Task 0:{'setpoints': {'velocity.x': 0.0, 'velocity.y': 0.0, 'velocity.z': 0.1, 'attitudeRate.yaw': '0.0°'}}
Task 1:{'setpoints': {'velocity.x': 0.1, 'velocity.y': 0.1, 'velocity.z': 0.1, 'attitudeRate.yaw': '0.0°'}, 'num_steps': 1000}