Title

scpi —— Estimation and Inference for Synthetic Control Methods.

Syntax

scpi , dfname(*string***)** [**p(***#***) direc(***string***) Q(***#***) lb(***#***) name(***string***) u_missp) u_sigma(***string***) u_order(***#***) u_lags(***#***) u_alpha(***#***) sims(***#***) e_method(***string***) e_order(***#***) e_lags(***#***) e_alpha(***#***) rho(***#***) rho_max(***#***) opt_est(***string***)**] **opt_inf(***string***)**]

Description

scpi implements estimation and inference procedures for Synthetic Control (SC) methods using least squares, lasso, ridge, or simplex-type constraints according to Cattaneo, Feng, and Titiunik (2021). The command is a wrapper of the companion Python package. As such, the user needs to have a running version of Python with the package installed. A tutorial on how to install Python and link it to Stata can be found here.

Companion R and Python packages are described in Cattaneo, Feng, Palomba and Titiunik (2022)

Companion commands are: scdata for data preparation, scest for estimation procedures, and scplot for SC plots.

Related Stata, R, and Python packages useful for inference in SC designs are described in the following website:

https://nppackages.github.io/scpi/

Options

dfname(*string***)** specifies the name of the Python object containing the processed data created with scdata.

Constraint

These options let the user specify the type of constraint to be imposed to estimate the SC weights. The user controls the norm of the weights to be constrained (option **p**), the direction of the constraint on the norm (option **dir**), and the size of the constraint on the norm (option **q**). Alternatively, some popular constraints can be selected through the option **name**. A detailed description of the popular constraints implemented can be found in Cattaneo, Feng, Palomba and Titiunik (2022).

name(*string***)** specifies the name of the constraint to be used. Options are:
- **simplex** classic SC estimator as proposed in Abadie (2021). Estimated weights are constrained to be non-negative and their L1 norm must be equal to 1.
- **lasso** weights are estimated using a Lasso-type penalization
- **ridge** weights are estimated using a Ridge-type penalization.
- **ols** weights are estimated without constraints using least squares

p(*#***)** sets the type of norm to be constrained. Options are:
- **0** no constraint on the norm of the weights is imposed.
- **1** a constraint is imposed on the L1 norm of the weights (the default).
- **2** a constraint is imposed on the L2 norm of the weights.

direc(*string***)** specifies the direction of the constraint on the norm of the weights. Options are:
- **<=** the constraint on the norm of the weights is an inequality constraint.
- **==** the constraint on the norm of the weights is an equality constraint (the default).

Q(*#***)** specifies the size of the constraint on the norm of the weights.

lb(*#***)** specifies the lower bound on the weights. The default is **lb(0)**.

In-sample Uncertainty

This set of options allows the user to specify her preferred approch to model in-sample uncertainty, that is uncertainty that stems from the estimation the weights.

u_missp if specified indicates that model misspecification should be taken into account.
u_sigma(*string***)** specifies the type of variance-covariance estimator to be used when estimating the conditional variance of the pseudo-residuals. Options are: **HC0**, **HC1** (default), **HC2**, and **HC3**.
u_order(#**)** specifies the order of the polynomial in the predictors used to estimate conditional moments of the pseudo-residuals. Default is **u_order(1)**.
u_lags(#**)** specifies the lags of the predictors used to estimate conditional moments of the pseudo-residuals. Default is **u_lags(0)**.
u_alpha(#**)** specifies the confidence level for in-sample uncertainty. Default is **u_alpha(0.05)**.
sims(#**)** specifies the number of simulations to be used in quantifying in-sample uncertainty. Default is **sims(200)**.

Out-of-sample Uncertainty

This set of options allows the user to specify her preferred approch to model out-of-sample uncertainty.

e_method(#**)** specifies the method to be used to quantify out-of-sample uncertainty. Options are:
gaussian conditional subgaussian bounds.
ls location-scale model.
qreg quantile regression.
all all of the above (the default).

e_order(#**)** specifies the order of the polynomial in the predictors used to estimate conditional moments of the out-of-sample error. Default is **e_order(1)**.
e_lags(#**)** specifies the lags of the predictors used to estimate conditional moments of the out-of-sample error. Default is **e_lags(0)**.
e_alpha(#**)** specifies the confidence level for out-fo-sample uncertainty. Default is **e_alpha(0.05)**.

Regularization

rho(#**)** specifies the regularizing parameter that imposes sparsity on the estimated vector of weights. If unspecified, the tuning parameter is computed based on optimization inequalities.
rho_max(#**)** specifies the maximum value attainable by the tuning parameter **rho**.

Others

opt_est(*string***)** a string specifying the stopping criteria used by the underling optimizer (nlopt) for point estimation. The default is a sequential quadratic programming (SQP) algorithm for nonlinearly constrained gradient-based optimization ('SLSQP'). In case a lasso-type constraint is implemented, the method of moving asymptotes (MMA) is used. The default value is **opt("'maxeval' = 5000, 'xtol_rel' = 1e-8, 'xtol_abs' = 1e-8, 'ftol_rel' = 1e-12, 'ftol_abs' = 1e-12, 'tol_eq' = 1e-8, 'tol_ineq' = 1e-8")**.

opt_inf(*string***)** a string specifying the stopping criteria used by the underling optimizer (nlopt) for point estimation. The default is a sequential quadratic programming (SQP) algorithm for nonlinearly constrained gradient-based optimization ('SLSQP'). In case a lasso-type constraint is implemented, the method of moving asymptotes (MMA) is used. The default value is **opt("'maxeval' = 5000, 'xtol_rel' = 1e-8, 'xtol_abs' = 1e-8, 'ftol_rel' = 1e-4, 'ftol_abs' = 1e-4, 'tol_eq' = 1e-8, 'tol_ineq' = 1e-8")**.

Example: Cattaneo, Feng and Titiunik (2021) Germany Data

Setup

```
. use scpi_germany.dta
```

Prepare data

```
. scdata gdp, dfname("python_scdata") id(country) outcome(gdp) time(year)
treatment(status) cointegrated
```

Estimate Synthetic Control with a simplex constraint and quantify uncertainty

```
. scpi, dfname("python_scdata") name(simplex) u_missp
```

marker stored_results}**Stored results**

scpi stores the following in **e()**:

Scalars

e(M)	number of features
e(KM)	number of covariates used for adjustment
e(J)	number of donors
e(T1)	number of post-treatment periods
e(q)	size of the constraint on the norm
e(rho)	post-estimation regularization parameter

Macros

e(features)	name of features
e(outcomevar)	name of outcome variable
e(constant)	logical indicating the presence of a common constant across features
e(cointegrated_data)	logical indicating cointegration
e(p)	type of norm of the weights used in constrained estimation
e(dir)	direction of the constraint on the norm of the weights
e(name)	name of constraint used in estimation
e(u_missp)	a logical indicating whether the model has been treated as misspecified or not
e(u_order)	order of the polynomial in the predictors used to estimate conditional moments of the pseudo-residuals
e(u_lags)	lags of the predictors used to estimate conditional moments of the pseudo-residuals
e(u_sigma)	estimator of the conditional variance-covariance matrix of the pseudo-residuals
e(u_alpha)	confidence level for in-sample uncertainty
e(e_method)	method used to quantify out-of-sample uncertainty
e(e_order)	order of the polynomial in the predictors used to estimate conditional moments of the out-of-sample error
e(e_lags)	order of the polynomial in the predictors used to estimate conditional moments of the out-of-sample error
e(e_alpha)	confidence level for out-of-sample uncertainty

Matrices

e(T0)	number of pre-treatment periods per feature
e(A)	pre-treatment features of the treated unit
e(B)	pre-treatment features of the control units
e(C)	covariates used for adjustment
e(pred)	predicted values of the features of the treated unit
e(res)	residuals **e(A)** - **e(pred)**
e(w)	weights of the controls
e(r)	coefficients of the covariates used for adjustment
e(beta)	stacked version of **e(w)** and **e(r)**
e(Y_post)	post-treatment outcome of the treated unit
e(Y_post_fit)	estimated post-treatment outcome of the treated unit
e(Y_pre)	pre-treatment outcome of the treated unit
e(Y_pre_fit)	estimate pre-treatment outcome of the treated unit
e(CI_in_sample)	prediction intervals taking only in-sample uncertainty into account
e(CI_all_gaussian)	prediction intervals taking in- and out-of-sample uncertainty into account

e(CI_all_ls)	prediction intervals taking in- and out-of-sample uncertainty into account
e(CI_all_qreg)	prediction intervals taking in- and out-of-sample uncertainty into account
e(e_mean)	estimated conditional mean of the out-of-sample error
e(e_var)	estimated conditional variance of the out-of-sample error
e(Sigma)	estimated conditional variance-covariance of the pseudo-residuals
e(failed_sims)	percentage of failed simulations per post-treatment period to estimate lower and upper bounds.

References

Abadie, A. 2021. Using synthetic controls: Feasibility, data requirements, and methodological aspects. *Journal of Economic Literature*, 59(2), 391-425.

Cattaneo, M. D., Feng, Y., and Titiunik, R. 2021. Prediction Intervals for Synthetic Sontrol Methods. *Journal of the American Statistical Association*, 116(536), 1865-1880.

Cattaneo, M. D., Feng, Y., Palomba F., and Titiunik, R. 2022. scpi - Uncertainty Quantification for Synthetic Control Estimators.

Authors

Matias D. Cattaneo, Princeton University, Princeton, NJ. cattaneo@princeton.edu.

Yingjie Feng, Tsinghua University, Beijing, China. fengyj@sem.tsinghua.edu.cn.

Filippo Palomba, Princeton University, Princeton, NJ. fpalomba@princeton.edu.

Rocio Titiunik, Princeton University, Princeton, NJ. titiunik@princeton.edu.