

Efficient Factor Graph Fusion for Multi-robot Mapping

by

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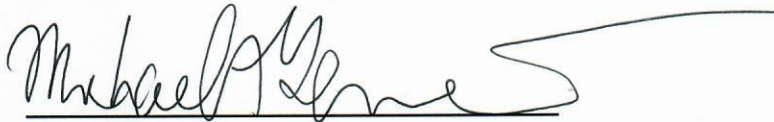
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