



MT793X IoT SDK for Flash Burning Tool

Version: 2.84
Release date: 2022-10-5

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Version History

Version	Date	Author	Description
2.77	2021-08-05	CY Chan	Create an external version
2.78	2021-12-28	CY Chan	Add customer eFuse read/write form. Add new flash ID. Modify new GUI and add supported Linux GUI
2.8	2022-1-12	CY Chan	Add customer eFuse read/write txt from. Modify pinmux pull up for new flash ID.
2.81	2022-2-9	CY Chan	Fixed get meid cmd. Change customer efuse table as mt7686 style.
2.82	2022-7-4	CY Chan	Fixed console mode path assign can't with "-". Add DA xip mode of Arduino. Console mode :add abs_path call fbtool Add buad rate 115200 for debug. Add show flash ID and size GUI mode add TLV parser Add query DA cmd for auto detect DA/BROM mode Fixed GUI readback struck error by textbox with yview. No support Mircro flash.
2.83	2022-8-31	CY Chan	Support GD25Q128E flash. GUI:add some teraterm functions and send CLI macro. Update libefuse.a for EDCSA -p256/384/521 Cmd_tab.txt:support customer command and it with any input arguments. Improve uart_start_cmd on data handshacking Support readback command with read small size for MP. Allow cmds_tab. txt within empty line. Implement flash auto unlock for winbond flash Support most common buad rate
2.84	2022-10-5	CY Chan	Fixed file naming with "." before endswitch .bin/.sgn Add log message when winbond flash be locked. Fixed end of cmd run console with error "armor" log Add section1.7: option of non-20.04 Ubuntu versions Unified executable file name from fbtool_v2p8x.exe to fbtool.exe and added -v and --version to check tool version

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1 Introduction

1.1 Purpose

The Flash Burning Tool is an application that mainly updates the flash. The tool works on MediaTek MT793X IoT platforms. The Flash Burning Tool supports both UART and USB interfaces.

The Flash Burning Tool communicates with BROM, and BROM loads DA (download agent) code into SRAM, and then jumps into DA code for execution. DA is mainly responsible for downloading all image bin files to each partition zone. In addition, erase, read back, eFuse read/write functions are added to this application. Table 1 lists the items supported by the Flash Burning Tool .

The Flash Burning Tool can be used on Microsoft Windows 7 (64-bit) and Windows 10 (64-bit) PC that support USB interface communication.

MediaTek MT793X HDK has a USB connector for the Flash Burning Tool to operate through the USB interface. The HDK also provides a USB to UART connector for the Flash Burning Tool to operate through the UART.

Before using the Flash Burning Tool, install the corresponding driver. Refer to Sections 2.1 and 2.2.

Acronyms used throughout the document are defined in the following table.

Acronym	Definition
BROM	Boot ROM
DA	Download Agent
GUI	Graphical User Interface
UART	Universal Asynchronous Receiver/Transmitter
USB	Universal Serial Bus
IoT	Internet of Things
DL	Download
FBTool	FlashBurningTool

1.2 Flash Burning Tool Feature List

Table 1: Flash Burning Tool feature list

Supported items			
	Item	Feature	Output file
	OS:		
V	Windows 64-bit (GUI mode)	FBTool_gui.exe, security by pyarmor tool	debug_log.txt
V	Windows 64-bit (Console mode)	fbtool.exe, security by pyarmor tool Whether to use an input argument is optional: fbtool.exe -e myefuse_tbl.txt -f my_scatterfile.ini -o order_command -s control_data -p uart_port	debug_log.txt DL_fa_log_app end.txt Process.ini
V	Linux 64-bit (GUI mode)	Ubuntu 20.04 or py37 FBTool_gui, run_FBTool_gui.py, security by pyarmor tool	debug_log.txt
V	Linux 64-bit (Console mode)	Ubuntu 20.04 or py37 fbtool, run_fbtool_console.py, security by pyarmor tool Whether to use an input argument is optional: ./fbtool -e myefuse_tbl.txt -f my_scatterfile.ini -o order_command -s control_data -p uart_port	debug_log.txt DL_fa_log_app end.txt Process.ini
	Connect Path:		
V	UART	CM33 UART port, baud rate: 921600. (reference test: 1.8M bin file, burning time ~= 42sec)	
V	USB	USB2.0 (reference test: 1.8M bin file, burning time ~= 22sec)	
	Command:		
V	Format	Quick erase of 64/32/4K alignment	
V	Download	Check sum, 32K buffering Support erasing before download or only download	
V	Read Back	Check sum + File compare UART: 32K buffering, USB: 32K buffering Support read full size or small size: 4k form header	"file name"+_readb ack.bin
V	Read eFuse	1) Input by control data to read eFuse, CR, and flash data. Support reads of GRP1/2/3, bin data sizes of which are 0x200, 0x200, 0x400 Support logical and physical reads of GRP2/3. 2) Support reads of GRP1 in customer mode.	working folder: 1) eFuse.bin 2.1) Customer_ef_t bl.txt 2.2) user define
V	Write eFuse	1) Input by control data to write eFuse, CR, and flash. eFuse only supports GRP1. 2) Support writes of GRP1 in customer mode.	Same as above.
	HW PCB:		
V	MT793X_DRQFN_EVB	UART: MT8127 debug board or FTDI debug board	
V	MT793X_BGA_EVB	UART: MT8127 debug board or FTDI debug board / USB download	
V	MT793X_QFN_RFB	UART: FTDI debug board	
V	MT793X_BGA_RFB	UART: FTDI debug board /USB download	

1.3 Flash Burning Tool supported Nor Flash list

Table2 show supported lists of nor flash.

Table 2: Support nor flash list

```
nor_flash_tbl[] = {  
  // ID0    ID1    ID2    Size    Erase size  Vendor name  
  {0xEF, 0x60, 0x18, 0x1000000, 0x10000, 1, "WINBOND(W25Q128JWPIQ)"},  
  {0xEF, 0x60, 0x19, 0x2000000, 0x10000, 1, "WINBOND(W25Q256JWPIQ)"},  
  {0xEF, 0x40, 0x17, 0x8000000, 0x10000, 1, "WINBOND(W25Q64JVIQ)"},  
  {0xC2, 0x25, 0x36, 0x4000000, 0x10000, 1, "MX25U32"},  
  {0xEF, 0x80, 0x16, 0x4000000, 0x10000, 1, "WINBOND(W25Q32JW)"},  
  {0xC2, 0x25, 0x37, 0x8000000, 0x10000, 1, "MXIC(25U64)"},  
  {0xC2, 0x20, 0x17, 0x8000000, 0x10000, 1, "MXIC(25L64)"},  
  {0xEF, 0x80, 0x17, 0x8000000, 0x10000, 1, "WINBOND(W25Q64JW)"},  
  {0xEF, 0x60, 0x17, 0x8000000, 0x10000, 1, "WINBOND(W25Q64FW)"},  
  {0xC2, 0x25, 0x38, 0x1000000, 0x10000, 1, "MXIC(25U128)"},  
  {0xC2, 0x20, 0x18, 0x1000000, 0x10000, 1, "MXIC(25L128)"},  
  {0xEF, 0x40, 0x18, 0x1000000, 0x10000, 1, "WINBOND(W25Q128FV)"},  
  {0x20, 0x40, 0x18, 0x1000000, 0x10000, 1, "XMC(XM25QH128C)"},  
  {0xC2, 0x25, 0x39, 0x2000000, 0x10000, 1, "MXIC(25U256)"},  
  {0xC2, 0x20, 0x19, 0x2000000, 0x10000, 1, "MXIC(25L256)"},  
  {0xEF, 0x80, 0x19, 0x2000000, 0x10000, 1, "WINBOND(W25Q256JW)"},  
  {0xEF, 0x70, 0x17, 0x8000000, 0x10000, 1, "W25Q64JVM"},  
  {0xEF, 0x40, 0x17, 0x8000000, 0x10000, 1, "W25Q64JVIQ"},  
  {0xC2, 0x20, 0x17, 0x8000000, 0x10000, 1, "MXIC(MX25L64356)"},  
  {0xEF, 0x70, 0x18, 0x1000000, 0x10000, 1, "WINBOND(W25Q128JVPIM)"},  
  {0xC8, 0x40, 0x18, 0x1000000, 0x10000, 1, "GD(GD25Q128E)"},  
  {0x00, 0x00, 0x00, 0x0000000, 0x00000, 1, "NULL Device"},  
};
```


1.4 Environment and Supported Versions

The IoT FlashBurningTool with GUI interface and command line can operate on Windows and Linux Ubuntu 20.04 both; the tool can be used on Microsoft Windows Win 7/10 (64-bit) and Linux (64-bit).

MediaTek MT793X IoT HDK has a USB connector for the Flash Burning Tool to operate through the USB interface. The HDK also provides a USB to UART connector for the Flash Burning Tool to operate through the UART. Before using the Flash Burning Tool, install the corresponding driver. Refer to Sections 2.1 and 2.2. Unzip the FlashBurningTool package. The folder name shows the supported Windows or Linux version.

(D:) > FlashBurningTool_V2.8 >

名稱	修改日期
doc	2022/1/12 下午 08:56
FBTool_v2p8_linux64_ubuntu_20.04_GUI	2022/1/12 下午 08:52
fbtool_v2p8_linux64_ubuntu20.04_Console	2022/1/12 下午 08:49
fbtool_v2p8_win64_Console	2022/1/12 下午 08:40
FBTool_v2p8_win64_GUI	2022/1/12 下午 08:38
MTK_USB_driver	2022/1/12 下午 02:52
V2p8_linux64_py37	2022/1/12 下午 02:52

Figure 1: OS versions supported by Flash Burning Tool

1.5 Installing the Flash Burning Tool on Windows

The tool supports both GUI and console modes as shown in Figure 1. To install the Flash Burning Tool, simply unzip the tool package to a folder on your Windows computer. No further steps are required.

1.6 Installing the Flash Burning Tool on Linux

The tool supports both GUI and console modes on Ubuntu 20.04 as Figure 1 shows. You can also choose to install Python 3.7 to use the tool package of V2p8_linux64_py37 for different Ubuntu versions.

Reference commands for installing Python 3.7:

```
sudo apt install python3.7
sudo apt-get install python3.7-dev
sudo apt-get install python3-pip
```

install modules:

```
sudo python3.7 -m pip install xxx --trusted-host pypi.python.org --trusted-host files.pythonhosted.org --trusted-host pypi.org
```

(xxx: modules name, which can be imported to the header on python script. e.g. pyserial, configparser, optparse-pretty ...)

install tkinter module on python3.7 : `sudo apt-get install python3.7-tk`

Check version: `python3 --version`

Add list table to version: `sudo update-alternatives --install /usr/bin/python3 python3 /usr/bin/python3.7 x (x=digital number).`

Choose version: `sudo update-alternatives --config python3`

1.7 Option of install tools on non-20.04 Ubuntu version

Another method for use tools on non-20.04 Ubuntu version that can base on Ubuntu 20.04 released package and overwrite related libraries (*.so files), we giving an example of use Ubuntu 18.04 OS and showing how to base on released package of Ubuntu 20.04_console to the different Ubuntu distribution.

Step1:

Install python3.7 and related modules on Ubuntu 18.04, Please reference section1.6

Step2:

Copy the installed Python3.7 libraries to the tool's directory with the following commands:

```
cp /usr/lib/x86_64-linux-gnu/libpython3.7m.so.1.0 fbtool_v2p8_linux64_ubuntu20.04_Console
cp /usr/lib/x86_64-linux-gnu/libpng16.so.16 fbtool_v2p8_linux64_ubuntu20.04_Console
cp /usr/lib/x86_64-linux-gnu/libtcl8.6.so fbtool_v2p8_linux64_ubuntu20.04_Console
cp /usr/lib/x86_64-linux-gnu/libtk8.6.so fbtool_v2p8_linux64_ubuntu20.04_Console
cp /usr/lib/x86_64-linux-gnu/libtk8.6.so.0 fbtool_v2p8_linux64_ubuntu20.04_Console
```

Step3:

Renaming folder :

"fbtool_v2p8_linux64_ubuntu20.04_Console" to "fbtool_v2p8_linux64_ubuntu18.04_Console"

2 MT793X HDK Application Note

2.1 UART Download Path: FDTI Debug Board Driver Installation

2.1.1 Install Windows UART Driver

You can install the FTDI driver from this reference link:

<https://www.ftdichip.com/Drivers/VCP.htm>

The FlashBurningTool uses the CM33_UART COM port to communicate.

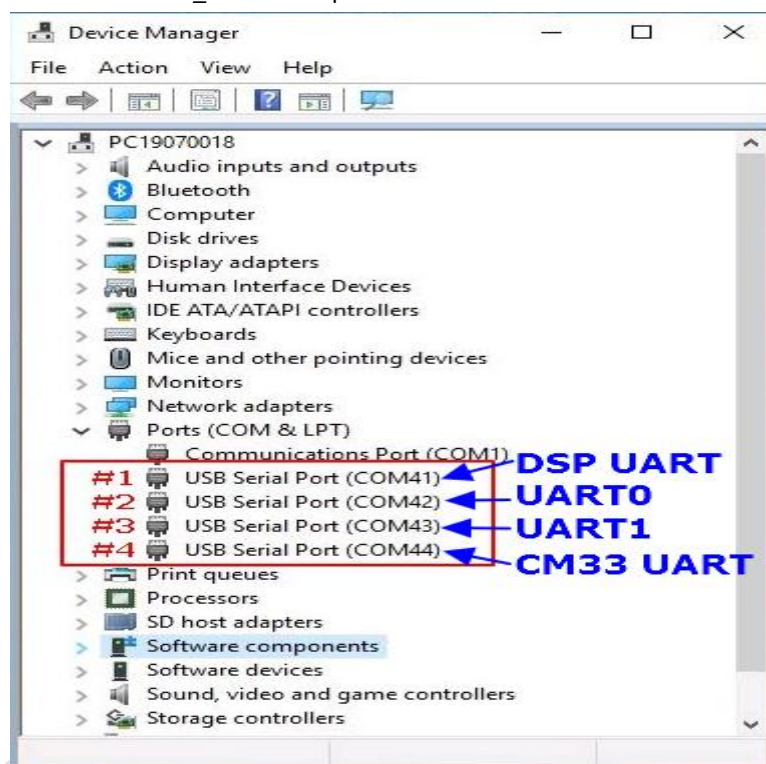


Figure 2: Select CM33 UART port on FTDI debug board

2.1.2 Install Linux UART Driver

(1) Set up Linux environment:

Copy mtk-usb.rules to /etc/udev/rules.d/; mtk-usb.rules is located in the folder under the Linux tool folder of this tool. Assign "mediatek" after tty:x:5 and dialout:x:20

Linux command:

```
$cp -f mtk-usb.rules /etc/udev/rules.d/mtk-usb.rules
```

```
$sudo nano /etc/group
```

```

mediatek@PC17010003-1: ~/Desktop/datool/pyarmor_testV273/dist/fbtool_v2p73 144x45
GNU nano 2.2.6                                File: /etc/group

root:x:0:
daemon:x:1:
bin:x:2:
sys:x:3:
adm:x:4:syslog,mediatek
tty:x:5:mediatek
disk:x:6:
lp:x:7:
mail:x:8:
news:x:9:
libreOffice Calc
proxy:x:13:
kmem:x:15:
dialout:x:20:mediatek
fax:x:21:
voice:x:22:
cdrom:x:24:mediatek
floppy:x:25:
tape:x:26:
sudo:x:27:mediatek
audio:x:29:pulse
dip:x:30:mediatek
www-data:x:33:
backup:x:34:
operator:x:37:
list:x:38:

```

Figure 3: Set up Linux environment

Reboot the computer to enable the **Udev** rules

(2) Normally you do not need to install FTDI or PL2303 driver for Linux. You can check by plugging in the USB to UART cable, and then enter “ls /dev”; the information similar to the following appears, and you can find ttyUSB0 is added to PL2303 debug board. Or, you can use FTDI, and ttyUSB0 to ttyUSB3 are displayed.

```

mediatek@PC17010003-1:~/Desktop/datool/pyarmor_testV273/dist/fbtool_v2p73$ ls /dev
autofs      hidraw0    loop2      ppp         ram7        snapshot    tty19       tty35       tty51       ttyS0       ttyS25
block       hidraw1    loop3      psaux       ram8        snd         tty20       tty36       tty52       ttyS1       ttyS26
bsg         hidraw2    loop4      ptmx        ram9        stderr      tty21       tty37       tty53       ttyS10      ttyS27
btrfs-control hpet       loop5      ptp0        random      stdin       tty22       tty38       tty54       ttyS11      ttyS28
bus         hwrng      loop6      pts         rfkill      stdout      tty23       tty39       tty55       ttyS12      ttyS29
char        i2c-0      loop7      ram0        rtc         tpm0        tty24       tty40       tty56       ttyS13      ttyS30
console     i2c-1      loop-control ram1         rtc0        tty         tty25       tty41       tty57       ttyS14      ttyS31
core        i2c-2      mapper     ram10       sda         tty0        tty26       tty42       tty58       ttyS15      ttyS32
cpu         i2c-3      mcelog     ram11       sda1        tty1        tty27       tty43       tty59       ttyS16      ttyS33
cpu_dma_latency i2c-4      mei0       ram12       sda2        tty10       tty28       tty44       tty60       ttyS17      ttyS34
cuse        i2c-5      mem        ram13       sda3        tty11       tty29       tty45       tty61       ttyS18      ttyS35
disk        input      memory_bandwidth ram14       sda4        tty12       tty30       tty46       tty62       ttyS19      ttyS36
dri         kmsg       mt_test_drv_sdio ram15       sda5        tty13       tty31       tty47       tty63       ttyS20      ttyS37
ecryptfs    kvm        net        ram2        sda6        tty14       tty32       tty48       tty64       ttyS21      ttyS38
fb0         lightning network_latency ram3         sda7        tty15       tty33       tty49       tty65       ttyS22      ttyS39
fd          log        network_throughput ram4        sda8        tty16       tty34       tty50       tty66       ttyS23      ttyS40
full        loop0      null       ram5        sg0         tty17       tty35       tty51       tty67       ttyS24      ttyS41
fuse        loop1      port       ram6        shm         tty18       tty36       tty52       tty68       ttyS25      ttyS42

```

Figure 4: UART port of debug board. (Linux)

(3) If you cannot find ttyUSB*, it means the driver installation is not successful. You can find the path of the file: “pl2303.ko” on PC and copy the file to /lib/modules/\$(uname -r)/kernel/drivers/

Linux command:

\$find / -type f -name pl2303.ko

\$cp path/of/pl2303.ko /lib/modules/\$(uname -r)/kernel/drivers/

\$sudo depmod

Then, reboot the PC.

2.2 Install USB Download Path Driver

2.2.1 Write eFuse to Enable USB DL Function

For USB DL function, if the chip is MT793X E1, you must be careful with two things:

(1) Rework the BGA_RFB PCB for USB DL mode. You can refer to Section 2.3.2.

(2) Write the eFuse using FlashBurningTool UART DL mode:

You need to write the eFuse to enable USB DL. You can use FlashBurningTool version 2.7 (or newer versions).

- (a) Copy the attached bin file doc\GRP1_usb_en.bin to the working folder.
- (b) Assign file_name GRP1_usb_en.bin in the scatter.ini in "EFUSE" partition.
- (c) Assign control_data = 0x01ff0000, and run the "Write Efuse" command.

2.2.2 Install Windows USB Driver

When you unzip this tool, you can see the folders mtk_usb_driver_win7 and mtk_usb_driver_win10.

Choose your PC's Windows version and install the tool. When the installation process finishes, you can open Device Manager and expand "Ports(COM&LPT)". A virtual COM port: "Mediatek USB Port(COMx)" should appear on your PC when your PCB is in USB DL mode.

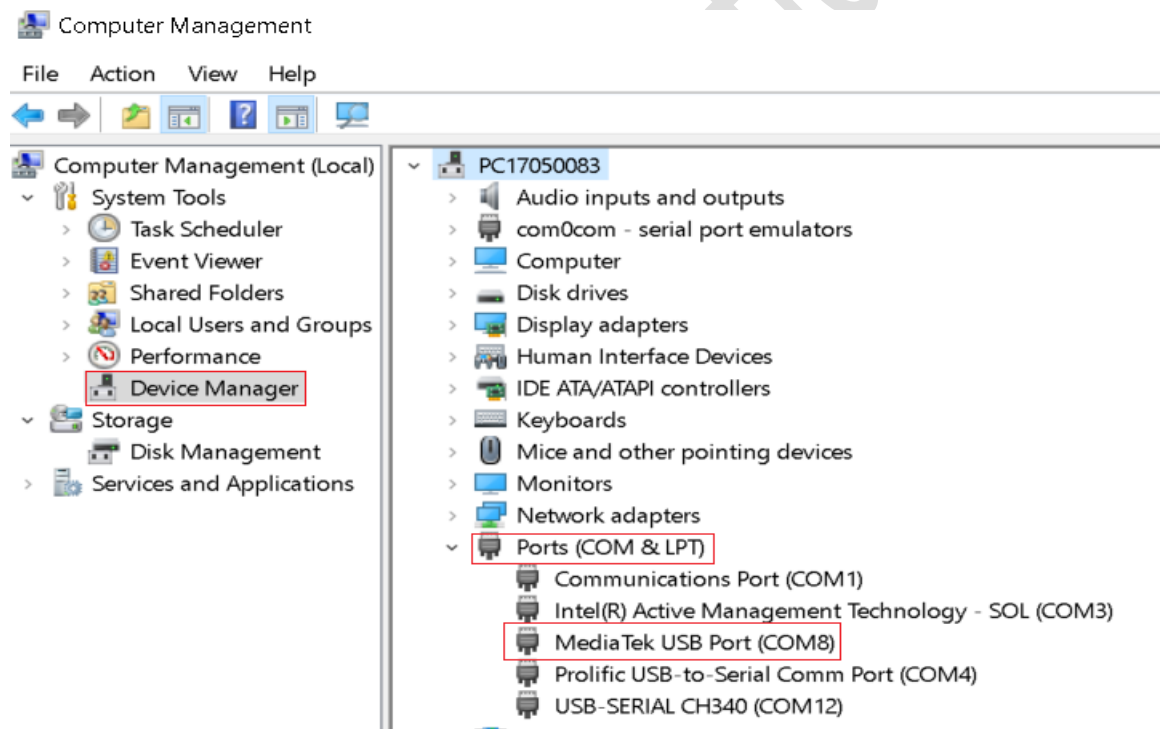


Figure 5: Install Windows USB driver via virtual COM port

2.2.3 Install Linux USB Driver

Normally you do not need to install a USB driver for Linux. To check whether you need to install a driver, plug in the USB cable of BGA-EVB after the platform powers on, or plug in the USB cable and then plug in the USB power cable of BGA-RFB. Then, enter the “lsusb” or “ls /dev” command, and “Mediatek Inc.” or “dev/ttyACM0” should appear.

```
mediatek@PC17010003-1:~/Desktop/datoool/pyarmor_testV273/dist/fbtool_v2p73$ lsusb
Bus 002 Device 001: ID 1d6b:0003 Linux Foundation 3.0 root hub
Bus 001 Device 003: ID 0461:4de2 Primax Electronics, Ltd
Bus 001 Device 002: ID 05af:0802 Jing-Mold Enterprise Co., Ltd
Bus 001 Device 009: ID 0e8d:0003 MediaTek Inc. MT6227 phone
Bus 001 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub
mediatek@PC17010003-1:~/Desktop/datoool/pyarmor_testV273/dist/fbtool_v2p73$ ls /dev
autofs          fb0             i2c-5           loop-control    ptmx            ram5            sda6            tty1            tty22          tty35          tty48          tty60
block           fd             input          mapper          ptp0            ram6            sda7            tty10          tty23          tty36          tty49          tty61
bsg             full          kmsg           mcelog          pts             ram7            sda8            tty11          tty24          tty37          tty5           tty62
btrfs-control   fuse          kvm            mei0            ram0            ram8            serial          tty12          tty25          tty38          tty50          tty63
bus             hidraw0        lightnvm        mem             ram1            ram9            sg0             tty13          tty26          tty39          tty51          tty7
char            hidraw1        log            memory_bandwidth ram10           random          shm             tty14          tty27          tty4           tty52          tty8
console         hidraw2        loop0          mt_test_drv_sdio ram11           rfkill          snapshot        tty15          tty28          tty40          tty53          tty9
core            hpet          loop1          net             ram12           rtc             snd             tty16          tty29          tty41          tty54          ttyACM0
cpu             hwrng         loop2          network_latency ram13           rtc0            stderr          tty17          tty3           tty42          tty55          ttyprintk
cpu_dma_latency i2c-0          loop3          network_throughput ram14           sda             stdin           tty18          tty30          tty43          tty56          ttyS0
cuse            i2c-1          loop4          null            ram15           sda1            stdout          tty19          tty31          tty44          tty57          ttyS1
disk            i2c-2          loop5          port            ram2            sda2            tpm0           tty2           tty32          tty45          tty58          ttyS10
dri             i2c-3          loop6          ppp             ram3            sda3            tty            tty20          tty33          tty46          tty59          ttyS11
ecryptfs        i2c-4          loop7          psaux           ram4            sda5            tty0           tty21          tty34          tty47          tty6           ttyS12
```

Figure 6: Linux USB driver DL via virtual COM port

2.3 MT793X_QFN_RFB / MT793X_BGA_RFB Download Operation

2.3.1 MT793X_QFN_RFB UART Download Mode

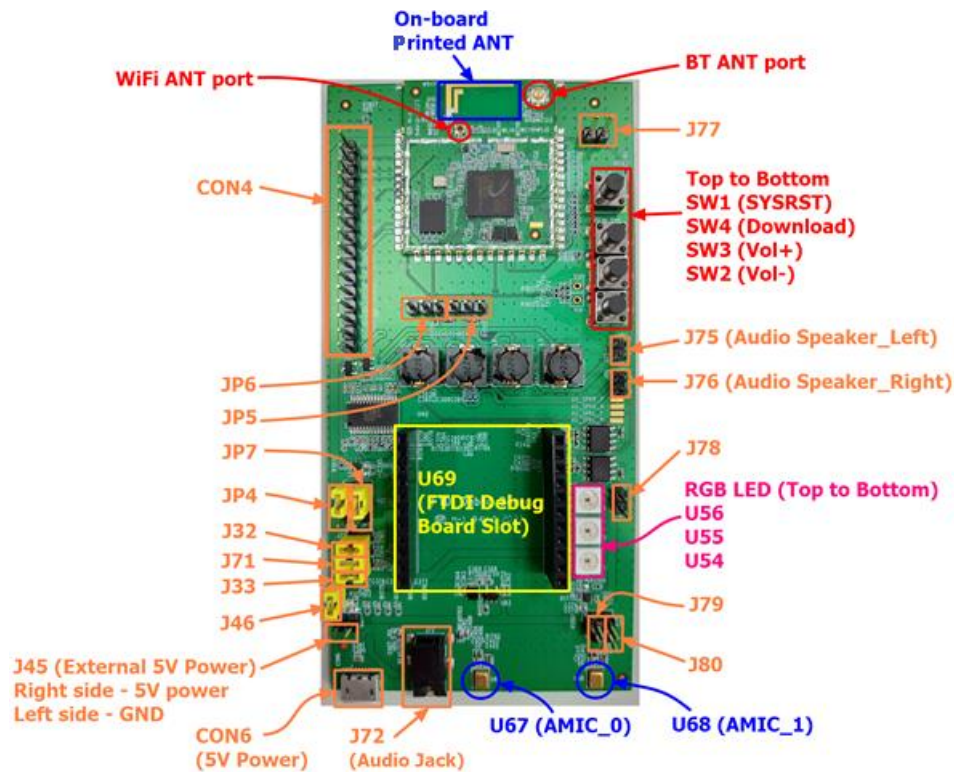


Figure 7: MT793X QFN_RFB debug board UART DL operation

For download key and SYSRST key usage, please also refer to Section 5.3.

- 1) **Keep pressing “SW1 and SW4” and release “SW4” only** and then wait for FlashBurningTool’s feedback.
- 2) If the FlashBurningTool does not feedback (the progress bar does not turn yellow) after about 2 to 3 seconds, repeat Step 1.
- 3) If the progress bar becomes yellow, it means the PC and platform handshaking is successful. You can release both SW1 and SW4 keys. Then, the progress bar turns green to indicate the progress.

MT793X_BGA_RFB_V20 has USB and UART download paths. If you select USB download mode, the UART path is disabled.

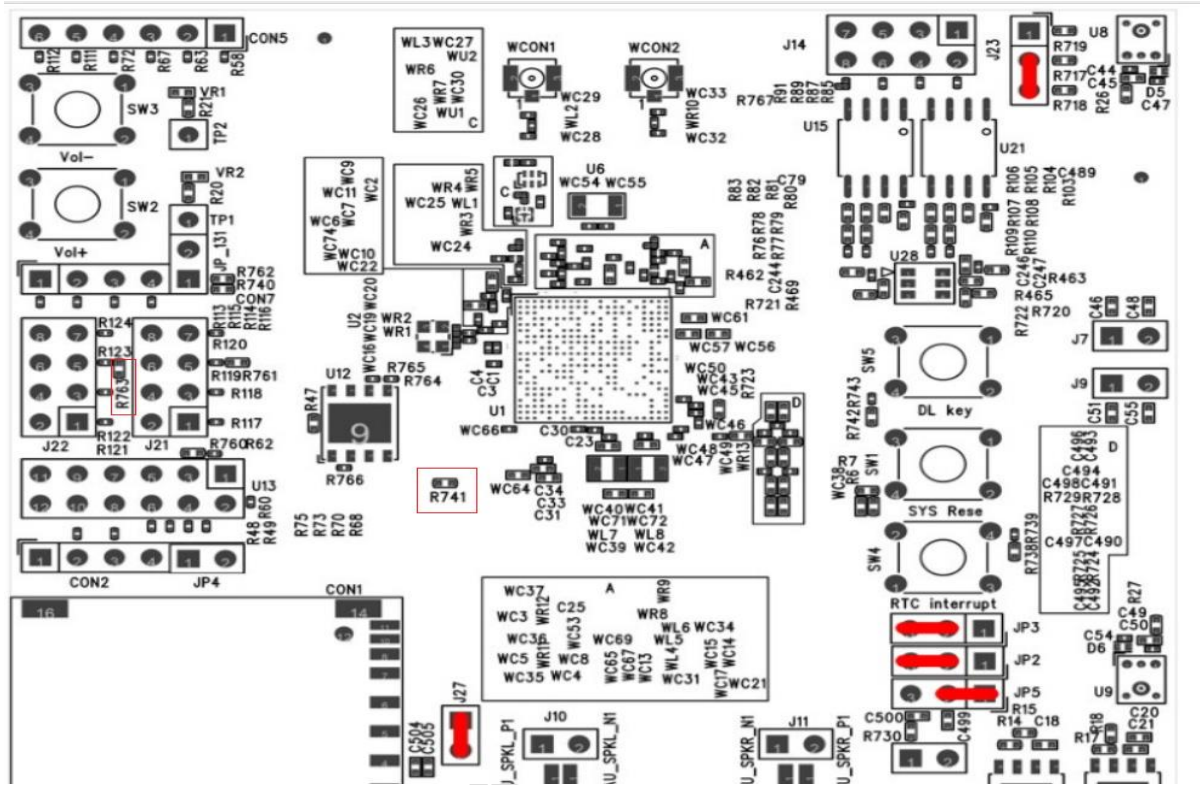


Figure 8: MT793X_BGA_RFB, UART/USB DL mode selection

- (1) UART DL mode: Remove R763, and R741 = 10K.(default)
- (2) USB DL mode: Remove R741, and R763 = 10K

For details of USB DL mode and normal mode, please refer to Section 2.2.3.

2.3.3 MT793X_BGA_RFB UART Download Mode

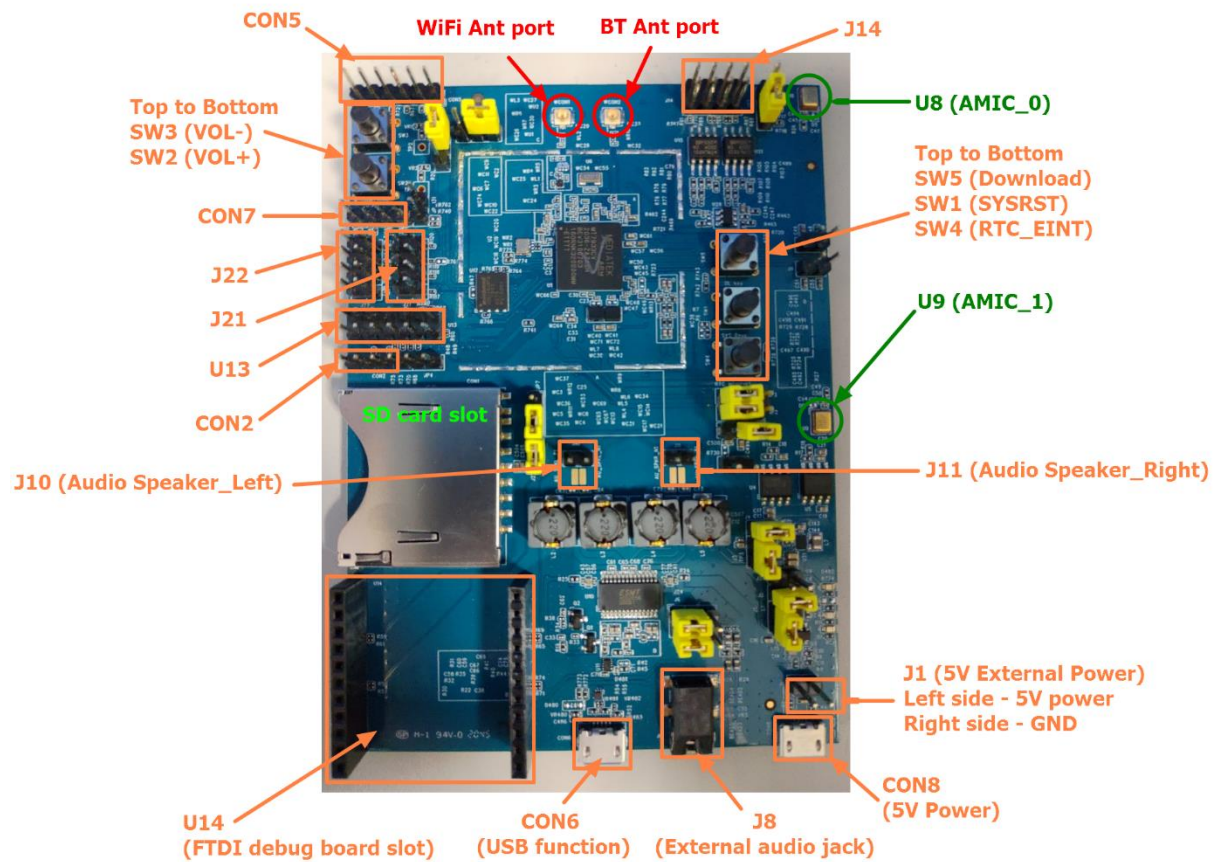
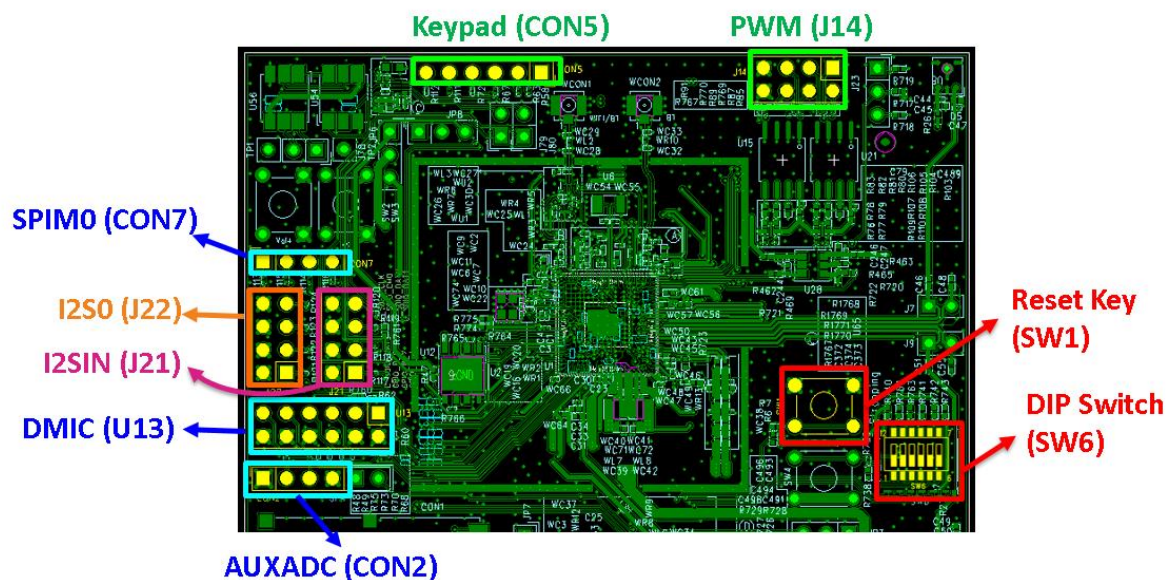


Figure 9: MT793X BGA_RFB Debug board (V20) UART DL operation



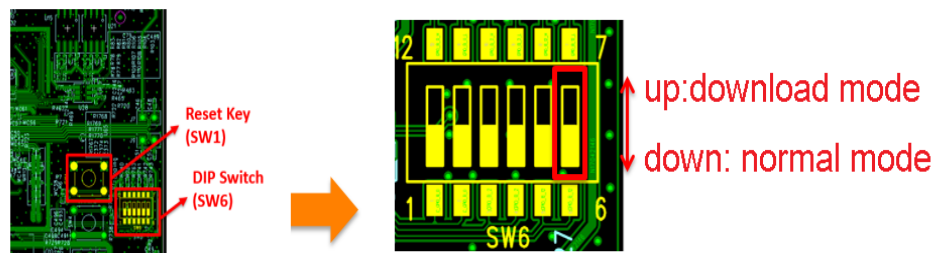


Figure 10: MT793X BGA_RFB Debug board (V21/V22) UART DL operation

2.3.4 MT793X_BGA_RFB USB Download Mode

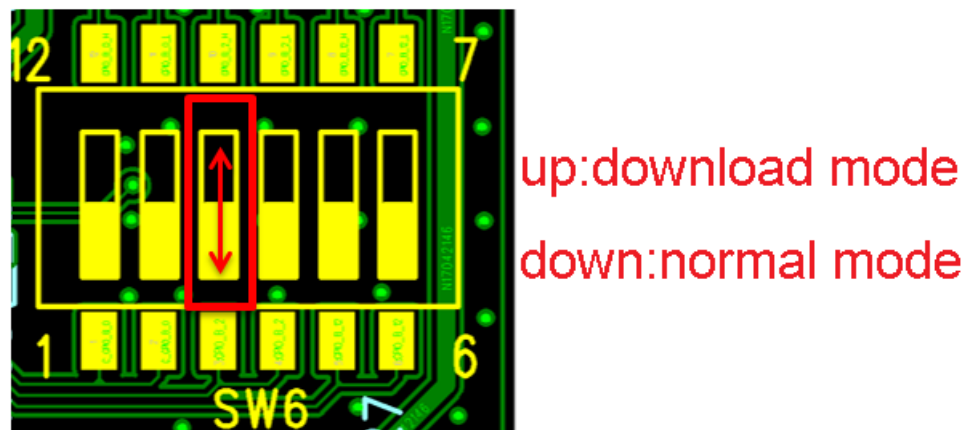


Figure 11: MT793X BGA_RFB Debug board (V21/V22) USB DL operation

MT793X_BGA_RFB_V20: You must power off the platform by unplugging the USB power cable first, and then run the FlashBurningTool command. After you see the log of wait for PC/DA handshaking, you can plug in the USB power cable to power on the platform to finish the command.

Please refer to Chapter 5 for details.

MT793X_BGA_RFB_V21/V22: You must power on the platform in normal mode. Then, change DIP to download mode, and then run the FlashBurningTool command. After you see the log of wait for PC/DA handshaking, you can press the reset key to finish the command.

3 Software Folder Structure and File Description

(D:) > FlashBurningTool_V2.8 > fbtool_v2p8_win64_Console >

名稱	修改日期	類型	大小
burn_files	2022/1/12 下午 0...	檔案資料夾	
Include	2022/1/12 下午 0...	檔案資料夾	
lib2to3	2022/1/12 下午 0...	檔案資料夾	
mtk_files	2022/1/12 下午 0...	檔案資料夾	
tcl	2022/1/12 下午 0...	檔案資料夾	
tk	2022/1/12 下午 0...	檔案資料夾	
_asyncio.pyd	2022/1/12 下午 0...	Python Extension ...	63 KB
_bz2.pyd	2022/1/12 下午 0...	Python Extension ...	85 KB
_ctypes.pyd	2022/1/12 下午 0...	Python Extension ...	124 KB
_decimal.pyd	2022/1/12 下午 0...	Python Extension ...	263 KB
_elementtree.pyd	2022/1/12 下午 0...	Python Extension ...	174 KB
_hashlib.pyd	2022/1/12 下午 0...	Python Extension ...	46 KB
_lzma.pyd	2022/1/12 下午 0...	Python Extension ...	248 KB
_multiprocessing.pyd	2022/1/12 下午 0...	Python Extension ...	29 KB
_overlapped.pyd	2022/1/12 下午 0...	Python Extension ...	45 KB
_pytransform.dll	2022/1/12 下午 0...	應用程式擴充	1,132 KB
_queue.pyd	2022/1/12 下午 0...	Python Extension ...	28 KB
_socket.pyd	2022/1/12 下午 0...	Python Extension ...	78 KB
_ssl.pyd	2022/1/12 下午 0...	Python Extension ...	151 KB
_testcapi.pyd	2022/1/12 下午 0...	Python Extension ...	111 KB
_tkinter.pyd	2022/1/12 下午 0...	Python Extension ...	63 KB
base_library.zip	2022/1/12 下午 0...	WinRAR ZIP archi...	769 KB
cmds_tbl.txt	2022/1/13 上午 0...	文字文件	1 KB
config.ini	2022/1/12 下午 0...	組態設定	2 KB
debug_log.txt	2022/1/12 下午 0...	文字文件	60 KB
debug_log_append.txt	2021/7/30 上午 1...	文字文件	22 KB
fbtool_v2p8.exe	2022/1/12 下午 0...	應用程式	2,399 KB

Figure 12: Software folder structure and file description

3.1 executable files

The root directory contains: executable files:

FBTool_gui.exe (run in win64-GUI mode)

fbtool.exe (run in win64-console mode)

FBTool_gui (run in Linux64-GUI mode)

fbtool (run in Linux64-console mode)

run_FBTool_gui.py (run in Linux64-python37-GUI mode)

run_fbtool_console.py (run in Linux64--python37-console mode)

3.2 Config.ini File

Config.ini: Configure this tool to set up the environment.

3.3 Folders

The “burn_files” folder is an optional folder for you to put necessary image files that you want to burn. It also With some necessary system environment files of the application, the folder can be defined as the default working folder.

The “mtk_files” folder contains some security files such as mt7933_auth.auth, mt7933_cert.cert and DA version file.

3.4 Scatter File

Scatter file: the file configures flash partitions and parameters. The scatter file can be built and output to the “out” folder of the project after SDK code built:

```
..\out\MT793X_hdk\bootloader\ mt7931an_bootloader_scatter.ini
```

```
..\out\MT793X_hdk\iot_sdk_demo\ iot_sdk_demo_scatter.ini
```

The scatter file must be put in the same folder where images files are located, which is defined as the working folder.

The default working folder is “burn_files” and the default scatter file is “scatter.ini”

3.5 Debug Log

Debug_log.txt is the recorded log message of the execution process. The log file is cleaned when FlashBurningTool is opened. DL_fa_log_append.txt is the Debug_log.txt appended when an error occurs. You can analyze this file to debug.

3.6 Commands Table File

Cmds_tbl.txt is the command lines list. The commands can be run in console mode of the product line. The commands are run in bypass BROM mode to reduce time. So, there is no need to power on/off between commands. Please also refer to Section 6.9.

4 Supported Commands

4.1 Format Command

Erase some partitions or erase all partitions:

Click “select all partitions” to erase the whole flash. Or, select some partitions, and the Flash Tool erases the selected partitions of the flash accordingly.

Console mode: it can order command:

-o erase

4.2 Download Command

When the bin file is burned to each partition, the flash is erased before data is written to the flash.

After the image bin files are burned to the target device, if the burn operation completes successfully, the burning ok message appears.

Console mode: it can order command:

-o burn

For reduce time on product line, user can enable burn only feature by order command on console mode:

-o burn_o

burn_o is a special command that can be applied after the whole flash is erased fully, and the command only burns images bin.

4.3 Read Back Command

To read back the flash, click the “ReadBack” button on the GUI. The ReadBack command outputs the read back file; the output path is the same as assigned in each partition. The name of the output file is the original file name + _readback

E.g. Original file name: bootloader.bin

Read back output file name: bootloader_readback.bin

The original file and the read back file are compared; if the contents are not exactly the same, an error occurs.

Console mode: it can order command:

-o rdback

For reduce time on product line, user can enable read small size feature by order command on console mode:

-o rdback_s

if GUI mode want to enable, it must assign it on config.ini:[GUI_CONFIG]:

rdback_small_confirm_gui=y

when read back small size feature be enable, the readback size can be assigned on config.ini:[MP_Feature]:

rdback_small_size=xxxx ,

the suggested rdback_small_size is 4096. If the image file size is smaller than rdback_small_size, rdback_small_size will change to image file size.

4.4 Read eFuse Command

The command supports logical/physical eFuse reads of GRP1, GRP2, and GRP3 by using specific control data in GUI mode or by argument input in console mode. You can assign eFuse bin file name in the scatter file. This command can read full group data, the size of which is 0x200 (GRP1 and GRP2) or 0x400 (GRP3). The command can also read offset address (aligned with 0x10) data of each GRP, the size of which is 16 bytes.

In customer mode, to read GRP1 eFuse, you can run the read eFuse command directly on GUI. The command outputs the result in the file `customer_ef_tbl.txt` under the working folder.

In console mode, you can assign eFuse file name and file path by input argument.

```
-o rdfuse -e path_of_efuse_tbl.txt
```

The tool supports another command “`rdfuse_c`” for reading back eFuse data to confirm the correctness after the write eFuse command.

Example:

```
-o rdfuse_c -e Y:/mtk_11/out/mt7933_hdk/bga_sdk_demo/my_ef_tbl.txt
```

The command reads back eFuse data to another file as: `my_ef_tbl.txt(readback)` and compares the file with `my_ef_tbl.txt`,

After the files are compared, if there is any error, you see an error message.

4.5 Write eFuse Command

The command supports eFuse writes of GRP1 only, by using specific control data on GUI or by argument input in console mode. You can assign eFuse bin file name in the scatter file. This command can write full group data, the size of which is 0x200 (GRP1). The command can also read offset address (aligned with 0x10) data of GRP1, the size of which is 16 bytes.

In GUI mode, the write eFuse command can be opened by selecting the checkbox after clicking GUI’s Settings button.

In customer mode, to write GRP1 eFuse, you can run the write eFuse command directly on GUI. The command writes the eFuse according to the file `customer_ef_tbl.txt` located under the working folder.

In console mode, you can assign eFuse file name and file path by input argument.

```
-o wrefuse -e path_of_efuse_tbl.txt
```

To enable writing eFuse content to the platform, you must assign: “`blow enable=y`” in your `eFuse_table.txt`.

4.6 Customer Command on `cmds_tab.txt`

Customer can input any command and its input argument on `cmds_tab.txt`, the command line format as:

```
-o customer -s [customer command and input arguments]
```

For windows executable file example:

```
-o customer -s customer_cmd.exe -k c:/data.txt
```

For linux executable file example:

```
-o customer -s ./customer_cmd argument1 argument2 ....
```

Customer command must locate on root of `fbtool`, and this mode only valid on `cmds_tab.txt`.

5 GUI Mode Operation Sequence

5.1 General Description

You can execute FlashBurningTool_Vx_GUI.exe first. Then, set the connection path and file location. Select partitions and choose one command to run. The tool waits to perform handshaking with the platform. Then, power on the platform with the hardware jumper in download mode. In order to start the protocol of each other. When handshaking successfully, it start to run command.

5.2 Operation Sequence

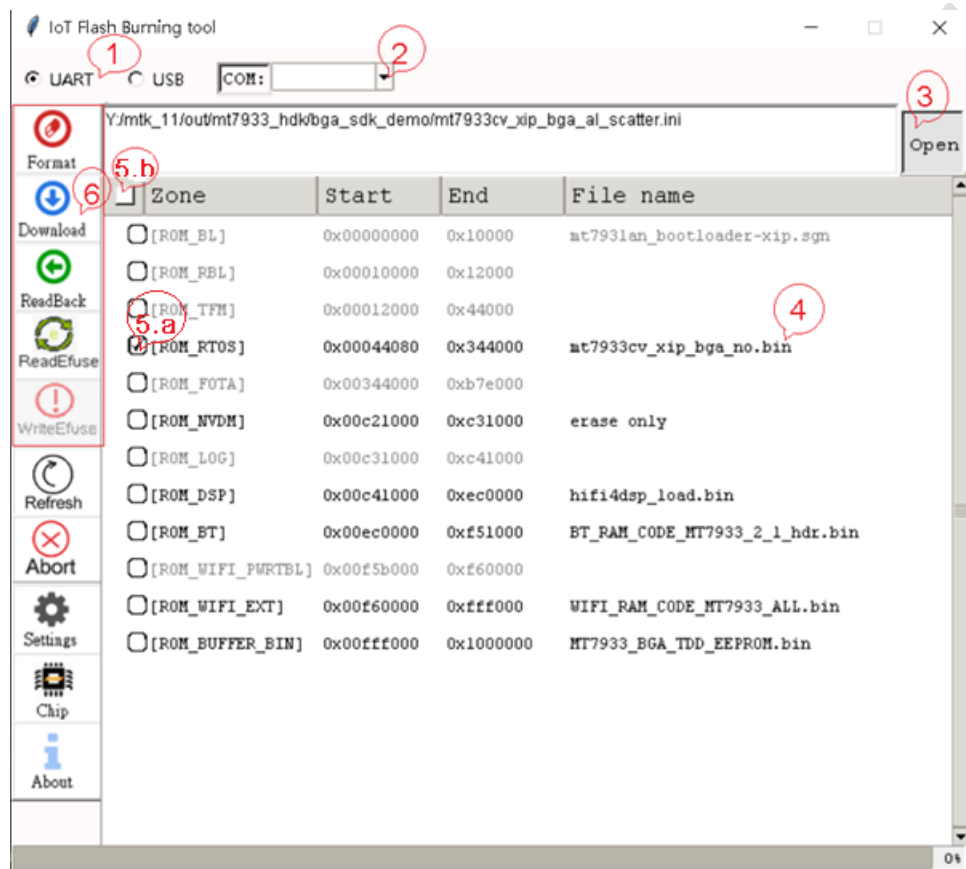


Figure 13: GUI mode operation sequence

General operating steps:

(Step 0) Power off the platform.

QFN_RFB/BGA_RFB in UART DL mode: Download key + SYSRST key: refer to Section 2.3.1.

BGA_RFB in USB DL mode: unplug the USB power cable.

(Step 1) Select the connection path. (UART or USB)

(Step 2) Select the COM port if you use the UART path.

(Step 3) Select the working folder to store the burned images and scatter file.

(Step 4) Assign file names in the scatter file (where the files are located) and then you can select the corresponding checkbox.

- (Step 5.a) Select zones.(multiple zones to choose from; only valid for Format, Download, ReadBack commands)
- (Step 5.b) You can select or clear all zones. (Optional)
- (Step 6.a) Select one command to run.

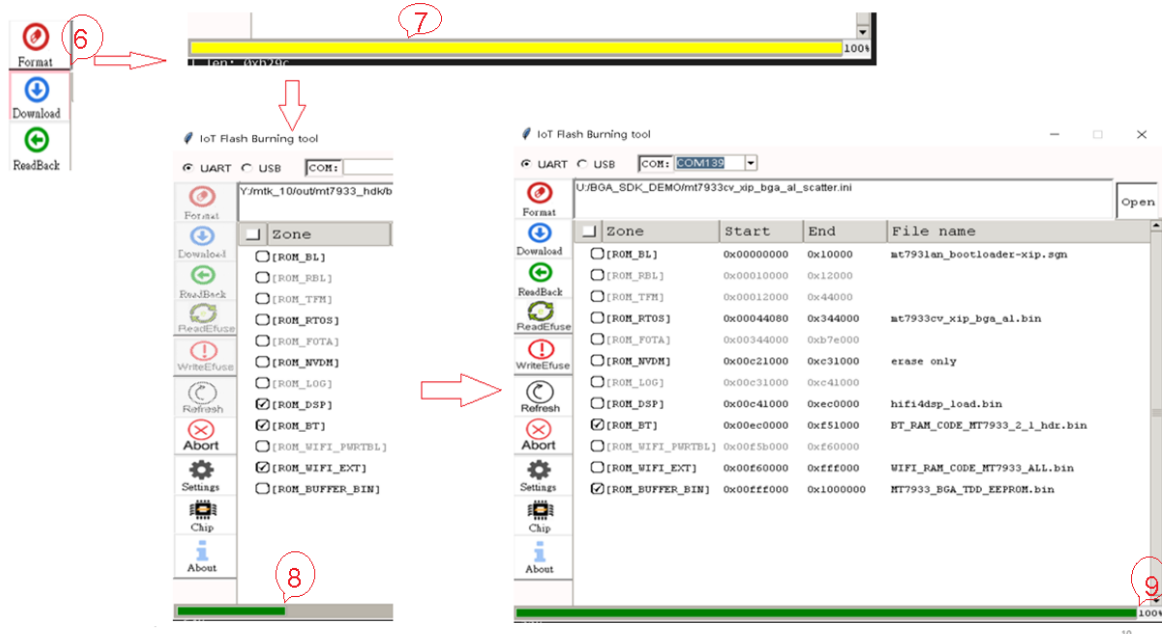


Figure 14: Process of running a command

(Step 6.b)

QFN_RFB/BGA/RFB in UART DL mode: Download key + SYSRST key: refer to Section 2.3.1.

BGA_RFB in USB DL mode: plug in the USB power cable.

(Step 7) If the progress bar turns yellow, it means handshaking is successful.

(Step 8) Wait for the progress bar to turn green.

(Step 9) Wait for the progress bar to turn completely green to indicate the task is finished.

(Step 10) Do not power off the platform if you want to run the command again. Repeat Steps 5 to 9.

(Step 11) Change to normal mode:

QFN_RFB in UART DL mode: press the SYSRST key: refer to Section 2.3.1.

BGA_RFB: unplug and then plug in the USB power cable.

(step 12) Run FlashBurningTool again: re-start flashburning.exe if you already exit the

GUI window. If not, press "Refresh" and then repeat Step 0.

```

loader disable 30s timeout
loader init
1. Burn Bootloader<0x0>
2. Burn RTOS <0x44080>
3. Burn WIFI PATCH <0x2D2000>
4. Burn WIFI FW <0x318000>
5. Burn WIFI_EXT <0x2E0000>
6. Burn BT <0x348000>
7. Burn DSP <0x41D000>
8. Burn TFM <0x12000>
9. Erase NUDM <0x7F0000>
c. Boot RTOS <0x44080>
d. Burn OTA image <0x69C000>
z. CLI
24

```

Figure 15: Normal mode UART log of strap to bootloader

Step 4 can be further elaborated as follows.

(Step 4.a) Assign bin file names in scatter.ini:

```
1 [BOOTLOADERS]
2 enable=y
3 start_addr = 0x00000000
4 partition_size=0x10000
5 file_name=mt7933_bootloader-ram.bin
6 readback=y
7 [R_BL]
8 enable=y
9 start_addr=0x00010000
0 partition_size=0x2000
1 file_name=test_small.bin
2 readback=y
3 [TFM]
4 enable=y
5 start_addr=0x00012000
6 partition_size=0x32000
7 file_name=mt7933_tfm.bin
8 readback=y
9 [RTOS]
```

Figure 16: Assign file names in scatter file

```
file_name=iot_sdk_demo.bin #iot_sdk_demo.bin #mt7933cv_xip_bga_al.bin
```

You can add a temp string after normal file name as shown above.

(Step 4.b) NVDM zone:

For NVDM, you do not need to assign the file name, which is named as “erase only” because it is an erase only area.

```
[NVDM]
enable=y
start_addr=0x007F0000
partition_size=0x10000
file_name=erase only
```

Figure 17: Scatter file of NVDM Zone

5.2.1 Bypass BROM

If you run a command for the first time, after the command is finished and you want to run the command again, you can run the command directly and do not need to power off the platform. However, if you have clicked the “Refresh” button to release bypass BROM mode, you need to power off the platform for the next command.

Or, if you power off the platform but do not close the GUI window, click the “Refresh” button to release bypass BROM mode.

5.3 Some GUI Element Descriptions

5.3.1 Refresh Button

The Refresh button can

- (1) Reset the tool to the initial state.
- (2) Reload scatter file content.
- (3) Reset bypass BROM mode.

If you do not assign the bin file or the working folder is empty, or if you have the wrong file name in "file_name=", you cannot select the checkbox of the partition zone. The tool shows a warning message to remind you. If you assign the bin file correctly, you can click the "Refresh" button to update scatter content.

5.3.2 Abort Button

If you are running a command, but you want to abort the command, you can click the "Abort" button. Note that the command does not always respond immediately.

6 Console Mode Operation Sequence

6.1 General Description

The UI is mainly controlled by config.ini and scatter.ini. After you plan ini, just execute fbtool.exe directly. Then, power on the platform with hardware jumper in download mode.

6.2 General Operation Sequence

Step 0: Power off the platform.

QFN_RFB/BGA/RFB in UART DL mode: Download key+SYSRST key: refer to Section 2.3.1.

BGA_RFB in USB DL mode: unplug the USB power cable.

Step 1: Select a connection path:



Figure 18: Console mode operating step: Config.ini

```
mt7933_scatter.ini
1  [BOOTLOADERS]
2  enable=y 3.a: Assign whether enable of this partition of Erase or Normal_Burning command
3  start_addr = 0x00000000
4  partition_size=0x10000
5  file_name=mt7933_bootloader-xip.sgn 3.Assign file name on each partition
6  readback=y 3.b: Assign whether enable of this
7  [R_BL] partition of Read_back command
8  enable=n
9  start_addr=0x00010000
10 partition_size=0x2000
11 file_name=test_small.bin
12 readback=n
13 [TFM]
14 enable=y
15 start_addr=0x00012000
16 partition_size=0x32000
```

Figure 19: Console mode operating step: assign data in scatter file

(1.a) Select the UART path to connect:

In config.ini, when UART = "y" and "COM_port" is specified, the UART download path can be selected first.

(1.b) Select the USB path to connect:

If the above conditions are not met, and if you set USB = "y", and have correct "Vid" and "Pid" values, you can select the USB path to connect.

Step 2: Assign the working folder of bin files that you want to burn.

Step 3: Assign file name of each partition, and choose whether to enable commands.

Step 4: Select the first command to run. Only assign "y" to the first command; assign "n" to other commands.

Step 5: Run fbtool_vx.exe.

```
total_size_to_erase+burn: 0x91f677
total_session_enable: 1
INFO: Goto open COM4
INFO: Got COM4
INFO: __uart_start_cmd
```

Figure 20: UART log of wait for user handshaking

If you select UART connection, you see the log, "__uart_start_cmd"; otherwise, you must check your COM port setting.

Step 6:

QFN_RFB/BGA/RFB in UART DL mode: Download key + SYSRST key: refer to Section 2.3.1.

BGA_RFB in USB DL mode: plug-in the USB power cable.

Step 7: Wait for the command to finish (check the log message.)

```

Session be erased:=BOOTLOADERS, Completed:= 1.0/10
Session be erased:=TFM, Completed:= 2.0/10
Session be erased:=RTOS, Completed:= 3.0/10
Session be erased:=WIFI_PATCH, Completed:= 4.0/10
Session be erased:=WIFI_EXT, Completed:= 5.0/10
Session be erased:=WIFI, Completed:= 6.0/10
Session be erased:=BT, Completed:= 7.0/10
Session be erased:=DSP, Completed:= 8.0/10
Session be erased:=OTA, Completed:= 9.0/10
Session be erased:=NUDM, Completed:= 10.0/10

```

Figure 21: UART log of command running process

Step 8: Power off the platform.

Step 9a: Repeat Step 3 to Step 8, if you want to run other commands.

Step 9b: The hardware jumper changes to normal mode and then powers on the platform; then, MT793X-bootloader-xip.sgn starts to run.

```

loader disable 30s timeout
loader init
1. Burn Boot loader<0x0>
2. Burn RTOS <0x44080>
3. Burn WIFI_PATCH<0x2D2000>
4. Burn WIFI_FW <0x318000>
5. Burn WIFI_EXT <0x2E0000>
6. Burn BT <0x348000>
7. Burn DSP <0x41D000>
8. Burn TFM <0x12000>
9. Erase NUDM <0x7F0000>
c. Boot RTOS <0x44080>
d. Burn OTA image <0x69C000>
z. CLI
24

```

Figure 22: Normal mode UART log of run bootloader

6.3 Scatter File Input Argument

You can select different scatter files for some specific applications.

fbtool.exe -f path_of_my_scatter.ini

Example:

fbtool.exe -f U:/BGA_SDK_DEMO/mt7933cv_xip_bga_al_scatter.ini

If there is no input argument, the default scatter file is burn_files/scatter.ini

The scatter file must be put in the working folder. In this case, the working folder is: U:/BGA_SDK_DEMO/

All images files are put in the working folder.

6.4 eFuse File Input Argument

You can select different eFuse file names for where the files are located for different applications.

fbtool.exe -e path_of_my_efuse_tbl.txt

Example:

fbtool.exe -e Y:/mtk_11/out/mt7933_hdk/bga_sdk_demo/my_ef_tbl.txt

fbtool.exe -e Y:/mtk_11/out/mt7933_hdk/bga_sdk_demo/my_ef_tbl_1.txt

If there is no input argument, the default file is the working folder/customer_ef_tbl.txt

6.5 Control Data Input Argument

You can input 4-byte control data to read or write eFuse. This argument is only valid for reading or writing eFuse commands.

```
fbtool.exe -s control_data
```

Example:

```
fbtool.exe -s 0x020001a0
```

```
fbtool.exe -s 0x34060000
```

P.S. You can read or write the eFuse without needing to input control data.

For more information, see the next chapter.

another application is customer command, please reference section 4.6.

6.6 Order Command Input Argument

You can select different commands by input argument.

```
fbtool.exe -o command_data
```

Example:

```
fbtool.exe.exe -o erase
```

```
fbtool.exe.exe -o burn
```

```
fbtool.exe.exe -o burn_o
```

```
fbtool.exe.exe -o rdback
```

```
fbtool.exe.exe -o rdback_s
```

```
fbtool.exe.exe -o wrefuse -s 0x01ff0000
```

```
fbtool.exe.exe -o rdefuse -s 0x01ff0000
```

```
fbtool.exe.exe -o wrefuse -e path_of_efuse_table.txt
```

```
fbtool.exe.exe -o rdefuse -e path_of_efuse_table.txt
```

```
fbtool.exe.exe -o rdefuse_c path_of_efuse_table.txt
```

```
fbtool.exe.exe -o cmds_tbl
```

-o customer command only valid on cmds_tab.txt:

-o customer my_cmd my_cmd_input_arguments

6.7 Run Command Table Input Argument

You can run commands in cmds_tbl.txt. The commands are run in bypass BROM mode to reduce time, so there is no need to power on/off between commands.

fbtool.exe -o cmds_table

Example:

```
1 #---test0
2 #-f U:/BGA_SDK_DEMO/mt7933cv_xip_bga_al_scatter.ini -o burn
3 #-f U:/BGA_SDK_DEMO/mt7933cv_xip_bga_al_scatter.ini -o rdback
4 #---test1:reduce erase time
5 #-f whole_flash.ini -o erase
6 #-f mt7933_bga_evb_scatter.ini -o burn_o
7 #---test2
8 #-f Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini -o burn
9 #-f Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini -o rdefuse -s 0x30405190
10 #-o customer -s cyberon_license.exe -h Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/efuse.bin
11 -- Allow empty line
12 -f Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini -o burn
13 -f Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini -o rdback_s
14 #-f Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini -o rdback
15 #-o rdefuse -e Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/customer_ef_tbl.txt
16 #-o wrefuse -f Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini -e Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/customer_ef_tbl.txt
17 #-o rdefuse_c -e Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/customer_ef_tbl.txt -f Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini
18 #-e Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/customer_ef_tbl_1.txt -f Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini -o wrefuse
19 #-e Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/customer_ef_tbl_1.txt -o rdefuse_c -f Y:/mtk-14/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini
```

Comment Syntax

Figure 23: Commands table

6.8 Run in Linux Console Mode

Running in Linux console mode is almost the same as running in Windows console mode. There are only some differences.

(1) You may need to change the permission the first time:

\$chmod 777 ./fbtool_vx

(2) Assign the COM port in config.ini:

```
config.ini
config.ini
1 [Download_Path]
2 USB=n
3 UART=y
4 [URAR_Port]
5 COM_port=/dev/ttyUSB3 linux com port assign
```

Figure 24: Assign Linux COM port

7 Read/Write eFuse

7.1 Control Data Format.

The control data is used to control the eFuse read/write group, choose whether to get a full dump or partial dump, and assign the offset address of each group. The control data is 4 bytes long.

To read or write the eFuse, you don't need to input control data.

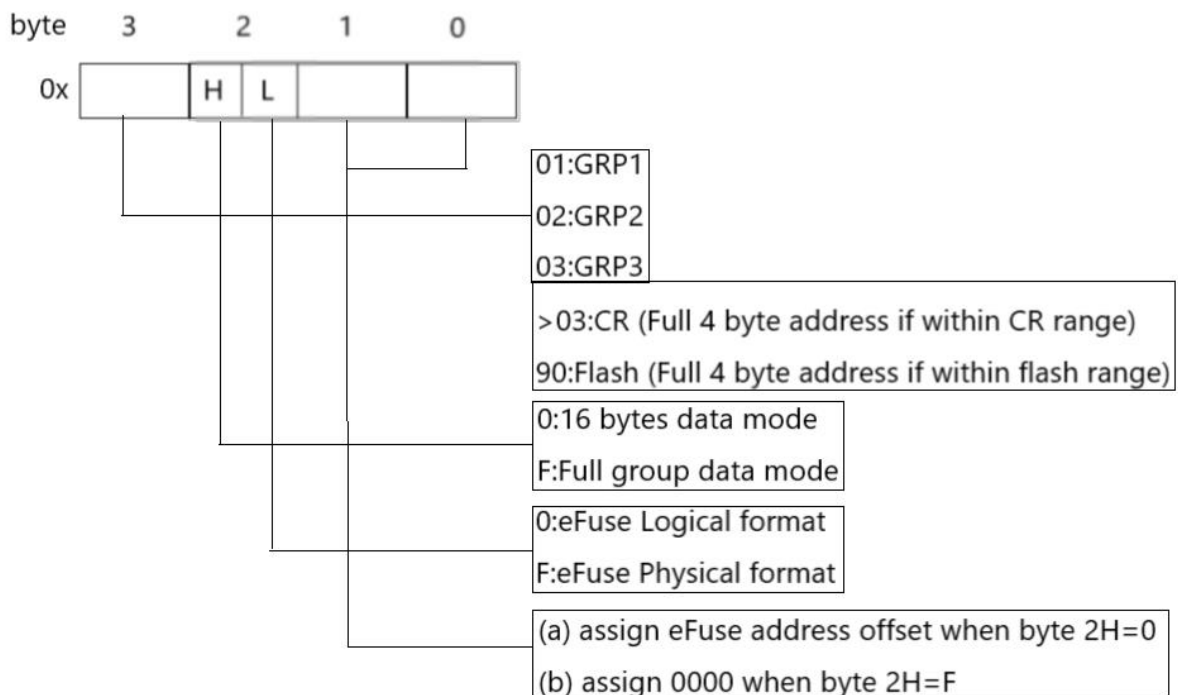


Figure 25: eFuse control data format

You can read GRP1, GRP2, GRP3 of eFuse data by using specific control data in GUI or console modes. The control data can be used to read full data, the size of which is 0x200 (GRP1, GRP2) and 0x400 (GRP3), or assign offset address (aligned with 0x10) to read/write a part of the data of each GRP, the size of which is 16 bytes.

For example:

- (1) Ctl-data=0x010001A0: Read/Write GRP1 in 16-byte data mode with offset address = 0x01A0.
- (2) Ctl-data=0x02FF0000: Physical reads of GRP2 in full data mode and related efuse.bin.
- (3) Ctl-data=0x02F00000: Logical reads of GRP2 in full data mode and related efuse.bin.
- (4) Ctl-data=0x02000060: Logical reads of GRP2 of address = 0x60 in 16-byte data mode.
- (5) Ctl-data=0x34040030: Read/Write CR in 16-byte data mode, with the address aligned with 0x10.
- (6) Ctl-data=0x90000010: Read/Write flash in 16-byte data mode.

7.2 Customer Mode: eFuse Table

In GUI mode, the tool contains a default template file, `customer_ef_tbl.txt`, in the “burn_files” folder, and the content data is filled with zeroes. When you select a new working folder, the file is copied to the new working folder. You can edit the file under the working folder. Do not edit the file under the “burn_files” folder.

When you run a read/ write eFuse command, the tool bases the operations on the file under the working folder. You can press the readEfuse or writeEfuse button directly in GUI mode.

For safety, the write eFuse button is disabled by default. You must enable eFuse writing by selecting the checkbox after clicking the Settings button, and then the write eFuse button will change to enabled.

To enable writing eFuse content to the platform, you must assign: “blow enable=y” in your `eFuse_table.txt`

In console mode, you can select the location of the eFuse file by an input argument. If you don't select a location, the default file location is `working folder/customer_ef_tbl.txt`

For example:

```
fbtool.exe -o rdefuse -e Y:/mtk_11/out/mt7933_hdk/bga_sdk_demo/my_ef_tbl.txt
```

Or

```
fbtool.exe -o rdefuse -f Y:/mtk_10/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini
```

In this case, because there is no input -e argument, so the eFuse file is under:

```
Y:/mtk_10/out/mt7933_hdk/bga_sdk_demo/customer_ef_tbl.txt
```

Or

```
fbtool.exe -o rdefuse -e Y:/mtk_11/out/mt7933_hdk/bga_sdk_demo/customer_ef_tbl.txt
```

```
-f Y:/mtk_10/out/mt7933_hdk/bga_sdk_demo/mt7933cv_xip_bga_al_scatter.ini
```

In this case, the -f input argument has no effect for read eFuse function.

Or

```
fbtool.exe -o rdefuse
```

In this case, because there is no -f argument, the default scatter is `burn_files/scatter.ini`, and eFuse file is: `burn_files/ customer_ef_tbl.txt`. But this file is the default template file with full data = 0 for the tool. The file can't be edited or modified. If the file is modified, the tool shows error messages.

Please also refer Sections 6.3, 6.4 and 6.6.

Figure 26: eFuse table (customer modified)

Figure 26 shows example of eFuse table. Please note the red blocks are modified.

The tool supports another command “rdefuse_c” for reading back eFuse data after the write eFuse command.

Example:

```
fbtool.exe.exe -o rdefuse_c -e Y:/mtk_11/out/mt7933_hdk/bga_sdk/
```

The command reads back eFuse data to another file as: my_ef_tbl.txt(rdefuse_c my_ef_tbl.txt,

After the files are compared, if there is any error, you see an error message.

Figure 26 shows example of eFuse table. Please note modified.

The tool supports another command “rdefuse_c” for the write eFuse command.

Example:

```
fbtool.exe.exe -o rdefuse_c -e Y:/mtk_11/out/mt7935/my_ef_tbl.txt
```

The command reads back eFuse data to another file a my_ef_tbl.txt,

After the files are compared, if there is any error, you

The tool supports another command “`rdefuse_c`” for reading back eFuse data to confirm the correctness after the write eFuse command.

Example:

```
fbtool.exe.exe -o rdefuse_c -e Y:/mtk_11/out/mt7933_hdk/bga_sdk_demo/my_ef_tbl.txt
```

The command reads back eFuse data to another file as: `my_ef_tbl.txt(readback)` and compares the file with `my_ef_tbl.txt`,

After the files are compared, if there is any error, you see an error message.

8 Manual Flash Operation

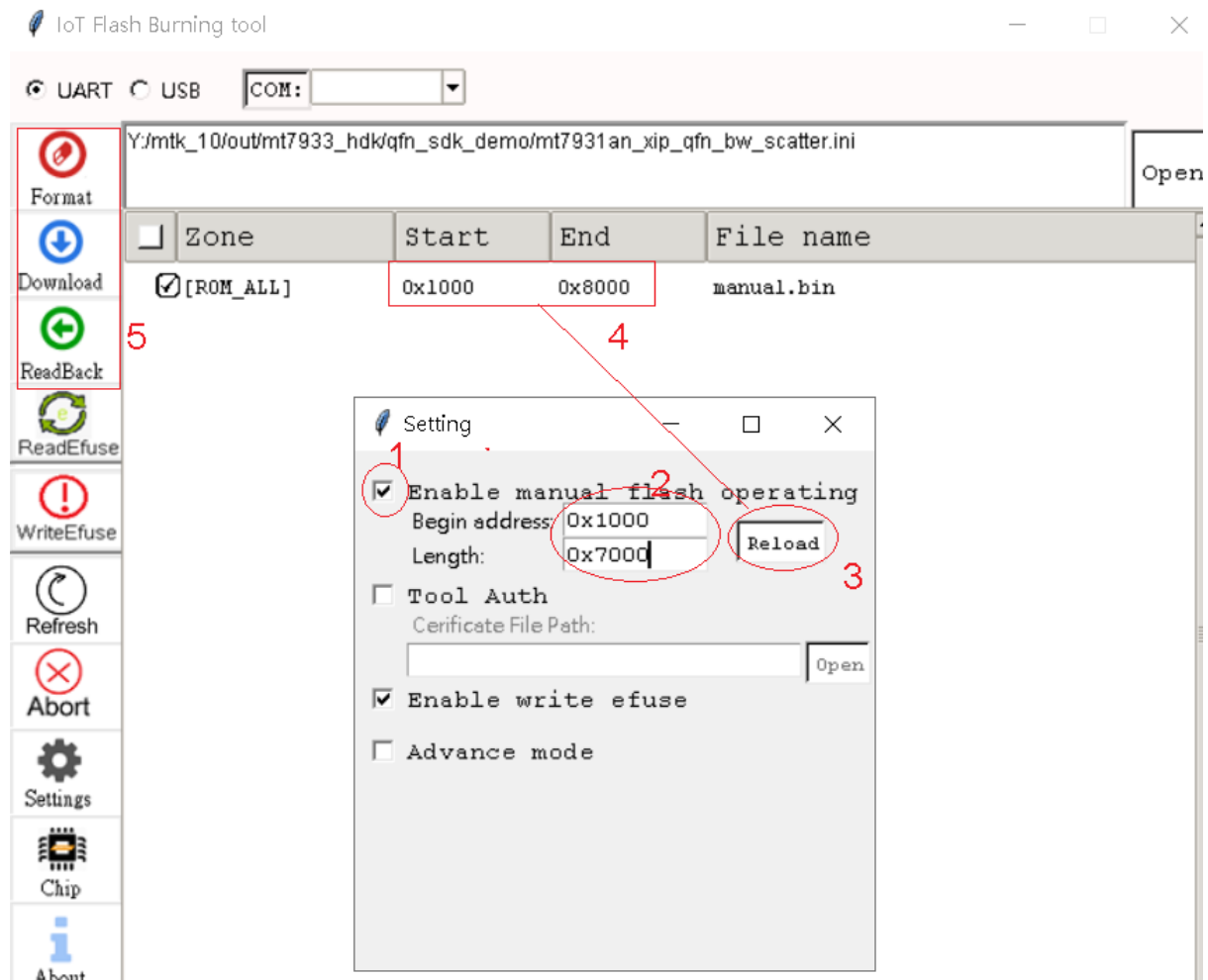


Figure 27: Manual flash operating

General operating steps:

(Step 1) Select the checkbox.

(Step 2) Enter the Begin address and Length

(Step 3) Click the Reload button.

(Step 4) Data will be updated to the scatter file.

(Step 5) Choose one command to run.

(Step 6) Repeat Steps 2 to 5.

If you run Read back command, it will outputs manual_readback.bin file to working folder.

If you run Download command, tool will burn manual.bin to flash.

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