# CSS332: Microcontrollers and Applications Midterm Mock Exam

#### curated by The Peanuts

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Conditions: Semi-Closed Book

#### **Directions:**

- 1. This exam has 15 pages (including this page).
- 2. If you finish early, stare at your paper like it's a masterpiece.
- 3. Write your name clearly, even microcontrollers need proper initialization.
- 4. Reading the problem is optional but highly recommended.
- 5. Answers must be written in a structured format. Random noise (scribbles) will not be processed correctly.
- 6. Going to the toilet may deduct your score, hold it like your grades depend on it.

For solution, click here.

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#### Answer the following questions:

Convert binary 1101 1011 to decimal



Convert decimal 123 to binary and hexadecimal



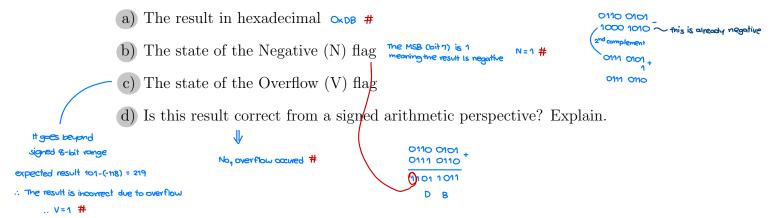
Convert hexadecimal 0xA7 to binary and decimal



For the addition of 8-bit unsigned numbers: 0xF7 + 0x19, determine:

- a) The result in hexadecimal  $\sim$ 140 #
- b) The state of the Carry (C) flag
- c) The state of the Zero (Z) flag
- d) The state of the Half-carry (H) flag #=1 #

For the subtraction of signed 8-bit numbers: 0x65 - 0x8A, determine:



Consider the following AVR assembly program:

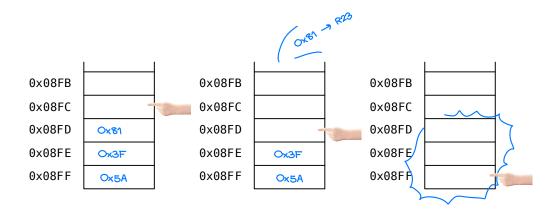
```
LDI R16, HIGH(RAMEND)
OUT SPH, R16
LDI R16, LOW(RAMEND)
OUT SPL, R16

LDI R20, Ox5A
LDI R21, Ox3F
LDI R22, Ox81
PUSH R20
PUSH R21
PUSH R22
POP R23
POP R24
POP R25
```

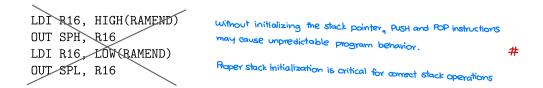
(a) What values will be stored in registers R23, R24, and R25 after executing this program?

```
R23 = 0x81
R24 = 0x3F #
R25 = 0x5A
```

b) Show the values stored and the stack pointer position each time at <u>three</u> <u>points</u>: after all three PUSH instructions, after the first POP instruction, and after all three POP instructions.



c) What would happen if the PUSH and POP instructions were executed without initializing the stack pointer (the first four instructions)? Explain.



Calculate the total time delay (in milliseconds) for the delay subroutine, assuming the microcontroller is running at 16MHz:

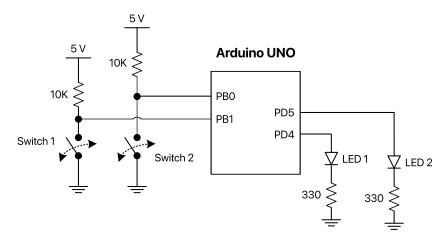
#### DELAY:

```
LDI R20, 160
L1:
    LDI R21, 200
L2:
    LDI R22, 250
L3:
    NOP
    NOP
                        1+ ({1+[{1+(5×250)-1+3}×200]-1+3}×160)-1+4
    DEC R22
    BRNE L3
    DEC R21
    BRNE L2
              2/1
    DEC R20
    BRNE L1
              2/1
    RET
```

Show your calculations step by step, counting instruction cycles accurately.

$$\left[1+\left(\left\{1+\left[\left\{1+\left(5\times250\right)-1+3\right\}\times200\right]-1+3\right\}\times160\right)-1+4\right]\times\frac{1}{16M}=2.506\text{ seconds }\#$$

The circuit below shows an *Arduino UNO* connected to two switches and two LEDs:



Write a complete assembly program that implements the following functionality:

- Correctly configures the I/O pins (PB0, PB1 as inputs with pull-up resistors; PD4, PD5 as outputs)
- When Switch 1 is pressed (closed state, LOW signal), LED 1 turns ON
- When Switch 1 is not pressed (open state, HIGH signal), LED 1 turns OFF
- $\bullet$  Similarly, when Switch 2 is pressed (closed state, LOW signal), LED 2 turns ON
- When Switch 2 is not pressed (open state, HIGH signal), LED 2 turns OFF

```
1
               .ORG 0
 2
               ; Configure LED pins as OUTPUT (PD4, PD5)
 3
                               ; Set PD4 as output (LED 0)
               SBI DDRD, 4
 4
 5
               SBI DDRD, 5
                                ; Set PD5 as output (LED 1)
 6
               ; Turn off LEDs initially
 7
 8
               CBI PORTD, 4
                                ; Ensure LED 0 is OFF
 9
               CBI PORTD, 5
                                ; Ensure LED 1 is OFF
10
               ; Configure switch pins as INPUT with pull-up resistors (PB0, PB1)
11
12
               CBI DDRB, 0
                                ; Set PB0 as input (Switch 0)
               SBI PORTB, 0
13
                                ; Enable pull-up resistor on PB0
14
                                ; Set PB1 as input (Switch 1)
15
               CBI DDRB, 1
               SBI PORTB, 1
                                ; Enable pull-up resistor on PB1
16
17
       AGAIN:
18
19
               ; Check Switch 0 (PB0)
               SBIS PINB, 0
                                ; Skip next instruction if PB0 is HIGH (not pressed)
20
                                ; If PB0 is LOW (pressed), jump to LED_On0
21
               RJMP LED_On0
22
               CBI PORTD, 4
                                ; Otherwise, turn off LED 0
23
               ; Check Switch 1 (PB1)
24
                                ; Skip next instruction if PB1 is HIGH (not pressed)
25
               SBIS PINB, 1
26
               RJMP LED_On1
                                ; If PB1 is LOW (pressed), jump to LED_On1
27
               CBI PORTD, 5
                                 ; Otherwise, turn off LED 1
28
               RJMP AGAIN
29
                                 ; Repeat loop
30
31
       LED_On0:
               SBI PORTD, 4
                                 ; Turn on LED 0 (PD4)
32
33
               RJMP AGAIN
34
35
       LED_On1:
               SBI PORTD, 5
                                ; Turn on LED 1 (PD5)
36
               RJMP AGAIN
37
```

#### Using the 7-segment display pinout provided in the appendix:

Write a complete assembly program that displays your student ID one digit at a time on a common cathode 7-segment display connected to PORTD.

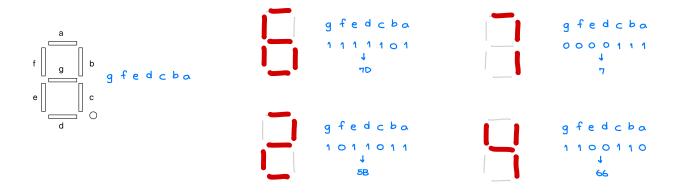
For example, if your student ID is 6622772422, the program should display each digit sequentially with an approximately 2-second delay between digits and loop continuously.

(For the delay subroutine, assume the microcontroller is running at **8MHz** and show your calculation of how many cycles your delay loop requires.)



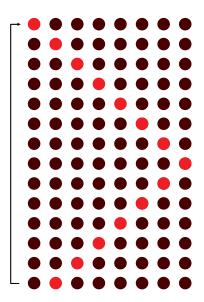
Your student ID has 10 digits. If you store these digits in program memory using the .DB directive, explain whether or not the padding effect will occur. Would you need to add an extra byte? Why or why not?

Rudding effect will not happen because our student ID is 10 digits long, and it's even number, so it's going to be okay since .DB defines bytes in program memory



```
.ORG 0x00
                          ; Set the origin to address 0x00 (start of flash memory)
2
         LDI R16, 0xFF
                            ; Load immediate value 0xFF into register R16
4
         OUT DDRD, R16
                            ; Set all pins of Port D as outputs (DDRD = 0xFF)
6
                            ; Label for the main loop
         LDI ZH, HIGH(0x400); Load the high byte of the address of MYDATA into ZH
         LDI ZL, LOW(0x400) ; Load the low byte of the address of MYDATA into ZL
8
9
                            ; Load loop counter (10 iterations) into R17
         LDI R17, 10
10
11
     AGAIN2:
                            ; Label for the inner loop
12
         LPM R16, Z+
                            ; Load program memory byte from the address in Z (ZL:ZH) into R16, then increment Z
13
         OUT PORTD, R16
                            ; Output the value in R16 to Port D (controlling LEDs or a display)
14
         CALL DELAY
                            ; Call the delay subroutine
15
         DEC R17
                            : Decrement the loop counter R17
16
         BRNE AGAIN2
                            ; Branch if R17 is not zero (loop back to AGAIN2)
                           ; Jump back to the beginning of the main loop (AGAIN1)
17
         JMP AGAIN1
18
19
      ; 2-second delay subroutine
20
      DELAY:
21
         LDI R23, 64
23
         LDI R24, 200
24
25
         LDI R25, 250
26
         NOP
27
28
         DEC R25
29
         BRNE L3
30
31
          DEC R24
32
         BRNE L2
33
         DEC R23
34
         BRNE L1
35
         RET
36
37
      .ORG 0x200
38
39
                            ; My student ID hereeeee...
40
          .DB 0x7D, 0x7D, 0x5B, 0x5B, 0x07, 0x07, 0x5B, 0x66, 0x5B, 0x5B
          X $ 64
```

Write a complete assembly program using macros to create a LED sequence on 8 LEDs connected to PORTD (PD0-PD7). The LEDs should light up in a pattern where a single LED appears to move back and forth across the row of LEDs. Each position change should have approximately 0.5 seconds delay. (assuming the microcontroller is running at 16MHz)



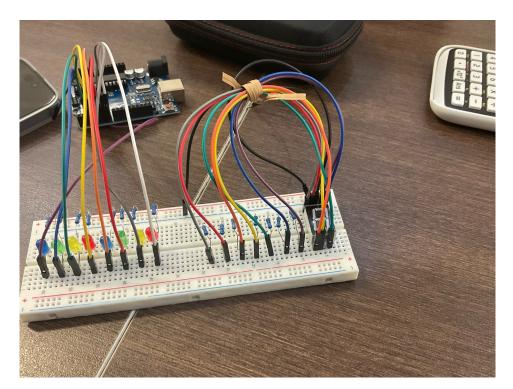
Use the following macros in your program:

```
.MACRO DELAY
LDI R20, @0
L1: LDI R21, @1
L2: LDI R22, @2
L3: NOP
NOP
DEC R22
BRNE L3
DEC R21
BRNE L2
DEC R20
BRNE L1
.ENDMACRO
```

**Draw a complete circuit diagram** showing the connection of 8 LEDs to PORTD (PD0-PD7) of the Arduino Uno board as described in the problem. Your diagram should include:

- 1. Arduino Uno board
- 2. Eight LEDs connected to the pins corresponding to PD0 through PD7
- 3. Current-limiting resistors for each LED (specify resistance value)
- 4. Power connections if needed

Note: Arrange the LEDs in a horizontal row to match the sequential pattern implemented in your assembly program.



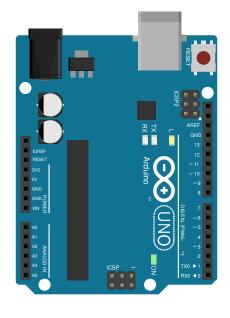
undes. 7

Hint: Use LSL/LSR to shift a single '1' bit left/right to move the LED position, and implement a direction flag (0 or 1) that changes when the LED reaches either PD0 or PD7 to create the back-and-forth effect. Use DELAY X, 200, 250, Calculate X to get approximately 0.5 seconds delay

```
.ORG 0x00
       .MACRO DELAY
          LDI R20, @0
      L1: LDI R21, @1
      L2: LDI R22, @2
      L3: NOP
          DEC R22
10
          BRNE L3
11
          DEC R21
          BRNE L2
12
          DEC R20
13
      .ENDMACRO
      .MACRO SETLED
17
         LDI R16, @0
18
          OUT PORTD, R16
      .ENDMACRO
22
         ; Initialize stack pointer
23
          LDI R16, HIGH(RAMEND)
         OUT SPH, R16
          LDI R16, LOW(RAMEND)
27
         OUT SPL, R16
28
          ; Initialize PORTD as output
29
          LDI R16, 0xFF
                           ; All pins as output
          OUT DDRD, R16
32
          ; Initialize direction flag and LED pattern
33
                          ; Direction: 1=right, 0=left
; Start with LED at PD0
34
          LDI R18, 0x01
          LDI R17, 0x01
38
          ; Output current LED pattern
39
          MOV R16, R17
         OUT PORTD, R16
40
                     make movement visible
        DELAY 32, 200, 250
43
44
          ; Check direction
45
          CPI R18, 0x01
          BRNE GO_LEFT
49
      GO_RIGHT:
          ; Shift LED to the right
50
51
          LSL R17
          ; Check if we've reached PD7
54
          CPI R17, 0x80
          BRNE LOOP
                              : If not at PD7, continue in same directi
55
          ; At PD7, change direction
          LDI R18, 0x00
                             ; Set direction to left
59
          RJMP LOOP
60
      GO_LEFT:
61
          ; Shift LED to the left
62
65
          ; Check if we've reached PD0
          CPI R17, 0x01
66
          BRNE LOOP
                              ; If not at PD0, continue in same directi
          ; At PD0, change direction
70
          LDI R18, 0x01
                              ; Set direction to right
          RJMP LOOP
```

# Appendix

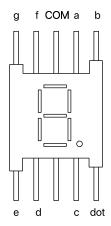
# Arduino UNO Pin Layout

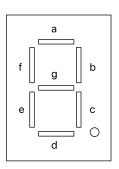


Label	Port
SCL	PC5(ADC5/SCL)
SDA	PC4(ADC4/SDA)
AREF	AREF
GND	GND
13	PB5(SCK)
12	PB4(MISO)
11	PB3(MOSI)
10	PB2(OC1B)
9	PB1(OC1A)
8	PB0
7	PD7
6	PD6
5	PD5
4	PD4
3	PD3(INT1)
2	PD2(INT0)
1	PD1(TXD)
0	PD0(RXD)

Label	Port
AO	PC0(ADC0)
A1	PC1(ADC1)
A2	PC2(ADC2)
А3	PC3(ADC3)
A4	PC4(ADC4)
A5	PC5(ADC5)

# 7-Segment Display Pinout





Number	g	f	е	d	С	b	a
0	0	1	1	1	1	1	1
1	0	0	0	0	1	1	0
2	1	0	1	1	0	1	1
3	1	0	0	1	1	1	1
4	1	1	0	0	1	1	0
5	1	1	0	1	1	0	1
6	1	1	1	1	1	0	1
7	0	0	0	0	0	1	1
8	1	1	1	1	1	1	1
9	1	1	0	1	1	1	1

Mnemonics	Operands	Description	Operation	Flags	#Clock			
Arithmetic and Logic Instructions								
ADD	Rd, Rr	Add two registers	$Rd \leftarrow Rd + Rr$	Z,C,N,V,H	1			
ADC	Rd, Rr	Add with carry	$Rd \leftarrow Rd + Rr + C$	Z,C,N,V,H	1			
ADIW	Rdl, K	Add immediate to word	$Rdh:Rdl \leftarrow Rdh:Rdl + K$	Z,C,N,V,S	2			
SUB	Rd, Rr	Subtract registers	$Rd \leftarrow Rd - Rr$	Z,C,N,V,H	1			
SUBI	Rd, K	Subtract immediate	$Rd \leftarrow Rd - K$	Z,C,N,V,H	1			
SBC	Rd, Rr	Subtract with carry	$Rd \leftarrow Rd - Rr - C$	Z,C,N,V,H	1			
SBCI	Rd, K	Subtract with carry imm.	$Rd \leftarrow Rd - K - C$	Z,C,N,V,H	1			
SBIW	Rdl, K	Subtract imm. from word	$Rdh:Rdl \leftarrow Rdh:Rdl - K$	Z,C,N,V,S	2			
AND	Rd, Rr	Logical AND	$Rd \leftarrow Rd \times Rr$	Z,N,V	1			
ANDI	Rd, K	AND with immediate	$Rd \leftarrow Rd \times K$	Z,N,V	1			
OR	Rd, Rr	Logical OR	$Rd \leftarrow Rd \vee Rr$	Z,N,V	1			
ORI	Rd, K	OR with immediate	$Rd \leftarrow Rd \vee K$	Z,N,V	1			
EOR	Rd, Rr	Exclusive OR	$Rd \leftarrow Rd \oplus Rr$	Z,N,V	1			
COM	Rd	One's complement	$Rd \leftarrow 0xFF - Rd$	Z,C,N,V	1			
NEG	Rd	Two's complement	$Rd \leftarrow 0x00 - Rd$	Z,C,N,V,H	1			
INC	Rd	Increment	$Rd \leftarrow Rd + 1$	Z,N,V	1			
DEC	Rd	Decrement	$Rd \leftarrow Rd - 1$	Z,N,V	1			
Branch Instructions								
RJMP	k	Relative jump	$PC \leftarrow PC + k + 1$	None	2			
JMP	k	Direct jump	$PC \leftarrow k$	None	3			
RCALL	k	Relative call	$PC \leftarrow PC + k + 1$	None	3			
CALL	k	Direct call	$PC \leftarrow k$	None	4			
RET		Return from subroutine	$PC \leftarrow STACK$	None	4			