## 1 Attention exploration (22 points)

Multi-headed self-attention is the core modeling component of Transformers. In this question, we'll get some practice working with the self-attention equations, and motivate why multi-headed self-attention can be preferable to single-headed self-attention. Recall that attention can be viewed as an operation on a query  $q \in \mathbb{R}^d$ , a set of value vectors  $\{v_1, ..., v_n\}$ ,  $v_i \in \mathbb{R}^d$ , and a set of key vectors  $\{k_1, ..., k_n\}$ ,  $k_i \in \mathbb{R}^d$ , specified as follows:

$$c = \sum_{i=1}^{n} v_i \alpha_i \tag{1}$$

$$\alpha_i = \frac{\exp(k_i^T q)}{\sum_{j=1}^n \exp(k_j^T q)} \tag{2}$$

with  $\alpha_i$  termed the "attention weights". Observe that the output  $c \in \mathbb{R}^d$  is an average over the value vectors weighted with respect to  $\alpha_i$ .

- (a) (4 points) Copying in attention. One advantage of attention is that it's particularly easy to "copy" a value vector to the output c. In this problem, we'll motivate why this is the case.
  - i. (1 point) **Explain** why  $\alpha$  can be interpreted as a categorical probability distribution.

Answer: There are n  $\alpha$  scores, each corresponding to a value in a sequence. These scores range from 0 to 1 and can be viewed as probabilities. The scores collectively form a distribution since they are normalized, meaning that their sum totals to 1.

ii. (2 points) The distribution  $\alpha$  is typically relatively "diffuse"; the probability mass is spread out between many different  $\alpha_i$ . However, this is not always the case. **Describe** (in one sentence) under what conditions the categorical distribution  $\alpha$  puts almost all of its weight on some  $\alpha_j$ , where  $j \in \{1, \ldots, n\}$  (i.e.  $\alpha_j \gg \sum_{i \neq j} \alpha_i$ ). What must be true about the query q and/or the keys  $\{k_1, \ldots, k_n\}$ ?

Answer: When the key values  $k_j$  are significantly larger compared to other key values  $k_{i\neq j}$  (i.e.,  $k_j \gg k_i$ , for  $i \in 1, ..., n$  and  $i \neq j$ ), the dot product between the key and the query will be large as well. As a result, the softmax function will assign a higher probability to the large value, concentrating most of its probability mass on that particular key value.

iii. (1 point) Under the conditions you gave in (ii), **describe** what properties the output c might have.

**Answer:** The  $j^{th}$  value will be assigned the highest weight, resulting in a similarity between c and  $v_i$ , denoted as  $c \approx v_i$ .

iv. (1 point) **Explain** (in two sentences or fewer) what your answer to (ii) and (iii) means intuitively.

Answer: When the dot product (similarity) between the key of a particular word (indexed as j) and a given query is significantly larger than the dot products of other words' keys with the same query, the attention output for that word (j) will converge towards its corresponding value. In other words, it can be interpreted as if the value is effectively "transferred" or "replicated" to the output.

- (b) (7 points) **An average of two**. Instead of focusing on just one vector  $v_j$ , a Transformer model might want to incorporate information from *multiple* source vectors. Consider the case where we instead want to incorporate information from **two** vectors  $v_a$  and  $v_b$ , with corresponding key vectors  $k_a$  and  $k_b$ .
  - i. (3 points) How should we combine two d-dimensional vectors  $v_a$ ,  $v_b$  into one output vector c in a way that preserves information from both vectors? In machine learning, one common way to do so is to take the average:  $c = \frac{1}{2}(v_a + v_b)$ . It might seem hard to extract information about the original vectors va and  $v_b$  from the resulting c, but under certain conditions one can do so. In this problem, we'll see why this is the case.

Suppose that although we don't know  $v_a$  or  $v_b$ , we do know that  $v_a$  lies in a subspace A formed by the m basis vectors  $\{a_1, a_2, \ldots, a_m\}$ , while  $v_b$  lies in a subspace B formed by the p basis vectors  $\{b_1, b_2, \ldots, b_p\}$ . (This means that any va can be expressed as a linear combination of its basis vectors, as can  $v_b$ . All basis vectors have norm 1 and orthogonal to each other.)

Additionally, suppose that the two subspaces are orthogonal; i.e.  $a_j^{\top}b_k = 0$  for all j, k. Using the basis vectors  $\{a_1, a_2, \ldots, a_m\}$ , construct a matrix M such that for arbitrary vectors  $v_a \in A$  and  $v_b \in B$ , we can use M to extract  $v_a$  from the sum vector  $s = v_a + v_b$ . In other words, we want to construct M such that for any  $v_a, v_b, M_s = v_a$ .

**Note:** both M and  $v_a$ ,  $v_b$  should be expressed as a vector in  $\mathbb{R}^d$ , not in terms of vectors from A and B.

**Hint:** Given that the vectors  $\{a_1, a_2, \ldots, a_m\}$  are both *orthogonal* and *form a basis* for  $v_a$ , we know that there exist some  $c_1, c_2, \ldots, c_m$  such that  $v_a = c_1 a_1 + c_2 a_2 + \ldots + c_m a_m$ . Can you create a vector of these weights c?

Answer: Let's consider matrices A and B, which contain concatenated basis vectors  $\{a_1, a_2, \ldots, a_m\}$  and  $\{b_1, b_2, \ldots, b_p\}$ , respectively. We want to find a matrix M that satisfies the following conditions: when multiplied with vector  $v_b$ , it results in the zero vector, and when multiplied with vector  $v_a$ , it produces the same vector  $v_a$  in terms of its own space. By observing the properties of the basis vectors, we can see that  $A^{\top}B = 0$  since the dot product of any  $a_i$  and  $b_j$  is zero for all i and j. Additionally,  $A^{\top}A = I$  (the identity matrix) because the dot product of ai with  $a_j$  equals 0 when  $i \neq j$ , and it equals 1 when i = j due to the normalization of the vectors. Now, if we substitute M with  $A^{\top}$  in the equation

$$Mv_a + Mv_b = v_a$$

, we get

$$A^{\top}Ac + A^{\top}Bd = Ic + 0d = c$$

. This means that when we multiply  $A^{\top}$  with vector  $v_a$ , we obtain the original vector c. Therefore, we can conclude that

$$M = A^{\top}$$

satisfies the desired conditions and produces the same result as vector  $v_a$  in terms of its own space ( $\mathbb{R}^d$ ), without explicitly referring to matrices A and B.

ii. (4 points) As before, let  $v_a$  and  $v_b$  be two value vectors corresponding to key vectors  $k_a$  and  $k_b$ , respectively. Assume that (1) all key vectors are orthogonal, so  $k_i^{\top}k_j$  for all  $i \neq j$ ; and (2) all key vectors have norm 1. Find an expression for a query vector q such that  $c \approx \frac{1}{2}(v_a + v_b)$ .

**Answer:** Assume that c is approximated as follows:

$$c \approx \frac{1}{2}\mathbf{v}_a + \frac{1}{2}\mathbf{v}_b$$

This means we want  $\alpha_a \approx 0.5$  and  $\alpha_b \approx 0.5$ , which can be achieved when (whenever  $i \neq a$  and  $i \neq b$ ):

$$\mathbf{k}_a^{\top} q \approx \mathbf{k}_b^{\top} q \gg \mathbf{k}_i^{\top} \mathbf{q}$$

Like explained in the previous question, if the dot product is big, the probability mass will also be big and we want a balanced mass between  $\alpha_a$  and  $\alpha_b$ . q will be largest for

<sup>&</sup>lt;sup>1</sup>Recall that a vector x has norm 1 if  $x^{\top}x = 1$ .

<sup>&</sup>lt;sup>2</sup>Hint: while the softmax function will never exactly average the two vectors, you can get close by using a large scalar multiple in the expression.

 $k_a$  and  $k_b$  when it is a large multiplicative of a vector that contains a component in  $k_a$  direction and in  $k_b$  direction:

$$\mathbf{q} = \beta(\mathbf{k}_a + \mathbf{k}_b), \text{ where } \beta \gg 0$$

Now, since the keys are orthogonal to each other, it is easy to see that:

$$\mathbf{k}_a^{\top} q = \beta; \mathbf{k}_b^{\top} q = \beta; \mathbf{k}_i^{\top} q = 0, \text{ whever } i \neq a \text{ and } i \neq b$$

Thus when we exponentiate, only  $\exp(\beta)$  will matter, because  $\exp(0)$  will be insignificant to the probability mass. We get that:

$$\alpha_a = \alpha_b = \frac{\exp(\beta)}{n - 2 + 2\exp(\beta)} \approx \frac{\exp(\beta)}{2\exp(\beta)} \approx \frac{1}{2}$$
, for  $\beta \gg 0$ 

- (c) (5 points) **Drawbacks of single-headed attention:** In the previous part, we saw how it was *possible* for a single-headed attention to focus equally on two values. The same concept could easily be extended to any subset of values. In this question we'll see why it's not a practical solution. Consider a set of key vectors  $\{k_1, \ldots, k_n\}$  that are now randomly sampled,  $k_i \sim \mathcal{N}(i, \Sigma_i)$ , where the means  $i \in \mathbb{R}^d$  are known to you, but the covariances  $\Sigma_i$  are unknown. Further, assume that the means i are all perpendicular;  $\mu_i^{\mathsf{T}}\mu_j = 0$  if  $i \neq j$ , and unit norm,  $\|\mu_i\| = 1$ .
  - i. (2 points) Assume that the covariance matrices are  $\Sigma_i = \alpha I \forall i \in 1, 2, ..., n$ , for vanishingly small  $\alpha$ . Design a query q in terms of the  $\mu_i$  such that as before,  $c \approx \frac{1}{2}(v_a + v_b)$ , and provide a brief argument as to why it works.

**Answer:** Because the covariance matrix is small,  $k_i$  can be approximately replaced by  $\mu_i$ :

$$k_i \approx \mu_i$$

Since the key vectors  $k_a$  and  $k_b$  are orthogonal to each other, the problem can be reduced to the previous case where all keys were orthogonal. Therefore, the expression for the query vector q remains the same as in the previous case:

$$\mathbf{q} = \beta(\mu_a + \mu_b)$$
, where  $\beta \gg 0$ 

ii. (3 points) Though single-headed attention is resistant to small perturbations in the keys, some types of larger perturbations may pose a bigger issue. Specifically, in some cases, one key vector  $k_a$  may be larger or smaller in norm than the others, while still pointing in the same direction as  $\mu_a$ . As an example, let us consider a covariance for item a as  $\Sigma_a = \alpha I + \frac{1}{2}(\mu_a \mu_a^{\mathsf{T}})$  for vanishingly small  $\alpha$  (as shown in Fig. 1). This causes  $k_a$  to point in roughly the same direction as  $\mu_a$ , but with large variances in magnitude. Further, let  $\Sigma_i = \alpha I$  for all  $i \neq a$ .

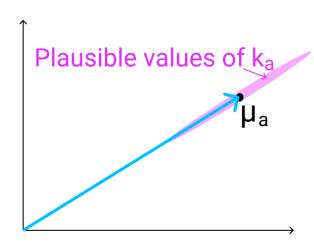


Figure 1: The vector  $\mu_a$  (shown here in 2D as an example), with the range of possible values of  $k_a$  shown in red. As mentioned previously,  $k_a$  points in roughly the same direction as  $\mu_a$ , but may have larger or smaller magnitude.

When you sample  $\{k_1, \ldots, k_n\}$  multiple times, and use the q vector that you defined in part i., what qualitatively do you expect the vector c will look like for different samples?

**Answer:** Since  $\mu_i^{\top} \mu_i = 1$ ,  $\mathbf{k}_a$  varies between  $(\alpha + 0.5)\mu_a$  and  $(\alpha + 1.5)\mu_a$ . All other  $\mathbf{k}_i$ , whenever  $i \neq a$ , almost don't vary at all. Noting that  $\alpha$  is vanishingly small:

$$\mathbf{k}_a \approx \gamma \mu_a$$
, where  $\gamma \sim \mathcal{N}(1, 0.5)$ 

$$\mathbf{k}_i \approx \mu_i$$
, whenever  $i \neq a$ 

Since  $\mathbf{q}$  is most similar in directions  $\mathbf{k}_a$  and  $\mathbf{k}_b$ , we can assume that the dot product between  $\mathbf{q}$  and any other key vector is 0 (since all key vectors are orthogonal). Thus there are 2 cases to consider (note that means are normalized and orthogonal to each other):

$$\mathbf{k}_a^{\mathsf{T}} \mathbf{q} \approx \gamma \mu_a^{\mathsf{T}} \beta (\mu_a + \mu_b) \approx \gamma \beta$$
, where  $\beta \gg 0$ 

$$\mathbf{k}_b^{\top} \mathbf{q} \approx \mu_b^{\top} \beta (\mu_a + \mu_b) \approx \beta$$
, where  $\beta \gg 0$ 

We can now directly solve for coefficients  $\alpha_a$  and  $\alpha_b$ , remembering that for large  $\beta$  values  $\exp(0)$  are insignificant (note how  $\frac{\exp(a)}{\exp(a) + \exp(b)} = \frac{\exp(a)}{\exp(a) + \exp(b)} \frac{\exp(-a)}{\exp(-a)} = \frac{1}{1 + \exp(b-a)}$ ):

$$\alpha_a \approx \frac{\exp(\gamma\beta)}{\exp(\gamma\beta) + \exp(\beta)} \approx \frac{1}{1 + \exp(\beta(1 - \gamma))}$$

$$\alpha_b \approx \frac{\exp(\beta)}{\exp(\beta) + \exp(\gamma\beta)} \approx \frac{1}{1 + \exp(\beta(\gamma - 1))}$$

Since  $\gamma$  varies between 0.5 and 1.5, and since  $\gamma \gg 0$ , we have that:

$$\alpha_a \approx \frac{1}{1+\infty} \approx 0; \quad \alpha_b \approx \frac{1}{1+0} \approx 1; \quad \text{when } \gamma = 0.5$$

$$\alpha_a \approx \frac{1}{1+0} \approx 1; \quad \alpha_b \approx \frac{1}{1+\infty} \approx 0; \quad \text{when } \gamma = 1.5$$

Since  $c \approx \alpha_a \mathbf{v}_a + \alpha_b \mathbf{v}_b$  because other terms are insignificant when  $\beta$  is large, we can see that  $\mathbf{c}$  oscillates between  $\mathbf{v}_a$  and  $\mathbf{v}_b$ :

$$\mathbf{c} \approx \mathbf{v}_b$$
, when  $\gamma \to 0.5$ ;  $\mathbf{c} \approx \mathbf{v}_b$ , when  $\gamma \to 1.5$ 

- (d) (3 points) **Benefits of multi-headed attention:** Now we'll see some of the power of multi-headed attention. We'll consider a simple version of multi-headed attention which is identical to single-headed self-attention as we've presented it in this homework, except two query vectors  $(q_1 \text{ and } q_2)$  are defined, which leads to a pair of vectors  $(c_1 \text{ and } c_2)$ , each the output of single-headed attention given its respective query vector. The final output of the multi-headed attention is their average,  $\frac{1}{2}(c_1 + c_2)$ . As in question 1(c), consider a set of key vectors  $\{k_1, \ldots, k_n\}$  that are randomly sampled,  $k_i \sim \mathcal{N}(\mu_i, \Sigma_i)$ , where the means  $\mu_i$  are known to you, but the covariances  $\Sigma_i$  are unknown. Also as before, assume that the means  $\mu_i$  are mutually orthogonal;  $\mu_i^{\top} \mu_j = 0$  if  $i \neq j$ , and unit norm,  $\|\mu_i\| = 1$ .
  - i. (1 point) Assume that the covariance matrices are  $\Sigma_i = \alpha I$ , for vanishingly small  $\alpha$ . Design  $q_1$  and  $q_2$  such that c is approximately equal to  $\frac{1}{2}(v_a + v_b)$ .

Answer: Under the given assumptions, we can construct two queries,  $q_1$  and  $q_2$ , such that  $q_1$  is designed to replicate  $v_a$  and  $q_2$  replicates  $v_b$ . By setting  $\beta$  to a significantly large value, we can express the queries as  $q_1 = \beta \mu_a$  and  $q_2 = \beta \mu_b$ , where  $\mu_a$  and  $\mu_b$  are the means of  $v_a$  and  $v_b$ , respectively. Since the means are orthogonal, this leads to

the approximations  $c_1 \approx v_a$  and  $c_2 \approx v_b$ . Since multiheaded attention is an average of the two values, we can observe that  $c \approx \frac{1}{2}(v_a + v_b)$ . It's worth noting two additional possibilities: We can also set  $q_1$  to  $\beta \mu_b$  and  $q_2$  to  $\beta \mu_a$ , which would yield the same result but with  $v_a$  and  $v_b$  swapped, resulting in  $c_1 = v_b$  and  $c_2 = v_a$ . Alternatively, we can use the same query design as in the previous question, where  $q_1 = q_2 = \beta(v_a + v_b)$ . In this case,  $c_1 = c_2 = c$ , indicating that the average of equal averages remains the same. These variations demonstrate the flexibility and interchangeability of the queries and their impact on the resulting averages.

ii. (2 points) Assume that the covariance matrices are  $\Sigma_a = \alpha I + \frac{1}{2}(\mu_a \mu_a^{\top})$  for vanishingly small  $\alpha$ , and  $\Sigma_i = \alpha I$  for all  $i \neq a$ . Take the query vectors  $q_1$  and  $q_2$  that you designed in part i.

What, qualitatively, do you expect the output c to look like across different samples of the key vectors? Please briefly explain why. You can ignore cases in which  $k_a^{\top} q_i < 0$ .

**Answer:** With regards to question (c) ii., if we choose  $\mathbf{q}_1 = \beta \mu_a$  and  $\mathbf{q}_2 = \beta \mu_b$ , we get that (note that all other key-query dot products will be insignificant):

$$\mathbf{k}_a^{\mathsf{T}} \mathbf{q}_1 \approx \gamma \mu_a^{\mathsf{T}} \beta \mu_a \approx \gamma \beta, \quad \text{where } \beta \gg 0$$

$$\mathbf{k}_b^{\mathsf{T}} \mathbf{q}_2 \approx \mu_b^{\mathsf{T}} \beta \mu_b \approx \beta$$
, where  $\beta \gg 0$ 

We can solve for  $\alpha$  values (again, note that all other key-query dot products will be insignificant when  $\beta$  is large):

$$\alpha_{a1} \approx \frac{\exp(\gamma \beta)}{\exp(\gamma \beta)} \approx 1; \quad \alpha_{b2} \approx \frac{\exp(\beta)}{\exp(\beta)} \approx 1;$$

Since we can say that  $\alpha_{i1} \approx 0$  for any  $i \neq a$  and  $\alpha_{i2} \approx 0$  for any  $i \neq b$  is is easy to see that:

$$\mathbf{c}_1 \approx \mathbf{v}_a, \quad \mathbf{c}_2 \approx \mathbf{v}_b$$

Which means that the final output will always approximately be an average of the values:

$$\mathbf{c} pprox rac{1}{2} (\mathbf{v}_a + \mathbf{v}_b).$$