1 Model

$$S' = bN - \beta \frac{SA}{N} - dS$$

$$A' = \beta \frac{SA}{N} - \xi T - (d + 0.5)A$$

$$T' = 0.5A - (d + \xi + \delta)T$$

$$Q' = \delta T - dQ$$

$$N' = (b - d)N$$

2 Reproduction Number

In order to find the reproduction number we reformulate the state space model of the SATQ model as follows:

Let X = (A, T, Q, S). Then we can write the state space model as:

$$\frac{dX}{dt} = \mathcal{F}(x) - \mathcal{V}(x)$$

where we define $\mathcal{F}(x)$ and $\mathcal{V}(x)$ as follows

$$\mathcal{F}(x) = \begin{pmatrix} \beta \frac{SA}{N} \\ 0 \\ 0 \\ 0 \end{pmatrix} \text{ and }$$

$$\mathcal{V}(x) = \begin{pmatrix} (0.5+d)A - \xi T \\ (d+\xi+\delta)T - 0.5A \\ dQ - \delta T \\ \beta \frac{S_N}{N} + dS - bN \end{pmatrix} \text{ and }$$

$$\mathcal{DV}(Eo) = \begin{pmatrix} 0.5 + d & \xi & 0 & 0 \\ 0.5 & d + \xi + \delta & 0 & 0 \\ 0 & -\delta & d & 0 \\ \beta & 0 & 0 & 0 \end{pmatrix} \text{ and }$$

$$R_0 = \rho(FV^{-1}) = \frac{b\beta(d+\xi+\delta)}{0.5d(d+\delta+d(d+\xi+\delta))}$$

3 Stability Analysis

3.1 Method 1 - Dealing with Populations

$$\mathcal{J}(Eo) = \begin{pmatrix} \beta(d+0.5) & \xi & 0 & 0\\ 0.5 & -(d+\xi+\delta) & 0 & 0\\ 0 & \delta & -d & 0\\ -\beta & 0 & 0 & -d \end{pmatrix}$$

We can easily solve for two eigenvalues $\lambda_1 = \lambda_2 = -d < 0$, while λ_3 and λ_4 satisfy the equation

$$\lambda^{2} + [2d + \xi + \delta + 0.5 - \beta]\lambda + (d + \xi + \delta)(d + 0.5 - \beta) - 0.5\xi = 0$$

Manipulation of this equation proves that Real parts of both λ_3 and λ_4 are less than 0.

Re
$$\lambda_3 < 0$$
, Re $\lambda_4 < 0$

3.2 Method 2 - Dealing with Proportions

4 Equlibibrium Points

$$S^* = \frac{0.5bN^2}{0.5dN + T^*\beta(d + \xi + \delta)}$$

$$A^* = \frac{(d+\xi+\delta)T^*}{0.5}$$

$$Q^* = \tfrac{T^*\delta}{d}$$

$$T^* = \frac{\sigma}{\beta(d+\xi+\delta)[d\xi+(\delta+d)(d+0.5)]}$$

where

$$\sigma = 0.5bN\beta(d+\xi+\delta) + 0.5^2dN\xi - 0.5dN(d+0.5)(d+\xi+\delta)$$

5 Proportion Model

$$s' = b - \beta sa - bs$$

$$a' = \beta sa - \xi t - (b + 0.5)a$$

$$t' = 0.5a - (b + \xi + \delta)t$$

$$q' = \delta t - bQ$$