<sup>&</sup>quot;\*openCV.txt"

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 $<sup>{\</sup>sim}/Documents/howe299r/python\$ begin; python IMU\_to\_file.py; watch -n 0.2 tail *\_accel\_data.txt watch -n 0.2 wc "**\_accel\_data.txt"$ 

<sup>~/</sup>Documents/howe299r/apriltags/build/bin\$ ./apriltags\_demo; watch -n 0.2 tail \*\_openCV.txt; watch -n 0.2 wc

Position		Time _											
Grams: 0	0	0	20	0	40	0	60	0	80	0	100	0	120
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Position _		Time _											
Grams:	0	0	20	0	40	0	60	0	80	0	100	0	120
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	140	0	160	0	180	0	200	0	220	0	240	U	200
0	140 280	0	<ul><li>160</li><li>300</li></ul>	0	180	U	200	U	220	U	240	U	200
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