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★ Classical Control Theory  $\Rightarrow$  It is a branch of control theory that deals with the behavior of dynamic systems with inputs and how their behavior is modified by feedback, using the Laplace transform as a basic tool to model such systems.

★ Modern Control theory  $\Rightarrow$  Instead of changing domains to avoid the complexities of time domain ODE mathematics, converts the differential equations into a system of lower order time domain equations called state equations which can then be manipulated using techniques from linear algebra.

\* Robust Control Theory  $\Rightarrow$  In control theory, robust control is an approach to controller design that explicitly deals with uncertainty.

