Creating your first ros2 package

ROS2 package

→ Can be considered as a Container for your ROS2 code.

↳ If you want to be able to install your code or share it with others, you'll need it organized in a package.

⇒ Package creation in ROS2 uses **ament** as its build system & **colcon** as its build tool.

 ↳ You can create a package using either (CMake) or (Python) which are officially supported.

⇒ You can have packages of different build type in one workspace, but you cannot have nested package.

———— ✕ —— ✕ ————