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Machine Learning (Andrew NG)

classmate



ALL THAT
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CHAPTER 1

Introduction

1 Introduction

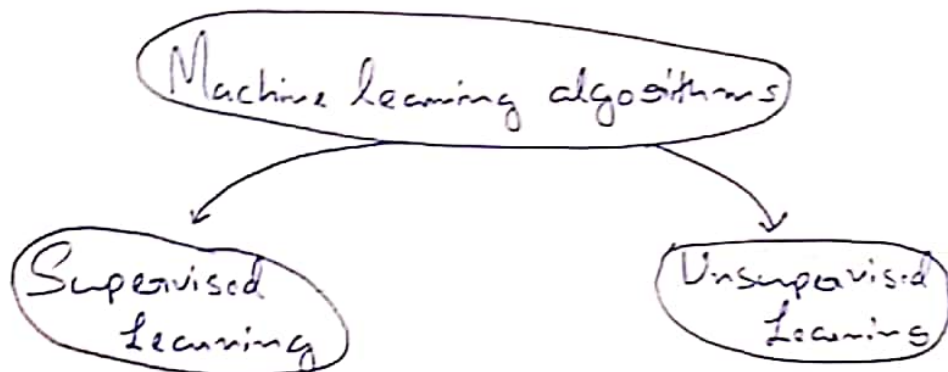
1.1) Welcome

→ Machine learning grew out of work in AI.

1.2) What is machine Learning

→ Field of study that gives computers the ability to learn without being explicitly programmed.

Arthur Samuel (1959)



1.3) Supervised learning

→ (We gave the algorithm the data set with right answers)

↓
} and the task of the algorithm was to predict the right answer for the next question }

⇒ Regression :: Predict continuous value output.

⇒ Classification :: Discrete valued output (0 or 1)

(Support Vector machine)

→ Can have more than two values.

1.4) Unsupervised - Learning

Algorithm ~~that~~ that learns from test data that has not been labeled, classified or categorized

→ Clustering

Give the algorithm a ton of data ask to find structure in it.



CHAPTER 2

Linear Regression With One Variable

Linear regression with one variable

2.1) Model representation

⇒ Data set is called training set.

Notation:

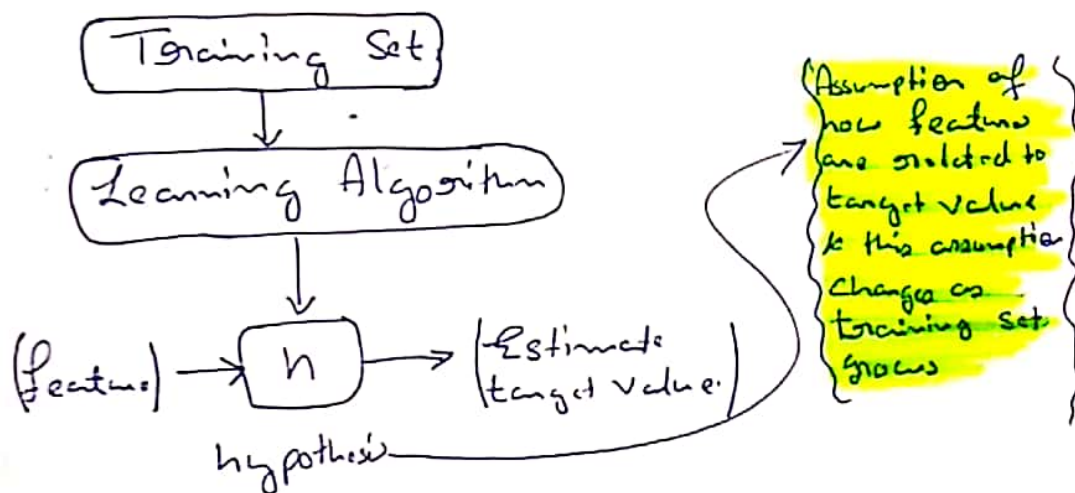
m ⇒ Number of training example

x 's ⇒ "input" variables / features

y 's ⇒ "Output" variable / "target" variable

(x, y) ⇒ To denote single training example.

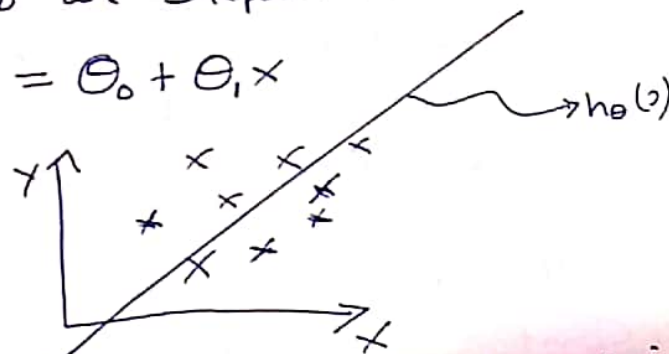
$(x^{(i)}, y^{(i)})$ ⇒ To denote i^{th} training example.



⇒ h is a function which maps x 's to y 's

⇒ How do we represent h ?

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$



⇒ Linear regression with one variable.
(i.e. Univariate linear regression)

2.2 > Cost function

Hypothesis: $h_{\theta}(x) = \theta_0 + \theta_1 x$

$\{\theta_{i's} \Rightarrow \text{Parameters}\}$

Objective: Choose θ_0, θ_1 so that $h_{\theta}(x)$ is close to y for our training examples (x, y) .

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

Cost function

$\left\{ \begin{array}{l} \text{Square error cost} \\ \text{function} \end{array} \right\}$

Goal: minimize $J(\theta_0, \theta_1)$
 θ_0, θ_1

$\rightarrow \left\{ \begin{array}{l} \text{Minimize } J(\theta_0, \theta_1) \text{ to} \\ \text{obtain value of } \theta_0 \text{ \& } \theta_1 \end{array} \right\}$

Contour line \Rightarrow A contour line of a function of two variables is a curve along which the function has a constant value, so that the curve joins points of equal value.

\rightarrow different colors are used to represent contour lines at different height.

2.5) Gradient descent

An algorithm for minimizing the cost function J

$$\min_{\theta_0, \dots, \theta_n} J(\theta_0, \dots, \theta_n)$$

First start from a random value

Gradient descent algorithm

repeat until convergence {

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \quad (\forall j=0 \text{ and } j=1)$$

}

↘ {Correct simulation update}

$$\text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$

$$\text{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$

$$\theta_0 := \text{temp0}$$

$$\theta_1 := \text{temp1}$$

→ {Assignment operator}

$\alpha \Rightarrow$ learning rate
(i.e. how big the step is)

$\{ \Rightarrow \text{Truth assertion} \}$

Issue: It can be susceptible to local optima.

⇒ The algorithm is also called 'Batch' Gradient Descent.

Each step of gradient descent uses all the training examples

Two extensions

Exact method

Larger number of features

x_1, x_2, \dots, x_n
can be different features



CHAPTER 3

Linear Regression With Multiple Variable

Linear regression with multiple variables

4.1) Multiple features

Notation:

n = Number of features

$x^{(i)}$ = input (features) of i^{th} training example

$x_j^{(i)}$ = Value of feature j in i^{th} training example

↘ (Will be a number)

{Will be n dimensional vector}

$$x^{(i)} \in \mathbb{R}^n$$

⇒ New hypothesis function: $h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n$

⇒ For convenience of notation define $x_0^{(i)} = 1$

$$\text{So } x = \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_n \end{bmatrix} \in \mathbb{R}^{n+1} \quad \& \quad \theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix} \in \mathbb{R}^{n+1}$$

$$h_{\theta}(x) = \theta_0 x_0 + \theta_1 x_1 + \dots + \theta_n x_n$$

$$h_{\theta}(x) = \theta^T x \quad \left\{ x = \begin{bmatrix} x_0 \\ x^{(i)} \end{bmatrix} \right\}$$

⇒ Multivariate linear regression

4.2> Gradient descent for multiple variables

Cost function

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

Vector

Vector

Gradient descent

Repeat {

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta) \quad \left\{ j = 0, 1, \dots, n \right\}$$

}

⇓

Repeat {

$$\theta_j := \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

(Simultaneously update θ_j
for $j = 0, \dots, n$)

}

1.5 Feature Scaling

If different features take different range of values then it becomes very difficult for algorithm to find minimum or it takes way more time for algorithm to find minimum.

→ To avoid this we scale every feature so that they are in similar range.

→ Get every feature into approximately a $-1 \leq x_i \leq 1$ range.

Mean Normalization

⇒ Replace x_i with $x_i - \mu_i$ to make features have approximately zero mean.

General rule $x_i \leftrightarrow \frac{x_i - \mu_i}{s_i}$

Annotations:

- μ_i : avg value of x_i in training set
- s_i : range of x_i (i.e. $\max x_i - \min x_i$)

⇒ To make sure gradient descent is working correctly.

→ Plot $J(\theta)$ vs (Number of iteration)

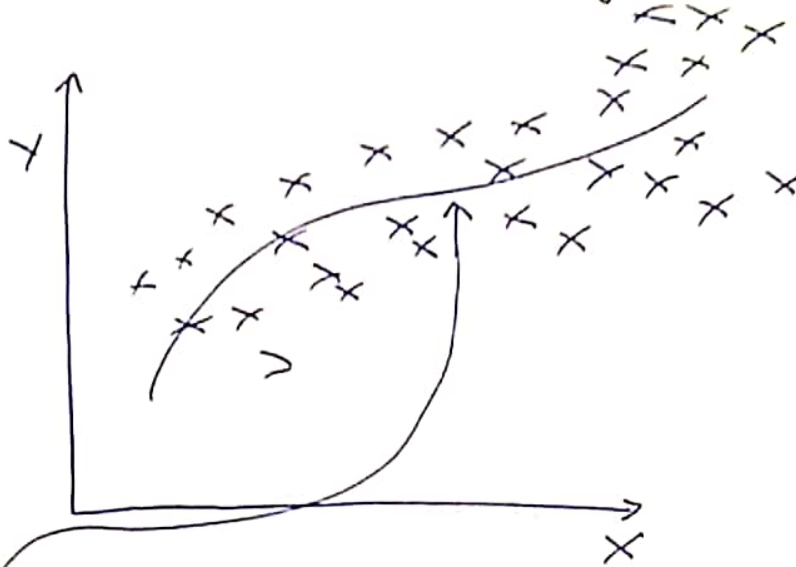
↓
{ If it is continuously decreasing }
{ then it's going well. }

↓
{ If it is almost flat then you }
{ can assume that it has converged }

\Rightarrow To choose α , try

... 0.001, 0.01, 0.1, 1 ...

4.5 > Polynomial regression



$$h_0(x) = \theta_0 + \theta_1 x \quad \left\{ \begin{array}{l} \text{X} \\ \text{doesn't give good} \\ \text{fit} \end{array} \right\}$$

So, $h_0(x) = \theta_0 + \theta_1 x + \theta_2 x^2 + \theta_3 x^3$

$\left\{ \text{Very good fit} \right\}$

$$\text{So } \left. \begin{array}{l} x_1 = x \\ x_2 = x^2 \\ x_3 = x^3 \end{array} \right\} \left\{ \begin{array}{l} \text{define three new} \\ \text{features} \end{array} \right\}$$

4.6) Normal Equations

Method to solve for θ analytically.

Let $X = \begin{bmatrix} x_1^1 & x_2^1 & \dots & x_n^1 \\ x_1^2 & x_2^2 & \dots & x_n^2 \\ \vdots & \vdots & \ddots & \vdots \\ x_1^m & x_2^m & \dots & x_n^m \end{bmatrix}_{m \times (n+1)}$

number of features

Matrix that contains all the training examples

number of training set

Similarly $y = \begin{bmatrix} y^1 \\ y^2 \\ \vdots \\ y^m \end{bmatrix}_{m \times 1}$

Collection of all the target variables in training example

$$\theta = (X^T X)^{-1} X^T y$$

This gives you the value of θ that minimizes the cost function

Note

$$J(\theta) = \frac{1}{2m} (X\theta - y)^T (X\theta - y)$$

Gradient Descent

- ⇒ Need to choose α .
- ⇒ Need many iterations.
- ⇒ Works well even when n is large

$$n > 10000$$

Normal Equation

- ⇒ No need to choose α .
- ⇒ Don't need to iterate.
- ⇒ Slow if n is very large.

$$O(n^3)$$

$$n = 100 \quad \text{OK}$$

$$n = 1000 \quad \text{OK}$$

$$n = 10000 \quad \leftarrow \text{Not greater than this}$$

CHAPTER 4

Logistic Regression

6

Logistic Regression

6.1) Classification

⇒ Logistic Regression is a classification algorithm.

$$0 \leq h_{\theta}(x) < 1$$

6.2) Hypothesis representation

$$h_{\theta}(x) = g(\theta^T x)$$

$$\text{where } g(z) = \frac{1}{1 + e^{-z}}$$

→ Sigmoid function
or
logistic function

$$\Rightarrow h_{\theta}(x) = \frac{1}{1 + e^{-\theta^T x}}$$

estimated probability that
 $y=1$ on input x

6.3) Decision boundary

Predict " $y=1$ " if $h_{\theta}(x) \geq 0.5$

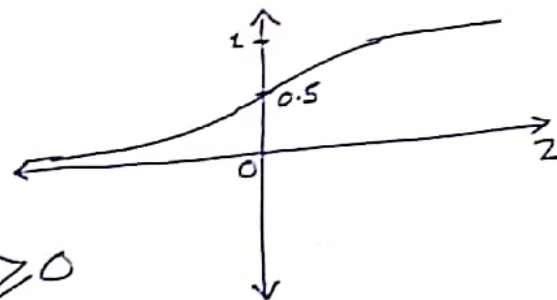
& Predict " $y=0$ " if $h_{\theta}(x) < 0.5$

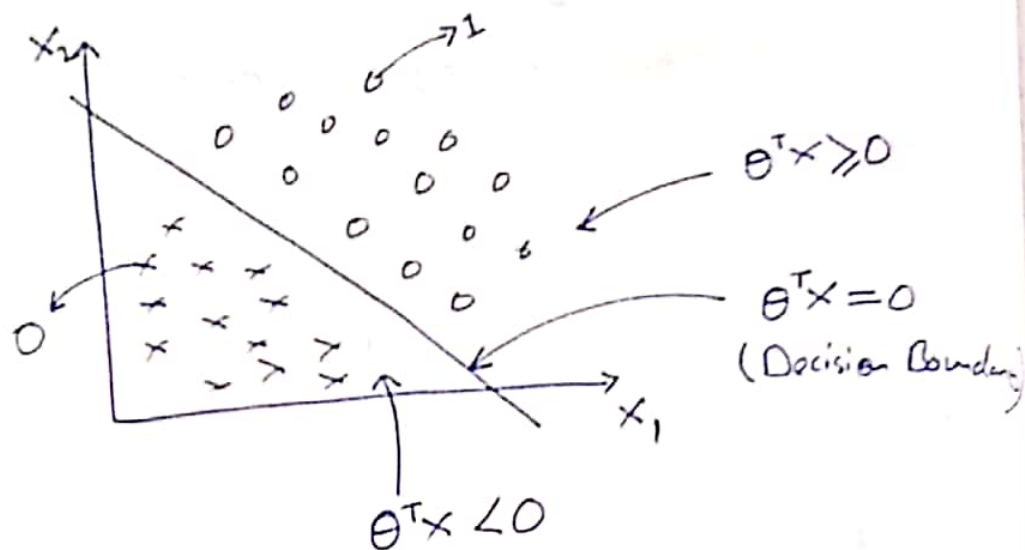
$$h_{\theta}(z) = \frac{1}{1 + e^{-z}}$$

$$\text{where } z = \theta^T x$$

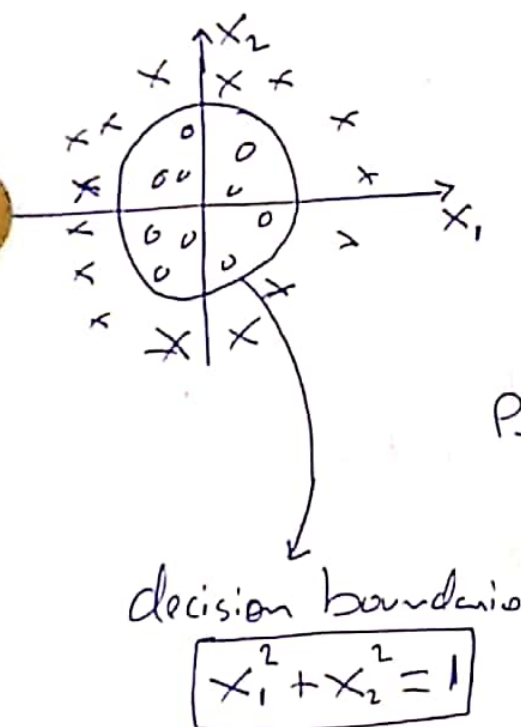
$$h_{\theta}(z) \geq 0.5 \Rightarrow z \geq 0$$

$$\& h_{\theta}(z) < 0.5 \Rightarrow z < 0$$





Non linear decision boundaries



$$h_{\theta}(x) = g(\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1^2 + \theta_4 x_2^2)$$

$$\theta = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

Predict "y=1" if $-1 + x_1^2 + x_2^2 > 0$
 $\Rightarrow x_1^2 + x_2^2 > 1$

decision boundary

$$x_1^2 + x_2^2 = 1$$

6.4) Cost function

Training Set: $\{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(m)}, y^{(m)})\}$
 {m examples}

$$x = \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$x_0 = 1 \quad y \in \{0, 1\}$$

$$h_{\theta}(x) = \frac{1}{1 + e^{-\theta^T x}}$$

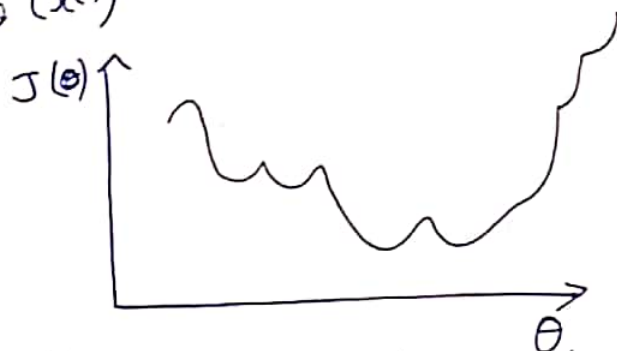
* Cost Function

$$J(\theta) = \frac{1}{m} \sum_{i=1}^m \text{Cost}(h_{\theta}(x^{(i)}), y)$$

b) \Rightarrow If $\text{Cost}(h_{\theta}(x^{(i)}), y) = \frac{1}{2} (h_{\theta}(x^{(i)}) - y)^2$

{Same as Linear regression}

\Rightarrow then, $J(\theta)$ is not a Convex function because of highly non linear term $h_{\theta}(x^{(i)})$



\Rightarrow So using gradient descent will not guarantee global minima.

\Rightarrow So to avoid this problem we will use the following as cost function.

$$\text{Cost}(h_{\theta}(x), y) = \begin{cases} -\log(h_{\theta}(x)) & \text{if } y=1 \\ -\log(1-h_{\theta}(x)) & \text{if } y=0 \end{cases}$$

\rightarrow It gives very high penalties if prediction is wrong and zero penalties if prediction is correct.

\rightarrow It guarantees a convex function.
(Proving this is out of scope of this course)

6.5) Simplified Cost function and gradient descent

⇒ Simplified Cost function:

$$\text{Cost}(h_{\theta}(x), y) = -y(\log(h_{\theta}(x))) - (1-y)\log(1-h_{\theta}(x))$$

$$J(\theta) = \frac{1}{m} \sum_{i=1}^m \text{Cost}(h_{\theta}(x^{(i)}), y^{(i)})$$

* Gradient Descent

$$J(\theta) = -\frac{1}{m} \left[\sum_{i=1}^m y^{(i)} \log h_{\theta}(x^{(i)}) + (1-y^{(i)}) \log(1-h_{\theta}(x^{(i)})) \right]$$

Want min_θ J(θ):

Repeat {

$$\theta_j: \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta)$$

}

{ Simultaneously update all θ_j }

$$\left\{ \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)} \right\}$$

6.6 > Advanced Optimization

⇒ Other optimization algorithms: $\left\{ \begin{array}{l} \text{other than } \underline{\text{gradient}} \\ \underline{\text{descent}} \end{array} \right\}$

- Conjugate gradient
- BFGS
- L-BFGS

Advantages

→ No need to manually pick α .

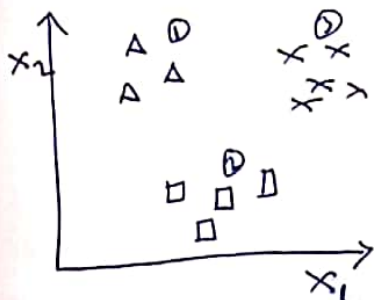
→ Often faster than gradient descent

Disadvantages

→ More complex

6.7 > Multiclass - Classification (one-vs-all)

⇒ Classification problem with more than two classes.



⇒ Turn this into three separate binary classification problems.

$$h_{\theta}^{(1)}(x) \rightarrow \Delta \text{ vs rest}$$

$$h_{\theta}^{(2)}(x) \rightarrow \square \text{ vs rest}$$

$$h_{\theta}^{(3)}(x) \rightarrow \times \text{ vs rest}$$

① Train a logistic regression classifier $h_{\theta}^{(i)}(x)$ for each class i to predict the probability that $y=i$.

② On a new input x , to make a prediction, pick the class i that maximizes

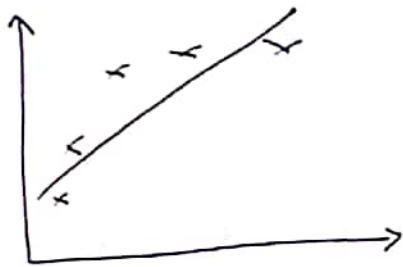
$$\max h_{\theta}^{(i)}(x)$$

CHAPTER 5

Regularization

Regularization

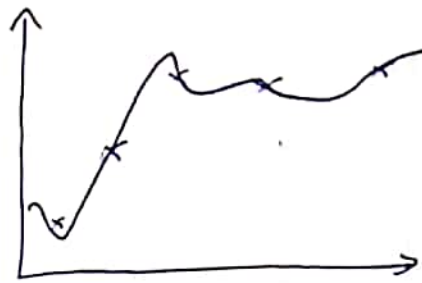
7.1) Problem of Overfitting



$$\theta_0 + \theta_1 x$$

⇒ "Under fit"

⇒ It has "high bias"



$$\theta_0 + \theta_1 x + \theta_2 x^2 + \theta_3 x^3 + \theta_4 x^4$$

⇒ "Overfit"

⇒ It has high variance

Overfitting

↳ If we have too many features, the learned hypothesis may fit the training set very well, but fails to generalize to example.

⇒ Overfitting can also be found in Classification.



Addressing Overfitting

1. Reduce number of features

- Manually select which features to keep.
- Model selection algorithm

2. Regularization

- Keep all the features, but reduce magnitude of parameters θ_j .

7.2 Cost Function

- Small values for parameters $\theta_0, \theta_1, \theta_2, \dots, \theta_n$
 - "Simpler" hypothesis.
 - Less prone to overfitting.

⇒ As we don't know which parameter is less important, so we will penalise all the parameters:-

$$J(\theta) = \frac{1}{2m} \left[\sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2 + \lambda \sum_{j=1}^n \theta_j^2 \right]$$

Regularization
Parameter

{ Objective: fit the
training data well }

{ Objective: Keep
the parameter
small }

{ It controls the trade off
between the two objectives }

7.3) Regularized - Normal equation

$$X = \begin{bmatrix} (x^{(1)})^T \\ \vdots \\ (x^{(m)})^T \end{bmatrix} \quad Y = \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix}$$

$m \times (n+1) \qquad m \times 1$

$$\theta = \left(X^T X + \lambda \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & \dots & 1 \end{bmatrix} \right)^{-1} X^T Y$$

$(n+1) \times (n+1)$

7.4) Regularized - logistic regression

$$J(\theta) = - \left[\frac{1}{m} \sum_{i=1}^m y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log (1 - h_{\theta}(x^{(i)})) \right]$$

$$+ \frac{\lambda}{2m} \sum_{j=1}^n \theta_j^2$$

