

## ★ Kernels

⇒ We have a problem in which input is  $x$ .

⇒ We consider performing regression with the features  $x, x^2$  &  $x^3$  to obtain a cubic function.

⇒ To distinguish between these two set of variables, we'll call the "original" input value the **input attributes** of a problem.

⇒ When that is mapped to some new set of quantities that are passed to the learning algorithm, we'll call those new quantities the **input features**.

⇒ We will also let  $\phi$  denote the **feature mapping**, which maps from the attributes to the features.

$$\phi(x) = \begin{bmatrix} x \\ x^2 \\ x^3 \end{bmatrix}$$

⇒ Rather than applying SVMs using the original input attributes  $x$ , we may instead want to learn using some features  $\phi(x)$

↳ To do so, we simply need to go over our previous algorithm, & replace  $x$  everywhere in it with  $\phi(x)$



⇒ Since the algorithm can be written entirely in terms of the inner products  $\langle x, z \rangle$ , this means that we could replace all those inner product with  $\langle \phi(x), \phi(z) \rangle$ .

⇒ Specifically, given a feature mapping  $\phi$ , we define the ~~spanning~~ corresponding **Kernel** to be:

$$K(x, z) = \phi(x)^T \phi(z)$$

⇒ Then, everywhere we previously had  $\langle x, z \rangle$  in our algorithm, we could simply replace it with  $K(x, z)$ , and our algorithm would now be learning using the features  $\phi$ .

⇒ Let's see an example. Suppose  $x, z \in \mathbb{R}^n$  and consider

$$K(x, z) = (x^T z)^2$$

$$K(x, z) = \left( \sum_{i=1}^n x_i z_i \right) \left( \sum_{j=1}^n x_j z_j \right)$$

$$= \sum_{i=1}^n \sum_{j=1}^n x_i x_j z_i z_j$$

$$= \sum_{i,j=1}^n (x_i x_j) (z_i z_j)$$



⇒ Thus, we see that  $k(x, z) = \phi(x)^T \phi(z)$ , where the feature mapping  $\phi$  is given by: (for  $n=3$ )

$$\phi(x) = \begin{bmatrix} x_1 x_1 \\ x_1 x_2 \\ x_1 x_3 \\ x_2 x_1 \\ x_2 x_2 \\ x_2 x_3 \\ x_3 x_1 \\ x_3 x_2 \\ x_3 x_3 \end{bmatrix}$$

⇒ Note that whereas calculating the high-dimensional  $\phi(x)$  requires  $O(n^2)$  time, finding  $K(x, z)$  takes only  $O(n)$  time.

⇒ For a related kernel, also consider

$$K(x, z) = (x^T z + c)^2$$

⇒ This corresponds to feature mapping:

$$\phi(x) = \begin{bmatrix} x_1 x_1 \\ x_1 x_2 \\ x_1 x_3 \\ x_2 x_1 \\ x_2 x_2 \\ x_2 x_3 \\ x_3 x_1 \\ x_3 x_2 \\ x_3 x_3 \\ \sqrt{c} x_1 \\ \sqrt{c} x_2 \\ \sqrt{c} x_3 \\ c \end{bmatrix} \quad \text{(for } n=3\text{)}$$



⇒ More broadly the kernel  $K(x, z) = (x^T z + c)^d$  corresponds to a feature mapping to an  $\binom{m+d}{d}$  feature space.

↳ Corresponding of all monomials of the form  $x_{i_1} x_{i_2} \dots x_{i_k}$  that are up to order  $d$ .



⇒ Intuitively:

- If  $\phi(x)$  &  $\phi(z)$  are close together, then we might expect  $K(x, z) = \phi(x)^T \phi(z)$  to be large.
- If  $\phi(x)$  &  $\phi(z)$  are far apart (say nearly orthogonal to each other) then  $K(x, z) = \phi(x)^T \phi(z)$  will be small.

⇒ So, we can think of  $K(x, z)$  as some measure of how similar are  $\phi(x)$  and  $\phi(z)$  or of how similar are  $x$  &  $z$ .

⇒ Given some function  $K$ , how can we tell if it's a valid kernel?

⇒ Suppose for now that  $K$  is indeed a valid kernel corresponding to some feature mapping  $\phi$ .

- Now consider a finite set of  $m$  points  $\{x^{(1)}, x^{(2)}, \dots, x^{(m)}\}$

- Let a square,  $m \times m$  matrix  $K$  be defined so that  $(i, j)$  entry is given by  $K_{ij} = K(x^{(i)}, x^{(j)})$

- This matrix is called **Kernel Matrix**.

⇒ Now, if  $K$  is a valid kernel, then  $K_{ij} = K_{ji}$  and hence  $K$  must be symmetric.



$\Rightarrow$  Let  $\phi_k(x)$  denote the  $k^{\text{th}}$  coordinate of the vector  $\phi(x)$ , we find that for any vector  $z$  we have

$$\begin{aligned} z^T K z &= \sum_i \sum_j z_i k_{ij} z_j \\ &= \sum_i \sum_j z_i \phi(x^{(i)})^T \phi(x^{(j)}) z_j \\ &= \sum_i \sum_j z_i \sum_k \phi_k(x^{(i)}) \phi_k(x^{(j)}) z_j \\ &= \sum_k \sum_i \sum_j z_i \phi_k(x^{(i)}) \phi_k(x^{(j)}) z_j \\ &= \sum_k \left( \sum_i z_i \phi_k(x^{(i)}) \right)^2 \geq 0 \end{aligned}$$

$\Rightarrow$  Since  $z$  was arbitrary, this shows that  $K$  is Positive Semi-definite.

$\Rightarrow$  If  $K$  is a valid Kernel, then the corresponding Kernel matrix  $K \in \mathbb{R}^{n \times n}$  is symmetric positive Semidefinite.

$\hookrightarrow$  This turns out to be not only a necessary, but also a sufficient condition for  $K$  to be a valid Kernel.  
(also called a Mercer Kernel)

$$K(x, z) = \exp\left(-\frac{\|x - z\|^2}{2\sigma^2}\right)$$

{ Gaussian Kernel }



Theorem (Mercer): Let  $K: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$  be given. Then for  $K$  to be a valid (Mercer) Kernel, it is necessary and sufficient that for any  $\{x^{(1)} \dots x^{(m)}\}$ , ( $m < \infty$ ), the corresponding Kernel matrix is symmetric positive semi-definite.

## \* Regularization and the non-separable case

- $\Rightarrow$  The derivation of the SVM as presented so far assumed that the data is linearly separable.
- $\Rightarrow$  While mapping data to a high-dimensional feature space via  $\phi$  does generally increase the likelihood that the data is separable, but we can't guarantee that it always will be so.
- $\Rightarrow$  It is not clear that finding a separating hyperplane is exactly what we'd want to do, since that might be susceptible to outliers.
- $\Rightarrow$  To make the algorithm work for non-linearly separable datasets as well as be less sensitive to outliers, we reformulate our optimization (using  $L_1$  regularization) as follows:

$$\min_{\gamma, \omega, b} \frac{1}{2} \|\omega\|^2 + C \sum_{i=1}^m \xi_i$$

$$\text{s.t. } y^{(i)} (\omega^T x^{(i)} + b) \geq 1 - \xi_i, \quad i = 1, \dots, m$$

$$\xi_i \geq 0 \quad i = 1, \dots, m$$