

# RNN Basic - 학습용 sequence length 의 영향

## 학습 데이터 mini-batch 구성의 차이 FCN, 2D-CNN vs RNN

- FCN ( Fully Connected Network, a.k.a. dense )
  - [batch, inputs]
  - e.g.: `tf.layers.dense()`
- 2D-CNN 의 경우 학습데이터 feed 구성
  - [batch, height, width, channel]:data\_format = "NHWC" (default)
  - [batch, channel, height, width]:data\_format = "NCHW"
  - e.g.: `tf.layers.conv2d()`
- RNN 의 경우 학습 데이터 feed 구성
  - [batch, sequence, input]:time\_major = False (default for `tf.nn.dynamic_rnn()`)
  - [sequence, batch, input]:time\_major = True (default for `tf.nn.static_rnn()`)

```
In [1]: %load_ext do_not_print_href
        %matplotlib inline
        from __future__ import print_function, division
        import sys
        import time
        import numpy as np
        import tensorflow as tf
        import matplotlib.pyplot as plt
```

```
In [2]: # !rm -fr logdir
        # !mkdir -p logdir
```

## 데이터 준비

- 1주차 실습에 사용한 것과 동일한 데이터
- 5주차 실습에서는 tensorflow example 의 기본 제공 메소드를 이용

```
In [3]: from tensorflow.examples.tutorials.mnist.input_data \
        import read_data_sets
```

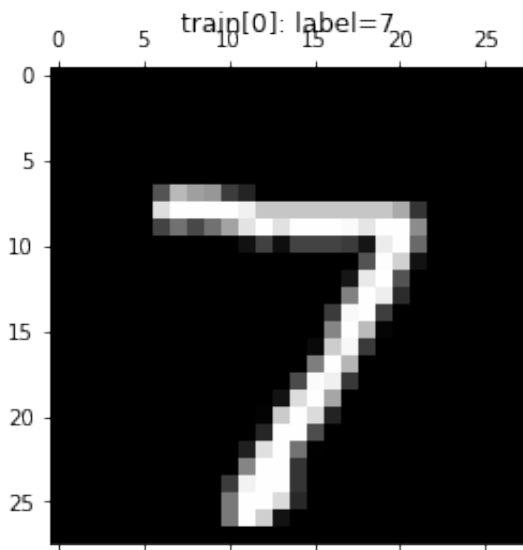
```
In [4]: mnist = read_data_sets('./mnist', one_hot=False)
mnist
```

```
Extracting ./mnist/train-images-idx3-ubyte.gz
Extracting ./mnist/train-labels-idx1-ubyte.gz
Extracting ./mnist/t10k-images-idx3-ubyte.gz
Extracting ./mnist/t10k-labels-idx1-ubyte.gz
```

```
Out[4]: Datasets(train=<tensorflow.contrib.learn.python.learn.datasets.mnist.DataSet object at 0x7fa365222e50>, validation=<tensorflow.contrib.learn.python.learn.datasets.mnist.DataSet object at 0x7fa317389d90>, test=<tensorflow.contrib.learn.python.learn.datasets.mnist.DataSet object at 0x7fa317389910>)
```

## 이미지 하나만 골라서 확인

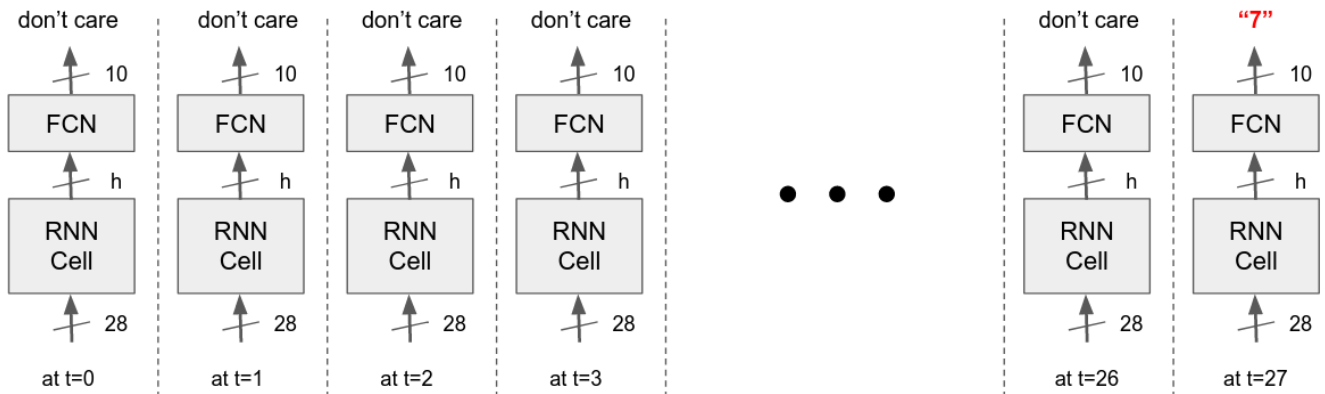
```
In [5]: i = 0
img = mnist.test.images[i,:].reshape([28,28])
lbl = mnist.test.labels[i]
plt.matshow(img,cmap=plt.get_cmap('gray'))
plt.title('train[{:d}]: label={:d}'.format(i,lbl))
plt.show()
```



## RNN 학습 입력으로 사용하기 위해서 입력값의 해석 방식을 달리함

- $28 \times 28 = 784$  개 입력값을
- 28개 입력값의 길이  $s$  ( $s \leq 28$ ) 인 시퀀스로 해석

## 참고: sequence length 제한 이전의 RNN 구조



## 학습 데이터의 규격 설정

```
In [6]: INPUT_UNITS = 28
        NUM_HIDDEN_UNITS = 31

        BATCH_SIZE = 128
        MAX_SEQ_LEN = 19  # <== s <= 28
```

## RNN 모델 구성

```
In [7]: class MnistRnn:
        def __init__(self,
                      inputs,
                      labels,
                      input_units,
                      num_hidden_units,
                      batch_size,
                      max_seq_len):
            ...
            inputs: in shape [batch_size, max_seq_len, input_size]
            labels: in shape [batch_size]
            ...

            # ==>>> MultiRNNCell <<==
            multi_cells = tf.contrib.rnn.MultiRNNCell([
                tf.contrib.rnn.BasicRNNCell(
                    num_hidden_units) \
                    for _ in \
                    range(3) ])

            sequence_length = [max_seq_len] * batch_size
            last, states = tf.nn.dynamic_rnn(
```

```

        multi_cells,
        inputs,
        sequence_length=sequence_length,
        dtype=tf.float32)

# 여기서,
# last.shape: [batch_size, max_seq_len, num_hidden_units]

#####
# MultiRNNCell 을 쓰면 states가 tensor 의 tuple 이 됨.
# states.shape : ([?, num_hidden_units],...)
#####

print('last.shape', last.get_shape().as_list())
print('states', states)

# max_seq_len 축으로 0~27 까지 값 중에
# 0~26 때의 출력 값은 사용하지 않음
rnn_output = last[:,max_seq_len-1,:]
# rnn_output shape: [batch_size, num_hidden_units]
print('rnn_output.shape', rnn_output.get_shape().as_list())

# 10 개의 output units 로 만들
# FCN (fully-connected-network) 구성
# ==> shape: [batch_size, 10]
outputs = tf.layers.dense(rnn_output, 10)
print('outputs.shape', outputs.get_shape().as_list())

# loss 함수
loss = tf.losses.sparse_softmax_cross_entropy(
    labels, outputs)
optimize = tf.train.AdamOptimizer(learning_rate=0.001). \
    minimize(loss)

# accuracy
preds = tf.argmax(outputs, axis=1)
errors = tf.count_nonzero(labels - preds)
accuracy = 1.0 - tf.cast(errors,tf.float32) / \
    tf.cast(tf.size(preds),tf.float32)

# 클래스 객체 외부에서 참고할 수 있도록 속성으로 저장
self.outputs = outputs
self.loss = loss
self.optimize = optimize
self.accuracy = accuracy

```

## 텐서플로우 그래프 초기화, Placeholders 정의, 그래프 빌드

```
In [8]: tf.reset_default_graph()

inputs_ = tf.placeholder(
    tf.float32,
    [BATCH_SIZE, MAX_SEQ_LEN, INPUT_UNITS],
    name='inputs')
labels_ = tf.placeholder(
    tf.int64,
    [BATCH_SIZE],
    name='labels')

model = MnistRnn(inputs_,
                 labels_,
                 INPUT_UNITS,
                 NUM_HIDDEN_UNITS,
                 BATCH_SIZE,
                 MAX_SEQ_LEN)

last.shape [128, 19, 31]
states (<tf.Tensor 'rnn/while/Exit_2:0' shape=(128, 31) dtype=float32>, <tf.Tensor 'rnn/while/Exit_3:0' shape=(128, 31) dtype=float32>, <tf.Tensor 'rnn/while/Exit_4:0' shape=(128, 31) dtype=float32>)
rnn_output.shape [128, 31]
outputs.shape [128, 10]
```

## 학습을 위한 세션 초기화, 변수 초기화

```
In [9]: config = tf.ConfigProto(gpu_options={'allow_growth':True})
sess = tf.InteractiveSession(config=config)

tf.global_variables_initializer().run()
```

## 훈련 진도 기록용 summary writer

```
In [10]: train_writer = tf.summary.FileWriter(
    'logdir/train3',
    graph=tf.get_default_graph())
test_writer = tf.summary.FileWriter(
    'logdir/test3',
    graph=tf.get_default_graph())
```

## 훈련용 데이터 시퀀스 준비

- MAX\_SEQ\_LEN == 28 일때

```

offs          = i * BATCH_SIZE
batch_input = \
    mnist.train.images[offs:offs+BATCH_SIZE,:]
batch_input = \
    batch_input.reshape([BATCH_SIZE,
                          MAX_SEQ_LEN,
                          INPUT_UNITS])

batch_label = \
    mnist.train.labels[offs:offs+BATCH_SIZE]

```

- MAX\_SEQ\_LEN != 28 일때

```

offs          = np.random.randint(
    mnist.train.num_examples // BATCH_SIZE) *
    BATCH_SIZE
batch_input = \
    mnist.train.images[offs:offs+BATCH_SIZE,:]
batch_input = \
    batch_input.reshape([BATCH_SIZE,
                          28, # MAX_SEQ_LEN,
                          INPUT_UNITS])

batch_collection = []
for ii in xrange(BATCH_SIZE):
    seq_start = np.random.randint(28 - MAX_SEQ_LEN + 1)
    batch_collection.append(
        batch_input[
            ii,
            seq_start:seq_start+MAX_SEQ_LEN,
            :])
batch_input = np.array(batch_collection)
batch_label = \
    mnist.train.labels[offs:offs+BATCH_SIZE]

```

## 훈련 루프 카운트 계산

```
In [11]: train_loop_count = mnist.train.num_examples * \
          (28 - MAX_SEQ_LEN + 1) // \
          BATCH_SIZE
test_loop_count = mnist.test.num_examples * \
          (28 - MAX_SEQ_LEN + 1) // \
          BATCH_SIZE

train_loop_count, test_loop_count
```

```
Out[11]: (4296, 781)
```

## 훈련 루프 정의

```
In [12]: def train(
          inputs,
          labels,
          max_epochs,
          train_writer=None,
          test_writer=None):

    step = 0
    for ep in range(max_epochs):

        train_elapsed = []
        train_losses = []
        train_accuracy = []
        for i in range(train_loop_count):
            t_start = time.time()

            offs = np.random.randint(
                mnist.train.num_examples // BATCH_SIZE) * \
                BATCH_SIZE
            batch_input = \
                mnist.train.images[offs:offs+BATCH_SIZE,:]
            batch_input = \
                batch_input.reshape([BATCH_SIZE,
                                     28, # MAX_SEQ_LEN,
                                     INPUT_UNITS])

            batch_collection = []
            for ii in xrange(BATCH_SIZE):
                seq_start = np.random.randint(28 - MAX_SEQ_LEN + 1)
                batch_collection.append(
                    batch_input[
                        ii,
                        seq_start:seq_start+MAX_SEQ_LEN,
                        :])
            batch_input = np.array(batch_collection)
            batch_label = \
                mnist.train.labels[offs:offs+BATCH_SIZE]

            optimize, loss, accuracy, = \
                sess.run([model.optimize,
                          model.loss,
                          model.accuracy],
```

```

        feed_dict = {
            inputs: batch_input,
            labels: batch_label })
train_losses.append(loss)
train_accuracy.append(accuracy)
t_elapsed = time.time() - t_start
train_elapsed.append(t_elapsed)

step += 1

if train_writer:
    summary = tf.Summary(
        value=[
            tf.Summary.Value(
                tag='train_accuracy',
                simple_value=accuracy
            ),
            tf.Summary.Value(
                tag='loss',
                simple_value=loss
            ),
        ]
    )
    train_writer.add_summary(summary, global_step=step)

if step % 500 == 0:
    print(('[trn] ep {:d}, step {:d}, ' +
          'loss {:.f}, accu {:.f}, ' +
          'sec/iter {:.f}').format(
        ep + 1,
        step,
        np.mean(train_losses),
        np.amin(train_accuracy),
        np.mean(train_elapsed)))
    train_losses = []
    train_accuracy = []
    train_elapsed = []

test_elapsed = []
test_accuracy = []
for i in range(test_loop_count):
    t_start = time.time()

    offs = np.random.randint(
        mnist.test.num_examples // BATCH_SIZE) * \
        BATCH_SIZE

    batch_input = \
        mnist.test.images[offs:offs+BATCH_SIZE,:]
    batch_input = \
        batch_input.reshape([BATCH_SIZE,
                              28, # MAX_SEQ_LEN,
                              INPUT_UNITS])

    batch_collection = []
    for ii in xrange(BATCH_SIZE):
        seq_start = np.random.randint(28 - MAX_SEQ_LEN + 1)
        batch_collection.append(

```



```

        batch_input[
            ii,
            seq_start:seq_start+MAX_SEQ_LEN,
            :])
batch_input = np.array(batch_collection)
batch_label = \
    mnist.test.labels[offs:offs+BATCH_SIZE]

accuracy, = \
    sess.run([model.accuracy],
              feed_dict = {
                  inputs: batch_input,
                  labels: batch_label })
test_accuracy.append(accuracy)
t_elapsed = time.time() - t_start
test_elapsed.append(t_elapsed)

step += 1

if test_writer:
    summary = tf.Summary(
        value=[
            tf.Summary.Value(
                tag='test_accuracy',
                simple_value=accuracy
            ),
        ]
    )
    test_writer.add_summary(summary,global_step=step)

if step % 500 == 0:
    print(('[tst] ep {:d}, ' +
          'step {:d}, accu {:f}, ' +
          'sec/iter {:f}').format(
        ep + 1,
        step,
        np.amin(test_accuracy),
        np.mean(test_elapsed)))
    test_accuracy = []
    test_elapsed = []

```

## 훈련 루프 실행

```
In [13]: tf.get_default_graph().finalize()  
train(inputs_, labels_, 2, train_writer, test_writer)
```

```
[trn] ep 1, step 500, loss 1.409534, accu 0.093750, sec/iter 0.009  
095  
[trn] ep 1, step 1000, loss 0.842891, accu 0.554688, sec/iter 0.00  
8731  
[trn] ep 1, step 1500, loss 0.611520, accu 0.656250, sec/iter 0.00  
8772  
[trn] ep 1, step 2000, loss 0.489022, accu 0.695312, sec/iter 0.00  
8870  
[trn] ep 1, step 2500, loss 0.407674, accu 0.757812, sec/iter 0.00  
8725  
[trn] ep 1, step 3000, loss 0.361474, accu 0.781250, sec/iter 0.00  
9582  
[trn] ep 1, step 3500, loss 0.333060, accu 0.765625, sec/iter 0.00  
9126  
[trn] ep 1, step 4000, loss 0.300694, accu 0.789062, sec/iter 0.00  
8858  
[tst] ep 1, step 4500, accu 0.789062, sec/iter 0.003388  
[tst] ep 1, step 5000, accu 0.789062, sec/iter 0.003339  
[trn] ep 2, step 5500, loss 0.279479, accu 0.796875, sec/iter 0.00  
8812  
[trn] ep 2, step 6000, loss 0.262950, accu 0.820312, sec/iter 0.00  
8824  
[trn] ep 2, step 6500, loss 0.257611, accu 0.828125, sec/iter 0.00  
9544  
[trn] ep 2, step 7000, loss 0.249612, accu 0.828125, sec/iter 0.00  
9519  
[trn] ep 2, step 7500, loss 0.239785, accu 0.828125, sec/iter 0.00  
8875  
[trn] ep 2, step 8000, loss 0.220055, accu 0.851562, sec/iter 0.00  
8829  
[trn] ep 2, step 8500, loss 0.219775, accu 0.820312, sec/iter 0.00  
8912  
[trn] ep 2, step 9000, loss 0.207872, accu 0.828125, sec/iter 0.00  
8850  
[tst] ep 2, step 9500, accu 0.859375, sec/iter 0.003214  
[tst] ep 2, step 10000, accu 0.843750, sec/iter 0.003307
```

## 훈련 진행 점검 - 텐서보드

```
In [14]: # !tensorboard --ip 0.0.0.0 --logdir logdir
```