

# Computational Biology 1 (FFR110), Examples sheet 3

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## Abstract

In this examples sheet we work with two models with diffusion. For both of them we conduct linear stability analysis of a spatially homogeneous case (without diffusion). Then we analyze traveling waves solutions and diffusion driven instability, confirming our results using numerical simulations.

14 pages overall.

The report is available online: [http://nrg3.github.io/comp\\_bio\\_3.pdf](http://nrg3.github.io/comp_bio_3.pdf).

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# 1 Traveling waves.

In this task we analyze the spatial spread of the Hantavirus infection, using the model given by:

$$\begin{aligned}\frac{\partial S}{\partial t} &= b(S + I) - cS - \frac{S(I + S)}{K} - aSI + D\nabla^2 S = f(S, I) + D\nabla^2 S \\ \frac{\partial I}{\partial t} &= -cI - \frac{I(I + S)}{K} - aSI + D\nabla^2 I = g(S, I) + D\nabla^2 I\end{aligned}$$

where  $a, b, c, K$  - positive,  $b > c$ .

At first we conduct linear stability analysis of the spatially homogeneous model ( $D = 0$ ), then check whether an equation for the total population size  $N = S + I$  admits a traveling wave solution and find its minimum speed. Finally, we analyze the model using numerical simulations.

## 1.1 a) Linear stability analysis of the spatially homogeneous model ( $D = 0$ ).

We will do linear stability analysis of homogeneous model ( $D = 0$ ) as described in the lecture notes [1, p. 85] (i.e. based on eigenvalues of the matrix  $\mathcal{A}$  - they should be smaller than 0, denote this as eigenvalues criterion).

At first we find steady states  $(S^*, I^*)$  such that  $\frac{\partial S^*}{\partial t} = \frac{\partial I^*}{\partial t} = 0$ , they are  $(0; 0)$ ,  $(K(b-c); 0)$ ,  $(b/a; -b+aK(b-c)/a)$ ,  $(c/a; -c/a)$ . Since according to the statement  $a > 0$  and  $c > 0$ , the last one is biologically irrelevant, because its  $I^*$  is always negative.

$$\mathcal{A} = \left( \begin{array}{cc} \frac{\partial f}{\partial S} \Big|_{(S^*, I^*)} & \frac{\partial f}{\partial I} \Big|_{(S^*, I^*)} \\ \frac{\partial g}{\partial S} \Big|_{(S^*, I^*)} & \frac{\partial g}{\partial I} \Big|_{(S^*, I^*)} \end{array} \right) = \left( \begin{array}{cc} b - c - aI^* - \frac{S^*}{K} - \frac{I^*+S^*}{K} & b - aS^* - \frac{S^*}{K} \\ aI^* - \frac{I^*}{K} & -c - \frac{I^*}{K} + aS^* - \frac{I^*+S^*}{K} \end{array} \right)$$

Now let's evaluate their linear stability:

1. state  $(0; 0)$ , eigenvalues of  $\mathcal{A}$  are  $b - c$  and  $-c$  - unstable since  $b > c$  according to the statement;
2. state  $(K(b - c); 0)$ , eigenvalues are  $c - b$  and  $aK(b - c) - b$  - stable if  $K < \frac{b}{a(b-c)}$ ;
3. state  $(b/a; -b+aK(b-c)/a)$ , eigenvalues are  $c - b$  and  $b + aK(c - b)$  - positive and stable if  $K > \frac{b}{a(b-c)}$ .

In order to find  $K_c$  above which both  $I$  and  $S$  in the stable steady state have positive nonzero values we need to consider the last state. It is positive and stable if  $K > \frac{b}{a(b-c)}$ , thus,  $K_c = \frac{b}{a(b-c)}$ .

## 1.2 b) The total population size $N$ and traveling waves.

Let's obtain an equation of the total population size  $N = S + I$ :

$$\frac{\partial N}{\partial t} = \frac{\partial S}{\partial t} + \frac{\partial I}{\partial t} = b(S + I) - c(S + I) - \frac{(S + I)^2}{K} + D\nabla^2(S + I) = N(b - c) - \frac{N^2}{K} + D\nabla^2 N$$

Dimensionless variables:

$$n = \frac{N}{(b - c)K}; \quad \tau = (b - c)t; \quad \chi = \sqrt{\frac{b - c}{D}} x;$$

$$\frac{\partial n}{\partial \tau} = n(1 - n) + \frac{\partial^2 n}{\partial \chi^2}$$

which is exactly Fisher's equation. Since it was exhaustively analyzed in the lecture notes [1, p. 159], we do not repeat the analysis here, but give only the results:

- it admits a traveling wave solution;
- minimal speed of the wave is 2 in dimensionless variables ( i.e.  $2\sqrt{D(b-c)}$  in dimensional).

I.e.  $N$  may propagate in a form of traveling wave over the habitat that is assumed to be initially empty, except in a narrow region that contains a small number of individuals. Its minimal speed is  $2\sqrt{D(b-c)}$ .

Traveling wave solution seems natural to us here. This model does not include death of individuals, they are only produced. However, there is a carrying capacity as well. Therefore, it is natural to colonize neighborhood in order to use its carrying capacity. Also one may notice light link to the spatial spread of a favoured gene in a population (and actually it is precisely this process, because Fisher equation describes it). One may consider  $N$  as a ratio of population with this gene. Then it will spread out to the neighborhood, since this gene gives advantages.

### 1.3 c) Numerical simulations.

Evolution of  $S$  and  $I$  vs. time  $t$  and space  $x$  are shown on Figures 1 and 2 correspondingly. As we can see population of susceptibles expand over the habitat through a traveling wave. Since they reached 50-th cell in  $\approx 35$  units of time, its speed is  $\approx 50/35 = 1.42$ . The system relaxes to the stable steady state with both nonzero susceptibles and infectives population (numerically it's  $S = 10$  and  $I = 5$ ). Infectives expand in the same manner, but with initial delay. Their speed including delay is  $\approx 1$ , without delay -  $\approx 50/38 = 1.31$ .

Explanation of this infectives expansion delay is that in this model infectives only infect susceptibles and do not produce new infectives, therefore, in order to travel in space to a new place they need susceptibles there.

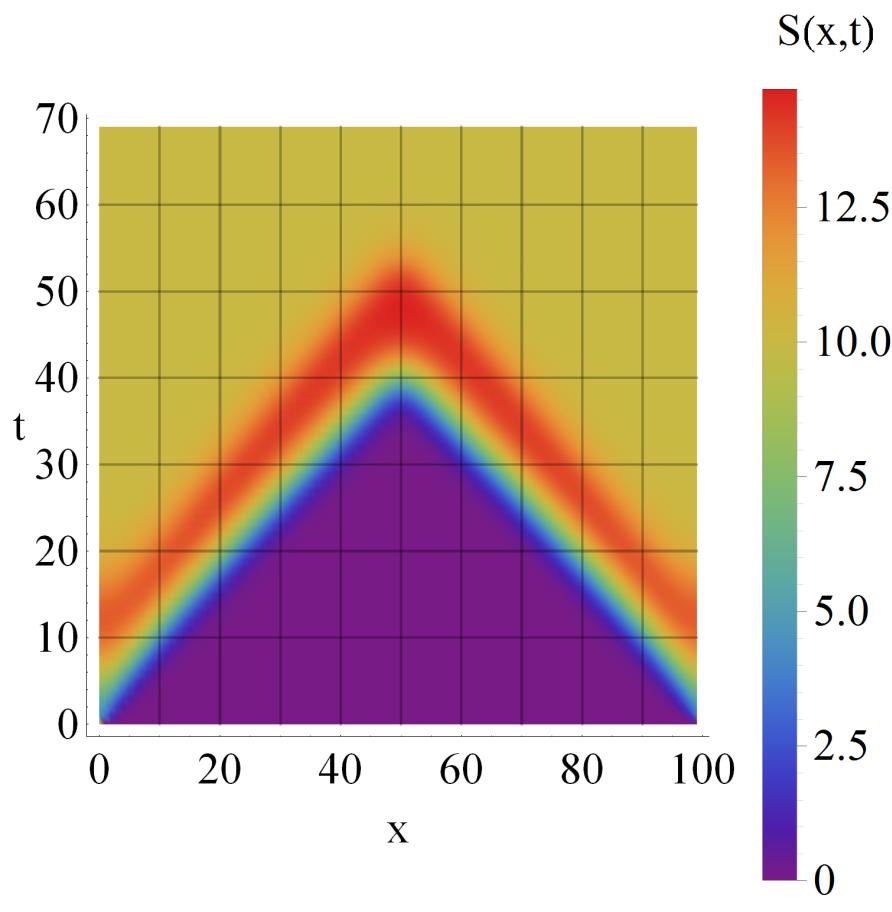


Figure 1: Evolution of  $S$  vs. time  $t$  and space  $x$ . Obtained under  $\delta t = 0.01$  with periodic boundary conditions. All other parameters are as suggested in the statement.

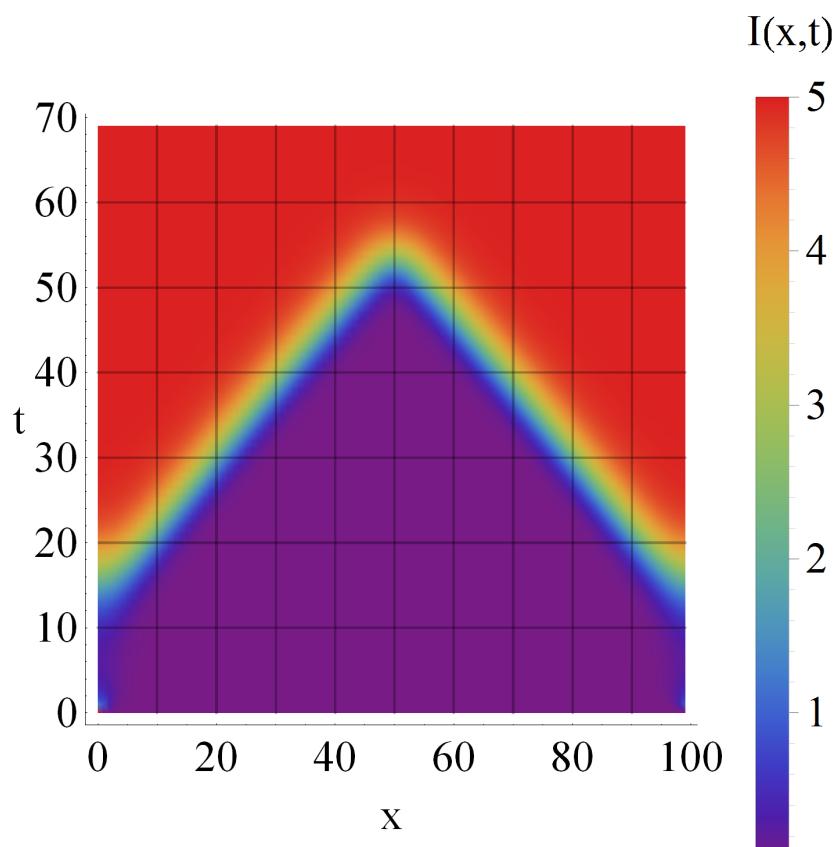


Figure 2: Evolution of  $I$  vs. time  $t$  and space  $x$ . Obtained under  $\delta t = 0.01$  with periodic boundary conditions. All other parameters are as suggested in the statements.

## 2 Diffusion driven instability.

In this task we analyze the effect of diffusion on stability of steady states under a model for two interacting chemicals undergoing a Belousov-Zhabotinsky reaction given by

$$\frac{\partial u}{\partial t} = a - (b + 1)u + u^2v + D_u \nabla^2 u = f(u, v) + D_u \nabla^2 u$$

$$\frac{\partial v}{\partial t} = bu - u^2v + D_v \nabla^2 v = g(u, v) + D_v \nabla^2 v$$

where  $D_u, D_v, a, b > 0$ .

At first we find steady states of spatially homogeneous model and then consider when they exhibit a diffusion-driven instability (in terms of value  $D_v$ ). Then we do numerical simulations and analyze obtained patterns for different  $D_v$ .

### 2.1 a) Steady states.

Let's start with determining spatially homogeneous steady states of the system (neglecting diffusion). The condition is  $f(u^*, v^*) = 0$  and  $g(u^*, v^*) = 0$ . This gives us one steady state  $(u^*, v^*) = (a, b/a)$ . Using eigenvalues criterion:

$$\mathcal{A} = \begin{pmatrix} \frac{\partial f}{\partial u} \Big|_{(u^*, v^*)} & \frac{\partial f}{\partial v} \Big|_{(u^*, v^*)} \\ \frac{\partial g}{\partial u} \Big|_{(u^*, v^*)} & \frac{\partial g}{\partial v} \Big|_{(u^*, v^*)} \end{pmatrix} = \begin{pmatrix} -1 - b + 2u^*v^* & u^{*2} \\ b - 2u^*v^* & -u^{*2} \end{pmatrix} = \begin{pmatrix} b - 1 & a^2 \\ -b & -a^2 \end{pmatrix}$$

$$\det \mathcal{A} = a^2; \quad \text{tr } \mathcal{A} = b - a^2 - 1;$$

$$\lambda_{1,2} = \frac{\text{tr } \mathcal{A} \pm \sqrt{(\text{tr } \mathcal{A})^2 - 4 \det \mathcal{A}}}{2}$$

$$\text{Re } \lambda_{1,2} < 0 \Leftrightarrow \text{tr } \mathcal{A} < 0 \wedge \det \mathcal{A} > 0 \Leftrightarrow b < a^2 + 1$$

I.e. this state is stable if  $b < a^2 + 1$ .

Now we consider a diffusion-driven instability. According to the lecture notes [1, p. 204] there are four conditions when such system exhibits a diffusion-driven instability:

$$\text{tr } \mathcal{A} < 0; \quad d \frac{\partial f}{\partial u} + \frac{\partial g}{\partial v} > 0; \quad \det \mathcal{A} > 0; \quad (d \frac{\partial f}{\partial u} + \frac{\partial g}{\partial v})^2 - 4d(\frac{\partial f}{\partial u} \frac{\partial g}{\partial v} - \frac{\partial f}{\partial v} \frac{\partial g}{\partial u}) > 0$$

with  $d = D_v/D_u$ .

Evaluating this at the steady state  $(u^*, v^*) = (a, b/a)$  under  $D_u = 1$ ,  $a = 3$ ,  $b = 8$ , we obtain that  $D_v > \frac{81+36\sqrt{2}}{49} \approx 2.69$ .

### 2.2 b) Numerical simulations.

In order to simulate the dynamics, first, we initialize the field as  $u(x, y, 0) = u^* \cdot \text{rand}(0.95; 1.05)$  and  $v(x, y, 0) = v^* \cdot \text{rand}(0.95; 1.05) \quad \forall x, y = 0, 1, \dots, L - 1$ , where  $\text{rand}(x; y)$  returns a pseudo random real number from  $[x; y]$ . Then, using Euler discretization and discretization of Laplacian, we obtain:

$$\frac{u(x, y, t + \delta t)}{\delta t} = f(u(x, y, t), v(x, y, t)) - 4u(x, y, t) + \sum_{(nx; ny) \in n(x, y)} u(nx, ny, t)$$

$$\frac{v(x, y, t + \delta t)}{\delta t} = g(u(x, y, t), v(x, y, t)) + D_v[-4v(x, y, t) + \sum_{(nx;ny) \in n(x,y)} v(nx, ny, t)]$$

where  $n(x, y)$  is a set of neighbors of  $(x; y)$  under periodic boundary conditions:

$$n(x, y) = \{(nx, ny) : (|x - nx| = 1 \vee |x - nx| = L - 1) \wedge (|y - ny| = 1 \vee |y - ny| = L - 1)\}$$

All simulations were done with  $\delta t = 0.001$ .

Results of simulation are shown on Figures 3 - 5.

As one can see, they consist with theoretical results above - under  $D_v = 2.3$  technically we got patterns, but the difference between maximum and minimum of  $u$  is insignificant and this may be caused by numerical errors. Under  $D_v \geq 3$  we got patterns with significant amplitude.

These patterns consist of one big connected region (background) and many smaller regions (islands), inside each region the value of  $u$  is almost the same. For smaller value  $D_v = 3$  background corresponds to higher values, but then this changes - for  $D_v = 5$ ,  $D_v = 9$  background is formed by lower values. Also  $D_v$  influences appearances of islands - under  $D_v = 3$  they are more connected and have greater area than for higher values of  $D_v$ .

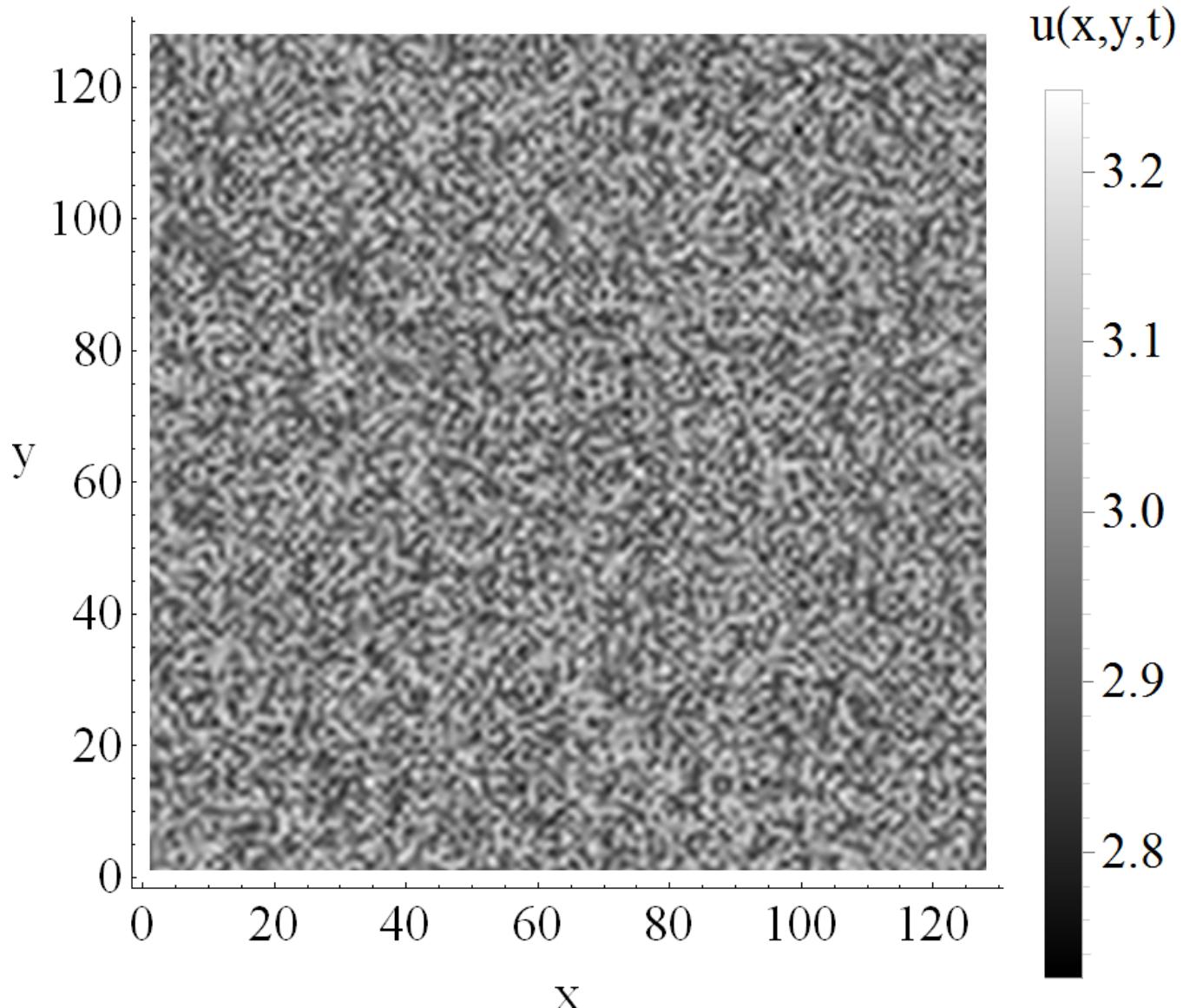
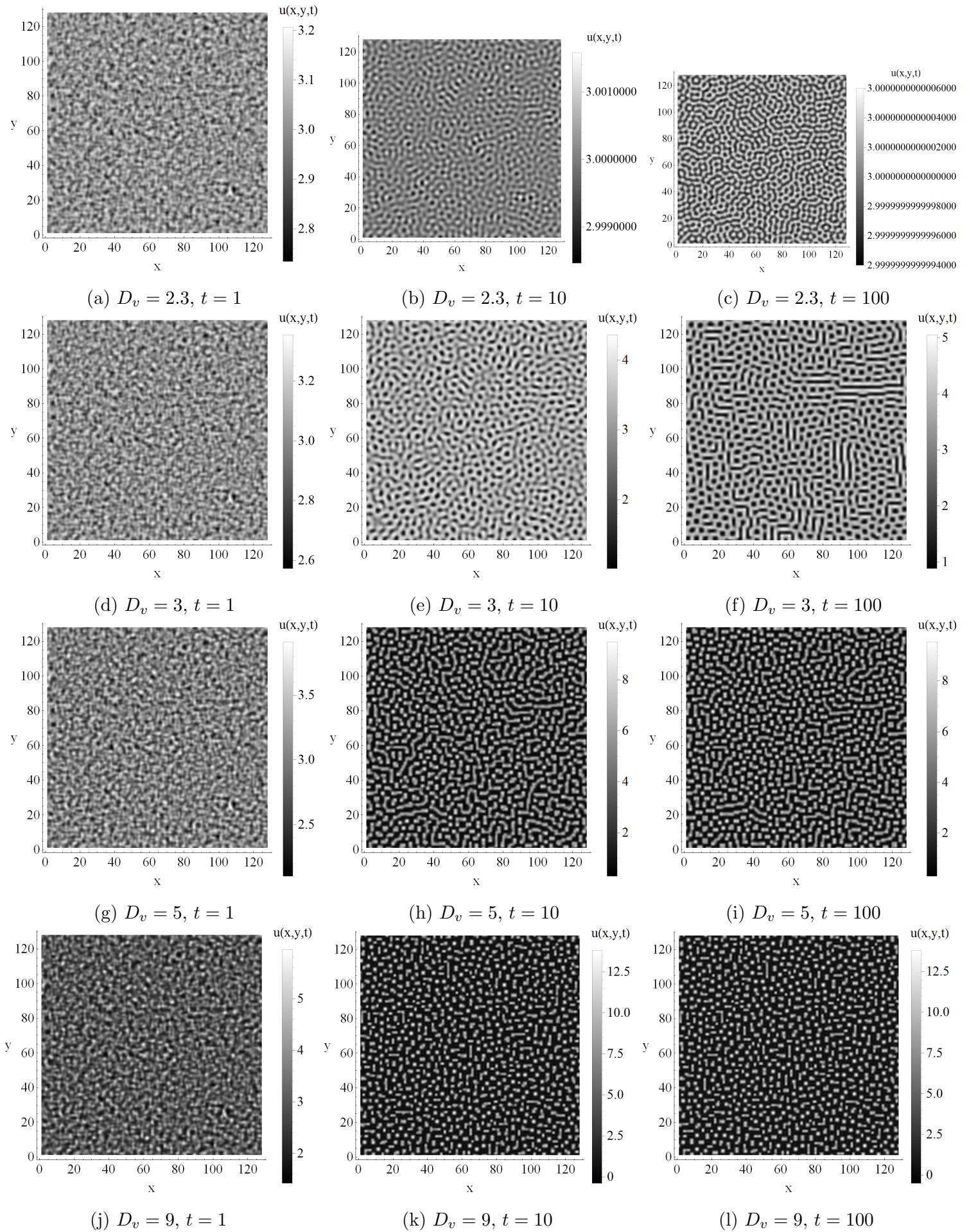


Figure 3: Initial  $u$  at  $t = 0$  under seed 123.

Figure 4: Dynamics of  $u$  vs.  $D_v$  and time  $t$ , seed 123. Other parameters are as suggested in the statement.

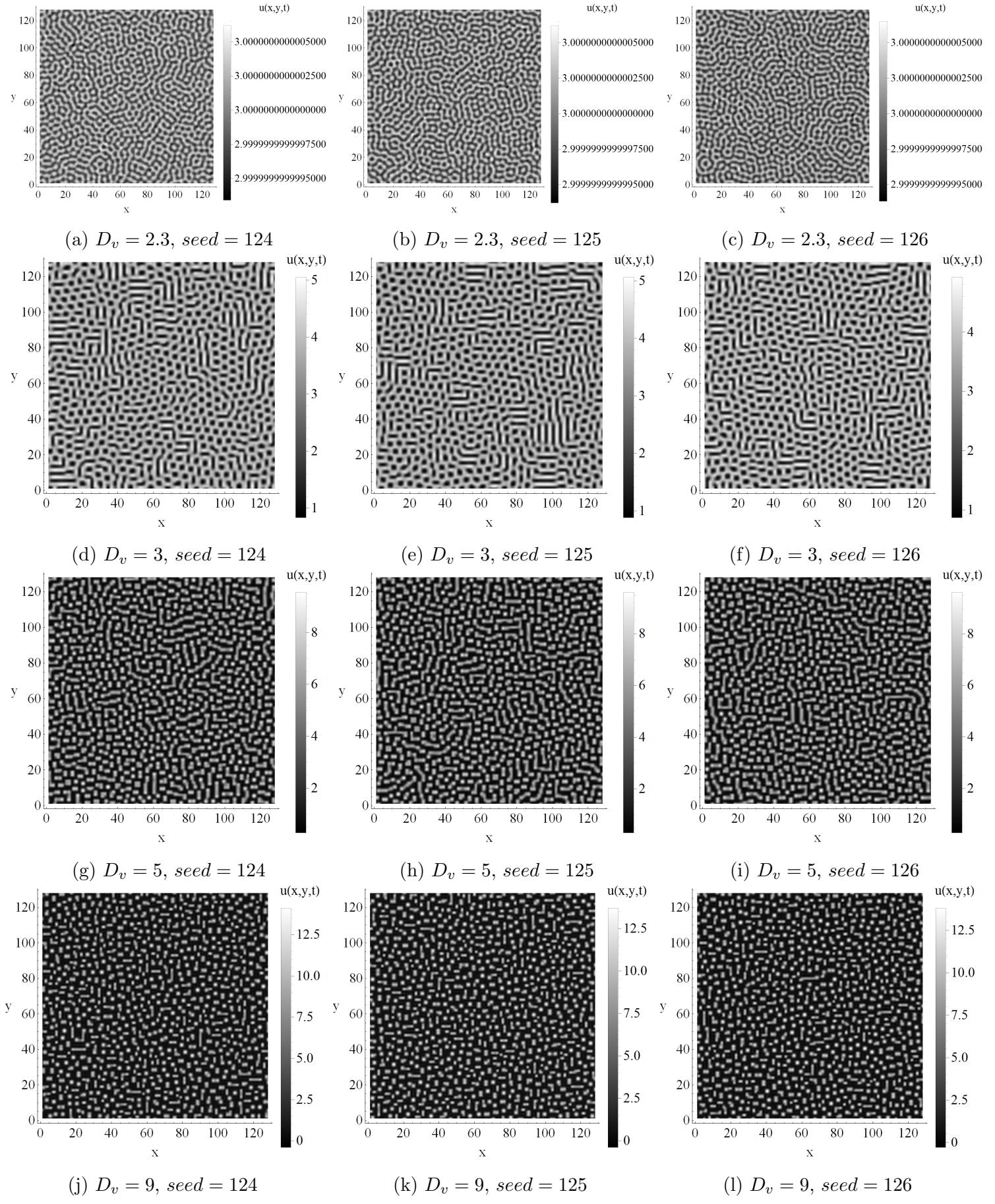


Figure 5: Results for other seeds:  $u$  vs.  $D_v$ ,  $t = 100$ . Other parameters are as suggested in the statement.

## References

[1] Bernhard Mehlig, *Computational Biology A: growth, morphogenesis, and ecological problems (lecture notes)*;

## A File 1c.nb:

```

1
2 codeDirectory = NotebookDirectory[];
3 CreateDirectory[codeDirectory <> "..\\report\\pics\\"]; // Quiet
4 SetDirectory[codeDirectory <> "..\\report\\pics\\"];
5 hack=Function[x, (* for static relative sizes of elements in plots while rasterizing *)
6 First@ImportString[ExportString[x, "PDF"]]]
7 ];
8 a=0.1;b=1;c=0.5;k=30;d=1;l=100;
9 dS=Function[{s,i},b(s+i)-c*s-s (i+s)/k-a*s*i];
10 dI=Function[{s,i},-c*i-i (i+s)/k+a*s*i];
11 Clear[s,i];
12 solutions=Solve[{dS[s,i]==0,dI[s,i]==0},{s,i}];
13 dt=0.01;
14 endTime=70;
15 patches=Table[{0,0},{1}];
16 delta=Table[{0,0},{1}];
17 patches[[1]]={s,i}/.solutions[[3]];
18
19 pointsS=Table[{0,0,0},{(endTime+1)*l}];
20 pointsI=pointsS;
21
22 last=1;
23
24 For[time=0, time <= endTime, time+=dt,
25
26 If[Mod[Floor[time*100],100]==0,
27 For[z=1, z<=l, ++z,
28 pointsS[[last]][[1]]=z-1;
29 pointsS[[last]][[2]]=time;
30 pointsS[[last]][[3]]=patches[[z]][[1]];
31
32 pointsI[[last]][[1]]=z-1;
33 pointsI[[last]][[2]]=time;
34 pointsI[[last]][[3]]=patches[[z]][[2]];
35 ++last;
36
37 ];
38 ];
39 ];
40
41
42 For[j=1, j<=Length[patches],++j,
43 s=patches[[j]][[1]];
44 i=patches[[j]][[2]];
45
46 If[j==1, sLeft=patches[[1]][[1]],sLeft=patches[[j-1]][[1]]];
47 If[j==1, iLeft=patches[[1]][[2]],iLeft=patches[[j-1]][[2]]];
48
49 If[j==l, sRight=patches[[1]][[1]],sRight=patches[[j+1]][[1]]];
50 If[j==l, iRight=patches[[1]][[2]],iRight=patches[[j+1]][[2]]];
51
52 delta[[j]][[1]]=dt*(dS[s,i]+sLeft-2*s+sRight);
53

```

```

54 delta [[ j ]][[ 2 ]] = dt*(dI[s , i]+iLeft -2*i+iRight );
55 ];
56
57 patches+=delta ;
58 ];
59 pic1=ListDensityPlot [ pointsS ,Frame→{True ,True ,False ,False} ,Mesh→{Table[i ,{i ,10 ,1 ,10 }],Table
   [i ,{i ,10 ,endTime ,10 }]} ,FrameLabel→{"x" , "t"} ,FrameStyle→18, RotateLabel→False ,(*
   ColorFunction \[Rule] GrayLevel ,*) ColorFunction→"Rainbow" ,InterpolationOrder→5,
60 PlotLegends→Placed [ BarLegend [ Automatic ,LegendMargins →{{0,0},{0,0}} ,LegendLabel→"S(x,t)" ,
   LabelStyle→{FontSize→18},LegendMarkerSize→350],Right]
61 ];
62 Export ["1c_s_color .png" ,pic1 ,ImageResolution→300];
63 pic1=ListDensityPlot [ pointsS ,Frame→{True ,True ,False ,False} ,Mesh→{Table[i ,{i ,10 ,1 ,10 }],Table
   [i ,{i ,10 ,endTime ,10 }]} ,FrameLabel→{"x" , "t"} ,FrameStyle→18, RotateLabel→False ,
   ColorFunction→GrayLevel ,InterpolationOrder→5,
64 PlotLegends→Placed [ BarLegend [ Automatic ,LegendMargins →{{0,0},{0,0}} ,LegendLabel→"S(x,t)" ,
   LabelStyle→{FontSize→18},LegendMarkerSize→350],Right]
65 ];
66 Export ["1c_s_gray .png" ,pic1 ,ImageResolution→300];
67
68 pic1=ListDensityPlot [ pointsI ,Frame→{True ,True ,False ,False} ,Mesh→{Table[i ,{i ,10 ,1 ,10 }],Table
   [i ,{i ,10 ,endTime ,10 }]} ,FrameLabel→{"x" , "t"} ,FrameStyle→18, RotateLabel→False ,(*
   ColorFunction \[Rule] GrayLevel ,*) ColorFunction→"Rainbow" ,InterpolationOrder→5,
69 PlotLegends→Placed [ BarLegend [ Automatic ,LegendMargins →{{0,0},{0,0}} ,LegendLabel→"I(x,t)" ,
   LabelStyle→{FontSize→18},LegendMarkerSize→350],Right]
70 ];
71 Export ["1c_i_color .png" ,pic1 ,ImageResolution→300];
72 pic1=ListDensityPlot [ pointsI ,Frame→{True ,True ,False ,False} ,Mesh→{Table[i ,{i ,10 ,1 ,10 }],Table
   [i ,{i ,10 ,endTime ,10 }]} ,FrameLabel→{"x" , "t"} ,FrameStyle→18, RotateLabel→False ,
   ColorFunction→GrayLevel ,InterpolationOrder→5,
73 PlotLegends→Placed [ BarLegend [ Automatic ,LegendMargins →{{0,0},{0,0}} ,LegendLabel→"I(x,t)" ,
   LabelStyle→{FontSize→18},LegendMarkerSize→350],Right]
74 ];
75 Export ["1c_i_gray .png" ,pic1 ,ImageResolution→300];

```

## B File 2b.cpp:

```

1
2 #include <iostream>
3 #include <fstream>
4
5 #include <vector>
6 using std::vector ;
7
8 #include <string>
9 using std::string ;
10
11 #include <sstream>
12 #include <direct.h>
13
14 typedef long double ValueType;
15
16 ValueType random () {
17     return static_cast<ValueType>(rand ()) / RANDMAX;
18 }
19
20 ValueType dif_V ;
21 const ValueType a = 3 , b = 8 ;
22
23 ValueType f (ValueType U, ValueType V) {

```

```

24     return a - U * (b+1) + U * U * V;
25 }
26
27 ValueType g(ValueType U, ValueType V) {
28     return b * U - U * U * V;
29 }
30
31 string to_string(int x) {
32     std::stringstream stream;
33     stream << x;
34     return stream.str();
35 }
36
37 void save(const vector<vector<ValueType>>& data, const string& path) {
38     std::ofstream out(path);
39
40     out.precision(15);
41     out << std::fixed;
42
43     for (int i = 0; i < data.size(); ++i) {
44         for (int j = 0; j < data[i].size(); ++j) {
45             if (j) {
46                 out << " ";
47             }
48             out << data[i][j];
49         }
50         out << "\n";
51     }
52
53     out.close();
54 }
55
56 int main() {
57
58     srand(123);
59
60     ValueType dt = 0.001;
61     int L = 128;
62     ValueType perturbation = 0.1;
63     int iters = 105000;
64     ValueType end_time = dt * iters;
65
66
67     ValueType dif_Vs[] = {2.3, 3, 5, 9};
68     vector<vector<vector<ValueType>> field(2, vector<vector<ValueType>>(L, vector<ValueType>(L)));
69     vector<vector<vector<ValueType>> next = field;
70     ValueType start_U = 3, start_V = 8. / 3;
71
72     int seeds = 5;
73
74     int all = iters * 4 * seeds;
75     int done = 0;
76
77     ValueType max_dif = 1e300;
78
79     mkdir("txt");
80     for (int id = 0; id < 4; ++id) {
81         mkdir(string("txt/" + to_string(id)).c_str());
82         for (int seed = 0; seed < 5; ++seed) {

```

```

83     mkdir(string("txt/") + to_string(id) + "/" + to_string(seed + 123)).c_str());
84     srand(seed + 123);
85
86     dif_V = dif_Vs[id];
87
88
89     for (int j = 0; j < L; ++j) {
90         for (int z = 0; z < L; ++z) {
91             field[0][j][z] = start_U * (1 + (random() - 0.5) * perturbation);
92             field[1][j][z] = start_V * (1 + (random() - 0.5) * perturbation);
93         }
94     }
95
96     int dx[] = {0, 0, -1, 1};
97     int dy[] = {-1, 1, 0, 0};
98
99     int last_save = -1e9;
100    int saving_time = 1000;
101
102    int iter = 0;
103
104
105    max_dif = 1e300;
106    for (ValueType time = 0; time < end_time; time += dt) {
107
108
109        if (iter - last_save >= saving_time) {
110            last_save = iter;
111            save(field[0], "txt/" + to_string(id) + "/" + to_string(seed + 123) + "/"
112                + to_string(int(dif_V * 100)) + "_" + to_string(iter) + ".txt");
113
114            std::cerr << "\r" << 1. * done / all << " " << iter << " " << max_dif << "
115            r";
116
117            /*
118            if (max_dif < 1e-12) {
119                done += iters - iter;
120                break;
121            }
122            */
123        }
124
125
126        max_dif = 0;
127
128        ++iter;
129        ++done;
130
131        for (int i = 0; i < L; ++i) {
132            for (int j = 0; j < L; ++j) {
133
134                ValueType sum_U = 0, sum_V = 0;
135
136                for (int z = 0; z < 4; ++z) {
137                    int nx = i + dx[z];
138                    int ny = j + dy[z];
139                    if (nx < 0) {
140                        nx = L - 1;
141                    }

```

```

142         if (nx >= L) {
143             nx = 0;
144         }
145         if (ny < 0) {
146             ny = L - 1;
147         }
148         if (ny >= L) {
149             ny = 0;
150         }
151
152         sum_U += field [0][nx][ny];
153         sum_V += field [1][nx][ny];
154     }
155
156     ValueType dU = (f( field [0][i][j], field [1][i][j]) + sum_U - 4 * field [0][i][j]);
157     ValueType dV = (g( field [0][i][j], field [1][i][j]) + dif_V *(sum_V - 4 * field [1][i][j]));
158
159     next [0][i][j] = field [0][i][j] + dt * dU;
160     next [1][i][j] = field [1][i][j] + dt * dV;
161
162     if (max_dif < fabs(dU)) {
163         max_dif = fabs(dU);
164     }
165     if (max_dif < fabs(dV)) {
166         max_dif = fabs(dV);
167     }
168 }
169
170
171     }
172     field .swap(next);
173 }
174 }
175 }
176 }
177 }
```

## C File 2b.nb:

```

1 Dvs={"2.3","3","5","9"};
2.CreateDirectory["D:\\\\projects\\\\compbio3\\\\pics\\\\"]; //Quiet
3 For[id=1, id <=4, ++id,
4 For[seed = 0, seed<5,++seed,
5 folder="D:\\\\projects\\\\compbio3\\\\txt\\\\"\<>ToString[id-1]<>"\\\"\<>ToString[seed+123]<>"\\";
6 SetDirectory[folder];
7 files=FileNames[];
8
9 For[i=1, i<= Length[files],++i,
10 l=StringSplit[files[[i]],[{"_","."}]];
11 iter=FromDigits[l[[2]]];
12 If[iter==0||iter==1000||iter==10000||iter==100000,
13 data=Import[files[[i]],"Table"];
14 res="rel_"\<>Dvs[[id]]<>"_"\<>ToString[seed+123]<>"_"\<>ToString[iter *0.001];
15 res=StringReplace[res,"."->"_"];
16
17 pic=ListDensityPlot[data,
18 Frame->{True,True,False,False},
19 FrameLabel->{"x","y"},FrameStyle->18,RotateLabel->False,
20 ColorFunction->GrayLevel,(*ColorFunctionScaling\[Rule]False,*)]
```

```
21 InterpolationOrder->5,
22 PlotLegends->Placed [BarLegend[Automatic, LegendMargins ->{{0,0},{0,0}}, LegendLabel->"u(x,y,t)" ,
   LabelStyle ->{FontSize->18}, LegendMarkerSize ->350],Right]
23 ];
24 Export ["D:\\\\projects\\\\compbio3\\\\pics\\\\">>res<< .png",pic ,ImageResolution->150];
25 ];
26 ];
27 ];
28 ];
```