

# Combinatorial optimization: Max-Cut, Min UnCut and Sparsest Cut Problems

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# Outline

## 1 Combinatorial Optimization

- Max-Cut
- Min UnCut
- Sparsest Cut

## 2 Approaches

- Naive Algorithm
- SDP relaxations

# Max-Cut Problem

Given an undirected weighted graph  $G = (V, E, W)$ , where

$V = \{1, \dots, n\}$  – set of vertices

$E \subseteq V \times V$  – set of edges

$W : E \rightarrow \mathbb{R}$  – weights

One wants to find a partition  $f : V \rightarrow \{0, 1\}$  in order to maximize the sum of edges in the cut:

$$\sum_{(i,j) \in E: f(i) \neq f(j)} w_{ij} \rightarrow \max,$$

where  $w_{ij}$  stands for weight of the edge  $(i, j)$ .

# Min UnCut Problem

Given an undirected weighted graph  $G = (V, E, W)$ , one wants to find a partition  $f : \{0, 1\}$  in order to minimize the sum of edges out of the cut:

$$\sum_{(i,j) \in E: f(i) \neq f(j)} w_{ij} \rightarrow \min$$

REMARK. Let  $Opt(MUC)$  and  $Opt(MC)$  stand for optimal solutions of Min UnCut and Max-Cut problems respectively. Then it holds

$$Opt(MUC) + Opt(MC) = \sum_{(i,j) \in E} w_{ij}$$

# Sparsest Cut Problem

Given an undirected weighted graph  $G = (V, E)$  and a capacity function  $c : E \rightarrow \mathbb{R}_+$ . Also given a set of demand pairs  $(s_1, t_1), (s_2, t_2), \dots, (s_k, t_k)$  and demand values  $d_1, d_2, \dots, d_k$ . One wants to find a set  $E' \subseteq E$  minimizing

$$\frac{c(E')}{D(E')} \rightarrow \min,$$

where

$$c(f) = \sum_{(i,j) \in E'} c_{ij}$$
$$D(f) = \sum_{i: (s_i, t_i) \text{ are separated by } E'} d_i$$

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Approaches:

- Use naive algorithm of discrete optimization
- Use convex relaxations



# Greedy algorithm

Idea:

- On the  $k$ -th iteration choose a point  $x_{k+1}$  from neighbourhood of the current position  $x_k$ , such that

$$\text{Obj}(x_{k+1}) < \text{Obj}(x_k)$$

- If there is no such point  $x_{k+1}$  stop and return  $x_k$

Problems:

- How to choose the neighbourhood?
- How far will be the result from the solution?

# Semi-Definite-Programming

The following type of optimisation problems is considered to be the SDP problems:

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & c^T x \\ \text{s.t.} \quad & A_0 - x_1 A_1 - \dots - x_n A_n \succeq 0 \end{aligned}$$

# SDP relaxation

Suppose we have the initial problem:

$$\min_{x \in X} f(x),$$

where  $X$  is a feasible region. If we construct the SDP problem with the  $X'$  feasible region, s.t.  $X \subseteq X'$ , then this SDP problem is considered to be an SDP relaxation for the initial problem.

# SDP relaxation with triangle constraints

In order to improve the SDP relaxation one can add triangle constraints like:

$$x_{ij} + x_{jk} + x_{ki} \leq 2,$$

$$x_{ij} + x_{jk} \geq x_{ki}.$$

Such constraints are appropriate for the cut problems on graphs. In these cases  $x_{ij}$  could be:

$$x_{ij} = \begin{cases} 1 & \text{if } (i, j) \text{ edge is in the cut,} \\ 0 & \text{otherwise.} \end{cases}$$

# Interior Point Method

- One can find solutions of SDP-relaxations via interior-point method
- Use log-det barrier function

Thank you for attention!

# SDP relaxation for MaxCut

The following optimisation problem represents the SDP relaxation for MaxCut

$$\begin{aligned} \min_X \quad & \text{tr}(WX), \\ \text{s.t.} \quad & X \succeq 0, \\ & X_{ii} = 1 \quad \forall i. \end{aligned}$$

Here  $W$  is a matrix of weights.

# SDP relaxation for Sparsest cut Problem

Let  $x_e = \mathbb{I}\{e \in E'\}$  and  $y_i$  represents whether or not the pair  $(s_i, t_i)$  should be separated, then we have the following SDP relaxation:

min  $t$

s.t.

$$\begin{pmatrix} t & 1 \\ c^T x & d^T y \end{pmatrix} \succeq 0$$

$$\sum_{e \in p} x_e \geq y_i,$$

$$p \in \mathcal{P}_{s_i t_i}$$

$$1 \geq y_i \geq 0$$

$$i \in \overline{1, k}$$

$$1 \geq x_e \geq 0$$

$$e \in E$$