

FCL (I)

• Fuzzy Control Lenguaje
• INTERNATIONAL ELECTROTECHNICAL COMMISSION (IEC) TECHNICAL COMMITTEE No. 65: INDUSTRIAL PROCESS MEASUREMENT AND CONTROL SUB-COMMITTEE 65 B: DEVICES
• IEC 1131 - PROGRAMMABLE CONTROLLERS
• Part 7 - Fuzzy Control Programming
• Committee Draft CD 1.0 (Rel. 19 Jan 97)
• http://jfuzzylogic.sourceforge.net/doc/iec_1131_7_cd1.pdf

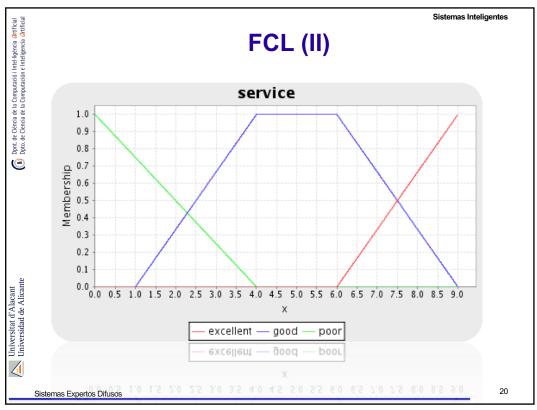
```
Sistemas Inteligentes
Dpnt. de Ciència de la Computació i Intel·ligència atificial Dpto. de Ciencia de la Computación e Intel·ligencia atificial
                                                                        FCL (II)
                     / Block definition (there may be more than one block per file,
                    FUNCTION_BLOCK tipper
                    // Define input variables
                    VAR INPUT
                           service : REAL;
                           food : REAL;
                   END_VAR
٥
                    // Define output variable
                   VAR_OUTPUT
                          tip : REAL;
                   END_VAR
                   // Fuzzify input variable 'service'
FUZZIFY service
                          ZIFY service
TERM poor := (0, 1) (4, 0);
TERM good := (1, 0) (4,1) (6,1) (9,0);
TERM excellent := (6, 0) (9, 1);
                     ND FUZZIFY
                    TERM poor := (0, 1) (4, 0);

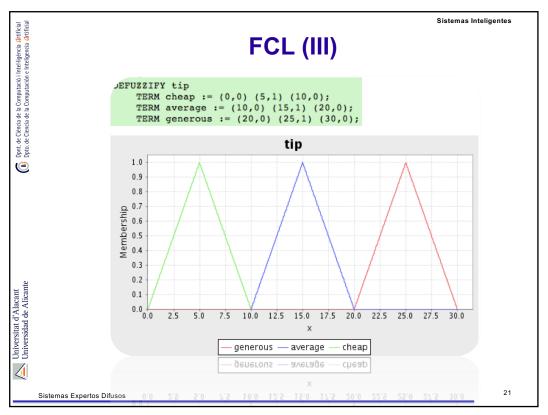
TERM good := (1, 0) (4,1) (6,1) (9,0);

TERM excellent := (6, 0) (9, 1);

VND FUZZIFY

AD_LOSZIFY
4
                                                                                                                                                     19
       Sistemas Expertos Difusos
```





```
Sistemas Inteligentes
Dpnt, de Ciència de la Computació i Intel·ligència artificial Dpto, de Ciencia de la Computación e Inteligencia artificial
                                                       FCL (IV)
                            Defzzzify output variable 'tip'
                         DEFUZZIFY tip
                              TERM cheap := (0,0) (5,1) (10,0);
                              TERM average := (10,0) (15,1) (20,0);
TERM generous := (20,0) (25,1) (30,0);
                              // Use 'Center Of Gravity' defuzzification method
                              METHOD : COG;
                              // Default value is 0 (if no rule activates defuzzifier)
                         DEFAULT := 0;
END_DEFUZZIFY
(2)
                         RULEBLOCK No1
                              // Use 'min' for 'and' (also implicit use 'max' // for 'or' to fulfill DeMorgan's Law)
                              AND : MIN;
                              // Use 'min' activation method
                              ACT : MIN;
                               // Use 'max' accumulation method
                              ACCU : MAX;
Universitat d'Alacant
Universidad de Alicante
                              RULE 1 : IF service IS poor OR food IS rancid
                                               THEN tip IS cheap;
                              RULE 2 : IF service IS good
                                               THEN tip IS average;
                              RULE 3 : IF service IS excellent AND food IS delicious
4
                                               THEN tip is generous;
                          ND_RULEBLOCK
                                                                                                                    22
      Sistemas Expertos Difusos
```

