

Task 0: {'setpoints': {'velocity.x': 0.0, 'velocity.y': 0.0, 'position.z': 1, 'attitudeRate.yaw': '0.0°'}}
Task 1: {'setpoints': {'velocity.x': 0.0, 'velocity.y': 0.0, 'velocity.z': 0.0, 'attitudeRate.yaw': '30.0°'}, 'num_steps': 1000}

