Dimensionality Reduction

* Motivation

- · Complexity of most estimations depends on the number of imputs.
- * Affects time and Space complexity.
- 1 reducing the dimensionality of the imput

Coutribule little to the Solution.

* Agguments for Dimensionality Reduction for Classifications

- · Reduces Complexity of the Classifien-
- · Isosdavet dimensions add to the variance.
- · If data is explained with fewer features, we can get a better idea about the underlying process.
- to our problem?

* Feature Selection vs Feature Extension

Feature Selection vs Feature Extension

Feature of the Kond of Odimensions that Contain

wost of the information. We discard the Other (D-K) dimensions.

facture Extraction

-> We try to find a new set of K dimensions that are Combindies of the D dimensions and yield most of the information.

* Popular Dimensionality Orduction Techniques
for Fedure Extraction

- * PCA: Poincipal Component Analyis
- * Fisher-LDA: Fisher's Liman Discrimined Analysis.
- · LLE: Lucally Linean Embedding

* Paincipal Component Analysis (P(A)

Idea of P(A

- -> Find the mapping from the original O to K dimension d'spece cuit minimum loss of information (K<D).
- -> PCA analysis the sponead of the data and tories to find new dimensions And Cover the Sparad best.

Data Maloix

-> Matorix of N vectors with O dimensions

-> God: Find K. dimensions and oneposismits the data as good as possible.

$$\mathcal{M}_{\alpha} = \frac{1}{N} \sum_{N=1}^{N} \alpha_{n} = \frac{1}{N} X^{T} 1_{N}$$

$$\sum_{XX} = \frac{1}{N-1} \cdot \overline{X}^{T} \overline{X}^{T}$$

D-dimensiond

Ocostion: What and the bost KKD dimension to apponionini ate the data?

* Eigenvector and Eigenvelne

- The Eigenverton Us Coonespording to the largest the larges Eigenvalue of Exx is the direction of maximum sporead.
- -> Make this Eigenvectors us the first posincipal
- -> All other Eigenvactors are arthogonal to Uz.
- -> Repeat the process K times for the oremains

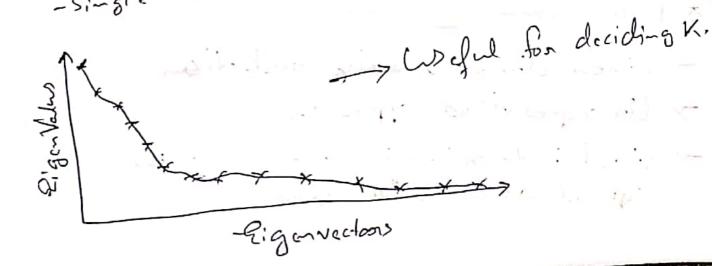
 Pign values Nortons.

* Eigenvalue Decomposition

=> Eigenvelre decomposition yields.

Southin diagondi mutair medaix

=> Eigenvelnes/Vactors ane Computed via SVD -Si-sle velne decomposition (on Special Vanionts).



* Mapping to the Reduced Space = [w,, -- . wx] K dimosion data points D-dim wial data port * Mapping to the Oniginal Space => We can also map from the sieduced K-dimensional Space to the osiginal and 2=H+ \(\subsection \omega: U; \) one construction enoon: e(a) = 112-2112 * PCA Summary -> Linear dimensionality oreduction -> Unsupervised approach -> Goal is to minimize the sum of the squand speconstruction espoon

-> Parincipal componeds are the directions of maximum spriad. -> Computed via Eigenvolues/vector> of the Covariace metrix of the training date Points.

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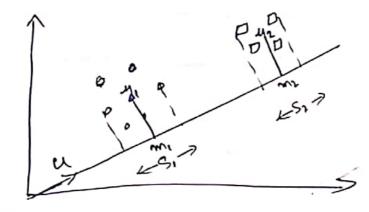
Fisher's Linear Discriminant Analysis

Emitation of PCA)

> The direction of maximum variance is not always good for classification,

=> Fisher's LDA tories to find the best direction to Sepande classes,

- maximizes 11 m,-m21
- minimizes S, and Sz



=> Compute the means of the classes

$$M_{r} = \frac{\sum_{t} u x^{t} c^{t}}{\sum_{t} c^{t}} \qquad m_{2} = \frac{\sum_{t} u^{t} s c^{t} (1 - c^{t})}{\sum_{t} (1 - c^{t})}$$

$$m_2 = \frac{\sum_t u^{\dagger} sc^{\dagger} (1-c^{\dagger})}{\sum_t (1-c^{\dagger})}$$

$$c^t = l \rightarrow m, \quad c^t = 0 \rightarrow m_2$$

=> Similarly for Si2.

$$S_1^2 + S_2^2 = u^T S_1 u' + u^T S_2 u'$$

$$= u^T (S_1) u'$$

$$= u^T (S_2) u'$$

$$= u^T (S_3) u'$$

$$= u^T (S_4) u$$

- > Fisher-LDA is the optimal 'Solution if both Feature are normally distributed.
- -> Also applicable for non-normally distributed features.
- -> Can be easily generalized to N classes and K>1.
- -> Linear dimensionality reduction.

* Fischer's LDA vs PCA'

- PCA minimizes the one construction error
- PCA is the standard choice for unsupervisord Psoblem (no labels)

* Fisher-LDA emploite class lokals to find a Subspace so that sepanates the classes as good as possible.

* Locally Linear Embedding (LLE)

- a Technique for or supervised mon -linear dimensionality oraduction
 - · Compule for each imput data point a coordinate on a low-dim ensioned marifold.

* LLE Koy Slaps.

- 1. Stop 0: Find neighbors for each imput point.
- 2. Step: Compute for each imput point a cover the covight vector that best orecover the Paint itself from its neighbors.
- 3. Step: For each point, Pind lader Coordinates
 Such that the Same wights can be
 used for sen Construction.

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