# Nur Muhammad "Mahi" Shafiullah

Contact Information	60 Fifth Avenue, Fl. 5 New York, NY 10011	Web: https://mahis.life E-Mail: mahi@cs.nyu.edu PHONE: +1 (617) 909 3049		
Education	Courant Institute of Mathematical Sciences New York University  Ph.D. Candidate in Computer Science (GPA: 4.0/4.0)  Advisor: Prof. Lerrel Pinto	Sep. 2020 – Present		
	Massachusetts Institute of Technology	Sep. 2015 – Aug. 2020		
	M.Eng. in Electrical Engineering and Computer Science (GPA: 5. Advisor: Prof. Aleksander Mądry			
	S.B. in Mathematics and in Computer Science (GPA: 4.89/5.0)	Sep. '15 – Jun. '19		
Research Experience	Hello Robot Inc.; Research Consultant with Dr. Aaron Edsinge GenAI & FAIR @ Meta AI; Visiting Scientist with Dr. Ishan Mi Embodied AI @ Meta AI; Reserach Intern with Dr. Arthur Szla MIT CSAIL; Research Assistant to Prof. Aleksander Madry	sra Oct. 2022 – Oct. 2023		
Honors and	PhD Communications Award, Amazon Robotics Research Sym	nposium 2024		
Awards	Best Paper, Lifelong Learning for Home Robots workshop @ Co	oRL 2024 2024		
	Outstanding Paper, MFM-EAI workshop @ ICML 2024	2024		
	Best Demo Award (Finalist), International Conference in Robotics and Automation 2024			
	Apple Scholars in AI/ML Fellowship, Apple MLR	2023-25		
	Two Sigma Fellowship, (Finalist, Declined)	2023		
	Jacob T. Schwartz Ph.D. Fellowship, NYU Courant	2023		
	AI Mentorship (AIM) Program, Meta & NYU	2022-23		
	Best Paper, Language and Robot Learning (LangRob) workshop	p @ CoRL 2022 2022		
	Henry M. MacCracken Doctoral Fellowship, NYU	2020-25		
	Burchard Scholars Program, MIT	2018–19		
	AMD Undergraduate Research and Innovation Scholarship, M	MIT 2017–18		
	Silver Medal, International Mathematical Olympiad (IMO)	2014		
	Bronze Medal, International Mathematical Olympiad (IMO) $\times$	2 2012–13		
	Bangladesh Natl. Team, International Olympiad in Informatics	(IOI) ×2 2012, 2015		
	National Champion, Bangladesh Mathematical Olympiad $\times 6$	2009–14		
References	1. <b>Prof. Russ Tedrake</b> , <i>Professor of EECS</i> , <i>Aero/Astro</i> , <i>MechE</i> , <i>MIT</i> . russt@mit.edu			
	2. Prof. Abhinav Gupta, Professor, CMU Robotics Institute. abhinavg@cs.cmu.edu			
	3. Prof. Rob Fergus, Professor of CS, NYU Courant. fergus@cs.nyu.edu			

- 4. **Dr. Charles C. Kemp**, Cofounder & Chief Technology Officer, Hello Robot Inc. Previously Associate Professor, Georgia Institute of Technology. ck@hello-robot.com
- 5. Prof. Lerrel Pinto, Assistant Professor of CS, NYU Courant. lerrel@cs.nyu.edu

#### **PREPRINTS**

† Equal Contribution, ‡ Equal Advising. Works Presented Reverse Chronologically.

#### [1] DynaMem: Online Dynamic Spatio-Semantic Memory for Open World **Mobile Manipulation** DOI: ARXIV:2411.04999

International Conference of Robotics and Automation (ICRA) (Under Review) Live Demo at Conference on Robot Learning (CoRL) 2024 Best Paper Award at CoRL 2024 Workshop on Lifelong Learning for Home Robots Liu, P., Guo, Z., Warke, M., Chintala, S., Paxton, C., Shafiullah, Nur Muhammad Mahi<sup>‡</sup> & Pinto, L.<sup>‡</sup>

## [2] Robot Utility Models: General Policies for Zero-Shot Deployment in **New Environments**

DOI: ARXIV:2409.05865

International Conference of Robotics and Automation (ICRA) (Under Review) Live Demo at Conference on Robot Learning (CoRL) 2024 **Oral Presentation** at CoRL 2024 Workshop on Language and Robot Learning (LangRob) Etukuru, H.<sup>†</sup>, Naka, N., Hu, Z., Lee, S., Mehu, J., Edsinger, A., Paxton, C., Chintala, S., Pinto, L., Shafiullah, Nur Muhammad Mahi<sup>†</sup>

#### [3] On Bringing Robots Home

DOI: ARXIV:2311.16098

*International Journal of Robotics Research (Under Review)* Live Demo at Neural Information Processing Systems (NeurIPS) 2023 Best Demo Award (Finalist) at International Conference on Robotics and Automation (ICRA) 2024 Shafiullah, Nur Muhammad Mahi<sup>†</sup>, Rai, A.<sup>†</sup>, Etukuru, H., Liu, Y., Misra, I., Chintala, S., Pinto, L.

## Refereed **PUBLICATIONS**

[4] OK-Robot: What Really Matters in Integrating Open-Knowledge Models for Robotics Robotics: Science and Systems (RSS) 2024 Live demo at International Conference on Robotics and Automation (ICRA) 2024 Liu, P.<sup>†</sup>, Orru, Y.<sup>†</sup>, Vakil, J., Paxton, C., *Shafiullah, Nur Muhammad Mahi*<sup>‡</sup> & Pinto, L.<sup>‡</sup>

#### [5] Behavior Generation with Latent Actions

Spotlight (3.5%) at International Conference of Machine Learning (ICML) 2024 Outstanding Paper Award at Multi-modal Foundation Models for Embodied AI workshop, ICML 2024 Lee, S., Wang, Y., Etukuru, H., Kim, H., Shafiullah, Nur Muhammad Mahi<sup>‡</sup>& Pinto, L.<sup>‡</sup>

- [6] Open X-Embodiment: Robotic learning datasets and RT-x models Best Paper Award at International Conference in Robotics and Automation (ICRA) 2024 Open X-Embodiment Collaboration
- [7] CLIP-Fields: Weakly Supervised Semantic Fields for Robotic Memory Robotics: Science and Systems (RSS) 2023 Best Paper Award at CoRL Workshop on Language and Robot Learning 2023 Shafiullah, Nur Muhammad Mahi, Paxton, C., Pinto, L., Chintala, S., Szlam, A.

- [8] From Play to Policy: Conditional Behavior Generation from Uncurated Robot Data Oral Presentation (5%) at Intl. Conference on Learning Representations (ICLR) 2023 Cui, Zichen, Wang, Yibin, Shafiullah, Nur Muhammad Mahi, Pinto, Lerrel
- [9] Behavior Transformers: Cloning k Modes with One Stone
  Neural Information Processing System (NeurIPS) 2022
  Shafiullah, Nur Muhammad Mahi, Cui, Zichen, Altanzaya, Ariuntaya, Pinto, Lerrel
- [10] The Surprising Effectiveness of Representation Learning for Visual Imitation Robotics: Science and Systems (RSS) 2022
  Pari, J.†, Shafiullah, Nur Muhammad Mahi†, Arunachalam, S.P., Pinto, L.
- [11] One After Another: Learning Incremental Skills for a Changing World International Conference on Learning Representations (ICLR) 2022 Shafiullah, Nur Muhammad Mahi, Pinto, Lerrel
- [12] Training for Faster Adversarial Robustness Verification via Inducing ReLU Stability International Conference on Learning Representations (ICLR) 2019
  Xiao, K. Y., Tjeng, V., Shafiullah, Nur Muhammad Mahi, Madry, A.

## TUTORIALS [13] Supervised Policy Learning for Real Robots

Robotics: Science and Systems (RSS) 2024 https://supervised-robot-learning.github.io/ Shafiullah, Nur Muhammad Mahi, Feng, Siyuan, Pinto, Lerrel & Tedrake, Russ

#### INVITED TALKS On Building General, Zero-Shot Robot Policies

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Harvard Computational Robotics Group	Oct. 2024
MIT Embodied Intelligence Seminar	Oct. 2024
OpenAI Robotics Reading Group	Oct. 2024
CMU Manipulation Group Seminar	Sep. 2024
Behavior Generation with Latent Actions	
HuggingFace LeRobot Research Talks	Aug. 2024
On Bringing Robots Home	
Apple AI/ML Research	May 2024
UMich EECS 598: Action & Perception	Mar. 2024
Google Deepmind Robotics	Mar. 2024
Berkeley Robot Learning Lab	Feb. 2024
Meta Embodied AI Seminar	Jan. 2024
NYU CILVR Seminar	Dec. 2023
Robot Learning in a Post-Turing World	
Honda Research, Tokyo	Jul. 2023
REAL Lab @ Columbia (now Stanford)	Nov. 2022

## Press Coverage

Robot Utility Models: General Policies for Zero-Shot Deployment in New Environments MIT Technology Review, The Robot Report, Elektropraktiker (Germany), IndiaAI.gov (India)

OK Robot: What Really Matters in Integrating Open-Knowledge Models for Robotics MIT Technology Review, Fox News, VentureBeat, TechXplore, Notebookcheck, Digital Information World (Pakistan)

#### On Bringing Robots Home

MIT Technology Review, New Scientist, TechXplore, TV Tokyo (Japan), Neue Zürcher Zeitung (Switzerland), NDTV (India), MarkTechPost, Washington Square News

## Open X-Embodiment: Robotic Learning Datasets and RT-X Models

VentureBeat, Tech Times, Synced Review (Canada), TechForge (UK) Analytics India Magazine (India)

# The Surprising Effectiveness of Representation Learning for Visual Imitation TechXplore

## TEACHING Experience

# **Graduate Deep Reinforcement Learning (CSCI-GA 3033-090)**

Fall 2021

New York University

Graduate Teaching Assistant with Prof. Lerrel Pinto

Introduction to Machine Learning (6.036)  $\times 2$ 

Jointly Instructed with Applied Machine Learning (6.862) Spring & Fall 2019

Massachusetts Institute of Technology

Graduate Teaching Assistant with Prof. Leslie P. Kaelbling

# Principles of Discrete Applied Mathematics (18.200)

Fall 2018

Massachusetts Institute of Technology

Teaching Assistant (Grading) with Prof. Andrej Risteski

#### Design and Analysis of Algorithms (6.046/18.410) $\times 4$

Fall 2015 - Spring 2017

Massachusetts Institute of Technology

Volunteer Student Tutor with Eta Kappa Nu (HKN) Honor Society

## Combinatorics and Euclidean Geometry

2010-15, 2022-23

Bangladesh Mathematical Olympiad National Camps Instructor under Dr. Mahbub A. Majumdar

## RESEARCH MENTORING

#### **Current Students**

Haritheja Etukuru (2023 - Present, BS @ New York University; Graduating '25)

Omar Rayyan (2024 - Present, BS @ New York University (Abu Dhabi); Graduating '25)

Zhanqiu "Jack" Guo (2024 – Present, BS @ New York University; Graduating '25)

Lisa Kondrich (2024 – Present, MS @ New York University; Graduating '26)

Norihito Naka (2023 - Present, MS @ New York University; Graduating '25)

Yibin Wang (2022 - Present, BS, MS @ New York University; Graduating '25)

#### **Past Students**

Seungiae Lee (2023 – 24, MS @ Seoul National University; Next Ph.D. at UMD)

Peiqi Liu (2023 – 24, BS @ New York University; Next at Hello Robot Inc.)

Anant Rai (2022 – 23, MS @ New York University; Next at 1X.tech)

Zichen "Jeff" Cui (2022 – 24, MS @ New York University; Next Ph.D. at NYU GRAIL)

Yaswanth Orru (2023 – 24, MS @ New York University; Next at Fauna Robotics)

Ariuntaya Altanzaya (2022–23, MS @ New York University; Next at Roboflow)

Sridhar Pandian Arunachalam (2021–22, MS @ New York University; Next at 1X.tech)

Jyothish Pari (2020 – 21, BS @ New York University; Next Ph.D. at MIT)

#### SERVICE

### Workshop and Tutorial Organization

7<sup>th</sup> Workshop on Robot Learning @ ICLR '25 (proposed)

Tutorial on Supervised Policy Learning for Real Robots @ RSS '24

1<sup>st</sup> Workshop on Vision-Language Models for Navigation and Manipulation @ ICRA '24 1<sup>st</sup> Workshop on Learning Dexterous Manipulation @ RSS '23

# **Peer Reviewing**

Robotics — RSS, CoRL, RA-L, ICRA, T-RO, IROS, IJRR

 ${\it Machine Learning}-{\it ICLR}, {\it NeurIPS}, {\it ICML}$ 

Computer Vision — T-PAMI

Workshops at the intersection of ML, CV, and Robotics.

# Volunteering, Outreach, and Social Good

2021-Present
2023
2023
2020-22
2020-21
2019-20
2018
2017-18
2015-17
2014-2015
2010-2015