

CSS322: Scientific Computing Midterm Mock Exam

curated by The Peanuts

Name. [Peanuts12345](#) ID.....Section.....Seat No.....

Conditions: Semi-closed Book

Directions:

1. This exam has 11 pages (including this page).
2. You may bring **two A4 cheat sheets**, written/printed/photocopied on both sides. They must be submitted with your exam paper. Treasure them well, for they will not return.
3. **Calculators** are allowed. Dictionaries are not.
4. Cheating is strictly prohibited.
5. For inspiration you may look at the ceiling, but not at your friend
6. Good luck!

For solution, [click here](#).

Will be available soon, probably the night before the real exam.

Question 1

(a) Let $v = \begin{bmatrix} -3 \\ 2 \\ 0 \\ -5 \end{bmatrix}$. Compute $\|v\|_1$, $\|v\|_2$, and $\|v\|_\infty$.

$$\|v\|_1 = |-3| + |2| + |0| + |-5| = 10$$

$$\|v\|_2 = \sqrt{(-3)^2 + 2^2 + (-5)^2} = \sqrt{9+4+25} = \sqrt{38}$$

$$\|v\|_\infty = \max\{|-3|, |2|, |0|, |-5|\} = 5$$

(b) Let $A = \begin{bmatrix} 2 & -3 & 1 \\ 0 & 4 & -2 \\ -1 & 0 & 3 \end{bmatrix}$. Compute $\|A\|_F$, $\|A\|_1$, and $\|A\|_\infty$.

$$\|A\|_F = \sqrt{2^2 + (-3)^2 + 1^2 + 0^2 + 4^2 + (-2)^2 + (-1)^2 + 0^2 + 3^2} = \sqrt{44} = 2\sqrt{11}$$

$$\|A\|_1 = \max\{|2| + |0| + |-1|, |-3| + |4| + |0|, |1| + |-2| + |3|\} = 7$$

$$\|A\|_\infty = \max\{|2| + |-3| + |1|, |0| + |4| + |-2|, |-1| + |0| + |3|\} = 6$$

Question 2

Perform Gaussian Elimination with Partial Pivoting (GEPP) on the matrix

$$A = \begin{bmatrix} 1 & 4 & 2 \\ 3 & 2 & 1 \\ 2 & -1 & 3 \end{bmatrix}$$

to find its $P^T LU$ factorization.

Step 1

$$A \leftarrow \begin{bmatrix} 1 & 4 & 2 \\ 3 & 2 & 1 \\ 2 & -1 & 3 \end{bmatrix} \quad P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Column 1: Swap Row 1 and Row 2 of A and P (since 3 is max)

$$A \leftarrow \begin{bmatrix} 3 & 2 & 1 \\ 1 & 4 & 2 \\ 2 & -1 & 3 \end{bmatrix} \quad P = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Eliminate Column 1 : Subtract $\frac{1}{3}$ of Row 1 from Row 2

Subtract $\frac{2}{3}$ of Row 1 from Row 3

$$A \leftarrow \begin{bmatrix} 3 & 2 & 1 \\ 0 & 3.33 & 1.67 \\ 0 & -2.33 & 2.33 \end{bmatrix} \quad L \leftarrow \begin{bmatrix} 1 \\ 1/3 \\ 2/3 \end{bmatrix}$$

Eliminate Column 2 : Subtract $\frac{-2.33}{3.33}$ of Row 2 from Row 3

$$A \leftarrow \begin{bmatrix} 3 & 2 & 1 \\ 0 & 3.33 & 1.67 \\ 0 & 0 & 3.5 \end{bmatrix} = U \quad L = \begin{bmatrix} 1 & 0 & 0 \\ 1/3 & 1 & 0 \\ 2/3 & \frac{-2.33}{3.33} & 1 \end{bmatrix} \quad \#$$

$$P = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \#$$

$$\begin{bmatrix} 0 & -2.33 & 2.33 \end{bmatrix} - \frac{-2.33}{3.33} \begin{bmatrix} 0 & 3.33 & 1.67 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 3.5 \end{bmatrix}$$

Question 3

We are solving the linear system

$$A = \begin{bmatrix} 4 & 1 \\ 1 & 3 \end{bmatrix} x = \begin{bmatrix} 6 \\ 5 \end{bmatrix} \quad A x = b$$

and have computed an approximate solution

$$x_0 = \begin{bmatrix} 1.1 \\ 1.9 \end{bmatrix}.$$

Perform one iteration of iterative refinement to obtain a better approximate solution x_1 .

$$\text{Step 1 : } r_0 = b - A x_0 = \begin{bmatrix} 6 \\ 5 \end{bmatrix} - \begin{bmatrix} 4 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1.1 \\ 1.9 \end{bmatrix} = \begin{bmatrix} 4.4 + 1.9 \\ 1.1 + 5.7 \end{bmatrix} = \begin{bmatrix} 6 \\ 5 \end{bmatrix} - \begin{bmatrix} 6.3 \\ 6.8 \end{bmatrix} = \begin{bmatrix} -0.3 \\ -1.8 \end{bmatrix}$$

$$\text{Step 2 : } A s_0 = r_0$$

$$\begin{bmatrix} 4 & 1 \\ 1 & 3 \end{bmatrix} s_0 = \begin{bmatrix} -0.3 \\ -1.8 \end{bmatrix}$$

$$s_0 = A^{-1} r_0 = \frac{1}{11} \begin{bmatrix} 3 & -1 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} -0.3 \\ -1.8 \end{bmatrix} = \frac{1}{11} \begin{bmatrix} -0.9 + 1.8 \\ 0.3 + 7.2 \end{bmatrix} = \begin{bmatrix} 0.9/11 \\ 7.5/11 \end{bmatrix}$$

$$\text{Step 3 : } x_1 = x_0 + s_0 = \begin{bmatrix} 1.1 \\ 1.9 \end{bmatrix} + \begin{bmatrix} 0.9/11 \\ 7.5/11 \end{bmatrix} = \begin{bmatrix} 1.18 \\ 2.5818 \end{bmatrix} \quad \#$$

$$A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \quad ad-bc \neq 0$$

$$= \frac{1}{12-1} \begin{bmatrix} 3 & -1 \\ -1 & 4 \end{bmatrix}$$

$$= \frac{1}{11} \begin{bmatrix} 3 & -1 \\ -1 & 4 \end{bmatrix}$$

Question 4

Given the matrix $A = \begin{bmatrix} 3 & 1 \\ 1 & 2 \end{bmatrix}$:

(a) Find A^{-1} .

$$A = \begin{bmatrix} 3 & 1 \\ 1 & 2 \end{bmatrix}$$

$$A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \quad ad-bc \neq 0$$

Check: $\det(A) = ad-bc = (3)(2) - (1)(1) = 5 \neq 0$ invertible

$$A^{-1} = \frac{1}{5} \begin{bmatrix} 2 & -1 \\ -1 & 3 \end{bmatrix} = \begin{bmatrix} 2/5 & -1/5 \\ -1/5 & 3/5 \end{bmatrix}$$

(b) Compute the condition numbers $\text{cond}_1(A)$ and $\text{cond}_\infty(A)$.

$$\begin{aligned} \text{Cond}_1(A) &= \|A\|_1 \cdot \|A^{-1}\|_1 = 4 \cdot 4.5 = 18 \\ &\quad \downarrow \quad \quad \quad \hookrightarrow \max\{|2/5| + |-1/5|, |-1/5| + |3/5|\} \\ &\quad \quad \quad = 4/5 \end{aligned}$$

$$\begin{aligned} \text{Cond}_\infty(A) &= \|A\|_\infty \cdot \|A^{-1}\|_\infty = 18 \\ &\quad \downarrow \quad \quad \quad \hookrightarrow 4/5 \\ &\quad \quad \quad = 4/5 \end{aligned}$$

Question 5

Find the Cholesky factorization (LL^T factorization) of the symmetric positive definite matrix by the algorithm described in the lecture:

$$A = \begin{bmatrix} 4 & -2 & 2 \\ -2 & 2 & -1 \\ 2 & -1 & 5 \end{bmatrix}$$

Show your calculations step by step.

$$l_{11} = \sqrt{a_{11}} = \sqrt{4} = 2$$

$$l_{21} = a_{21} / l_{11} = -2/2 = -1$$

$$l_{22} = \sqrt{2 - (-1)^2} = \sqrt{2-1} = 1$$

$$L = \begin{pmatrix} 2 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & 0 & 2 \end{pmatrix}$$

$$\begin{matrix} k=3 \\ i=1 \end{matrix} l_{31} = \frac{2-0}{2} = 1$$

$$\begin{matrix} k=3 \\ i=2 \end{matrix} l_{32} = \frac{-1 - (-1)(1)}{1} = 0$$

$$\begin{matrix} k=3 \\ i=3 \end{matrix} l_{33} = \sqrt{5 - 1^2 - 0^2} = \sqrt{4} = 2$$

$$A = LL^T = \begin{pmatrix} 2 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & 0 & 2 \end{pmatrix} \begin{pmatrix} 2 & -1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} 4 & -2 & 2 \\ -2 & 2 & -1 \\ 2 & -1 & 5 \end{pmatrix} \quad \#$$

Question 6 Catastrophic Cancellation

เราจะคำนวณ

$$f(x) = \sqrt{x+1} - \sqrt{x}$$

ถ้า x ใหญ่ ตัวเลขสองตัวที่เราลบกันคือ $\sqrt{x+1}$ กับ \sqrt{x} ซึ่งมีค่า ใกล้เคียงกันมาก
การลบเลขที่เกือบเท่ากัน จะทำให้ "หลักที่เหมือนกันหายไป" เหลือผลต่างเล็กๆ
→ เกิด catastrophic cancellation (ตัวเลขสำคัญหายไปจากการปัดเศษ)

For what range of values of x is it difficult to compute

$$f(x) = \sqrt{x+1} - \sqrt{x}$$

accurately in floating-point arithmetic? Explain why.

algebra • multiply & divide by the conjugation

$$\sqrt{x+1} - \sqrt{x} = \frac{(\sqrt{x+1} - \sqrt{x})(\sqrt{x+1} + \sqrt{x})}{\sqrt{x+1} + \sqrt{x}} = \frac{1}{\sqrt{x+1} + \sqrt{x}}$$

(มีค่าเท่ากับ 1)

↓ test

old formula: $f(9) = \sqrt{10} - \sqrt{9} = 3.1623 - 3 = 0.1623$

New formula: $f(9) = \frac{1}{\sqrt{10} + \sqrt{9}} = \frac{1}{3.1623 + 3} = 0.1623$

for large x

old formula: $f(10^6) = \sqrt{1000001} - \sqrt{1000000} = 0.000499999875$

New formula: $f(10^6) = \frac{1}{\sqrt{1000001} + \sqrt{1000000}} = 0.000499999875$ ← ค่าเดียวกัน แต่ไม่ต้องลบ เลขใหญ่

Cancellation_demo_direct_vs_rationalized

x	direct (float32)	stable (float32)	rel. error direct32	direct (float64)	stable (float64)	rel. error direct64	ref (high-precision)
1.0	0.41421353816986100	0.41421353816986100	5.84317762459163E-08	0.41421356237309500	0.41421356237309500	2.68031548330893E-16	0.41421356237309500
100.0	0.04987525939941410	0.04987562075257300	7.25247060748756E-06	0.049875621120889900	0.04987562112089030	6.53882610691021E-15	0.04987562112089030
10000.0	0.00499725341796875	0.004999875091016290	0.0005243307637855850	0.004999875006248540	0.004999875006249610	2.1302936831789E-13	0.004999875006249610
1000000.0	0.00048828125	0.0004999998491257430	0.023437255859436100	0.0004999998750463420	0.0004999998750000630	9.2558796285644E-11	0.0004999998750000630
100000000.0	0.0	4.99999987368938E-05	1.0	5.00000005558832E-05	4.9999999875E-05	1.36176632106052E-08	4.9999999875E-05
10000000000.0	0.0	4.99999987368938E-06	1.0	4.99999441672117E-06	4.99999999875E-06	1.11663076706565E-06	4.99999999875E-06
1000000000000.0	0.0	4.99999998737621E-07	1.0	5.00003807246685E-07	4.999999999875E-07	7.61449361997803E-06	4.999999999875E-07
100000000000000.0	0.0	5.00000005843049E-08	1.0	5.02914190292358E-08	4.99999999999999E-08	0.005828380584719370	4.99999999999999E-08
1E+16	0.0	4.99999996961265E-09	1.0	0.0	5E-09	1.0	5E-09

ทำไมเป็น

Question 7

Find the Lagrange interpolant $p(t)$ for the following data points:

$$(0, 2), \quad (1, 3), \quad (3, 1), \quad (4, 5)$$

Also, evaluate $p(2)$.

T_n Y

4 data points : $(0, 2), (1, 3), (3, 1), (4, 5) \rightarrow$ use polynomial of degree 3

$$p_3(t) = y_1 l_1(t) + y_2 l_2(t) + y_3 l_3(t) + y_4 l_4(t)$$

$$= 2 l_1(t) + 3 l_2(t) + 1 l_3(t) + 5 l_4(t)$$

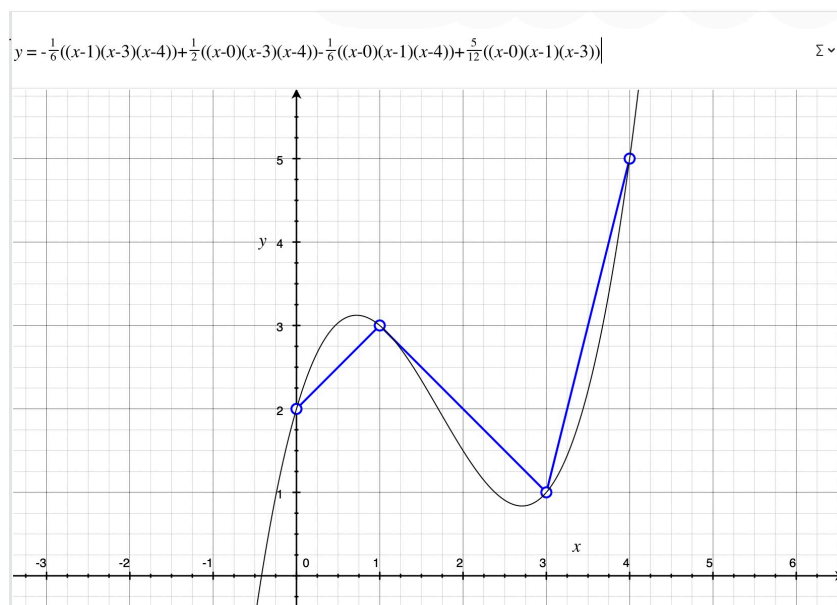
$$l_1(t) = \frac{(t-t_2)(t-t_3)(t-t_4)}{(t_1-t_2)(t_1-t_3)(t_1-t_4)} = \frac{(t-1)(t-3)(t-4)}{(0-1)(0-3)(0-4)} = \frac{(t-1)(t-3)(t-4)}{-12}$$

$$l_2(t) = \frac{(t-t_1)(t-t_3)(t-t_4)}{(t_2-t_1)(t_2-t_3)(t_2-t_4)} = \frac{(t-0)(t-3)(t-4)}{(1-0)(1-3)(1-4)} = \frac{(t-0)(t-3)(t-4)}{6}$$

$$l_3(t) = \frac{(t-t_1)(t-t_2)(t-t_4)}{(t_3-t_1)(t_3-t_2)(t_3-t_4)} = \frac{(t-0)(t-1)(t-4)}{(3-0)(3-1)(3-4)} = \frac{(t-0)(t-1)(t-4)}{-6}$$

$$l_4(t) = \frac{(t-t_1)(t-t_2)(t-t_3)}{(t_4-t_1)(t_4-t_2)(t_4-t_3)} = \frac{(t-0)(t-1)(t-3)}{(4-0)(4-1)(4-3)} = \frac{(t-0)(t-1)(t-3)}{12}$$

$$p_3(t) = 2 \frac{(t-1)(t-3)(t-4)}{-12} + 3 \frac{(t-0)(t-3)(t-4)}{6} + 1 \frac{(t-0)(t-1)(t-4)}{-6} + 5 \frac{(t-0)(t-1)(t-3)}{12} \quad \#$$



Question 8

Suppose we have the following six data points:

$$(-1, 3), \quad (0, -2), \quad (1, 1), \quad (2, 5), \quad (3, -4), \quad (5, 8)$$

- (a) Set up the linear system that needs to be solved in order to compute the polynomial interpolant in Newton basis for the above data points. Write the full matrix equation $Ax = b$. No need to solve the system.

6 data points \rightarrow Newton polynomial of degree 5

$$P_5(t) = x_1 + x_2(t-t_1) + x_3(t-t_1)(t-t_2) + x_4(t-t_1)(t-t_2)(t-t_3) + x_5(t-t_1)(t-t_2)(t-t_3)(t-t_4) + x_6(t-t_1)(t-t_2)(t-t_3)(t-t_4)(t-t_5)$$

$$P_5(t) = x_1 + x_2(t-(-1)) + x_3(t-(-1))(t-0) + x_4(t-(-1))(t-0)(t-1) + x_5(t-(-1))(t-0)(t-1)(t-2) + x_6(t-(-1))(t-0)(t-1)(t-2)(t-3)$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 2 & 2 & 0 & 0 & 0 \\ 1 & 3 & 6 & 6 & 0 & 0 \\ 1 & 4 & 12 & 24 & 24 & 0 \\ 1 & 6 & 30 & 120 & 360 & 720 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} 3 \\ -2 \\ 1 \\ 5 \\ -4 \\ 8 \end{bmatrix} \quad x = \begin{bmatrix} 3 \\ -5 \\ 4 \\ -7/6 \\ -7/24 \\ 2/9 \end{bmatrix}$$

1 ตลอดไป

$$P_5(t) = 3 - 5(t+1) + 4(t+1)(t-0) - \frac{7}{6}(t+1)(t-0)(t-1) - \frac{7}{24}(t+1)(t-0)(t-1)(t-2) + \frac{2}{9}(t+1)(t-0)(t-1)(t-2)(t-3) \quad \#$$

- (b) What algorithm should be used to solve this system and why? What is its computational complexity?

Structure of the system

- The interpolation system in the Newton basis always produces a **lower triangular** matrix A .
- Each row corresponds to evaluating $N_i(x)$ at a data point x_i .
- Since all entries above the diagonal are zero, the matrix is **triangular and nonsingular** (because x_i are distinct).

forward Substitution, $O(n^2)$

อัน Cheatsheet

(b) Algorithm

- The correct algorithm is **forward substitution** (sometimes called forward elimination).

Reason: For lower-triangular systems $Lx = b$, forward substitution allows solving coefficient-by-coefficient sequentially without Gaussian elimination or matrix inversion.

- Each step requires only a few multiplications and additions.

Complexity

- For an $n \times n$ lower-triangular system, forward substitution requires about $\frac{1}{2}n^2$ arithmetic operations.
- So the computational complexity is $O(n^2)$.

Answer (concise form):

Use **forward substitution** because the matrix is lower-triangular. The algorithm works in $O(n^2)$ time, much faster than Gaussian elimination ($O(n^3)$).

Question 9

$$e^{-2t}$$

Consider interpolating $f(t) = e^{-2t}$ with a polynomial of degree 2, using sample points at $t = 0, 0.5, 1$. Give a reasonably tight upper bound on the error of the interpolant over the interval $[0, 1]$. **Hint:** The derivative of e^{-x} is $-e^{-x}$

$$t = 0, 0.5, 1 \rightarrow n = 3$$

$$h = \max \{0.5 - 0, 1 - 0.5\} = 0.5$$

Finding M (diff min)

$$f'(t) = -2e^{-2t}$$

$$f''(t) = 4e^{-2t}$$

$$f'''(t) = -8e^{-2t}$$

$$\text{for all } t \in [0, 1]$$

เลือกค่าจาก Domain ที่ทำให้ได้ค่ามากที่สุด

$$|f'''(t)| = |-8e^{-2t}| \leq |-8e^{-2(0)}| = 8e^0 = 8 = M = 8e^{-2(1)} = 1.083 \times$$

$$\frac{Mh^n}{4n} = \frac{8e^0(0.5)^3}{4(3)} \approx \frac{1}{12} \approx 0.0833$$

Question 10 ยากเกินไม่ทำออก / เหลือห จะวิธีใช้ Matrix

- (a) Use the method of undetermined coefficients to derive a 3-point quadrature rule on the interval $[a, b]$ using

$$n=3$$

$$x_1 = a, \quad x_2 = \frac{a+b}{2}, \quad x_3 = b$$

Set up the system of equations and solve for the weights.

$$\int_a^b f(x) dx \approx \omega_1 f(x_1) + \omega_2 f(x_2) + \omega_3 f(x_3)$$

Find $\omega_1, \omega_2, \omega_3 \rightarrow$ polynomials of degree ≤ 2 (since 3 points)

$$1) f(x) = 1$$

$$\int_a^b 1 dx = b-a = \omega_1 + \omega_2 + \omega_3 = 2\omega + \omega_2 \Rightarrow \omega_2 = (b-a) - 2\omega \quad (1)$$

$$2) f(x) = x$$

$$\int_a^b x dx = \frac{b^2-a^2}{2} = a\omega_1 + \frac{a+b}{2}\omega_2 + b\omega_3$$

$$\text{collect } \omega \quad \text{using: } a^2+b^2 - \frac{(a+b)^2}{2} = \frac{(a-b)^2}{2}$$

$$3) f(x) = x^2$$

$$\int_a^b x^2 dx = \frac{b^3-a^3}{3} = a^2\omega_1 + \left(\frac{a+b}{2}\right)^2\omega_2 + b^2\omega_3 \quad \text{from (1): } a^2\omega + \left(\frac{a+b}{2}\right)^2((b-a)-2\omega) + b^2\omega \Rightarrow \omega \cdot \frac{(a-b)^2}{2} + \frac{(a+b)^2}{4}(b-a) = \frac{b^3-a^3}{3}$$

- (b) Apply your quadrature rule from part (a) to approximate $\int_0^2 x^2 dx$. Let $h=b-a$, $s=a+b$

<p>$a=0, b=2 \rightarrow \frac{a+b}{2} = 1$</p> <p>$x_1=0, x_2=1, x_3=2$</p> <p>Approximate:</p> $\int_0^2 x^2 dx \approx \omega_1 f(0) + \omega_2 f(1) + \omega_3 f(2)$ <p>$\downarrow f(0)=0, f(1)=1, f(2)=4$</p> $= \frac{1}{3} \cdot 0 + \frac{4}{3} \cdot 1 + \frac{1}{3} \cdot 4 = \frac{8}{3} \quad \#$	<p>$\omega = \frac{b-a}{6} = \frac{1}{3}$</p> <p>$\omega_2 = (b-a) - 2\frac{(b-a)}{6} = (b-a)\left(1 - \frac{1}{3}\right) = \frac{2}{3}(b-a) \quad \#$</p>	<p>$\omega \cdot \frac{h}{2} = \frac{a^2 - 2ab + b^2}{12}$</p> <p>$(a-b)^2 = (b-a)^2 = h^2$</p> <p>$\omega \cdot \frac{h}{2} = \frac{h^2}{12}$</p> <p>$6\omega = h$</p> <p>$\omega = \frac{h}{6}$</p> <p>$\omega_1 = \omega_3 =: \omega = \frac{b-a}{6} \quad \#$</p>	<p>Since $b^3 - a^3 = h(a^2 + ab + b^2)$</p> <p>divide both side by h ($a \neq b$)</p> $\omega \cdot \frac{h}{2} + \frac{s^2}{4} = \frac{a^2 + ab + b^2}{3}$ $\omega \cdot \frac{h}{2} + \frac{a^2 + 2ab + b^2}{4} = \frac{a^2 + ab + b^2}{3}$ $\omega \cdot \frac{h}{2} = \frac{a^2 + ab + b^2}{3} - \frac{a^2 + 2ab + b^2}{4}$ $\omega \cdot \frac{h}{2} = \frac{4a^2 + 4ab + 4b^2 - 3a^2 - 6ab - 3b^2}{12}$
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- (c) Compare your result with the exact value of the integral.

• Exact Value

$$\int_0^2 x^2 dx = \left. \frac{x^3}{3} \right|_0^2 = \frac{8}{3}$$

$$\text{Error} = \left| \frac{8}{3} - \frac{8}{3} \right| = 0 \quad \#$$

$$\frac{2^3}{3} - \frac{0^3}{3} = \frac{8}{3}$$

ทำไมบอกว่า $\omega_1 = \omega_3$?

- เพราะตำแหน่งของจุด a และ b สมมาตร กันรอบจุดกึ่งกลาง $\frac{a+b}{2}$.
- ใน numerical integration ถ้าจุดอยู่ "สมมาตร" แบบนี้ ค่า weight (น้ำหนัก) ก็ต้องเท่ากันด้วย ไม่งั้นสูตรจะไม่ "บาลานซ์" รอบกึ่งกลาง
- ☞ เช่น ถ้าเราให้ด้านซ้าย (ที่ a) นหนักกว่าด้านขวา (ที่ b) ทั้งที่อยู่ห่างกึ่งกลางเท่ากัน มันก็จะไม่ถูกต้อง

ดังนั้น เราจึงได้เลยว่า

$$\omega_1 = \omega_3 =: \omega.$$

วิธีใช้เมทริกซ์หาค่าเวท (weights)

ให้จุดเก็บตัวอย่าง 3 จุดบนช่วง $[a, b]$:

$$x_1 = a, \quad x_2 = m = \frac{a+b}{2}, \quad x_3 = b$$

และต้องการ

$$\int_a^b f(x) dx \approx w_1 f(a) + w_2 f(m) + w_3 f(b).$$

บังคับให้ "อินทิเกรตได้ตรง" สำหรับพหุนาม $1, x, x^2$:

$$\int_a^b 1 dx = b - a = w_1 + w_2 + w_3,$$

$$\int_a^b x dx = \frac{b^2 - a^2}{2} = a w_1 + m w_2 + b w_3,$$

$$\int_a^b x^2 dx = \frac{b^3 - a^3}{3} = a^2 w_1 + m^2 w_2 + b^2 w_3.$$

เขียนเป็นเมทริกซ์ $A\mathbf{w} = \mathbf{b}$:

$$\begin{bmatrix} 1 & 1 & 1 \\ a & m & b \\ a^2 & m^2 & b^2 \end{bmatrix} A \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} \mathbf{w} \begin{bmatrix} b-a \\ \frac{b^2-a^2}{2} \\ \frac{b^3-a^3}{3} \end{bmatrix} \mathbf{b}$$

แก้ระบบ (ใช้เกาส์/อินเวอร์สก็ได้) จะได้คำตอบทั่วไป:

$$w_1 = w_3 = \frac{b-a}{6}, \quad w_2 = \frac{2}{3}(b-a)$$

ซึ่งก็คือกฎซิมป์สันแบบ 1/3

ตัวอย่างช่วง $[0, 2]$

$$a = 0, \quad b = 2, \quad m = 1$$

เมทริกซ์และเวกเตอร์:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 1 & 4 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 2 \\ 2 \\ \frac{8}{3} \end{bmatrix}.$$

แก้ได้

$$\mathbf{w} = \begin{bmatrix} \frac{1}{3} \\ [2pt] \frac{4}{3} \\ [2pt] \frac{1}{3} \end{bmatrix},$$

ดังนั้น

$$\int_0^2 f(x) dx \approx \frac{1}{3} f(0) + \frac{4}{3} f(1) + \frac{1}{3} f(2).$$