ESO207 Theoretical Assignment 3

QP1 All or None

(a).

If only the sequence of nodes is given (without backtracking), it is impossible to recover the graph. Even if it is given after backtracking, still cannot recover all the original edges of graph, same with DFS tree. Thus not possible to find a tour with given condition.

For example, same sequence can correspond to two graphs (cyclic, acyclic).

(b).

If we are again given the sequence of BFS traversal (even with backtracking), it is not possible to recover all edges. This is because the last edge in a cycle simply wont get traversed.

Since, all edges in BFS tree are in the original graph, but such edges which complete a cycle in original graph may or may not be present in the BFS tree.

Thus, not possible to find (an Euler) tour.

(c).

We claim that it is possible to traverse each edge exactly once and return back to the starting city iff every vertex has an even degree.

("Only if" side is trivial since odd number of edges would mean, we either entered that vertex or left that vertex odd number of times, which is not possible for the source vertex, nor for the intermediate vertices.)

Start with some vertex v, we choose an edge and move further (this is always possible since we have even degree i.e. we have a different edge to leave once we enter a vertex). The number of edges being finite, we arrive back at vertex v. Let this be a cycle C. If all edges are covered then we have found the required tour.

If not, then let the subgraph excluding edges of C be S. All the connected components of S will be connected to cycle C (since the graph is connected). Now, we can invoke induction on the number of edges and thus all the connected components of S will also have such tours. Thus, the original graph will also admit such a tour since on the cycle C, if we reach a connection point (at which another connected component of S is connected), we complete that tour first and then further complete the cycle C.

(d).

We modify our DFS a bit and explore all unvisited edges in each traversal and mark those which are visited, and keep appending those in our (Euler) "tour". Thus, total time complexity is O(|E|) or O(|V| + |E|) if we intend to check if the graph is Eulerian or not.

Pseudocode:

```
\begin{array}{l} \mathbf{function} \ \mathrm{DFS}(u,G,visited\_edge,path) \\ \quad \mathrm{tour.APPEND}(path) \\ \mathbf{for} \ \mathrm{each} \ v \ \mathrm{in} \ \mathrm{G}[\mathrm{u}] \ \mathbf{do} \\ \quad \mathbf{if} \ !visited\_edge[u][v] \ \mathbf{then} \\ \quad \mathrm{Set} \ visited\_edge[u][v] \ \mathrm{and} \ visited\_edge[v][u] \ \mathrm{to} \ \mathrm{true} \\ \quad \mathrm{Call} \ \mathrm{DFS}(v,G,visited\_edge,path) \\ \quad \mathbf{end} \ \mathbf{if} \\ \quad \mathbf{end} \ \mathbf{for} \end{array}
```

```
\mathbf{return} \ \mathrm{path}
function GETDEGREE(G)
                                                                                          \triangleright O(|V| + |E|)
   odd\_deg\_count \leftarrow 0
   odd \quad node \leftarrow -1
   for vertex i in G do
       if the degree of node i in G is odd then
           Increment odd\_deg\_count by 1
           Set odd node to i
       end if
   end for
   if odd\_deg\_count is 0 then
       return (1, odd\_node)
   else if odd\_deg\_count is 2 then
       return (0, odd\_node)
   end if
function CHECKEULER(G)
   visited\_edge \leftarrow [false]_{n \times n}
   check, odd \quad node \leftarrow \texttt{GetDegree}(\texttt{G})
   if check is 1 then
       Print ("Graph has an Euler tour")
   else
       Print("Graph has no such tour")
   end if
   path \leftarrow DFS(start\ node, G, visited\ edge)
   PRINT(path)
```

QP2 Chaotic Dino

(a).

We traverse the graph using BFS for a particular vertex upto $power \leftarrow x$ levels, and then recursively BFS again from those vertices which have towers. Now, if we somehow reach the destination in the process, we are done. We are not actually interested in getting the actual path from source to destination, just to check if that is a possibility.

Each BFS traversal takes O(|V| + |E|) time and we'd do these traversals max for n = |V| times. Thus, overall time complexity being O(|V|(|V| + |E|)).

Pseudocode:

```
visited = [false]_n
master\_queue \leftarrow \text{Queue}()
function Tower-ReSearch(G, S, x, D)
   power \leftarrow x
   queue \leftarrow Queue()
   visited[S] \leftarrow True
   queue.enqueue(S)
   while !Q.isEmpty() and power \ge 0 do
       node \leftarrow Q.dequeue()
       power \leftarrow power - 1
       for each neighbour in G[node] do
           if neighbour == D then
              Print("Possible")
              return true
           end if
           if !visited[neighbour] and HASTOWER(neighbour) then
              master queue.enqueue(neighbour)
           end if
       end for
   end while
end function
function Get-Tower(G, S, x, D)
   while !master queue.isEmpty() do
       v \leftarrow master \quad queue. \text{dequeue}()
       if Tower-research(G, v, x, D) then
           return true
       end if
   end while
   return false
```

(b).

We can employ binary search on the value of power, x. The minimum and maximum possible values of x are 0 and the length of longest path from S to D respectively (we may take that as n as well).

Since again, the Tower-ReSearch function acts as a predicate function on the power x i.e. becomes true after a certain minimum power. Thus, we are able to apply binary search. Total time complexity is $O(\log n \cdot |V|(|V|+|E|))$ (log n times that of Tower-ReSearch)

Pseudocode:

```
\begin{array}{l} \textbf{function Bin-Search}(lo,hi,x,n) \\ \textbf{if !Tower-reSearch}(G,S,n,D) \textbf{ then} \\ \textbf{return -1} \\ \textbf{end if} \\ lo \leftarrow 0, hi \leftarrow n \\ \textbf{while } lo \leq hi \textbf{ do} \\ mid \leftarrow \lfloor \frac{lo+hi}{2} \rfloor \\ \textbf{if !Tower-reSearch}(G,S,mid,D) \textbf{ then} \\ hi \leftarrow mid - 1 \\ \textbf{else} \\ lo \leftarrow mid + 1 \\ \textbf{end if} \\ \textbf{end while} \\ \textbf{return } hi \end{array}
```

QP3 Room Colours

We create a segment tree with each node on it storing the colour for that particular segment. Nodes are created by dividing the original segment into two halves recursively.

Range-Assignment takes O(h) where, h is the height of tree where $O(h) = O(\log n)$ (since we are recursively dividing segments into halves). Also, lookup takes $O(\log n)$ time.

Thus, for m updations (m bombings) and n lookups (for n rooms), we have total time complexity $O((m+n)\log n)$.

```
Pseudocode:
 function PUSHDOWN(id)
     if painted[id] then
         t[2id] = t[2id+1] = t[id]
         painted[2id] = painted[2id + 1] = true
         painted[id] = false
     end if
  end function
 function UPDATE(id, x, y, l, r, c)
                                                                                            \triangleright O(\log n)
     if l > r then
         return
     end if
     if l == x and y == r then
         t[id] = c
         painted[id] = true
     else
         PushDown(id)
         mid = \frac{x+y}{2}
         UPDATE (2id, x, mid, l, min(r, mid), c)
         UPDATE(2id+1, mid+1, y, \max(l, mid+1), r, c)
     end if
 end function
 function WHICHCOLOUR(id, x, y, pos)
                                                                                            \triangleright O(\log n)
     if x == y then
         return t[id]
     end if
     PushDown(id)
     mid = \frac{x+y}{2}
     if pos \leq mid then
         return WHICHCOLOUR(2id, x, mid, pos)
     else
         return WhichColour(2id + 1, mid + 1, y, pos)
     end if
 end function
 function Bomb-N-Final
                                                                                   \triangleright O((m+n)\log n)
     painted \leftarrow [false]_{4n}
     t \leftarrow [0]_{4n}
     for i in range(0, m) do
         l, r, c \leftarrow input
```

```
\begin{array}{l} \text{Update}(0,0,n-1,l,r,c) & \Rightarrow \text{labelling root node as } 0 \\ \textbf{end for} \\ colour = []_n \\ \textbf{for } i \text{ in range}(0,n) \textbf{ do} \\ colour[i] = \text{WhichColour}(0,0,n-1,l,r,c) \\ \textbf{end for} \end{array}
```

QP4 Fest Fever

We can keep track of the cost of the sweets in an array and thus a segment tree implemented on it stores the range-sums.

Range-Updation takes O(h) where, h is the height of tree, and since we are dividing our segments into halves recursively $O(h) = O(\log n)$

```
Thus, for n queries, the total time complexity is O(n \log n)
Pseudocode:
  function BUILDTREE(prices, idx, l, r)
                                                                                               \triangleright O(4n) = O(n)
      if l == r then
          tree[idx] \leftarrow prices[l]
      else
           mid \leftarrow \frac{l+r}{2}
           Build Tree (prices, 2idx + 1, l, mid)
           BuildTree(prices, 2idx + 2, mid + 1, r)
          tree[idx] \leftarrow tree[2idx+1] + tree[2idx+2]
      end if
  end function
  function SUM-QUERY (idx, l, r, x, y)
                                                                                                      \triangleright O(\log n)
      if x \leq l and r \leq y then
          return tree[idx]
      end if
      if r < x or l > y then
          return 0
      end if
      mid \leftarrow \frac{l+r}{2}
      l\_sum \leftarrow \text{Sum-Query}(2idx + 1, l, mid, x, y)
      r sum \leftarrow \text{Sum-Query}(2idx + 2, mid + 1, r, x, y)
      \mathbf{return}\ l\ \_sum + r\ \_sum
  end function
                                                                                                      \triangleright O(\log n)
  function UPDATE (idx, l, r, target, val)
      if l = r = target then
          tree[idx] \leftarrow val
      else
          mid \leftarrow \frac{(l+r)}{2}
          if target \leq mid then
               UPDATE (2idx + 1, l, mid, target, val)
          else
               UPDATE (2idx + 2, mid + 1, r, target, val)
          tree[idx] \leftarrow tree[2idx+1] + tree[2idx+2]
      end if
  end function
  function Handle-Query(a, b, c)
                                                                                                       \triangleright O(\log n)
      if a == 1 then
          result \leftarrow \text{Sum-Query}(0, 0, n - 1, b, c)
          if result \leq M then
              PRINT("YES")
```

```
else \operatorname{Print}("\operatorname{NO}") end if \operatorname{else} \ if \ a == 2 \ \operatorname{then} \operatorname{UPDATE}(0,0,n-1,b,c) end if \operatorname{end} \ \operatorname{function} function \operatorname{Eat-SWEETS}(n) > O(n\log n) prices \leftarrow [0]_{4n} \operatorname{BuildTree}(prices,0,0,n-1) for i in range(0,n) do a,b,c \leftarrow input \operatorname{Handle-Query}(a,b,c) end for
```

QP5 Edible Sequence

We first run a modified BFS search on the graph and store the parent child relationships in a $n \times n$ matrix, as well as store the child count of a particular node. Now, we keep two pointers p and q where q points to the (probable) child of p and both of them are iterated over the given sequence and are checked if they are infact parent-child (q is iterated as much times as the child count of p), if not, we return "Not Edible" else "Edible".

We are basically checking nodes from consecutive levels in the BFS tree i.e. V_i, V_{i+1} and whether they occur in order i.e. If 2, 3 occur in this particular order in sequence, then children of 2 should precede that of 3 as well.

Pseudocode:

```
function IsSequenceEdible(T, sequence)
    n \leftarrow \text{length(sequence)}
    parent \leftarrow \{\}
    children \leftarrow \{0\}_n
    q \leftarrow 1
    visited \leftarrow \{\}
    queue \leftarrow Queue()
    start node \leftarrow sequence[0]
    visited[start\ node] \leftarrow True
    queue.enqueue(start node)
    while !queue.isEmpty() do
                                                         \triangleright (BFS) O(|V| + |E|) = O(n + n - 1) = O(n)
        node \leftarrow queue.dequeue()
        for neighbour in T[node] do
            if neighbour not in visited then
                visited[neighbour] \leftarrow True
                queue.enqueue(neighbour)
                parent[node][neighbour] \leftarrow 1
                children[node] \leftarrow children[node] + 1
            end if
        end for
    end while
    for p in range(0, n) do
                                                                                                       \triangleright O(n)
        for i in range(0, children[sequence[p]]) do
            if parent[sequence[p]][sequence[q]] \neq 1 then
                return "Not Edible"
            else
                q \leftarrow q + 1
            end if
        end for
    end for
    return "Edible"
```