State-Space Equation

Lat us Consider the System whose TF is given by:-

$$G(s) = \frac{Y(s)}{U(s)}$$

=> The System may be onepresented Din State Space by the following equations:-

=> Taking Laplace transform of ear DKD+

$$\gamma(s) = c \times (s) + Du(s)$$

$$\times$$
(s) = (SI-A) BU(s)

$$G(s) = \frac{Y(s)}{V(s)} = C(SI-A)^{-1}G + D$$

-> Charactonistic of a(s)

Poles of G(s).

## alaccusta

## \* Toronsfer Matrix

=> Consider a multiple input - Multiple Output system.
=> Assume that there are or inputs & m outputs.

$$y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} \qquad u = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{bmatrix}$$

$$G(s) = \frac{Y(s)}{u(s)} = C(SI-A)^{-1}B + D$$

$$\Rightarrow Torcuster meetrix$$