

Task 0: {'setpoints': {'velocity.x': 0.0, 'velocity.y': 0.0, 'position.z': 1, 'attitudeRate.yaw': '0.0°'}}  
Task 1: {'setpoints': {'velocity.x': 0.1, 'velocity.y': 0.1, 'velocity.z': 0.0, 'attitudeRate.yaw': '0.0°'}, 'num\_steps': 1000}

