

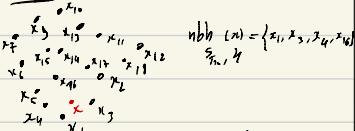
K-nearest Neighbor classifier

K-nearest neighbor:

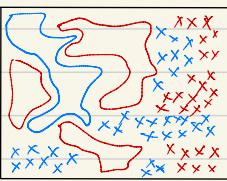
$$(x_i, y_i) \sim D$$

$$S_{T_{\text{train}}} = \{(x_i, y_i)\}_{i=1}^N \text{ iid } \sim D_f$$

Ex:



why is it meaningful?



- meaningful when there is spatial correlation
- Implicitly learn very complex decision boundaries in low dimension!!

Nearest neighbor functions:

$$\text{nbh}_{T_{\text{train}}, k}(x) = \{ \text{set of } k \text{ elements of } S_{T_{\text{train}}} \text{ the closer to } x \}$$

Regression: $y \in \mathbb{R}$

$$f_{S_{T_{\text{train}}}, k}(x) = \frac{1}{k} \sum_{i \in \text{nbh}_{T_{\text{train}}, k}(x)} y_i$$

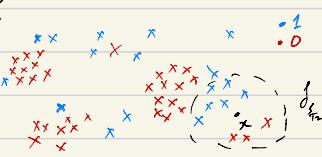


$$f(x) = \frac{1}{4} (y_1 + y_2 + y_3 + y_4)$$

Classification:

$$y \in \{0, 1\} \quad (\text{Binary classification}) \quad f_{S_{T_{\text{train}}}, k}(x) = \text{majority } (y_i) \quad i \in \text{nbh}_{T_{\text{train}}, k}(x)$$

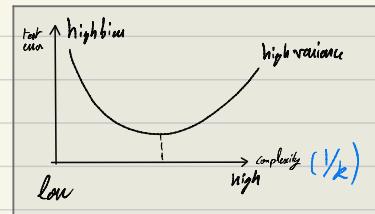
Ex:



- take k odd to avoid tie
- Not training method
- Correct classification is odd weighted (closest to y)

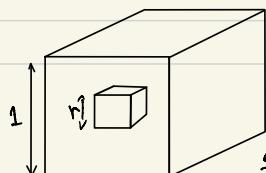
Bias-variance function of K.

- small K, $K=1 \rightarrow$ complex model. (but high variance)
- large K, $K=\# \text{ samples} \rightarrow$ simple model (high bias)
(overfitting)
- complexity scales as \sqrt{k} \rightarrow complexity \sqrt{k} when $k \rightarrow \infty$



Curse of dimensionality

$$\mathcal{X} = [0, 1]^d$$



What is the chance that a random point is in the large box is in the small box

$$\rightarrow r^d \quad (\text{very small})$$

$(1 - r^d)^N$: none of the samples is inside the small box.

\approx if $N=500, d=10$ then $r=0.52$ to find a neighbor

Comparing nearest-neighbor
classifier with the optimal
Bayes classifier.

• Analysis: $(x, y) \sim D$; $y \in \{0, 1\}$ $X = \mathbb{R}^d$

$$\mathcal{L}(f) = \mathbb{P}(y \neq f(x))$$

Bayes Predictor:

$$\eta(x) = \mathbb{P}(y=1|x) = 1 - \mathbb{P}(y=0|x)$$

if I know η , how can I predict when given x .

$$\text{if } \eta(x_0) > \frac{1}{2} \rightarrow 1$$

$$\text{if } \eta(x_0) < \frac{1}{2} \rightarrow 0$$

$$f^*(x) = \begin{cases} 1 & \eta(x) > \frac{1}{2} \\ 0 & \text{otherwise} \end{cases}$$

$$\mathcal{L}(f^*) = \mathbb{P}(f^*(x) \neq y) = \mathbb{E}_{x \sim D_x} [\min \{\eta(x), 1 - \eta(x)\}] \quad (\text{Bayes Loss, (MAP)})$$

• Claim:

$$\mathbb{E}_{S_{\text{train}}} [\mathcal{L}(f^*)] \leq 2 \mathcal{L}(f^*) + \text{geometric term}$$

. we assume that $\exists c \geq 0$, $\forall x, x' \in \mathcal{X}$, $|\eta(x) - \eta(x')| \leq c \|x - x'\|_2$

$$\Rightarrow \text{Geometric term} = c \mathbb{E}_{\substack{x \sim D \\ x \in S_{\text{train}}}} [\|x - \text{ubh}_{S_{\text{train}}, 1}(x)\|]$$

$$\boxed{\mathbb{E}_{S_{\text{train}}} [\mathcal{L}(f^*)] \leq 2 \mathcal{L}(f^*) + c \mathbb{E}_{\substack{x \sim D \\ x \in S_{\text{train}}}} [\|x - \text{ubh}_{S_{\text{train}}, 1}(x)\|]}$$

$$\boxed{\mathbb{E}_{S_{\text{train}}} [\mathcal{L}(f^*)] \leq 2 \mathcal{L}(f^*) + 4c \sqrt{d} (N)^{-\frac{1}{d+1}}}$$

$$\text{if } N \rightarrow \infty \quad \mathbb{E}_{S_{\text{train}}} [\mathcal{L}(f^*)] \leq 2 \mathcal{L}(f^*)$$

(Proof p12-13, L6b)