

## DESIGN NOTE

# Quadrature phase shifter for audio frequency sinewaves

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**Abstract.** A quadrature phase shifter for sinusoidal signals is presented. The circuit provides  $90^\circ$  phase delay (within  $1^\circ$ ) and unity gain (within 6%) in the frequency range 100 Hz to 10 kHz. It consists of a second-order lowpass current-controlled filter; the cutoff frequency is maintained equal to the input frequency with a frequency to current converter. In this way, the filter provides a  $90^\circ$  phase delay between input and output. The main feature of the phase shifter is the absence of internal feedback; this avoids the introduction of long settling time constants when the phase shifter is part of control loops and gives almost instantaneous (within a period) resettling of the  $90^\circ$  phase delay when amplitude or phase variations of the input signal occur.

## 1. Introduction

Many applications require a circuit which produces, given an input sinusoidal signal of amplitude  $A$  and frequency  $f$ ,  $V_{in} = A \sin(2\pi ft)$ , a sinusoidal output of the same amplitude and frequency but with a  $90^\circ$  phase delay with respect to input,  $V_{out} = A \cos(2\pi ft)$ . A number of active and passive networks have been proposed [1] which, given an input, provide two outputs whose phase difference is  $90^\circ$ ; only a few circuits have been reported which give the quadrature relation directly between input and output [2] and they suffer from a very limited working frequency range. A very good quadrature and amplitude precision can be accomplished [3, 4] with a feedback control. These feedbacks require, for good precision and noise rejection, long settling time constants (several seconds for audio frequencies). This feature becomes a serious drawback when the phase shifter itself is part of a control loop; examples of this employ can be found in synchronous vector compensators for automatic bridges [5, 6].

The circuit presented here permits one to obtain acceptable amplitude and phase quadrature precision in a wide frequency range, without internal feedback control loops. Phase and amplitude response is almost instantaneous (within a period of the input frequency); response to frequency variations depend on the precision requested and in the present circuit the time constant is around 1 s. The frequency range can be easily extended if one accepts a loss of precision or a switch for different ranges.

## 2. Working principle

The principle of operation is indicated by the block diagram of figure 1. The two current-controlled filters (ICFs) are single-pole, lowpass filters with a transfer function

$$G(\omega) = \sqrt{2} / \left( 1 + j \frac{\omega}{2\pi f_{cut}} \right) \quad (1)$$

where  $f_{cut}$  can be controlled by a current  $I_{control}$ .

The remainder of the circuit is a frequency to current converter (with two outputs for the two filters); it is made with a square shaper, a frequency to voltage (F/V) converter and two voltage to current converters, and is tuned in a way to maintain  $f_{cut} = f$ . For this condition, the transfer function (1) gives for the ICF:

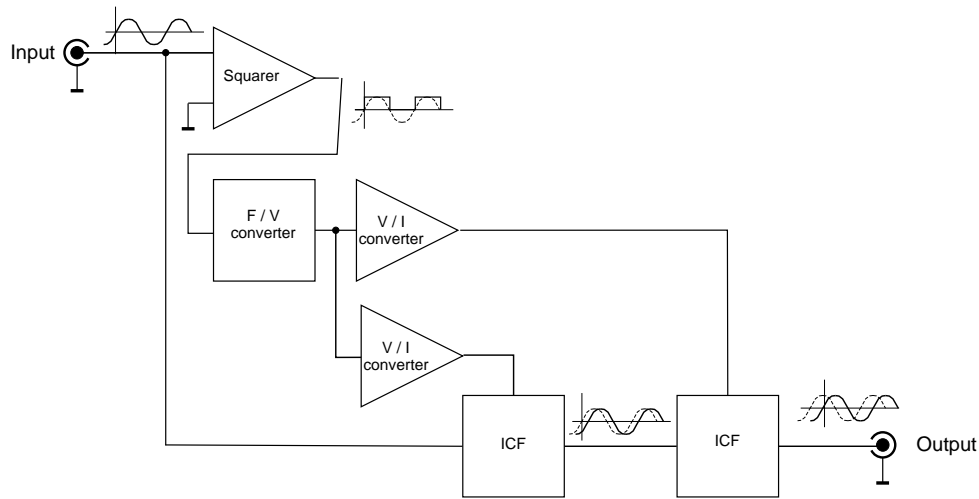
$$G = 1 \quad \arg(G) = 45^\circ$$

i.e. unit gain and a  $45^\circ$  phase shift.

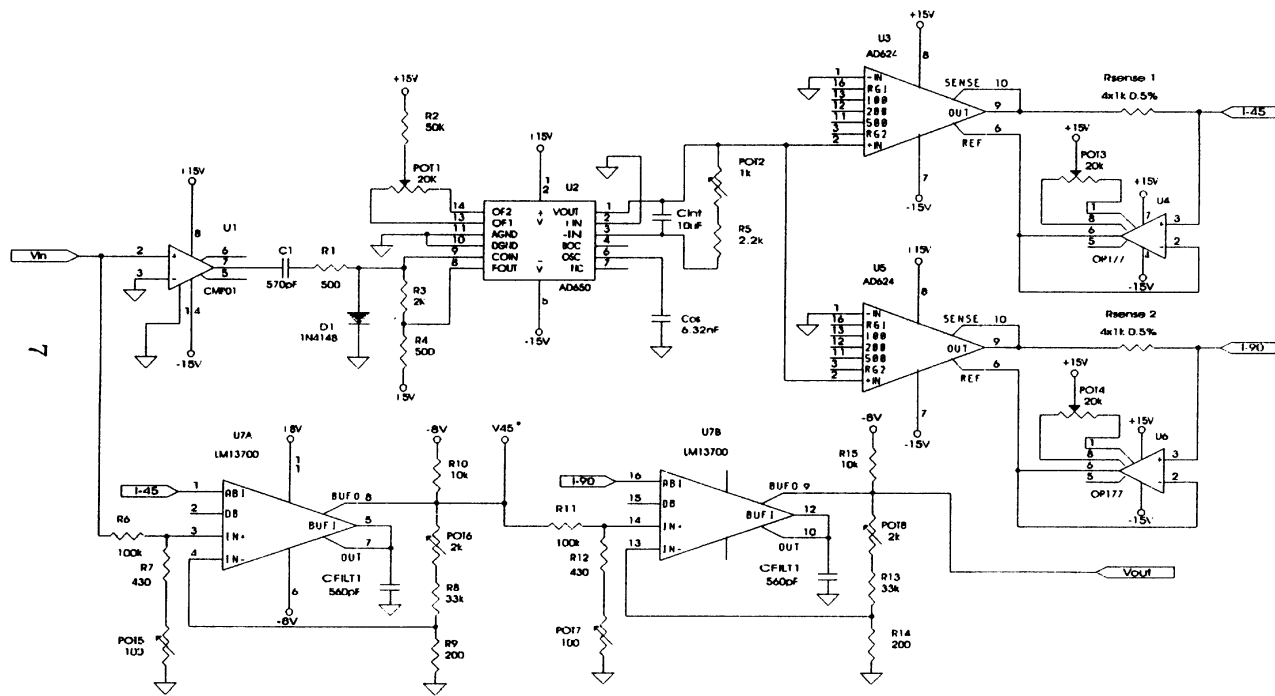
For a series of two ICFs, we have  $G_{series} = 1$  and  $\arg(G_{series}) = 90^\circ (ret)$ .

## 3. Circuit details

The circuit diagram is shown in figure 2. The sinusoidal input voltage  $V_{in}$  is squared in a comparator  $U_1$  (CMP01) and fed, through AC coupling, into a F/V converter constructed around  $U_2$  (AD650). The output goes through voltage to current converters which are formed by an instrumentation amplifier  $U_{3/5}$  (AD624) and a sensing resistor  $R_{sense1/2}$ , whose signal is fed back to  $U_{3/5}$  by



**Figure 1.** Block diagram of the phase shifter. ICF represents the current-controlled lowpass filter.



**Figure 2.** The complete circuit diagram of the phase shifter.

a low-offset buffer  $U_{4/6}$  (OP177). The current  $I_{-45/90^\circ}$  drives a lowpass filter [7] constructed around  $U_{7A/B}$  (the two independent sections of LM13700) which acts as an active filter whose cut frequency depends on  $C_{filt1/2}$  and the driving current  $I_{-45/90^\circ}$ . The output  $V_{out}$  must be collected with an AC coupler (not present in the diagram).

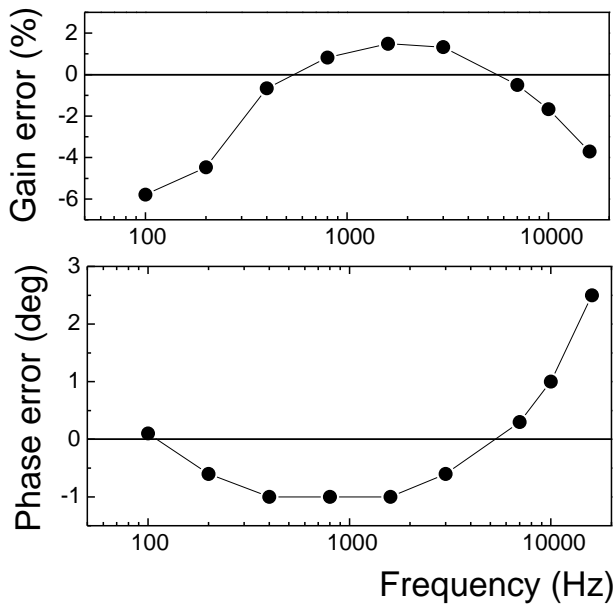
The circuit is designed for a maximum working frequency  $f_{max} = 20$  kHz, and  $I_{-45/90^\circ}(f_{max}) = 1.25$  mA. The choice of values of the lowpass filters is made following a formula from the National Semiconductor Corp. [7]. This can be easily altered.

The circuit requires five power supply voltages (+5 V,  $\pm 8$  V,  $\pm 15$  V), easily obtained with standard regulators

(e.g. 7805, 7808, 7908, 7815, 7915) not shown in the diagram.

#### 4. Regulations

- Trim the offset of  $U_2$  (with  $R_2$ ),  $U_{4/6}$  (with  $POT_{3/4}$ ).
- Apply a signal  $f_{max}$  at  $V_{in}$ , trim  $POT_2$  to have the correct current  $I_{-45/90^\circ}$  (the voltage drop on  $R_{sense1/2}$  must be 5 V).
- Applying a signal  $f_{trim}$  (select the frequency where the minimum error is desired), trim  $POT_5$  (gain) and  $POT_6$  (phase) to achieve unity gain and  $45^\circ$  phase delay at  $V_{45^\circ}$ .



**Figure 3.** Deviations of the transfer function of the phase shifter with respect to the perfect case (gain = 1, phase delay =  $90^\circ$ ).

auxiliary output. Repeat the procedure at  $POT_7$  (gain) and  $POT_8$  (phase) to maintain unity gain and  $90^\circ$  phase delay at  $V_{out}$ .

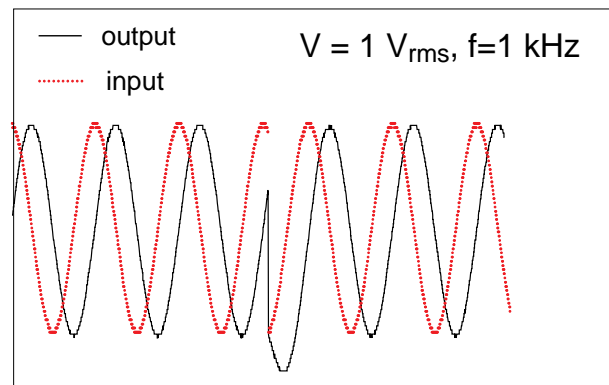
Better precision at low frequencies can be obtained with slight adjustments of the offsets ( $R_2$ ,  $POT_{3/4}$ ).

## 5. Test results

Test results have been obtained using a synthesized sine generator (SRS DS345) as source and a two-channel lock-in amplifier (EG&G 5210) as vector voltmeter.

The transfer function of the phase shifter is shown in figure 3.

To test the recovery time of the quadrature phase delay between input and output after a phase or amplitude jump of the input wave, we modulated in phase or amplitude the synthesized generator with a square wave. The time response to a phase change is shown in figure 4, which



**Figure 4.** Time domain measurements of the response of the phase shifter. The dotted curve is the input sinewave from a synthesized generator; (the full curve is the) output of the phase shifter. A phase jump of the input is provoked by phase modulation of the generator; the resettling time of the  $90^\circ$  phase delay occurs after less than a period.

shows that, as expected from a second-order lowpass filter, quadrature is recovered after a delay of the period of the input wave. A similar response was obtained with an amplitude modulation.

## References

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