correlation

August 14, 2022

```
import os
import networkx as nx
import numpy as np
import pandas as pd

import matplotlib.pyplot as plt
import plotly.express as px
import plotly.graph_objects as go
```

```
[2]: import plotly.io as pio
pio.renderers.default = "plotly_mimetype+notebook+vscode+pdf"
```

0.1 Modify Data

0.1.1 Create Merged .csv File with Data from All Cities

```
[3]: | # setup global variables - data file directory and name
     DATA_FILES_DIR = 'original_data_files'
     DATA_FILE_NAME = 'data/data.csv.gz'
     all_data_files = os.listdir(DATA_FILES_DIR)
     def create_data_file():
         # read each data original data file and concatanate it to single df
         os.chdir(DATA_FILES_DIR)
         df = pd.concat(map(pd.read_csv, all_data_files), ignore_index=True)
         os.chdir('...') # return to previous dir - main dir
         # remove some patterns from city column
         df['city'] = df['city'].str.replace(',Croatia', '')
         df['city'] = df['city'].str.replace(r'+', ' ', regex=False)
         # fix json
         df['weatherIconUrl'] = df['weatherIconUrl'].str.replace("\[{'value': '", "")}
         df['weatherIconUrl'] = df['weatherIconUrl'].str.replace("'}]", "")
         df['weatherDesc'] = df['weatherDesc'].str.replace("\[{'value': '", "")}
```

```
df['weatherDesc'] = df['weatherDesc'].str.replace("'}]", "")

# sort data by datetime and city and save it to .csv file
    df = df.sort_values(by=['date_time', 'city'])
    df.to_csv(DATA_FILE_NAME, index=False, compression='gzip')
    print('Data processed successfully')

# create data file if does not exist
if not os.path.exists(DATA_FILE_NAME):
    print('Creating data file')
    create_data_file()
else:
    print('Data has already been processed')

# import data
df_full_data = pd.read_csv(DATA_FILE_NAME, compression='gzip')
```

Data has already been processed

1 Correlation

```
[4]: def create_folder(folder_name):
    if not os.path.exists(folder_name):
        print(f'Creating folder {folder_name}')
        os.mkdir(folder_name)

# to always have the newest plot versions, delete file before creating new one
def remove_file_if_exists(file_path):
    if os.path.exists(file_path):
        os.remove(file_path)

create_folder('data/')
create_folder('data/correlation')
```

```
if sign == '<':
            df = df.loc[df[column] < value]</pre>
        elif sign == '>':
            df = df.loc[df[column] > value]
        elif sign == '=':
            df = df.loc[df[column] == value]
        elif sign == 'in':
            df = df.loc[df[column].isin(value)]
        prefix_str += f'-condition-{column}-{sign}-' + '_'.join(value)
columns_to_keep = ['date_time'] + columns_to_keep + ['city']
df = df[columns_to_keep]
if years:
    df = df[df['date_time'].dt.year.isin(years)]
    prefix_str += '-years-' + '_'.join(map(str, years))
if months:
    df = df[df['date_time'].dt.month.isin(months)]
    prefix_str += '-months-' + '_'.join(map(str, months))
if hours:
    df = df[df['date_time'].dt.hour.isin(hours)]
    prefix_str += '-hours-' + '_'.join(map(str, hours))
prefix_str = prefix_str.replace(' ', '')
return df, prefix_str
```

```
[6]: # function to calculate correlation matrix values
     def create_correlation_matrix(data, towns, field):
         if len(field) == 1:
             field = field[0]
         else:
            pass
             # TO DO - merge and somehow calculate on multiple fields
         towns cnt = len(towns)
         # init zero matrix with m=n=count of cities
         # set values to -13, just to be sure it is an imposible correlation value
         ret_matrix = np.zeros((towns_cnt, towns_cnt)) - 13
         # iterate through every city combination and calculate the correlation
         for i, town1 in enumerate(towns):
             town1_values = np.array(data.loc[data['city'] == town1][field])
             # town1_values = (town1_values - np.mean(town1_values)) / (np.
      →std(town1_values) * len(town1_values))
```

```
# correlation 1 on diagonal
ret_matrix[i,i] = 1.0

# having in mind that ret_matrix[i,j] == ret_matrix[j,i]
for j, town2 in enumerate(towns[i+1:], i+1):
    town2_values = np.array(data.loc[data['city'] == town2][field])
    # town2_values = (town2_values - np.mean(town2_values)) / (np.

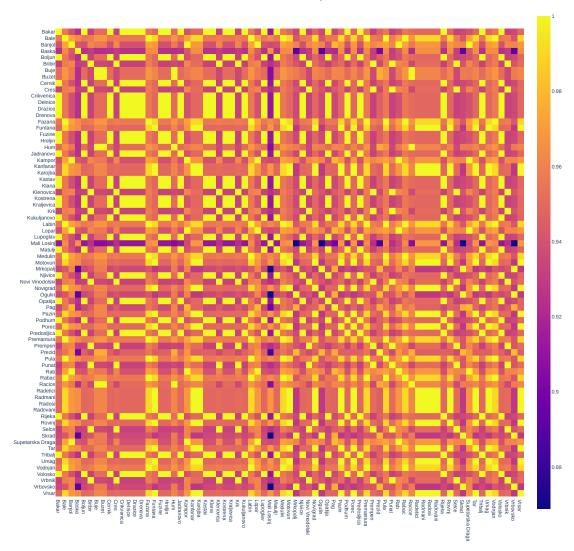
std(town2_values))

# ret_matrix[i,j] = np.correlate(town1_values, town2_values)[0]
ret_matrix[i,j] = np.corrcoef(town1_values, town2_values)[0,1]
ret_matrix[j,i] = ret_matrix[i,j]

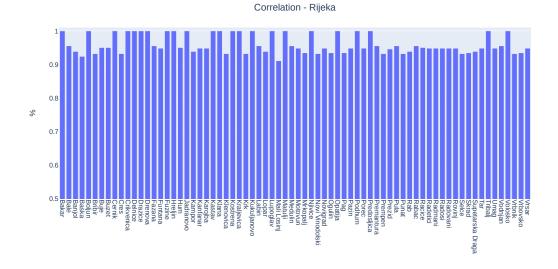
return ret_matrix
```

```
[7]: # global variables
     CORRELATION_DIR = 'correlation_plots'
     # select which columns to keep
     COLUMNS_TO_KEEP = ['tempC']
     # COLUMNS_TO_KEEP = ['humidity']
     # create directory if does not exist
     create_folder(CORRELATION_DIR)
     # list of all towns
     unique_towns = sorted(list(df_full_data['city'].unique()))
     # create dataframe and string needed to create out files
     df_data, PREFIX_STR = truncate_df(
         df=df full data,
         columns_to_keep=COLUMNS_TO_KEEP,
         # months=[6,7,8,9]
         # additional_conditions=[('weatherDesc', 'in', ['Clear', 'Sunny', ], )]
         # additional_conditions=[('weatherDesc', 'in', ['Partly cloudy', 'Cloudy',
      →], )]
     # modify output folder
     CORRELATION_DIR = f'{CORRELATION_DIR}/{PREFIX_STR}'
     create_folder(CORRELATION_DIR)
     CORRELATION_DATA_FILENAME = f'data/correlation/{PREFIX_STR}_correlation_data.
     onpy'
     # check if we already have correlation matrix saved
     if os.path.exists(CORRELATION_DATA_FILENAME):
         print('Correlation file exists!')
         corr_matrix = np.load(CORRELATION_DATA_FILENAME)
```

Correlation file does not exist.. Creating one...



```
curr_df = pd.DataFrame({'CITY': curr_towns, 'VALUES': curr_values})
fig = px.bar(
    curr_df,
    x='CITY',
    y='VALUES',
    hover_name='CITY',
    width=1000,
    height=500
)
fig.update_layout(title_text=f'Correlation - {town}', title_x=0.5)
fig.update_xaxes(
    tickangle=90,
    tickmode='linear',
    title=''
)
fig.update_yaxes(
    title='%',
    range=[0.5,1.01]
fig.write_image(CORRELATION_IMAGE_FILENAME)
if town == 'Rijeka':
    fig.show()
```



1.1 Correlation Map

```
[11]: # plot map with values from SVD V (towns to concept)
      def plot_correlation_map(partitions, data_geo, corr_matrix, map_borders):
          named colorscales = px.colors.DEFAULT PLOTLY COLORS * 10
          CORR_MAP_FILENAME = f'{CORRELATION_DIR}/
       →{PREFIX_STR}_correlation_map_{len(partitions)}communities.png'
          remove_file_if_exists(CORR_MAP_FILENAME)
          mapbox_access_token = (open(".mapbox_token").read())
          fig = go.Figure()
          fig.update_layout(
              width=1800,
              height=800,
          )
          # create a list with all dfs to plot cities in scatter plot at the end
          list data geo nodes = []
          # itterate through partitions and draw them on the map
          for i, partition in enumerate(partitions):
              # cast set to list and extract wanted cities from df
              partition = list(partition)
              # if there is a single element in the partition, print it
              data_geo_nodes = data_geo.loc[data_geo.index.isin(partition)]
              if len(partition) < 2:</pre>
                  ind = partition[0]
                  print(f'There is a single element partition: {unique_towns[ind]}')
                  fig.add_trace(
                      go.Scattermapbox(
                          mode = "markers",
                          lon=data geo nodes['LNG'],
                          lat=data_geo_nodes['LAT'],
                          name=data_geo_nodes['CITY'].values[0],
                          legendgroup=f'Partition {i+1}',
                          showlegend=True,
                          marker=dict(color=named_colorscales[i], size=14)
                      )
                  )
                  continue
              # append df to list
              list_data_geo_nodes.append(data_geo_nodes)
```

```
# itterate through elements in partition and plot the pairs
       for j in range(len(partition)-1):
           # extract values
           corr_value = corr_matrix[partition[j], partition[j+1]]
           nodes_index = [partition[j], partition[j+1]]
           # truncate df to just two cities
           data_geo_pair = data_geo_nodes.loc[data_geo_nodes.index.
→isin(nodes_index)]
           city_from, city_to = data_geo_nodes.at[partition[j], "CITY"],__

data_geo_nodes.at[partition[j+1], "CITY"]

           # calculate scaled width and opacity
           scaled_width = scale_range(
               old_value=corr_value,
               corr_matrix=corr_matrix,
               new_min=0.5,
               new_max=3.5,
           scaled_opacity = scale_range(
               old_value=corr_value,
               corr_matrix=corr_matrix,
               new_min=0.3,
               new_max=1.0,
           )
           # draw lines and group them by partitions using legendgroup
           fig.add_trace(
               go.Scattermapbox(
                   mode = "lines",
                   lon = data_geo_pair['LNG'],
                   lat = data_geo_pair['LAT'],
                   name=f'{city_from} - {city_to}: corr:{round(corr_value,__
\hookrightarrow 2)\}',
                   legendgroup=f'Partition {i+1}',
                   showlegend=True,
                   line=dict(color=named_colorscales[i], width=scaled_width),
                   # opacity=scaled_opacity
               )
           )
   # plot cities as scatters on the map with different color
  all_data_geo_nodes = pd.concat(list_data_geo_nodes)
  fig.add_trace(
       go.Scattermapbox(
           mode = "markers",
```

```
lon = all_data_geo_nodes['LNG'],
        lat = all_data_geo_nodes['LAT'],
        text=all_data_geo_nodes['CITY'],
        showlegend=False,
        marker=dict(color=named_colorscales[i+1], size=7)
    )
)
# setup layout parameters
fig.update_layout(
    width=1485,
    height=700,
    margin = {
        '1':15,
        'r':35,
        't':35,
        'b':15,
    },
    autosize=True,
    mapbox = {
        'accesstoken': mapbox_access_token,
        'center': {
            'lon': np.average(map_borders[0:2]),
            'lat': np.average(map_borders[2:4])
        },
        'style': "open-street-map",
        'zoom': 7.5
    },
    title_text=f'Correlation Between Cities ({len(partitions)} Partitions)',
    title_x=0.5
)
fig.write_image(CORR_MAP_FILENAME)
fig.show()
```

```
from geopy.distance import geodesic as GD

# function to scale up correlation values
def scale_range(old_value, corr_matrix, new_min, new_max):
    old_min = np.min(corr_matrix)
    old_max = np.max(corr_matrix)

old_range = old_max - old_min
    new_range = new_max - new_min

if old_value == old_min:
    return new_min
```

```
new_value = (((old_value - old_min) * new_range) / old_range) + new_min
return new_value

# function to create graph from correlation matrix
def create_graph(corr_matrix, towns_index, data_geo):
   G = nx.Graph()
   for i in towns_index:
        for j in towns_index[i+1:]:
            G.add_edge(i, j, weight=corr_matrix[i,j])

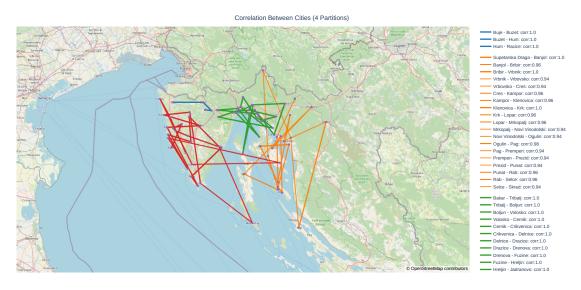
return G
```

```
[13]: # import cities with its logitude and latitude
      GEO_POSITION_FILENAME = 'data/geo_position.csv'
      df_geo_position = pd.read_csv(GEO_POSITION_FILENAME, )
      df geo position.sort values(by=['CITY'], inplace=True)
      df_geo_position.reset_index(drop=True, inplace=True)
      # left right up down
      map_borders = (
          np.min(df_geo_position['LNG']),
          np.max(df_geo_position['LNG']),
          np.max(df_geo_position['LAT']),
          np.min(df_geo_position['LAT']),
      )
      # call function to create graph G
      G = create_graph(
          corr_matrix=corr_matrix,
          towns_index=list(df_geo_position.index),
          data geo=df geo position
      )
      # send G to create n partitions and plot them on data
      resoultion_value = 1
      min_no_of_communities = 4
      while True:
          while True:
              G_partitions = nx.algorithms.community.louvain_communities(
                  weight='weight',
                  seed=100,
                  threshold=1e-07,
                  resolution=resoultion_value
              curr_len = len(G_partitions)
```

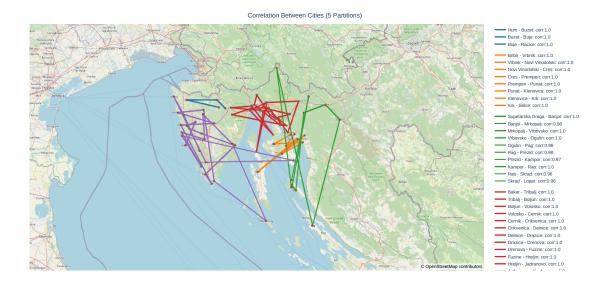
```
if curr_len >= min_no_of_communities:
          break
      resoultion_value += 0.001
  # break if there are 3 more communities than minimum set
  if len(G_partitions) >= min_no_of_communities + 3 or min_no_of_communities_u
⇒== 8:
      break
  # order them by number of cities in partition (just to have it better drawn)
  G_partitions.sort(key=len)
  print(f'Min communities: {min_no_of_communities} -- Resoluton value:

√{resoultion_value}')
  # plot map
  plot_correlation_map(
      partitions=G_partitions,
      data_geo=df_geo_position,
      corr_matrix=corr_matrix,
      map_borders=map_borders,
  )
  # increase min no of communities
  min_no_of_communities += 1
```

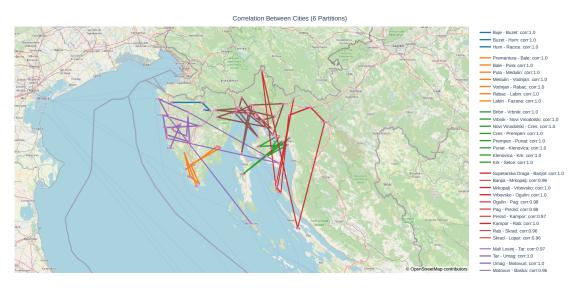
Min comumunities: 4 -- Resoluton value: 1.0189999999998



Min comumunities: 5 -- Resoluton value: 1.02799999999997



Min comumunities: 6 -- Resoluton value: 1.031999999999965



2 Export to HTML

[14]: # save notebook before nbconvert
import IPython
[15]: %%javascript

<IPython.core.display.Javascript object>

IPython.notebook.save_notebook()

[NbConvertApp] Converting notebook correlation.ipynb to HTML [NbConvertApp] Writing 4536207 bytes to output/columns-tempC_correlation.html