

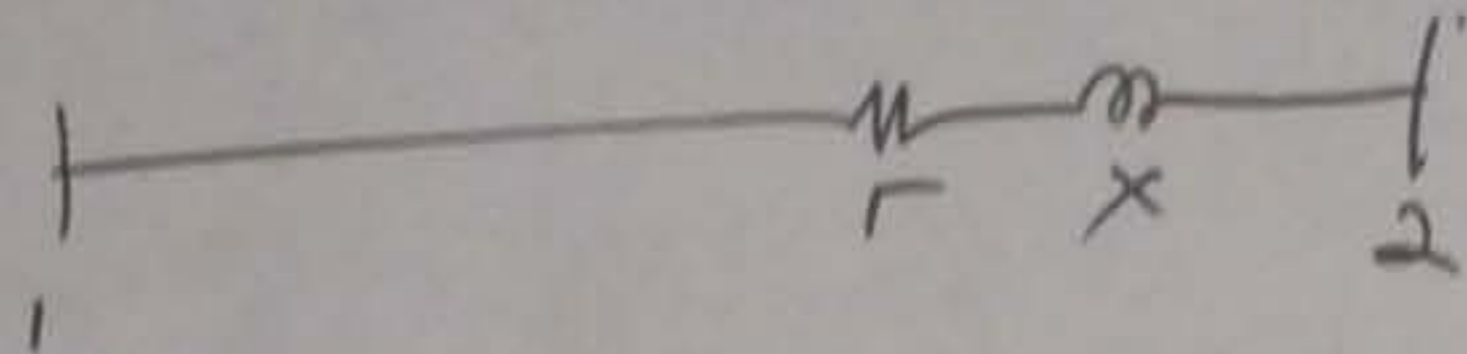
$$S = VI$$

$$\checkmark S = VI^*$$

$$S = V^* I$$

$$\checkmark S = P + jQ$$

$$S = P - jQ$$



$$Z_{12} = r + jx$$

$$Y_{12} = \text{admittansi}$$

$$= \frac{1}{Z_{12}} = \frac{1}{r + jx}$$

$$= G + jB$$

↑                      ↑  
konduktansi      susceptansi

$$G = f(r, x)$$

$$B = f(r, x)$$

$$I = 10 \angle 15$$

$$I^* = 10 \angle -15$$

$$V = 10 + j8$$

$$V^* = 10 - j8$$

$$S = VI$$

$$\checkmark S = VI^*$$

$$S = V^* I$$

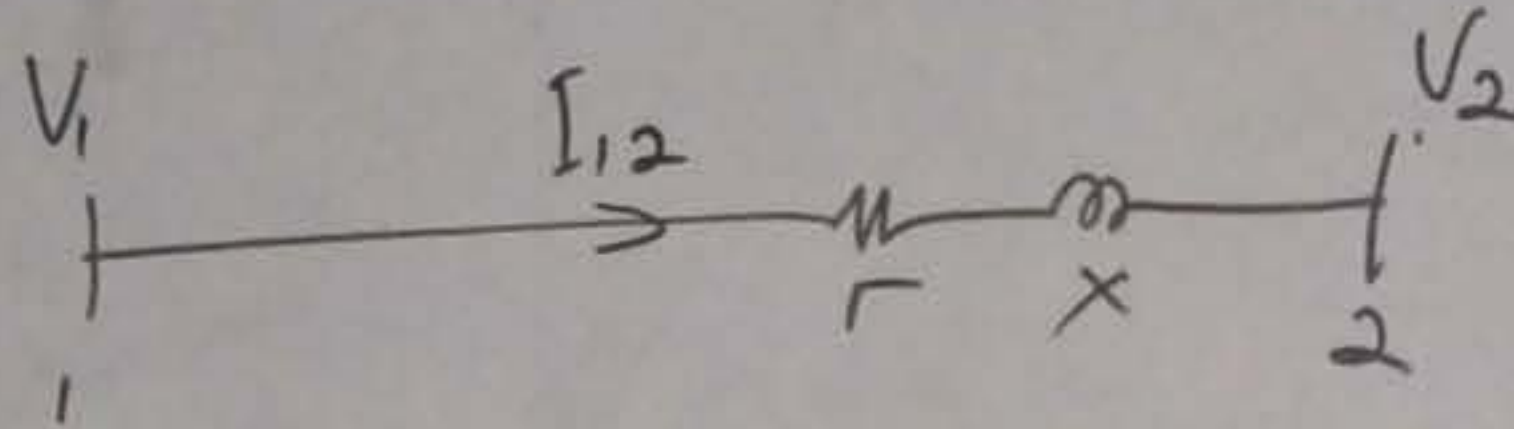
$$I = \frac{\text{tegangan}}{\text{impedansi}}$$

$$\checkmark S = P + jQ$$

$$S = P - jQ$$

$$\frac{1 \times (2 - j10)}{2 + j10 \times (2 - j10)} = \frac{2 - j10}{4 - (j10)^2} = \frac{2 - j10}{4 - (-100)} = \frac{2 - j10}{104}$$

$$I_{12} = \frac{V_{12}}{r + jx} = \frac{V_1 - V_2}{r + jx}$$



$$G = \frac{r}{r^2 + x^2}$$

$$B = \frac{x}{r^2 + x^2}$$

$$Z_{12} = r + jx$$

$$Y_{12} = \text{admittansi}$$

$$= \frac{1}{Z_{12}} = \frac{1}{r + jx}$$

$$= G + jB$$

$$\begin{matrix} \uparrow & \uparrow \\ \text{konduktansi} & \text{susceptance} \end{matrix}$$

$$G = f(r, x)$$

$$B = f(r, x)$$

$$I = 10 \angle 15$$

$$I^* = 10 \angle -15$$

$$V = 10 + j8$$

$$V^* = 10 - j8$$



$$\bar{S}_{12} + \bar{S}_{21} = ? \quad = \text{rugi daya pada saluran.}$$

$$P_{12} = V_1 I_{12} \cos(\theta_1 - \phi_{12})$$

$$Q_{12} = V_1 I_{12} \sin(\theta_1 - \phi_{12})$$

$$\bar{S} = \bar{V} \bar{I}^*$$

$$P_{12} = e_1 I_{x12} + f_1 I_{y12} \quad Q_{12} = f_1 I_{x12} - e_1 I_{y12}$$

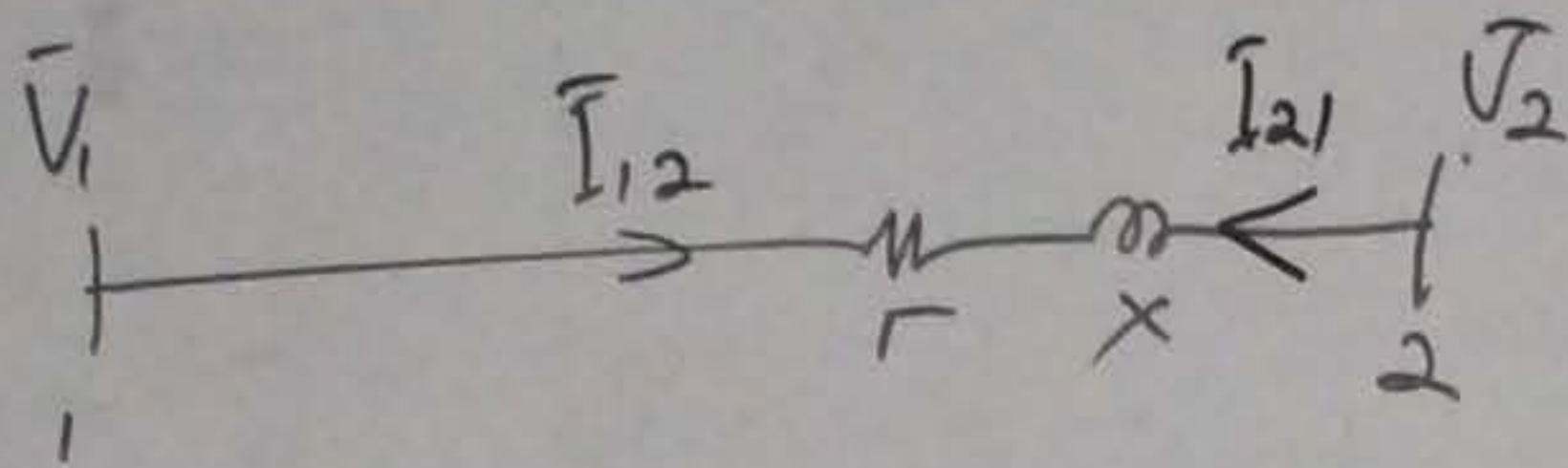
$$\bar{V}_1 = V_1 \angle \theta_1 = e + jf$$

$$\bar{I}_{12} = I_{12} \angle \phi_{12} = I_x + jI_y$$

$$\boxed{\bar{S}_{12} = V_1 I_{12} \angle \theta_1 - \phi_{12}}$$

$$\begin{aligned} \bar{S}_{12} &= e I_x - e j I_y + j I_x f + f I_y \\ &= \underbrace{e I_x + f I_y}_{P_{12}} + j \underbrace{(f I_x - e I_y)}_{Q_{12}} \end{aligned}$$

$$\bar{I}_{12} = \frac{\bar{V}_{12}}{r + jx} = \frac{\bar{V}_1 - \bar{V}_2}{r + jx}$$



$$\bar{I}_{12} = \frac{\bar{V}_{12}}{\bar{Z}_{12}} = Y_{12} V_{12}$$

$$Y_{12} = \frac{1}{\bar{Z}_{12}} \quad G_{12} = \frac{r}{r^2 + x^2} \quad B_{12} = \frac{x}{r^2 + x^2}$$

$$\bar{S}_{12} = \bar{V}_1 \bar{I}_{12}^*$$

$$\bar{S}_{12} = \bar{S}_{21} \neq$$

$$\bar{I}_{12} = -\bar{I}_{21}$$

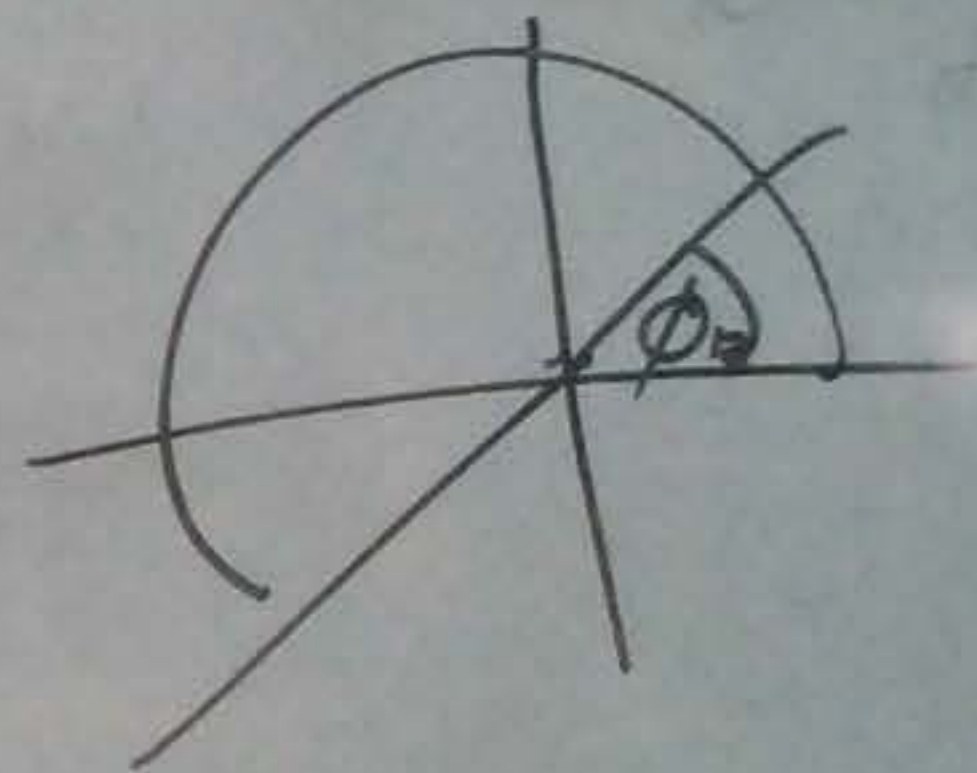
$$I_{12} = I_{21}$$

$$\phi_{12} = \phi_{21} + 180$$

$$\begin{aligned} \bar{I}_{21} &= \frac{\bar{V}_2 - \bar{V}_1}{\bar{Z}_{12}} = Y_{12} (\bar{V}_2 - \bar{V}_1) \\ &= \boxed{-\bar{I}_{12}} \end{aligned}$$

$$\begin{aligned} \bar{S}_{21} &= \bar{V}_2 \bar{I}_{21}^* \\ &= -\bar{V}_2 \bar{I}_{12}^* \end{aligned}$$

$$P_{21} = V_2 I_{21} \cos(\theta_2 - \phi_{21})$$





AST L 6-9-2016

$\bar{S}_{12} + \bar{S}_{21} = ?$  = rugi daya pada saluran.

$$P_{12} = V_1 I_{12} \cos(\theta_1 - \phi_{12})$$

$$Q_{12} = V_1 I_{12} \sin(\theta_1 - \phi_{12})$$

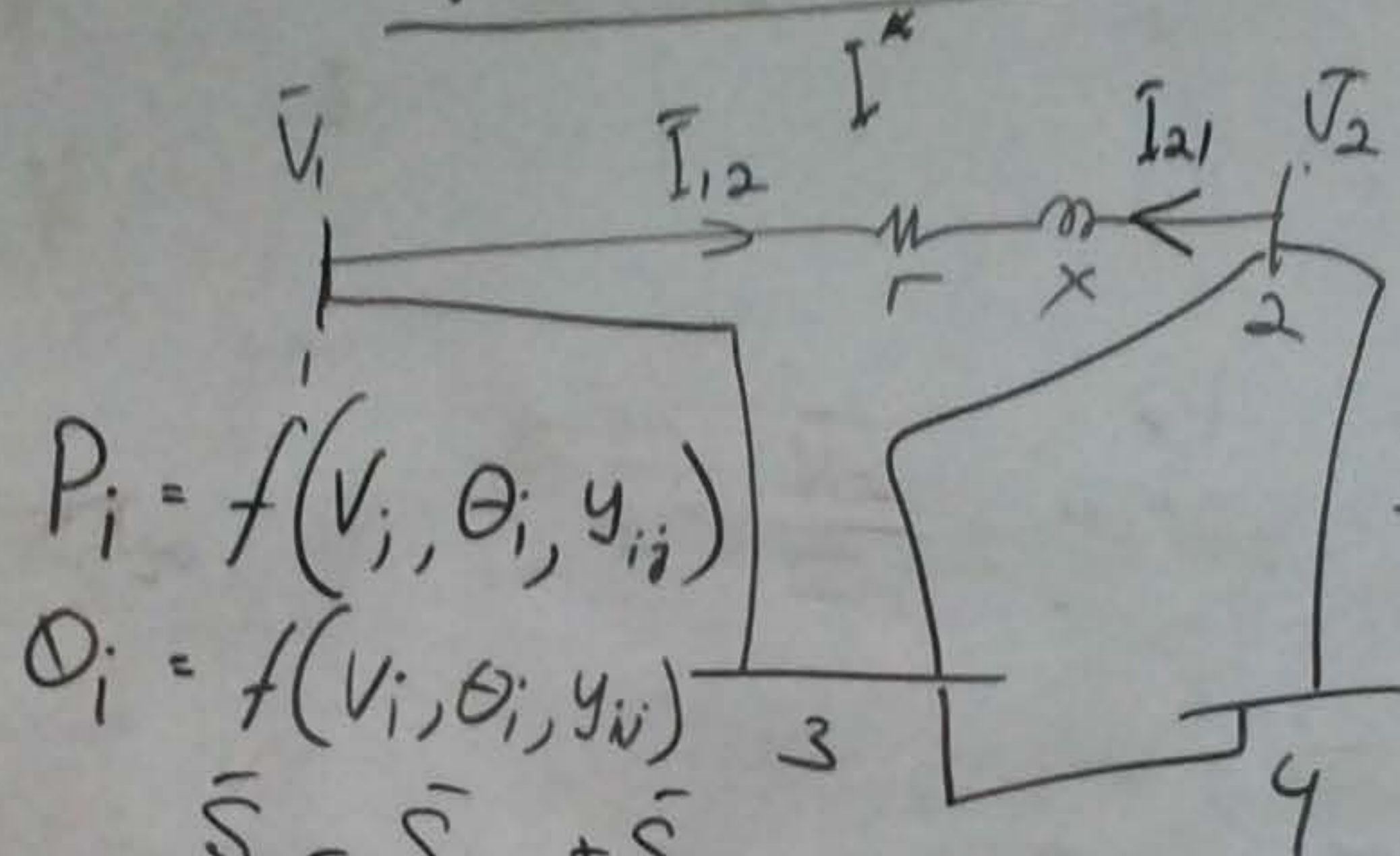
$$\bar{S} = \bar{V} \bar{I}^*$$

no	dari	ke	r	x
1	2	2	$r_{12}$	$x_{12}$
2	1	3	$r_{13}$	$x_{13}$
3	2	3	$r_{23}$	$x_{23}$

$$\bar{S}_2 = \bar{V}_2 \sum_j \bar{V}_2^* \bar{y}_{2j}^* - \bar{V}_j^* \bar{y}_{2j}^*$$

$$\bar{S}_3 = \bar{V}_3 \sum_{j \in \{1,2\}} \bar{V}_3^* \bar{y}_{3j}^* - \bar{V}_j^* \bar{y}_{3j}^*$$

$$\bar{S}_i = \bar{V}_i \sum_j \bar{V}_i^* \bar{y}_{ij}^* - \bar{V}_j^* \bar{y}_{ij}^*$$



$$P_i = f(V_i, \theta_i, y_{ij})$$

$$Q_i = f(V_i, \theta_i, y_{ij})$$

$$\bar{S}_1 = \bar{S}_{12} + \bar{S}_{13}$$

$$\bar{S}_2 = \bar{S}_{21} + \bar{S}_{23}$$

$$\bar{S}_3 = \bar{S}_{31} + \bar{S}_{32}$$

$$\bar{S}_4 = \dots$$

$$\bar{I}_{21} = \frac{\bar{V}_2 - \bar{V}_1}{\bar{z}_{12}} = \bar{y}_{12}(\bar{V}_2 - \bar{V}_1)$$

$$= -\bar{I}_{12}$$

$$= V_1 \sum_{j=2} (\bar{V}_1^* \bar{y}_{1j}^* - \bar{V}_j^* \bar{y}_{1j}^*)$$

$$\bar{S}_1 = \bar{V}_1 \bar{I}_{12}^* + \bar{V}_1 \bar{I}_{13}^*$$

$$= \bar{V}_1 \left[ (\bar{V}_1 - \bar{V}_2) \bar{y}_{12} \right]^* + \bar{V}_1 \left[ (\bar{V}_1 - \bar{V}_3) \bar{y}_{13} \right]^*$$

$$= \bar{V}_1 \left[ (\bar{V}_1^* - \bar{V}_2^*) \bar{y}_{12}^* \right] + \bar{V}_1 \left[ (\bar{V}_1^* - \bar{V}_3^*) \bar{y}_{13}^* \right]$$

$$= \bar{V}_1 \left[ \bar{V}_1^* \bar{y}_{12}^* - \bar{V}_2^* \bar{y}_{12}^* + \bar{V}_1^* \bar{y}_{13}^* - \bar{V}_3^* \bar{y}_{13}^* \right]$$

$$= \bar{V}_1 \left[ \bar{V}_1^* \bar{y}_{12}^* + \bar{V}_1^* \bar{y}_{13}^* - (\bar{V}_2^* \bar{y}_{12}^* + \bar{V}_3^* \bar{y}_{13}^*) \right]$$

$$= V_1 \left[ V_1^* \sum_{j=2}^3 \bar{y}_{1j}^* - \sum_{j=2}^3 \bar{V}_j^* \bar{y}_{1j}^* \right]$$



AST L 6-9-2016

$\bar{S}_{12} + \bar{S}_{21} = ?$  = rugi daya pada saluran.

$$P_{12} = V_1 I_{12} \cos(\theta_1 - \phi_{12})$$

$$Q_{12} = V_1 I_{12} \sin(\theta_1 - \phi_{12})$$

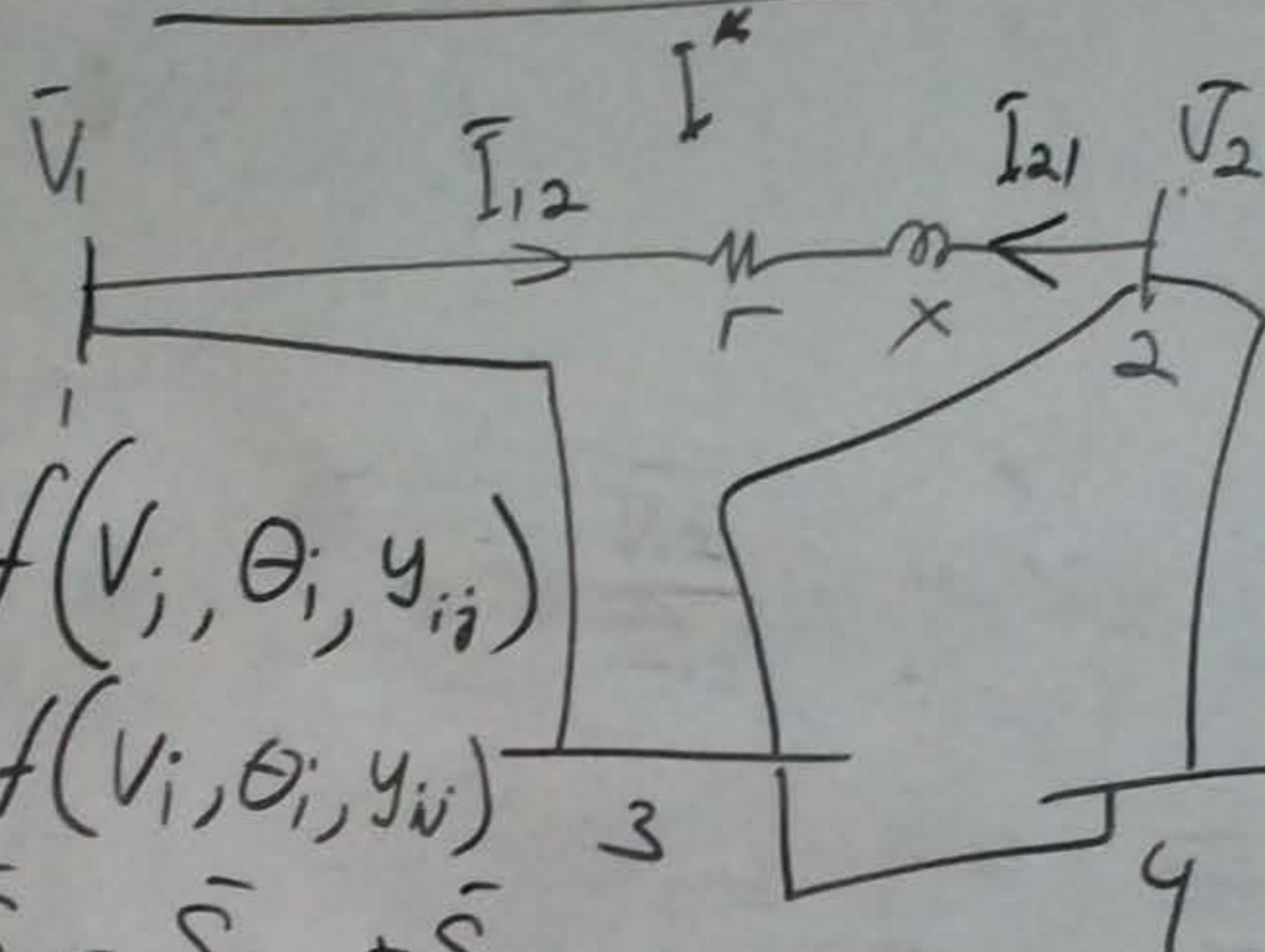
$$\bar{S} = \bar{V} \bar{I}^*$$

Saluran			
dari	ke	r	x
2	2	$r_{12}$	$x_{12}$
1	3	$r_{13}$	$x_{13}$
2	3	$r_{23}$	$x_{23}$

$$\bar{S}_2 = \bar{V}_2 \sum_j V_2^* y_{2j}^* - V_j^* y_{2j}^*$$

$$\bar{S}_3 = V_3 \sum_{j \in \{1,3\}} V_3^* y_{3j}^* - V_j^* y_{3j}^* \quad j \in \{1,2\}$$

$$\bar{S}_i = \bar{V}_i \sum_j V_i^* y_{ij}^* - V_j^* y_{ij}^*$$



$$P_i = f(V_i, \theta_i, y_{ij})$$

$$Q_i = f(V_i, \theta_i, y_{ij})$$

$$\bar{S}_1 = \bar{S}_{12} + \bar{S}_{13}$$

$$\bar{S}_2 = \bar{S}_{21} + \bar{S}_{23}$$

$$\bar{S}_3 = \bar{S}_{31} + \bar{S}_{32}$$

$$\bar{S}_4 = - - - \quad j \in \{2,3\}$$

$$\bar{I}_{21} = \frac{\bar{V}_2 - \bar{V}_1}{\bar{Z}_{12}} = \bar{Y}_{12}(\bar{V}_2 - \bar{V}_1)$$

$$= -\bar{I}_{12}$$

$$= V_1 \sum_{j=2} (V_1^* y_{1j}^* - V_j^* y_{1j}^*)$$

$$\bar{S}_1 = \bar{V}_1 \bar{I}_{12}^* + \bar{V}_1 \bar{I}_{13}^*$$

$$= \bar{V}_1 \left[ (\bar{V}_1 - \bar{V}_2) y_{12} \right]^* + \bar{V}_1 \left[ (\bar{V}_1 - \bar{V}_3) y_{13} \right]^*$$

$$= \bar{V}_1 \left[ (\bar{V}_1^* - \bar{V}_2^*) y_{12}^* \right] + \bar{V}_1 \left[ (\bar{V}_1^* - \bar{V}_3^*) y_{13}^* \right]$$

$$= \bar{V}_1 \left[ \bar{V}_1^* \bar{y}_{12}^* - \bar{V}_2^* \bar{y}_{12}^* + \bar{V}_1^* \bar{y}_{13}^* - \bar{V}_3^* \bar{y}_{13}^* \right]$$

$$= \bar{V}_1 \left[ V_1^* y_{12}^* + V_1^* y_{13}^* - (V_2^* y_{12}^* + V_3^* y_{13}^*) \right]$$

$$= V_1 \left[ V_1^* \sum_{j=2}^3 y_{1j} - \sum_{j=2}^3 V_j^* y_{1j} \right]$$