



Title

scest — Estimation for Synthetic Control Methods.

Syntax

```
scest , dfname(string) [p(#) direc(string) Q(#) lb(#) name(string) opt(string)]
```

Description

scest implements estimation procedures for Synthetic Control (SC) methods using least squares, lasso, ridge, or simplex-type constraints according to [Cattaneo, Feng, and Titiunik \(2021\)](#). The command is a wrapper of the companion Python package. As such, the user needs to have a running version of Python with the package installed. A tutorial on how to install Python and link it to Stata can be found [here](#).

Companion R and Python packages are described in [Cattaneo, Feng, Palomba and Titiunik \(2022\)](#).

Companion commands are: [scdata](#) for data preparation, [scpi](#) for inference procedures, and [scplot](#) for SC plots.

Related Stata, R, and Python packages useful for inference in SC designs are described in the following website:

<https://nppackages.github.io/scpi/>

Options

dfname(string) specifies the name of the Python object containing the processed data created with [scdata](#).

Constraint

These options let the user specify the type of constraint to be imposed to estimate the SC weights. The user controls the norm of the weights to be constrained (option **p**), the direction of the constraint on the norm (option **dir**), and the size of the constraint on the norm (option **q**). Alternatively, some popular constraints can be selected through the option **name**. A detailed description of the popular constraints implemented can be found in [Cattaneo, Feng, Palomba and Titiunik \(2022\)](#).

name(string) specifies the name of the constraint to be used. Options are:

- simplex** classic SC estimator as proposed in [Abadie \(2021\)](#). Estimated weights are constrained to be non-negative and their L1 norm must be equal to 1.
- lasso** weights are estimated using a Lasso-type penalization
- ridge** weights are estimated using a Ridge-type penalization.
- ols** weights are estimated without constraints using least squares

p(#) sets the type of norm to be constrained. Options are:

- 0 no constraint on the norm of the weights is imposed.
- 1 a constraint is imposed on the L1 norm of the weights (the default).
- 2 a constraint is imposed on the L2 norm of the weights.

direc(string) specifies the direction of the constraint on the norm of the weights. Options are:

- <=** the constraint on the norm of the weights is an inequality constraint.
- ==** the constraint on the norm of the weights is an equality constraint (the default).

Q(#) specifies the size of the constraint on the norm of the weights.

lb(#) specifies the lower bound on the weights. The default is **lb(0)**.

Others

opt(string) a string specifying the stopping criteria used by the underlying optimizer (**nlopt**) for point estimation. The default is a sequential quadratic programming (SQP) algorithm for nonlinearly constrained gradient-based optimization ('SLSQP'). The default value is **opt('maxeval' = 5000, 'xtol_rel' = 1e-8, 'xtol_abs' = 1e-8, 'ftol_rel' = 1e-12, 'ftol_abs' = 1e-12, 'tol_eq' = 1e-8, 'tol_ineq' = 1e-8)**. In case a lasso-type constraint is implemented, a different optimizer (**cvxpy**) is used and stopping criteria cannot be changed.

Example: Cattaneo, Feng and Titiunik (2021) Germany Data

```
Setup
. use scpi_germany.dta

Prepare data
. scdata gdp, dfname("python_scddata") id(country) outcome(gdp) time(year)
  treatment(status) cointegrated

Estimate Synthetic Control with a simplex constraint
. scest, dfname("python_scddata") name(simplex)
```

Stored results

scest stores the following in **e()**:

Scalars

e(M)	number of features
e(KM)	number of covariates used for adjustment
e(J)	number of donors
e(T1)	number of post-treatment periods
e(q)	size of the constraint on the norm

Macros

e(features)	name of features
e(outcomevar)	name of outcome variable
e(constant)	logical indicating the presence of a common constant across features
e(cointegrated_data)	logical indicating cointegration
e(p)	type of norm of the weights used in constrained estimation
e(dir)	direction of the constraint on the norm of the weights
e(name)	name of constraint used in estimation

Matrices

e(T0)	number of pre-treatment periods per feature
e(A)	pre-treatment features of the treated unit
e(B)	pre-treatment features of the control units
e(C)	covariates used for adjustment
e(pred)	predicted values of the features of the treated unit
e(res)	residuals e(A) - e(pred)
e(w)	weights of the controls
e(r)	coefficients of the covariates used for adjustment
e(beta)	stacked version of e(w) and e(r)
e(Y_post)	post-treatment outcome of the treated unit
e(Y_post_fit)	estimated post-treatment outcome of the treated unit
e(Y_pre)	pre-treatment outcome of the treated unit
e(Y_pre_fit)	estimate pre-treatment outcome of the treated unit

References

Abadie, A. 2021. Using synthetic controls: Feasibility, data requirements, and methodological aspects. *Journal of Economic Literature*, 59(2), 391-425.

Cattaneo, M. D., Feng, Y., and Titiunik, R. 2021. Prediction Intervals for Synthetic Sontrol Methods. *Journal of the American Statistical Association*, 116(536), 1865-1880.

Cattaneo, M. D., Feng, Y., Palomba F., and Titiunik, R. 2022. scpi - Uncertainty Quantification for Synthetic Control Estimators..

Authors

Matias D. Cattaneo, Princeton University, Princeton, NJ. cattaneo@princeton.edu.

Yingjie Feng, Tsinghua University, Beijing, China. fengyj@sem.tsinghua.edu.cn.

Filippo Palomba, Princeton University, Princeton, NJ. fpalomba@princeton.edu.

Rocio Titiunik, Princeton University, Princeton, NJ. titiunik@princeton.edu.