $(SI-A)$ is invertible (i.e., s is not an eigenvalue of A), then

$$y(t) = C e^{At} x(0) + C e^{At} (SI-A)^{-1} [e^{SI-A t} - I] B + D e^{st}$$

$$y(t) = C e^{At} [x(0) - (SI-A)^{-1} B] + [C (SI-A)^{-1} B + D] e^{st}$$

Transient response

Steady-state response

⇒ If the system is asymptotically stable, the transient response will converge to zero.

⇒ The steady state response to an input $u(t) = e^{st}$ can be written as:

$$y_{ss} = G(s) e^{st}, \quad G(s) = C(sI - A)^{-1}B + D$$

$$, G(s) \in \mathbb{C}$$

⇒ The function $G: S \rightarrow \mathbb{C}(s)$ is known as the transfer function.

★ Frequency response

⇒ Consider the case in which the input is a sinusoidal signal ($s = \pm j\omega$)

$$u(t) = e^{j\omega t} + e^{-j\omega t} = 2\cos(\omega t)$$

⇒ The output is

$$y(t) = G(j\omega) e^{j\omega t} + G(-j\omega) e^{-j\omega t}$$

$$= M e^{j\phi} e^{j\omega t} + M e^{-j\phi} e^{-j\omega t}$$

$$= 2M \cos(\omega t + \phi)$$

⇒ The output is another sinusoid of frequency ω , the magnitude of which is $M = |G(j\omega)|$ times the magnitude of the input, and with phase leading the input by $\angle G(j\omega)$.

⇒ Using linearity and the solution of $u(t) = e^{st}$ we can find the solution to more complex input.

★ From State-space to Transfer Function (SISO)

$$g(s) = C(sI - A)^{-1}B + d$$

⇒ If A is diagonal, with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ this simply becomes:

$$g(s) = \frac{C_1 b_1}{s - \lambda_1} + \dots + \frac{C_n b_n}{s - \lambda_n} + d$$

⇒ Or, given, the transfer function is a rational function of the form

$$g(s) = \frac{b_{n-1}s^{n-1} + b_{n-2}s^{n-2} + \dots + b_0}{s^n + a_{n-1}s^{n-1} + \dots + a_0} + d$$

★ From Transfer function to State Space (SISO)

⇒ Given a transfer function $g(s)$, there are many state-space models (A, B, C, D) such that $g(s) = C(sI - A)^{-1}B + D$.

⇒ If the transfer function is written as a partial fraction expansion of the form

$$g(s) = \frac{P_1}{s - \lambda_1} + \frac{P_2}{s - \lambda_2} + \dots + \frac{P_n}{s - \lambda_n} + d$$

then a realization is,

$$A = \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_n \end{bmatrix} \quad B = \begin{bmatrix} \sqrt{P_1} \\ \sqrt{P_2} \\ \vdots \\ \sqrt{P_n} \end{bmatrix}$$

$$C = [\sqrt{P_1} \ \sqrt{P_2} \ \dots \ \sqrt{P_n}] \quad D = d$$

⇒ In the general case,

$$g(s) = \frac{b_{m1}s^{n-1} + b_{m2}s^{n-2} + \dots + b_0}{s^n + a_{n1}s^{n-1} + \dots + a_0} + d$$

You can verify that the following is a minimal realization of $g(s)$

$$A = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ -a_0 & -a_1 & \dots & \dots & -a_{n-1} \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

$$C = [b_0 \ b_1 \ \dots \ b_{m1}] \quad D = [d]$$

★ The Laplace Transform

⇒ Can all input $u(t)$ be expressed as a (infinite) sum of complex exponentials?

↳ Yes! The tool for this is the Laplace transform and the inverse Laplace transform.

$$\mathcal{L}[u] = U(s) = \int_0^{\infty} u(t) e^{-st} dt$$

⇒ The inverse Laplace transform is denoted

$$\mathcal{L}^{-1}[U] = u$$

⇒ So,

$$u(t) = \frac{1}{2\pi j} \lim_{\omega \rightarrow \infty} \int_{\sigma-j\omega}^{\sigma+j\omega} U(s) e^{st} ds$$

⇒ So using the above expression we can convert any arbitrary input $u(t)$ as an (infinite) sum of complex exponentials.

⇒ So we can write output as:

$$y(t) = \frac{1}{2\pi j} \lim_{\omega \rightarrow \infty} \int_{\sigma-j\omega}^{\sigma+j\omega} g(s) U(s) e^{st} ds$$

$$\Rightarrow y(t) = \mathcal{L}^{-1}[g(s)U(s)](t)$$

$$\Rightarrow \mathcal{L}[y(t)] = g(s)U(s)$$

$$\Rightarrow \boxed{Y(s) = g(s)U(s)}$$



$$\mathcal{L}[U(s)] = U(s) = [U]$$

Introduce a unitary matrix U and a matrix U^T \Leftarrow

$$U = [U]^T - I$$

$$\mathcal{L}[U(s)] = U(s) = [U]$$

\Rightarrow To find the transfer function $g(s)$ we need to find the Laplace transform of the output $y(t)$ and the input $u(t)$ and then divide them.

Let's consider a system with input $u(t)$ and output $y(t)$.

$$\mathcal{L}[y(t)] = Y(s) = g(s)U(s)$$