# svd

### May 30, 2022

```
[1]: import os
     import numpy as np
     import pandas as pd
     import matplotlib.pyplot as plt
     import plotly.express as px
     import plotly.graph_objects as go
[2]: import plotly.io as pio
     pio.renderers.default = "plotly_mimetype+notebook+vscode"
[3]: # function used in case we would like to select desired timestamp
     def trunc_df(df):
         start = pd.to_datetime('2020-07-01 19:30:00')
         end = pd.to datetime('2020-08-01 19:30:00')
         ret_df = df.loc[start:end]
         return ret df
     def create_folder(folder_name):
         if not os.path.exists(folder_name):
             print(f'Creating folder {folder_name}')
             os.mkdir(folder_name)
     # to always have the newest plot versions, delete file before creating new one
     def remove_file_if_exists(file_path):
         if os.path.exists(file_path):
             os.remove(file_path)
[4]: # svd global variables and creating dirs
     SVD FOLDER PATH = 'svd plots'
     create_folder(SVD_FOLDER_PATH)
     # SVD_COLUMN = 'humidity'
     \# SVD\_COLUMN = 'tempC'
     SVD_COLUMN = 'windspeedKmph'
```

```
# ANALYSIS_TYPE = 'full'
ANALYSIS_TYPE = 'partial'

SVD_FOLDER_PATH = f'{SVD_FOLDER_PATH}/{SVD_COLUMN}'
create_folder(SVD_FOLDER_PATH)

# create reconstruction dir
SVD_RECONSTUCTION_FOLDER_PATH = f'{SVD_FOLDER_PATH}/reconstruction'
create_folder(SVD_RECONSTUCTION_FOLDER_PATH)
```

Creating folder svd\_plots/windspeedKmph
Creating folder svd\_plots/windspeedKmph/reconstuction

### 0.1 Prepare Data for SVD Analysis

```
[5]: # function to create csv file used for analysis
     def create_svd_df(column_value):
         FULL_DATA_FILENAME = 'data/data.csv.gz'
         OUTPUT_FILENAME = f'data/svd/data_svd_{column_value}_{ANALYSIS_TYPE}.csv'
         columns_to_read = ['date_time', 'city', column_value]
         df = pd.read_csv(FULL_DATA_FILENAME, usecols=columns_to_read,__
      ⇔compression='gzip')
         unique_towns = sorted(list(df['city'].unique()))
         new_index = pd.date_range(
             start=df.iloc[0]['date_time'],
             end=df.iloc[-1]['date_time'],
             freq='3h'
         )
         data = np.array(df[column_value])
         data = data.reshape(len(new index), len(unique towns))
         ret_df = pd.DataFrame(
             data=data,
             columns=unique_towns,
             index=new_index,
             dtype=float
         ret_df.to_csv(OUTPUT_FILENAME)
```

```
[6]: GEOLOCATION_FILENAME = 'data/geo_position.csv'

df_geolocation = pd.read_csv(GEOLOCATION_FILENAME).sort_values(by='CITY')

unique_towns = sorted(list(df_geolocation['CITY'].unique())) # get unique_

names of towns ordered by name

print(f'Doing analisys for {SVD_COLUMN}')
```

```
SVD_DATA_FILENAME = f'data/svd/data_svd_{SVD_COLUMN}_{ANALYSIS_TYPE}.csv'

if not os.path.exists(SVD_DATA_FILENAME):
    print(f'Creating svd file for {SVD_COLUMN}')
    create_svd_df(column_value=SVD_COLUMN)
    print('File created!')
```

Doing analisys for windspeedKmph Creating svd file for windspeedKmph File created!

### 0.2 SVD

```
[7]: print(f'Loading svd file for {SVD_COLUMN}')
    df_svd = pd.read_csv(SVD_DATA_FILENAME, index_col=0)
    df_svd.index = pd.to_datetime(df_svd.index)

# df_svd = trunc_df(df_svd)
svd_A = np.array(df_svd)

# build matrix U, S, V
svd_U, svd_S, svd_V = np.linalg.svd(svd_A, full_matrices=False)
```

Loading svd file for windspeedKmph

### 0.2.1 Precision of SVD Resconstrucion

```
[8]: # function to calculate and plot precision of svd reconstruction
     def svd_precision(svd_S):
         SVD_PRECISION_FILENAME = f'{SVD_FOLDER_PATH}/

¬{SVD_COLUMN}_svd_precision_{ANALYSIS_TYPE}.png'

         remove_file_if_exists(SVD_PRECISION_FILENAME)
         fig = go.Figure(
             data=[go.Bar(
                     x=np.arange(np.size(svd_S)),
                     y=np.cumsum(svd_S / np.sum(svd_S))
             ]
         )
         fig.update_layout(
             title_text='SVD Precision',
             title_x=0.5,
             xaxis_title='Rank',
             yaxis_title='Precision'
         )
         fig.update_yaxes(range=[0.5, 1])
```

```
fig.write_image(SVD_PRECISION_FILENAME)
fig.show()
```

```
[9]: # Calculating svd reconstruction precision svd_precision(svd_S)
```

#### 0.2.2 Full Reconstruction & Lower Rank Reconstruction

```
[10]: # full reconstruction - matrix svd_Ar
    svd_Ar = np.dot(svd_U * svd_S, svd_V)
    print(f'Diff: {np.mean(np.abs(svd_A - svd_Ar))}')

# lower rank reconstruction - matrix svd_Ar
    k = 5
    svd_Ar = np.dot(svd_U[:,:k] * svd_S[:k], svd_V[:k, :])

print(f'Diff reconstruction: {np.mean(np.abs(svd_A - svd_Ar))}')
```

Diff: 4.3518192208483686e-14 Diff reconstruction: 0.8253357196115587

# 0.2.3 Average SVD Error

```
[11]: |# function to calculate and plot average error of svd for k=n
      def svd average error(svd A, svd Ar, k, unique towns):
          SVD_AVG_ERR_FILENAME = f'{SVD_FOLDER_PATH}/

¬{SVD_COLUMN}_svd_avg_err_{ANALYSIS_TYPE}.png'
          remove_file_if_exists(SVD_AVG_ERR_FILENAME)
          svd_err = np.average(np.abs(svd_A - svd_Ar), axis=0)
          asix range = np.arange(0, len(unique towns))
          fig = go.Figure(data=[go.Bar(x=asix range,
                                       y=svd_err
                                       )])
          fig.update_layout(
              title_text='SVD Average Error', title_x=0.5,
              yaxis_title=f'Average error of reconstruction with rank k={k}',
              xaxis=dict(tickmode='array',
                  tickvals=asix_range,
                  ticktext=unique_towns
              )
          fig.update_xaxes(tickangle=90)
          fig.write image(SVD AVG ERR FILENAME)
          fig.show()
```

## 0.2.4 Dates to Concept - SVD\_U

```
[13]: # function to plot dates to concept for k=n

def svd_dates_to_concept(k, index, svd_U):
        SVD_DTC_FILENAME = f'{SVD_FOLDER_PATH}/
        SVD_COLUMN}_svd_dates_to_concept_{ANALYSIS_TYPE}.png'
        remove_file_if_exists(SVD_DTC_FILENAME)
        all_plots = []
        for i in range(k):
            all_plots.append(go.Scatter(x=index, y=svd_U[:, i], name=f'k={i}'))

        fig = go.Figure(data=all_plots)
        fig.write_image(SVD_DTC_FILENAME)
        fig.update_layout(xaxis=dict(rangeslider=dict(visible=True)))
        fig.show()
```

### 0.2.5 Towns to Concept - SVD\_V

```
[15]: # function to plot towns to concept for k=n

def svd_towns_to_concept(k, svd_V, unique_towns):
    SVD_TTC_FILENAME = f'{SVD_FOLDER_PATH}/

    SVD_COLUMN}_svd_towns_to_concept_{ANALYSIS_TYPE}.png'
    remove_file_if_exists(SVD_TTC_FILENAME)

asix_range = np.arange(0, len(unique_towns))
    all_plots = []
    for i in range(k):
        all_plots.append(go.Bar(x=asix_range, y=svd_V[i, :], name=f'{i}'))

fig = go.Figure(data=all_plots)
```

# 0.2.6 SVD Maps

```
[17]: # plot map with values from SVD V (towns to concept)
     def plot_svd_map(vector, k, data_geo):
         SVD_MAP_FILENAME = f'{SVD_FOLDER_PATH}/
      remove_file_if_exists(SVD_MAP_FILENAME)
         data_geo['VALUES'] = vector
         px.set_mapbox_access_token(open(".mapbox_token").read())
         fig = px.scatter_mapbox(
            data_geo,
             size = [2] * len(data_geo.index),
            lat="LAT",
            lon="LNG",
            color="VALUES",
            hover_name="CITY",
            color_continuous_scale=px.colors.cyclical.Phase,
         )
         fig.update_layout(
            height = 700,
            margin = {
                '1':5,
                 'r':5,
```

```
't':5,
    'b':5,
},
autosize=True,
mapbox = {
    'style': "open-street-map",
    'zoom': 7.5
}
)
fig.write_image(SVD_MAP_FILENAME)
fig.show()
```

```
[18]: # plot maps
for i in range(k):
    print(f'Ploting map for k = {i}')
    plot_svd_map(
        vector=svd_V[i, :],
        k=i,
        data_geo=df_geolocation.copy()
    )
```

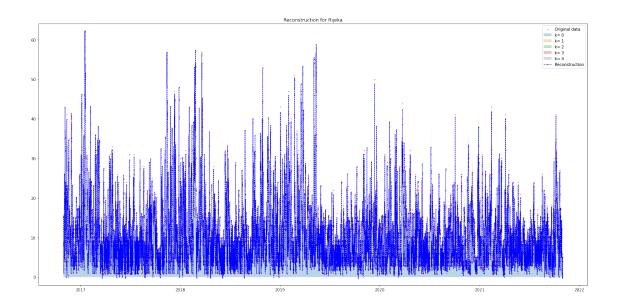
```
Ploting map for k = 0
Ploting map for k = 1
Ploting map for k = 2
Ploting map for k = 3
Ploting map for k = 4
```

### 0.2.7 SVD Reconstruction

```
a_cum = np.zeros(svd_A.shape[0])
      for i in range(k):
           a_k = np.dot(svd_U[:, i] * svd_S[i], svd_V[i, iloc])
           flbtw_k = plt.fill_between(df_svd.index, a_cum, a_cum + a_k,_
⇒alpha=0.3, label=f'k= {i}')
           legend handles.append(flbtw k)
           legend_labels.append(f'k= {i}')
           a_cum += a_k
      plt_recon, = plt.plot(df_svd.index, a_cum, marker='s', ls='--', c='b', __
\hookrightarrowlw=1, ms=1)
      legend handles.append(plt recon)
      legend_labels.append('Reconstruction')
      plt.legend(legend_handles, legend_labels)
      plt.ylim(df_svd[location].min() - 2, df_svd[location].max() + 2)
      fig.savefig(SVD_RESONSTRUCTION_FILENAME, dpi=90)
      if location == 'Rijeka':
           plt.title(f'Reconstruction for {location}')
           plt.show()
      plt.close(fig)
```

```
[20]: # SVD reconstruction temperature
svd_reconstruct(
    unique_towns=unique_towns,
    df_svd=df_svd,
    svd_A=svd_A,
    svd_U=svd_U,
    svd_S=svd_S,
    svd_V=svd_V,
    k=k
)
```

Saving reconstructins to svd\_plots/windspeedKmph/reconstuction



# 1 Export to HTML

```
[21]: # save notebook before nbconvert
import IPython

[22]: %%javascript
IPython.notebook.save_notebook()
```

<IPython.core.display.Javascript object>

[NbConvertApp] Converting notebook svd.ipynb to HTML [NbConvertApp] Writing 8437987 bytes to output/windspeedKmph\_svd\_partial.html