

CSS332: Microcontrollers and Applications

Midterm Mock Exam

curated by The Peanuts

Name. Nonprawich I ID. 6622772422 Section.....Seat No.....

Conditions: Semi-Closed Book

Directions:

1. This exam has 15 pages (including this page).
2. If you finish early, stare at your paper like it's a masterpiece.
3. Write your name clearly, even microcontrollers need proper initialization.
4. Reading the problem is optional but highly recommended.
5. Answers must be written in a structured format. Random noise (scribbles) will not be processed correctly.
6. Going to the toilet may deduct your score, hold it like your grades depend on it.

For solution, [click here](#).

Problem 1

↗ မှတ်မိရန်အတွက်

Answer the following questions:

Convert binary 1101 1011 to decimal

219₁₀ #

Convert decimal 123 to binary and hexadecimal

0111011₂ #
7B₁₆ #

Convert hexadecimal 0xA7 to binary and decimal

10100111₂ #
167₁₀ #

Problem 2

$$\begin{array}{r}
 \begin{array}{cc}
 \overset{1111}{1111} & \overset{111}{0111} \\
 0001 & 1001 \\
 + & \\
 1 & 00010000
 \end{array}
 \end{array}$$

For the addition of 8-bit unsigned numbers: $0xF7 + 0x19$, determine:

- a) The result in hexadecimal $0x110$ #
- b) The state of the Carry (C) flag $C=1$ #
- c) The state of the Zero (Z) flag $Z=0$ #
- d) The state of the Half-carry (H) flag $H=1$ #

For the subtraction of signed 8-bit numbers: $0x65 - 0x8A$, determine:

- a) The result in hexadecimal $0xDB$ #
- b) The state of the Negative (N) flag $N=1$ #
- c) The state of the Overflow (V) flag
- d) Is this result correct from a signed arithmetic perspective? Explain.

It goes beyond signed 8-bit range
 expected result $101 - (-118) = 219$
 \therefore The result is incorrect due to overflow
 $\therefore V=1$ #

\Downarrow
 No, overflow occurred #

$$\begin{array}{r}
 0110 \ 0101 \\
 0111 \ 0110 \\
 + \\
 \hline
 1101 \ 1011 \\
 \text{D} \quad \text{B}
 \end{array}$$

$$\begin{array}{r}
 0110 \ 0101 \\
 - \\
 1000 \ 1010 \\
 \hline
 0111 \ 0101 \\
 \text{1} \\
 0111 \ 0110
 \end{array}$$

~ this is already negative
 2nd complement

Problem 3

Consider the following AVR assembly program:

```
.ORG 0
LDI R16, HIGH(RAMEND)
OUT SPH, R16
LDI R16, LOW(RAMEND)
OUT SPL, R16

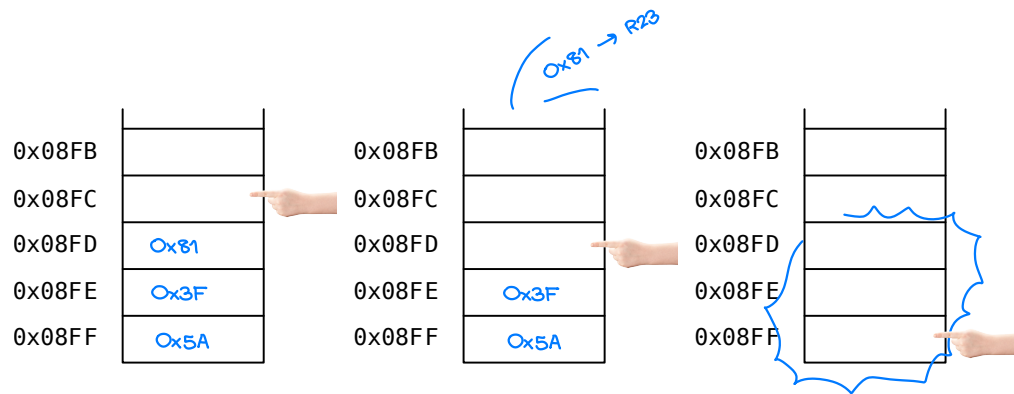
LDI R20, 0x5A
LDI R21, 0x3F
LDI R22, 0x81
PUSH R20
PUSH R21
PUSH R22
POP R23
POP R24
POP R25
```

- a) What values will be stored in registers R23, R24, and R25 after executing this program?

R23 = 0x81
R24 = 0x3F #
R25 = 0x5A

garm stack of registers?

- b) Show the values stored and the stack pointer position each time at three points: after all three PUSH instructions, after the first POP instruction, and after all three POP instructions.



- c) What would happen if the PUSH and POP instructions were executed without initializing the stack pointer (the first four instructions)? Explain.

```
LDI R16, HIGH(RAMEND)
OUT SPH, R16
LDI R16, LOW(RAMEND)
OUT SPL, R16
```

Without initializing the stack pointer, PUSH and POP instructions may cause unpredictable program behavior.

Proper stack initialization is critical for correct stack operations

#

Problem 4

Calculate the total time delay (in milliseconds) for the delay sub-routine, assuming the microcontroller is running at 16MHz:

DELAY:

```

LDI R20, 160
L1:
    LDI R21, 200
L2:
    LDI R22, 250
L3:
    NOP      1
    NOP      1
    DEC R22   1
    BRNE L3  2/1
    DEC R21   1
    BRNE L2  2/1
    DEC R20   1
    BRNE L1  2/1
    RET      4
  
```

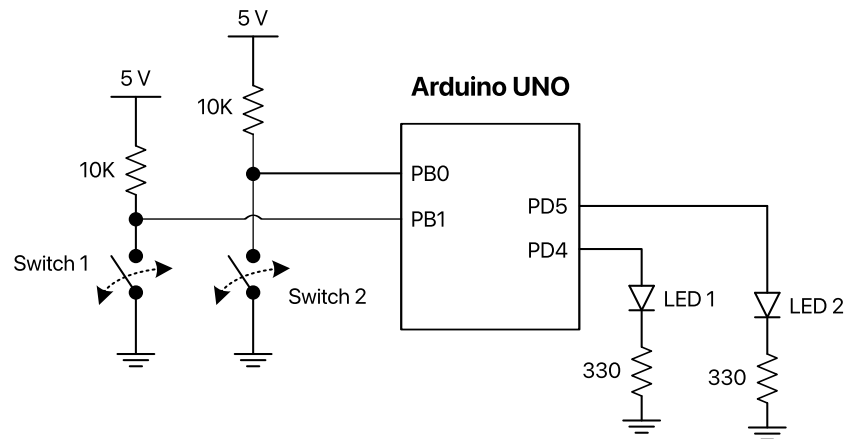
$$1 + \left(\left\{ 1 + \left[\left\{ 1 + (5 \times 250) - 1 + 3 \right\} \times 200 \right] - 1 + 3 \right\} \times 160 \right) - 1 + 4$$

Show your calculations step by step, counting instruction cycles accurately.

$$\left[1 + \left(\left\{ 1 + \left[\left\{ 1 + (5 \times 250) - 1 + 3 \right\} \times 200 \right] - 1 + 3 \right\} \times 160 \right) - 1 + 4 \right] \times \frac{1}{16M} = 2.506 \text{ seconds} \#$$

Problem 5

The circuit below shows an *Arduino UNO* connected to two switches and two LEDs:



Write a complete assembly program that implements the following functionality:

- Correctly configures the I/O pins (PB0, PB1 as inputs with pull-up resistors; PD4, PD5 as outputs)
- When Switch 1 is pressed (closed state, LOW signal), LED 1 turns ON
- When Switch 1 is not pressed (open state, HIGH signal), LED 1 turns OFF
- Similarly, when Switch 2 is pressed (closed state, LOW signal), LED 2 turns ON
- When Switch 2 is not pressed (open state, HIGH signal), LED 2 turns OFF

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```
1      .ORG 0
2
3      ; Configure LED pins as OUTPUT (PD4, PD5)
4      SBI DDRD, 4      ; Set PD4 as output (LED 0)
5      SBI DDRD, 5      ; Set PD5 as output (LED 1)
6
7      ; Turn off LEDs initially
8      CBI PORTD, 4      ; Ensure LED 0 is OFF
9      CBI PORTD, 5      ; Ensure LED 1 is OFF
10
11     ; Configure switch pins as INPUT with pull-up resistors (PB0, PB1)
12     CBI DDRB, 0      ; Set PB0 as input (Switch 0)
13     SBI PORTB, 0      ; Enable pull-up resistor on PB0
14
15     CBI DDRB, 1      ; Set PB1 as input (Switch 1)
16     SBI PORTB, 1      ; Enable pull-up resistor on PB1
17
18     AGAIN:
19     ; Check Switch 0 (PB0)
20     SBIS PINB, 0      ; Skip next instruction if PB0 is HIGH (not pressed)
21     RJMP LED_On0      ; If PB0 is LOW (pressed), jump to LED_On0
22     CBI PORTD, 4      ; Otherwise, turn off LED 0
23
24     ; Check Switch 1 (PB1)
25     SBIS PINB, 1      ; Skip next instruction if PB1 is HIGH (not pressed)
26     RJMP LED_On1      ; If PB1 is LOW (pressed), jump to LED_On1
27     CBI PORTD, 5      ; Otherwise, turn off LED 1
28
29     RJMP AGAIN        ; Repeat loop
30
31     LED_On0:
32     SBI PORTD, 4      ; Turn on LED 0 (PD4)
33     RJMP AGAIN
34
35     LED_On1:
36     SBI PORTD, 5      ; Turn on LED 1 (PD5)
37     RJMP AGAIN
```


Problem 6

Using the 7-segment display pinout provided in the appendix:

Write a complete assembly program that displays your student ID one digit at a time on a common cathode 7-segment display connected to PORTD.

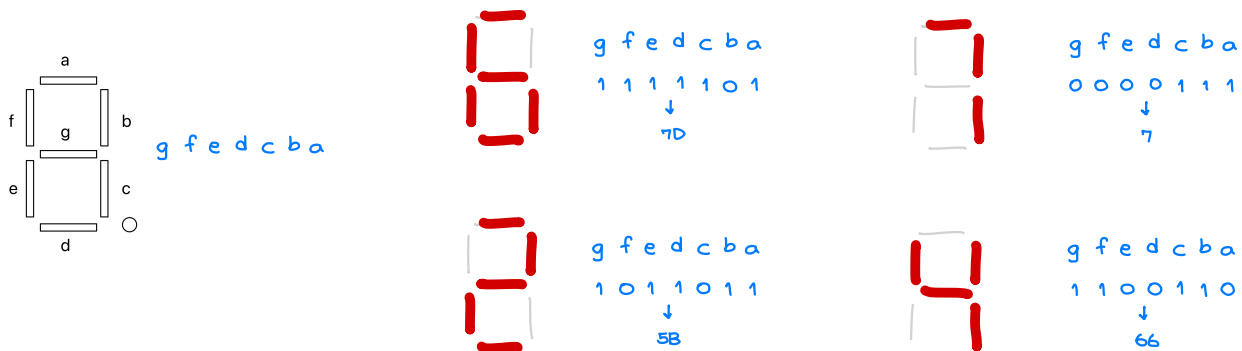
For example, if your student ID is 6622772422, the program should display each digit sequentially with an approximately 2-second delay between digits and loop continuously.

(For the delay subroutine, assume the microcontroller is running at 8MHz and show your calculation of how many cycles your delay loop requires.)



Your student ID has 10 digits. If you store these digits in program memory using the .DB directive, explain whether or not the padding effect will occur. Would you need to add an extra byte? Why or why not?

Padding effect will not happen because our student ID is 10 digits long, and it's even number, so it's going to be okay since .DB defines bytes in program memory



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```

1  .ORG 0x00          ; Set the origin to address 0x00 (start of flash memory)
2
3      LDI R16, 0xFF    ; Load immediate value 0xFF into register R16
4      OUT DDRD, R16    ; Set all pins of Port D as outputs (DDRD = 0xFF)
5
6  AGAIN1:            ; Label for the main loop
7      LDI ZH, HIGH(0x400) ; Load the high byte of the address of MYDATA into ZH
8      LDI ZL, LOW(0x400) ; Load the low byte of the address of MYDATA into ZL
9      LDI R17, 10      ; Load loop counter (10 iterations) into R17
10
11     AGAIN2:         ; Label for the inner loop
12     LPM R16, Z+      ; Load program memory byte from the address in Z (ZL:ZH) into R16, then increment Z
13     OUT PORTD, R16   ; Output the value in R16 to Port D (controlling LEDs or a display)
14     CALL DELAY       ; Call the delay subroutine
15     DEC R17          ; Decrement the loop counter R17
16     BRNE AGAIN2      ; Branch if R17 is not zero (loop back to AGAIN2)
17     JMP AGAIN1       ; Jump back to the beginning of the main loop (AGAIN1)
18
19     ; 2-second delay subroutine
20     DELAY:
21     LDI R23, 64
22     L1:
23     LDI R24, 200
24     L2:
25     LDI R25, 250
26     L3:
27     NOP
28     NOP
29     DEC R25
30     BRNE L3
31     DEC R24
32     BRNE L2
33     DEC R23
34     BRNE L1
35     RET
36
37     .ORG 0x200
38
39     MYDATA:          ; My student ID hereeeee...
40     .DB 0x7D, 0x7D, 0x5B, 0x5B, 0x07, 0x07, 0x5B, 0x66, 0x5B, 0x5B

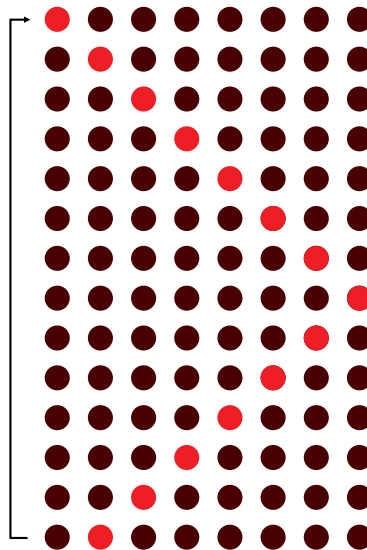
```

$$\left[1 + \left(\left\{ 1 + \left[1 + (5 \times 250) - 1 + 3 \right] \times 200 \right\} - 1 + 3 \right) \times X \right] - 1 + 4 \times \frac{1}{8M} = 2 \text{ seconds}$$

$$X \approx 64$$

Problem 7

Write a complete assembly program using macros to create a LED sequence on 8 LEDs connected to PORTD (PD0-PD7). The LEDs should light up in a pattern where a single LED appears to move back and forth across the row of LEDs. Each position change should have approximately 0.5 seconds delay. (assuming the microcontroller is running at 16MHz)



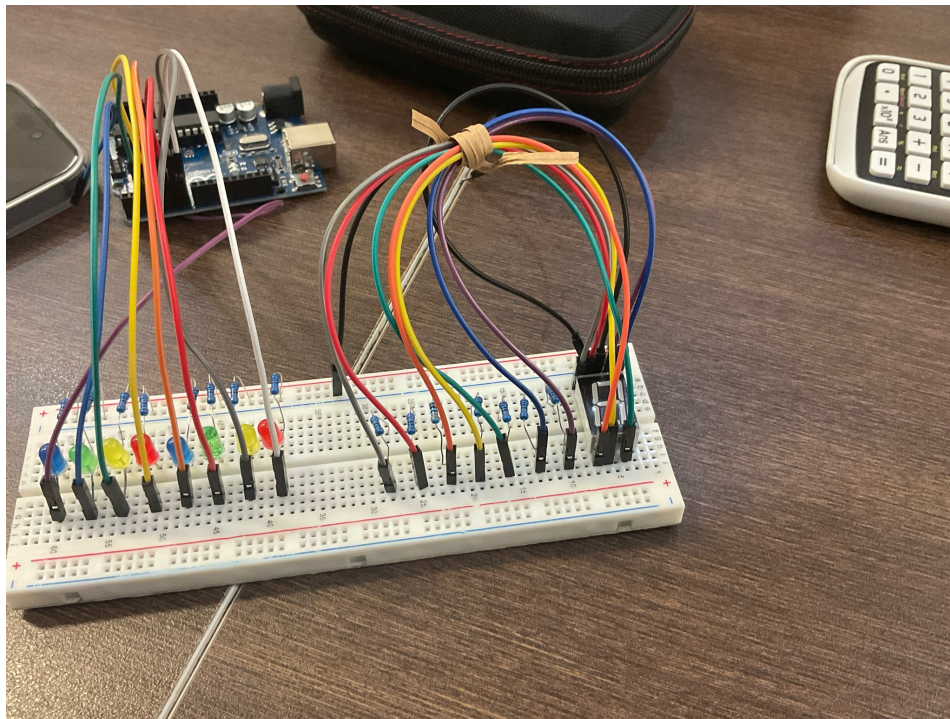
Use the following macros in your program:

```
.MACRO DELAY
    LDI R20, @0
L1: LDI R21, @1
L2: LDI R22, @2
L3: NOP
    NOP
    DEC R22
    BRNE L3
    DEC R21
    BRNE L2
    DEC R20
    BRNE L1
.ENDMACRO
```

Draw a complete circuit diagram showing the connection of 8 LEDs to PORTD (PD0-PD7) of the Arduino Uno board as described in the problem. Your diagram should include:

1. Arduino Uno board
2. Eight LEDs connected to the pins corresponding to PD0 through PD7
3. Current-limiting resistors for each LED (specify resistance value)
4. Power connections if needed

Note: Arrange the LEDs in a horizontal row to match the sequential pattern implemented in your assembly program.



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Hint: Use LSL/LSR to shift a single '1' bit left/right to move the LED position, and implement a direction flag (0 or 1) that changes when the LED reaches either PD0 or PD7 to create the back-and-forth effect. Use DELAY X, 200, 250, Calculate X to get approximately 0.5 seconds delay

```

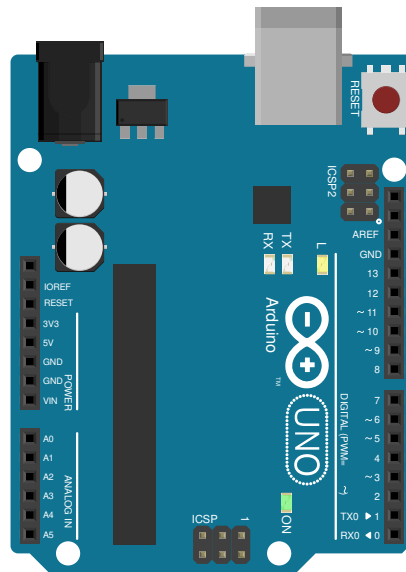
1  .ORG 0x00
2
3  .MACRO DELAY
4      LDI R20, @0
5      L1: LDI R21, @1
6      L2: LDI R22, @2
7      L3: NOP
8          NOP
9          DEC R22
10         BRNE L3
11         DEC R21
12         BRNE L2
13         DEC R20
14         BRNE L1
15     .ENDMACRO
16
17     MAIN:
18         ; Initialize stack pointer
19         LDI R16, HIGH(RAMEND)
20         OUT SPH, R16
21         LDI R16, LOW(RAMEND)
22         OUT SPL, R16
23
24         ; Initialize PORTD as output
25         LDI R16, 0xFF ; All pins as output
26         OUT DDRD, R16
27
28         ; Initialize direction flag and LED pattern
29         LDI R18, 0x01 ; Direction: 1=right, 0=left
30         LDI R17, 0x01 ; Start with LED at PD0
31
32     LOOP:
33         ; Output current LED pattern
34         MOV R16, R17
35         OUT PORTD, R16
36
37         ; Delay to make movement visible
38         DELAY 32, 200, 250
39
40         ; Check direction
41         CPI R18, 0x01
42         BRNE GO_LEFT
43
44     GO_RIGHT:
45         ; Shift LED to the right
46         LSL R17
47
48         ; Check if we've reached PD7
49         CPI R17, 0x80
50         BRNE LOOP ; If not at PD7, continue in same direction
51
52         ; At PD7, change direction
53         LDI R18, 0x00 ; Set direction to left
54         RJMP LOOP
55
56     GO_LEFT:
57         ; Shift LED to the left
58         LSR R17
59
60         ; Check if we've reached PD0
61         CPI R17, 0x01
62         BRNE LOOP ; If not at PD0, continue in same direction
63
64         ; At PD0, change direction
65         LDI R18, 0x01 ; Set direction to right
66         RJMP LOOP

```

Appendix

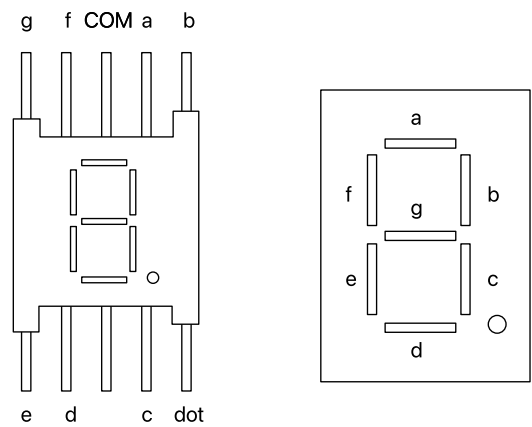
Arduino UNO Pin Layout

| Label | Port |
|-------|-----------|
| A0 | PC0(ADC0) |
| A1 | PC1(ADC1) |
| A2 | PC2(ADC2) |
| A3 | PC3(ADC3) |
| A4 | PC4(ADC4) |
| A5 | PC5(ADC5) |



| Label | Port |
|-------|---------------|
| SCL | PC5(ADC5/SCL) |
| SDA | PC4(ADC4/SDA) |
| AREF | AREF |
| GND | GND |
| 13 | PB5(SCK) |
| 12 | PB4(MISO) |
| 11 | PB3(MOSI) |
| 10 | PB2(OC1B) |
| 9 | PB1(OC1A) |
| 8 | PB0 |
| 7 | PD7 |
| 6 | PD6 |
| 5 | PD5 |
| 4 | PD4 |
| 3 | PD3(INT1) |
| 2 | PD2(INT0) |
| 1 | PD1(TXD) |
| 0 | PD0(RXD) |

7-Segment Display Pinout



| Number | g | f | e | d | c | b | a |
|--------|---|---|---|---|---|---|---|
| 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 0 | 1 | 1 | 0 |
| 2 | 1 | 0 | 1 | 1 | 0 | 1 | 1 |
| 3 | 1 | 0 | 0 | 1 | 1 | 1 | 1 |
| 4 | 1 | 1 | 0 | 0 | 1 | 1 | 0 |
| 5 | 1 | 1 | 0 | 1 | 1 | 0 | 1 |
| 6 | 1 | 1 | 1 | 1 | 1 | 0 | 1 |
| 7 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| 8 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 9 | 1 | 1 | 0 | 1 | 1 | 1 | 1 |

| Mnemonics | Operands | Description | Operation | Flags | #Clock |
|--|----------|--------------------------|----------------------------------|-----------|--------|
| Arithmetic and Logic Instructions | | | | | |
| ADD | Rd, Rr | Add two registers | $Rd \leftarrow Rd + Rr$ | Z,C,N,V,H | 1 |
| ADC | Rd, Rr | Add with carry | $Rd \leftarrow Rd + Rr + C$ | Z,C,N,V,H | 1 |
| ADIW | Rdl, K | Add immediate to word | $Rdh:Rdl \leftarrow Rdh:Rdl + K$ | Z,C,N,V,S | 2 |
| SUB | Rd, Rr | Subtract registers | $Rd \leftarrow Rd - Rr$ | Z,C,N,V,H | 1 |
| SUBI | Rd, K | Subtract immediate | $Rd \leftarrow Rd - K$ | Z,C,N,V,H | 1 |
| SBC | Rd, Rr | Subtract with carry | $Rd \leftarrow Rd - Rr - C$ | Z,C,N,V,H | 1 |
| SBCI | Rd, K | Subtract with carry imm. | $Rd \leftarrow Rd - K - C$ | Z,C,N,V,H | 1 |
| SBIW | Rdl, K | Subtract imm. from word | $Rdh:Rdl \leftarrow Rdh:Rdl - K$ | Z,C,N,V,S | 2 |
| AND | Rd, Rr | Logical AND | $Rd \leftarrow Rd \times Rr$ | Z,N,V | 1 |
| ANDI | Rd, K | AND with immediate | $Rd \leftarrow Rd \times K$ | Z,N,V | 1 |
| OR | Rd, Rr | Logical OR | $Rd \leftarrow Rd \vee Rr$ | Z,N,V | 1 |
| ORI | Rd, K | OR with immediate | $Rd \leftarrow Rd \vee K$ | Z,N,V | 1 |
| EOR | Rd, Rr | Exclusive OR | $Rd \leftarrow Rd \oplus Rr$ | Z,N,V | 1 |
| COM | Rd | One's complement | $Rd \leftarrow 0xFF - Rd$ | Z,C,N,V | 1 |
| NEG | Rd | Two's complement | $Rd \leftarrow 0x00 - Rd$ | Z,C,N,V,H | 1 |
| INC | Rd | Increment | $Rd \leftarrow Rd + 1$ | Z,N,V | 1 |
| DEC | Rd | Decrement | $Rd \leftarrow Rd - 1$ | Z,N,V | 1 |
| Branch Instructions | | | | | |
| RJMP | k | Relative jump | $PC \leftarrow PC + k + 1$ | None | 2 |
| JMP | k | Direct jump | $PC \leftarrow k$ | None | 3 |
| RCALL | k | Relative call | $PC \leftarrow PC + k + 1$ | None | 3 |
| CALL | k | Direct call | $PC \leftarrow k$ | None | 4 |
| RET | | Return from subroutine | $PC \leftarrow STACK$ | None | 4 |