

HA Energy
Solar Project #1

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Chapter 1

Data Structure Index

1.1 Data Structures

Here are the data structures with brief descriptions:

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Chapter 2

File Index

2.1 File List

Here is a list of all documented files with brief descriptions:

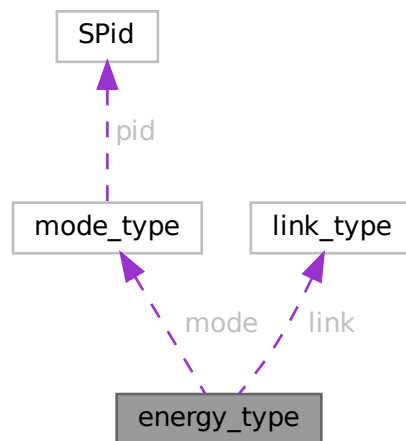
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Chapter 3

Data Structure Documentation

3.1 energy_type Struct Reference

Collaboration diagram for energy_type:



Data Fields

- volatile double **print_vars** [MAX_IM_VAR]
- volatile double **im_vars** [IA_LAST][PHASE_LAST]
- volatile double **mvar** [V_DLAST+1]
- volatile bool **once_gti**
- volatile bool **once_ac**
- volatile bool **iammeter**
- volatile bool **fm80**
- volatile bool **dumpload**
- volatile bool **homeassistant**

- volatile bool **once_gti_zero**
- volatile double **gti_low_adj**
- volatile double **ac_low_adj**
- volatile double **dl_excess_adj**
- volatile bool **ac_sw_on**
- volatile bool **gti_sw_on**
- volatile bool **ac_sw_status**
- volatile bool **gti_sw_status**
- volatile bool **solar_shutdown**
- volatile bool **solar_mode**
- volatile bool **startup**
- volatile bool **ac_mismatch**
- volatile bool **dc_mismatch**
- volatile bool **mode_mismatch**
- volatile bool **dl_excess**
- volatile uint32_t **speed_go**
- volatile uint32_t **im_delay**
- volatile uint32_t **im_display**
- volatile uint32_t **gti_delay**
- volatile int32_t **rc**
- volatile int32_t **sane**
- volatile uint32_t **ten_sec_clock**
- volatile uint32_t **log_spam**
- volatile uint32_t **log_time_reset**
- pthread_mutex_t **ha_lock**
- struct [mode_type](#) **mode**
- struct [link_type](#) **link**
- MQTTClient **client_p**
- MQTTClient **client_sd**
- MQTTClient **client_ha**

The documentation for this struct was generated from the following file:

- [ha_energy/energy.h](#)

3.2 ha_flag_type Struct Reference

Data Fields

- volatile MQTTClient_deliveryToken **deliveredtoken**
- volatile MQTTClient_deliveryToken **receivedtoken**
- volatile bool **runner**
- volatile bool **rec_ok**
- int32_t **ha_id**
- volatile int32_t **var_update**
- volatile int32_t **energy_mode**
- enum client_id **cid**

The documentation for this struct was generated from the following file:

- [ha_energy/mqtt_rec.h](#)

3.3 link_type Struct Reference

Data Fields

- volatile uint32_t **iammeter_error**
- volatile uint32_t **iammeter_count**
- volatile uint32_t **mqtt_error**
- volatile uint32_t **mqtt_count**
- volatile uint32_t **shutdown**

The documentation for this struct was generated from the following file:

- [ha_energy/energy.h](#)

3.4 local_type Struct Reference

Data Fields

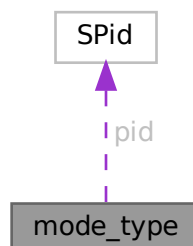
- volatile double **ac_weight**
- volatile double **gti_weight**
- volatile double **pv_voltage**
- volatile double **bat_current**
- volatile double **batc_std_dev**
- volatile double **bat_voltage**
- double **bat_c_std_dev** [DEV_SIZE]
- double **coef**

The documentation for this struct was generated from the following file:

- [ha_energy/bsoc.c](#)

3.5 mode_type Struct Reference

Collaboration diagram for mode_type:



Data Fields

- volatile double **error**
- volatile double **target**
- volatile double **total_system**
- volatile double **gti_dumpload**
- volatile double **pv_bias**
- volatile double **dl_mqtt_max**
- volatile double **off_grid**
- volatile double **sequence**
- volatile bool **mode**
- volatile bool **in_pid_control**
- volatile bool **con0**
- volatile bool **con1**
- volatile bool **con2**
- volatile bool **con3**
- volatile bool **con4**
- volatile bool **con5**
- volatile bool **con6**
- volatile bool **con7**
- volatile bool **no_float**
- volatile bool **data_error**
- volatile bool **bat_crit**
- volatile uint32_t **mode_tmr**
- volatile struct [SPid](#) **pid**
- enum energy_state **E**
- enum running_state **R**

The documentation for this struct was generated from the following file:

- [ha_energy/energy.h](#)

3.6 SPid Struct Reference

Data Fields

- double **dState**
- double **iState**
- double **iMax**
- double **iMin**
- double **iGain**
- double **pGain**
- double **dGain**

The documentation for this struct was generated from the following file:

- [ha_energy/pid.h](#)

Variables

- struct [ha_flag_type](#) [ha_flag_vars_pc](#)
- struct [ha_flag_type](#) [ha_flag_vars_ss](#)
- struct [ha_flag_type](#) [ha_flag_vars_sd](#)
- struct [ha_flag_type](#) [ha_flag_vars_ha](#)
- const char * **board_name** = "NO_BOARD"
- const char * **driver_name** = "NO_DRIVER"
- FILE * **fout**
- struct [energy_type](#) [E](#)

4.1.1 Detailed Description

V0.25 add Home Assistant Matter controlled utility power control switching V0.26 BSOC weights for system condition for power diversion V0.27 -> V0.28 GTI power ramps stability using battery current STD DEV V0.29 log date-time and spam control V0.30 add iammeter http data reading and processing V0.31 refactor http code and a few vars V0.32 AC and GTI power triggers reworked V0.33 refactor system parms into energy structure [energy_type](#) [E](#) V0.↔ 34 GTI and AC Inverter battery energy run down limits adjustments per energy usage and solar production V0.35 more refactors and global variable consolidation V0.36 more command repeat fixes for ramp up/down dumpload commands V0.37 Power feedback to use PV power to GTI and AC loads V0.38 signal filters to smooth large power swings in control optimization V0.39 fix optimizer bugs and add AC load switching set-points in BSOC control V0.↔ 40 shutdown and restart fixes V0.41 fix errors and warning per cppcheck V0.42 fake ac charger for dumpload using FAKE_VPV define V0.43 adjust PV_BIAS per float or charging status V0.44 tune for spring/summer solar conditions V0.50 convert main loop code to FSM V0.51 logging time additions V0.52 tune GTI inverter levels for better conversion efficiency V0.53 sync to HA back-end switch status V0.54 data source shutdown functions V0.55 off-grid inverter power tracking for HA V0.56 run as Daemon in background V0.62 adjust battery critical to keep making energy calculations V0.63 add IP address logging V0.64 Dump Load excess load mode programming V0.65 DL excess logic tuning and power adjustments V0.66 -> V0.68 Various timing fixes to reduce spamming commands and logs V0.69 send MQTT showdown commands to HA when critical energy conditions are meet V0.70 process Home Assistant MQTT commands sent from automation's

V0.71 comment additions, logging improvements and code cleanups V0.72 -> V0.73 fine tune GTI and AC power lower limits V0.74 Doxygen comments added V0.75 connection lost logging and Keep Alive fixes

4.1.2 Function Documentation

4.1.2.1 connlost()

```
void connlost (
    void * context,
    char * cause)
```

trouble in River-city

```
00301 {
00302     struct ha_flag_type *ha_flag = context;
00303     int32_t id_num = ha_flag->ha_id;
00304     static uint32_t times = 0;
00305     char * where = "Missing Topic";
00306
00307     switch (ha_flag->cid) {
00308     case ID_C1:
00309         where = TOPIC_SS;
00310         break;
00311     case ID_C2:
00312         where = TOPIC_SD;
00313         break;
00314     case ID_C3:
00315         where = TOPIC_HA;
00316         break;
```

```

00317     }
00318
00319     // bug-out if no context variables passed to callback
00320     if (context == NULL) {
00321         id_num = -1;
00322         goto bugout;
00323     } else {
00324         if (times++ > MQTT_RECONN) {
00325             goto bugout;
00326         } else {
00327
00328             fprintf(fout, "\n%s Connection lost, exit ha_energy program\n", log_time(false));
00329             fprintf(fout, "%s      cause: %s, h_id %d c_id %d %s \n", log_time(false), cause, id_num,
ha_flag->cid, where);
00330             fprintf(fout, "%s MQTT DAEMON failure  LOG Version %s : MQTT Version %s\n",
log_time(false), LOG_VERSION, MQTT_VERSION);
00331             fflush(fout);
00332         }
00333     }
00334
00335 bugout:
00336     fprintf(fout, "\n%s Connection lost, exit ha_energy program\n", log_time(false));
00337     fprintf(fout, "%s      cause: %s, h_id %d c_id %d %s \n", log_time(false), cause, id_num,
ha_flag->cid, where);
00338     fprintf(fout, "%s MQTT DAEMON failure  LOG Version %s : MQTT Version %s\n", log_time(false),
LOG_VERSION, MQTT_VERSION);
00339     fflush(fout);
00340     exit(EXIT_FAILURE);
00341 }

```

4.1.2.2 ha_ac_off()

```

void ha_ac_off (
    void )

00978 {
00979     mqtt_ha_switch(E.client_p, TOPIC_PACC, false);
00980     E.ac_sw_status = false;
00981 }

```

4.1.2.3 ha_ac_on()

```

void ha_ac_on (
    void )

00984 {
00985     mqtt_ha_switch(E.client_p, TOPIC_PACC, true);
00986     E.ac_sw_status = true;
00987 }

```

4.1.2.4 ha_dc_off()

```

void ha_dc_off (
    void )

00993 {
00994     mqtt_ha_switch(E.client_p, TOPIC_PDCC, false);
00995     E.gti_sw_status = false;
00996 }

```

4.1.2.5 ha_dc_on()

```

void ha_dc_on (
    void )

00999 {
01000     mqtt_ha_switch(E.client_p, TOPIC_PDCC, true);
01001     E.gti_sw_status = true;
01002 }

```

4.1.2.6 log_time()

```

char * log_time (
    bool log)

01063 {
01064     static char time_log[RBUF_SIZ] = {0};
01065     static uint32_t len = 0, sync_time = TIME_SYNC_SEC - 1;
01066     time_t rawtime_log;
01067
01068     tzset();
01069     timezone = 0;
01070     daylight = 0;
01071     time(&rawtime_log);
01072     if (sync_time++ > TIME_SYNC_SEC) {
01073         sync_time = 0;
01074         snprintf(time_log, RBUF_SIZ - 1, "VT%lut", rawtime_log); // format for dumpload controller gti
time commands
01075         mqtt_gti_time(E.client_p, TOPIC_P, time_log);
01076     }
01077
01078     sprintf(time_log, "%s", ctime(&rawtime_log));
01079     len = strlen(time_log);
01080     time_log[len - 1] = 0; // munge out the return character
01081     if (log) {
01082         fprintf(fout, "%s ", time_log);
01083         fflush(fout);
01084     }
01085
01086     return time_log;
01087 }

```

4.1.2.7 log_timer()

```

bool log_timer (
    void )

01122 {
01123     bool itstime = false;
01124
01125     if (E.log_spam < LOW_LOG_SPAM) {
01126         E.log_time_reset = 0;
01127         itstime = true;
01128     }
01129     if (E.log_time_reset > RESET_LOG_SPAM) {
01130         E.log_spam = 0;
01131         itstime = true;
01132     }
01133     return itstime;
01134 }

```

4.1.2.8 main()

```

int main (
    int argc,
    char * argv[])

00350 {
00351     struct itimerval new_timer = {
00352         .it_value.tv_sec = CMD_SEC,
00353         .it_value.tv_usec = 0,
00354         .it_interval.tv_sec = CMD_SEC,
00355         .it_interval.tv_usec = 0,
00356     };
00357     struct itimerval old_timer;
00358     time_t rawtime;
00359     MQTTClient_connectOptions conn_opts_p = MQTTClient_connectOptions_initializer,
00360     conn_opts_sd = MQTTClient_connectOptions_initializer,
00361     conn_opts_ha = MQTTClient_connectOptions_initializer;
00362     MQTTClient_message pubmsg = MQTTClient_message_initializer;
00363     MQTTClient_deliveryToken token;
00364     char hname[256], *hname_ptr = hname;
00365     size_t hname_len = 12;
00366
00367     gethostname(hname, hname_len);
00368     hname[12] = 0;

```



```

00369     printf("\r\n LOG Version %s : MQTT Version %s : Host Name %s\r\n", LOG_VERSION, MQTT_VERSION,
hname);
00370     showIP();
00371     skeleton_daemon();
00372
00373     while (true) {
00374         switch (E.mode.E) {
00375             case E_INIT:
00376
00377 #ifdef LOG_TO_FILE
00378         fout = fopen(LOG_TO_FILE, "a");
00379         if (fout == NULL) {
00380             fout = fopen(LOG_TO_FILE_ALT, "a");
00381             if (fout == NULL) {
00382                 fout = stdout;
00383                 printf("\r\n%s Unable to open LOG file %s \r\n", log_time(false),
LOG_TO_FILE_ALT);
00384             }
00385         }
00386 #else
00387         fout = stdout;
00388 #endif
00389         fprintf(fout, "\r\n%s LOG Version %s : MQTT Version %s\r\n", log_time(false), LOG_VERSION,
MQTT_VERSION);
00390         fflush(fout);
00391
00392         if (!bsoc_init()) {
00393             fprintf(fout, "\r\n%s bsoc_init failure \r\n", log_time(false));
00394             fflush(fout);
00395             exit(EXIT_FAILURE);
00396         }
00397         /*
00398          * set the timer for MQTT publishing sample speed
00399          * CMD_SEC      10
00400          */
00401         setitimer(ITIMER_REAL, &new_timer, &old_timer);
00402         signal(SIGALRM, timer_callback);
00403
00404         if (strcmp(hname, TNAME, 6) == 0) {
00405             MQTTClient_create(&E.client_p, LADDRESS, CLIENTID1,
MQTTCLIENT_PERSISTENCE_NONE, NULL);
00406             conn_opts_p.keepAliveInterval = KAI;
00407             conn_opts_p.cleansession = 1;
00408             hname_ptr = LADDRESS;
00409         } else {
00410             MQTTClient_create(&E.client_p, ADDRESS, CLIENTID1,
MQTTCLIENT_PERSISTENCE_NONE, NULL);
00411             conn_opts_p.keepAliveInterval = KAI;
00412             conn_opts_p.cleansession = 1;
00413             hname_ptr = ADDRESS;
00414         }
00415
00416         fprintf(fout, "%s Connect MQTT server %s, %s\n", log_time(false), hname_ptr, CLIENTID1);
00417         fflush(fout);
00418         ha_flag_vars_ss.cid = ID_C1;
00419         MQTTClient_setCallbacks(E.client_p, &ha_flag_vars_ss, connlost, msgarrvd, delivered);
00420         if ((E.rc = MQTTClient_connect(E.client_p, &conn_opts_p)) != MQTTCLIENT_SUCCESS) {
00421             fprintf(fout, "%s Failed to connect MQTT server, return code %d %s, %s\n",
log_time(false), E.rc, hname_ptr, CLIENTID1);
00422             fflush(fout);
00423             pthread_mutex_destroy(&E.ha_lock);
00424             exit(EXIT_FAILURE);
00425         }
00426
00427         if (strcmp(hname, TNAME, 6) == 0) {
00428             MQTTClient_create(&E.client_sd, LADDRESS, CLIENTID2,
MQTTCLIENT_PERSISTENCE_NONE, NULL);
00429             conn_opts_sd.keepAliveInterval = KAI;
00430             conn_opts_sd.cleansession = 1;
00431             hname_ptr = LADDRESS;
00432         } else {
00433             MQTTClient_create(&E.client_sd, ADDRESS, CLIENTID2,
MQTTCLIENT_PERSISTENCE_NONE, NULL);
00434             conn_opts_sd.keepAliveInterval = KAI;
00435             conn_opts_sd.cleansession = 1;
00436             hname_ptr = ADDRESS;
00437         }
00438
00439         fprintf(fout, "%s Connect MQTT server %s, %s\n", log_time(false), hname_ptr, CLIENTID2);
00440         fflush(fout);
00441         ha_flag_vars_sd.cid = ID_C2;
00442         MQTTClient_setCallbacks(E.client_sd, &ha_flag_vars_sd, connlost, msgarrvd, delivered);
00443         if ((E.rc = MQTTClient_connect(E.client_sd, &conn_opts_sd)) != MQTTCLIENT_SUCCESS) {
00444             fprintf(fout, "%s Failed to connect MQTT server, return code %d %s, %s\n",
log_time(false), E.rc, hname_ptr, CLIENTID2);
00445             fflush(fout);
00446             pthread_mutex_destroy(&E.ha_lock);
00447         }
00448     }

```

```

00451         exit(EXIT_FAILURE);
00452     }
00453
00454     /*
00455     * Home Assistant MQTT receive messages
00456     */
00457     if (strcmp(hname, TNAME, 6) == 0) {
00458         MQTTClient_create(&E.client_ha, LADDRESS, CLIENTID3,
00459             MQTTCLIENT_PERSISTENCE_NONE, NULL);
00460         conn_opts_ha.keepAliveInterval = KAI;
00461         conn_opts_ha.cleansession = 1;
00462         hname_ptr = LADDRESS;
00463     } else {
00464         MQTTClient_create(&E.client_ha, ADDRESS, CLIENTID3,
00465             MQTTCLIENT_PERSISTENCE_NONE, NULL);
00466         conn_opts_ha.keepAliveInterval = KAI;
00467         conn_opts_ha.cleansession = 1;
00468         hname_ptr = ADDRESS;
00469     }
00470
00471     fprintf(fout, "%s Connect MQTT server %s, %s\n", log_time(false), hname_ptr, CLIENTID3);
00472     fflush(fout);
00473     ha_flag_vars_ha.cid = ID_C3;
00474     MQTTClient_setCallbacks(E.client_ha, &ha_flag_vars_ha, connlost, msgarrvd, delivered);
00475     if ((E.rc = MQTTClient_connect(E.client_ha, &conn_opts_ha)) != MQTTCLIENT_SUCCESS) {
00476         log_time(false), E.rc, hname_ptr, CLIENTID3);
00477         fprintf(fout, "%s Failed to connect MQTT server, return code %d %s, %s\n",
00478             log_time(false), E.rc, hname_ptr, CLIENTID3);
00479         fflush(fout);
00480         pthread_mutex_destroy(&E.ha_lock);
00481         exit(EXIT_FAILURE);
00482     }
00483
00484     /*
00485     * on topic received data will trigger the msgarrvd function
00486     */
00487     MQTTClient_subscribe(E.client_p, TOPIC_SS, QOS); // FM80 Q84
00488     MQTTClient_subscribe(E.client_sd, TOPIC_SD, QOS); // DUMPLOAD K42
00489     MQTTClient_subscribe(E.client_ha, TOPIC_HA, QOS); // Home Assistant Linux AMD64 and ARM64
00490
00491     pubmsg.payload = "online";
00492     pubmsg.payloadlen = strlen("online");
00493     pubmsg.qos = QOS;
00494     pubmsg.retained = 0;
00495     ha_flag_vars_ss.deliveredtoken = 0;
00496     // notify HA we are running and controlling AC power plugs
00497     MQTTClient_publishMessage(E.client_p, TOPIC_PACA, &pubmsg, &token);
00498     MQTTClient_publishMessage(E.client_p, TOPIC_PDCA, &pubmsg, &token);
00499
00500     // sync HA power switches
00501     mqtt_ha_switch(E.client_p, TOPIC_PDCC, false);
00502     mqtt_ha_switch(E.client_p, TOPIC_PACC, false);
00503     mqtt_ha_switch(E.client_p, TOPIC_PDCC, true);
00504     mqtt_ha_switch(E.client_p, TOPIC_PACC, true);
00505     mqtt_ha_switch(E.client_p, TOPIC_PDCC, false);
00506     mqtt_ha_switch(E.client_p, TOPIC_PACC, false);
00507
00508     E.ac_sw_on = true; // can be switched on once
00509     E.gti_sw_on = true; // can be switched on once
00510
00511     /*
00512     * use libcurl to read AC power meter HTTP data
00513     * iammeter connected for split single phase monitoring and one leg GTI power exporting
00514     */
00515     iammeter_read();
00516
00517     /*
00518     * start the main energy monitoring loop
00519     */
00520     fprintf(fout, "\r\n%s Solar Energy AC power controller\r\n", log_time(false));
00521
00522     #ifdef FAKE_VPV
00523     fprintf(fout, "\r\nFaking dumpload PV voltage\r\n");
00524     #endif
00525     ha_flag_vars_ss.energy_mode = NORM_MODE;
00526     E.mode.E = E_WAIT;
00527     break;
00528     case E_WAIT:
00529     if (ha_flag_vars_ss.runner || E.speed_go++ > 1500000) {
00530         E.speed_go = 0;
00531         ha_flag_vars_ss.runner = false;
00532         E.mode.E = E_RUN;
00533     }
00534     usleep(100);
00535     /*
00536     * main state-machine update sequence
00537     */

```

```

00537         bsoc_data_collect();
00538         if (!sanity_check()) {
00539             fprintf(fout, "\r\n%s Sanity Check error %d %s \r\n", log_time(false), E.sane,
mqtt_name[E.sane]);
00540             fflush(fout);
00541         }
00542
00543         /*
00544          * stop and restart the energy control processing
00545          * from inside the program or from a remote Home Assistant command
00546          */
00547         if (solar_shutdown()) {
00548             if (!E.startup) {
00549                 fprintf(fout, "%s SHUTDOWN Solar Energy Control ---> \r\n", log_time(false));
00550             }
00551             fflush(fout);
00552             ramp_down_gti(E.client_p, true);
00553             usleep(100000); // wait
00554             ramp_down_ac(E.client_p, true);
00555             usleep(100000); // wait
00556             ramp_down_gti(E.client_p, true);
00557             usleep(100000); // wait
00558             ramp_down_ac(E.client_p, true);
00559             usleep(100000); // wait
00560             if (!E.startup) {
00561                 fprintf(fout, "%s Completed SHUTDOWN, Press again to RESTART.\r\n",
log_time(false));
00562                 fflush(fout);
00563             }
00564             fflush(fout);
00565
00566             uint8_t iam_delay = 0;
00567             while (solar_shutdown()) {
00568                 mqtt_ha_shutdown(E.client_p, TOPIC_SHUTDOWN);
00569                 usleep(USEC_SEC); // wait
00570                 if ((int32_t) E.mvar[V_HACSW]) {
00571                     ha_ac_off();
00572                 }
00573                 if ((int32_t) E.mvar[V_HDCSW]) {
00574                     ha_dc_off();
00575                 }
00576                 if ((iam_delay++ > IAM_DELAY) && E.link.shutdown) {
00577                     E.fm80 = true;
00578                     E.dumpload = true;
00579                     E.iammeter = true;
00580                     E.homeassistant = true;
00581                 }
00582             }
00583             E.link.shutdown = 0;
00584             fprintf(fout, "%s RESTART Solar Energy Control\r\n", log_time(false));
00585             fflush(fout);
00586             bsoc_set_mode(E.mode.pv_bias, true, true);
00587             E.dl_excess = true;
00588             mqtt_gti_power(E.client_p, TOPIC_P, "Z#", 1); // zero power at startup
00589             E.dl_excess = false;
00590 #ifdef AUTO_CHARGE
00591             mqtt_ha_switch(E.client_p, TOPIC_PDCC, true);
00592 #endif
00593             usleep(100000); // wait
00594             E.gti_sw_status = true;
00595             ResetPI(&E.mode.pid);
00596             ha_flag_vars_ss.runner = true;
00597             E.fm80 = true;
00598             E.dumpload = true;
00599             E.iammeter = true;
00600             E.homeassistant = true;
00601             E.mode.in_pid_control = false; // shutdown auto energy control
00602             E.mode.R = R_INIT;
00603         }
00604         if (ha_flag_vars_ss.receivedtoken) {
00605             ha_flag_vars_ss.receivedtoken = false;
00606         }
00607         if (ha_flag_vars_sd.receivedtoken) {
00608             ha_flag_vars_sd.receivedtoken = false;
00609         }
00610         break;
00611     case E_RUN:
00612         usleep(100);
00613         switch (E.mode.R) {
00614             case R_INIT:
00615                 E.once_ac = true;
00616                 E.once_gti = true;
00617                 E.ac_sw_on = true;
00618                 E.gti_sw_on = true;
00619                 E.mode.R = R_RUN;
00620                 E.mode.no_float = true;
00621                 break;

```

```

00622     case R_FLOAT:
00623         if (E.mode.no_float) {
00624             E.once_ac = true;
00625             E.once_gti = true;
00626             E.ac_sw_on = true;
00627             E.gti_sw_on = true;
00628             E.gti_sw_status = false;
00629             E.ac_sw_status = false;
00630             E.mode.no_float = false;
00631         }
00632         if (!E.gti_sw_status) {
00633             if (gti_test() > MIN_BAT_KW_GTI_HI) {
00634                 mqttt_ha_switch(E.client_p, TOPIC_PDCC, true);
00635                 E.gti_sw_status = true;
00636                 fprintf(fout, "%s R_FLOAT DC switch true \r\n", log_time(false));
00637             }
00638         }
00639         usleep(100000); // wait
00640         if (!E.ac_sw_status) {
00641             if (ac_test() > MIN_BAT_KW_AC_HI) {
00642                 mqttt_ha_switch(E.client_p, TOPIC_PACC, true);
00643                 E.ac_sw_status = true;
00644                 fprintf(fout, "%s R_FLOAT AC switch true \r\n", log_time(false));
00645             }
00646         }
00647         E.mode.pv_bias = PV_BIAS;
00648         fm80_float(true);
00649         break;
00650     case R_RUN:
00651     default:
00652         E.mode.R = R_RUN;
00653         E.mode.no_float = true;
00654         break;
00655     }
00656     /*
00657     * main state-machine update sequence and control logic
00658     */
00659     /*
00660     * check for idle/data errors flags from sensors and HA
00661     */
00662     if (!E.mode.data_error) {
00663         bsoc_set_mode(E.mode.pv_bias, true, false);
00664         if (E.gti_delay++ >= GTI_DELAY) {
00665             char gti_str[SBUF_SIZ];
00666             int32_t error_drive;
00667
00668             /*
00669             * reset the control mode from simple switched power to PID control
00670             */
00671             if (!E.mode.in_pid_control) {
00672                 mqttt_ha_switch(E.client_p, TOPIC_PDCC, true);
00673                 E.gti_sw_status = true;
00674                 usleep(100000); // wait
00675                 mqttt_ha_switch(E.client_p, TOPIC_PACC, true);
00676                 E.ac_sw_status = true;
00677                 E.mode.pv_bias = PV_BIAS;
00678                 fprintf(fout, "%s in_pid_mode AC/DC switch true \r\n", log_time(false));
00679                 fm80_float(true);
00680             } else {
00681                 if (!fm80_float(true)) {
00682                     E.mode.pv_bias = (int32_t) E.mode.error - PV_BIAS;
00683                 }
00684             }
00685             /*
00686             * use PID style set-point error correction
00687             */
00688             E.mode.in_pid_control = true;
00689             E.gti_delay = 0;
00690             /*
00691             * adjust power balance if battery charging energy is low
00692             */
00693             if (E.mvar[V_DPBAT] > PV_DL_BIAS_RATE) {
00694                 error_drive = (int32_t) E.mode.error - E.mode.pv_bias; // PI feedback control
00695                 signal
00696                 } else {
00697                     error_drive = (int32_t) E.mode.error - PV_BIAS_RATE;
00698                 }
00699             /*
00700             * when main battery is in float, crank-up the power draw from the solar panels
00701             */
00702             if (fm80_float(true)) {
00703                 error_drive = (int32_t) (E.mode.error + PV_BIAS);
00704             }
00705             /*
00706             * don't drive to zero power
00707             */
00707             if (error_drive < 0) {

```

```

00708         error_drive = PV_BIAS_LOW; // control wide power swings
00709         if (!fm80_sleep()) { // check for using sleep bias
00710             if ((E.mvar[V_FBEKW] > MIN_BAT_KW_BSOC_SLP) && (E.mvar[V_PWA] >
PWA_SLEEP)) {
00711                 error_drive = PV_BIAS_SLEEP; // use higher power when we still have
sun for better inverter efficiency
00712             }
00713         }
00714     }
00715
00716     /*
00717     * reduce charging/diversion power to safe PS limits
00718     */
00719     if (E.mode.dl_mqtt_max > PV_DL_MPTT_MAX) {
00720         if (!E.dl_excess) {
00721             error_drive = PV_DL_MPTT_IDLE;
00722         } else {
00723             if (E.mode.dl_mqtt_max > PV_DL_MPTT_EXCESS) {
00724                 error_drive = PV_DL_MPTT_IDLE;
00725             }
00726         }
00727     } else {
00728         if (E.dl_excess) {
00729             error_drive = PV_DL_EXCESS + E.dl_excess_adj;
00730         }
00731     }
00732
00733     /*
00734     * shutdown GTI power at low DL battery Ah or Voltage
00735     */
00736     if ((E.mvar[V_DAHBAT] < PV_DL_B_AH_LOW) || (E.mvar[V_DVBAT] < PV_DL_B_V_LOW)) {
00737         error_drive = PV_BIAS_ZERO;
00738     }
00739
00740     snprintf(gti_str, SBUF_SIZ - 1, "V%04dX", error_drive); // format for dumpload
controller gti power commands
00741     mqtt_gti_power(E.client_p, TOPIC_P, gti_str, 2);
00742 }
00743
00744 #ifndef FAKE_VPV
00745     if (fm80_float(true) || ((ac1_filter(E.mvar[V_BEN]) > BAL_MAX_ENERGY_AC) && (ac_test()
> MIN_BAT_KW_AC_HI))) {
00746         ramp_up_ac(E.client_p, E.ac_sw_on); // use once control
00747     #ifdef PSW_DEBUG
00748         fprintf(fout, "%s MIN_BAT_KW_AC_HI AC switch %d \r\n", log_time(false),
E.ac_sw_on);
00749     #endif
00750     E.ac_sw_on = false; // once flag
00751 }
00752 #endif
00753     if ((ac2_filter(E.mvar[V_BEN]) < BAL_MIN_ENERGY_AC) || ((ac_test() <
(MIN_BAT_KW_AC_LO + E.ac_low_adj)))) {
00754         if (!fm80_float(true)) {
00755             ramp_down_ac(E.client_p, E.ac_sw_on);
00756             if (log_timer()) {
00757                 fprintf(fout, "%s RAMP DOWN AC, MIN_BAT_KW_AC_LO AC switch %d \r\n",
log_time(false), E.ac_sw_on);
00758             }
00759         }
00760         E.ac_sw_on = true;
00761     }
00762
00763     /*
00764     * Dump Load Excess testing
00765     * send excess power into the home power grid taking care not to export energy to the
utility grid
00766     */
00767     if ((dc1_filter(E.mvar[V_BEN]) > BAL_MAX_ENERGY_GTI) && (gti_test() >
MIN_BAT_KW_GTI_HI) || E.dl_excess) {
00768         #ifndef FAKE_VPV
00769         #ifdef B_DLE_DEBUG
00770             if (E.dl_excess) {
00771                 fprintf(fout, "%s DL excess ramp_up_gti, DC switch %d \r\n", log_time(false),
E.gti_sw_on);
00772             }
00773         #endif
00774         ramp_up_gti(E.client_p, E.gti_sw_on, E.dl_excess);
00775         if (log_timer()) {
00776             fprintf(fout, "%s RAMP DOWN DC, MIN_BAT_KW_GTI_HI DC switch %d \r\n",
log_time(false), E.gti_sw_on);
00777         }
00778         E.gti_sw_on = false; // once flag
00779     #endif
00780     } else {
00781         if ((dc2_filter(E.mvar[V_BEN]) < BAL_MIN_ENERGY_GTI) || (gti_test() <
(MIN_BAT_KW_GTI_LO + E.gti_low_adj))) {

```

```

00783             if (!E.dl_excess) {
00784                 if (log_timer()) {
00785                     ramp_down_gti(E.client_p, true);
00786 #ifdef PSW_DEBUG
00787                     fprintf(fout, "%s MIN_BAT_KW_GTI_LO DC switch %d \r\n",
00788 log_time(false), E.gti_sw_on);
00788 #endif
00789                 }
00790                 E.gti_sw_on = true;
00791             }
00792         }
00793     }
00794 };
00795
00796 #ifdef B_ADJ_DEBUG
00797     fprintf(fout, "\r\n LO ADJ: AC %8.2fWh, GTI %8.2fWh\r\n", MIN_BAT_KW_AC_LO + E.ac_low_adj,
00798 MIN_BAT_KW_GTI_LO + E.gti_low_adj);
00798 #endif
00799 #ifdef B_DLE_DEBUG
00800     if (E.dl_excess) {
00801         fprintf(fout, "%s DL excess vars from ha_energy %d %d : Flag %d\r\n", log_time(false),
00802 E.mode.con4, E.mode.con5, E.dl_excess);
00802     }
00803 #endif
00804
00805     time(&rawtime);
00806
00807     if (E.im_delay++ >= IM_DELAY) {
00808         E.im_delay = 0;
00809         iammeter_read();
00810     }
00811     if (E.im_display++ >= IM_DISPLAY) {
00812         char buffer[SYSLOG_SIZ];
00813         uint32_t len;
00814
00815         E.im_display = 0;
00816         mqtt_ha_pid(E.client_p, TOPIC_PPID);
00817         if (!(E.fm80 && E.dumpload && E.iammeter)) {
00818             if (!E.iammeter) {
00819                 E.link.iammeter_error++;
00820             } else {
00821                 E.link.mqtt_error++;
00822             }
00823             E.link.shutdown++;
00824             fprintf(fout, "\r\n%s !!!! Source data update error !!!! , check FM80 %i, DUMpload
00825 %i, IAMMETER %i channels M %u,%u I %u,%u\r\n", log_time(false), E.fm80, E.dumpload, E.fm80,
00826 E.link.iammeter_error);
00827             snprintf(buffer, SYSLOG_SIZ - 1, "\r\n%s !!!! Source data update error !!!! ,
00828 check FM80 %i, DUMpload %i, IAMMETER %i channels M %u,%u I %u,%u\r\n", log_time(false), E.fm80,
00829 E.dumpload, E.fm80,
00830 E.link.mqtt_count, E.link.mqtt_error, E.link.iammeter_count,
00831 E.link.iammeter_error);
00832             syslog(LOG_NOTICE, buffer);
00833             mqtt_ha_shutdown(E.client_p, TOPIC_SHUTDOWN);
00834             E.mode.data_error = true;
00835         } else {
00836             E.mode.data_error = false;
00837             E.link.shutdown = 0;
00838         }
00839         snprintf(buffer, RBUF_SIZ - 1, "%s", ctime(&rawtime));
00840         len = strlen(buffer);
00841         buffer[len - 1] = 0; // munge out the return character
00842         fprintf(fout, "%s ", buffer);
00843         fflush(fout);
00844         E.fm80 = false;
00845         E.dumpload = false;
00846         E.homeassistant = false;
00847         E.iammeter = false;
00848         sync_ha();
00849         print_im_vars();
00850         print_mvar_vars();
00851         fprintf(fout, "%s\r", ctime(&rawtime));
00852     }
00853     E.mode.E = E_WAIT;
00854     fflush(fout);
00855     if (E.mode.con6) {
00856         E.mode.R = R_IDLE;
00857     }
00858     if (E.mode.con7) {
00859         E.mode.E = E_STOP;
00860     }
00861     break;
00862 case E_STOP:
00863 default:
00864     fflush(fout);

```

```
00862         fprintf(fout, "\r\n%s HA Energy stopped and exited.\r\n", log_time(false));
00863         fflush(fout);
00864         return 0;
00865         break;
00866     }
00867 }
00868 }
```

4.1.2.9 ramp_down_ac()

```
void ramp_down_ac (
    MQTTClient client_p,
    bool sw_off)

00968 {
00969     if (sw_off) {
00970         mqtt_ha_switch(client_p, TOPIC_PACC, false);
00971         E.ac_sw_status = false;
00972         usleep(500000);
00973     }
00974     E.once_ac = true;
00975 }
```

4.1.2.10 ramp_down_gti()

```
void ramp_down_gti (
    MQTTClient client_p,
    bool sw_off)

00935 {
00936     if (sw_off) {
00937         mqtt_ha_switch(client_p, TOPIC_PDCC, false);
00938         E.once_gti_zero = true;
00939         E.gti_sw_status = false;
00940     }
00941     E.once_gti = true;
00942
00943     if (E.once_gti_zero) {
00944         mqtt_gti_power(client_p, TOPIC_P, "Z#", 7); // zero power
00945         E.once_gti_zero = false;
00946     }
00947 }
```

4.1.2.11 ramp_up_ac()

```
void ramp_up_ac (
    MQTTClient client_p,
    bool start)

00953 {
00954
00955     if (start) {
00956         E.once_ac = true;
00957     }
00958
00959     if (E.once_ac) {
00960         E.once_ac = false;
00961         mqtt_ha_switch(client_p, TOPIC_PACC, true);
00962         E.ac_sw_status = true;
00963         usleep(500000); // wait for voltage to ramp
00964     }
00965 }
```

4.1.2.12 ramp_up_gti()

```

void ramp_up_gti (
    MQTTClient client_p,
    bool start,
    bool excess)

00874 {
00875     static uint32_t sequence = 0;
00876
00877     if (start) {
00878         E.once_gti = true;
00879     }
00880
00881     if (E.once_gti) {
00882         E.once_gti = false;
00883         sequence = 0;
00884         if (!excess) {
00885             mqtt_ha_switch(client_p, TOPIC_PDCC, true);
00886             E.gti_sw_status = true;
00887             usleep(500000); // wait for voltage to ramp
00888         } else {
00889             sequence = 1;
00890         }
00891     }
00892
00893     switch (sequence) {
00894     case 4:
00895         E.once_gti_zero = true;
00896         break;
00897     case 3:
00898     case 2:
00899     case 1:
00900         E.once_gti_zero = true;
00901         if (bat_current_stable() || E.dl_excess) { // check battery current std dev, stop
'motorboating'
00902             sequence++;
00903             if (!mqtt_gti_power(client_p, TOPIC_P, "+#", 3)) {
00904                 sequence = 0;
00905             }; // +100W power
00906         } else {
00907             usleep(500000); // wait a bit more for power to be stable
00908             sequence = 1; // do power ramps when ready
00909             if (!mqtt_gti_power(client_p, TOPIC_P, "-#", 4)) {
00910                 sequence = 0;
00911             }; // - 100W power
00912         }
00913         break;
00914     case 0:
00915         sequence++;
00916         if (E.once_gti_zero) {
00917             mqtt_gti_power(client_p, TOPIC_P, "Z#", 5); // zero power
00918             E.once_gti_zero = false;
00919         }
00920         break;
00921     default:
00922         if (E.once_gti_zero) {
00923             mqtt_gti_power(client_p, TOPIC_P, "Z#", 6); // zero power
00924             E.once_gti_zero = false;
00925         }
00926         sequence = 0;
00927         break;
00928     }
00929 }

```

4.1.2.13 sanity_check()

```

bool sanity_check (
    void )

00257 {
00258     if (E.mvar[V_PWA] > PWA_SANE) {
00259         E.sane = S_PWA;
00260         return false;
00261     }
00262     if (E.mvar[V_PAMPS] > PAMPS_SANE) {
00263         E.sane = S_PAMPS;
00264         return false;
00265     }
00266     if (E.mvar[V_PVOLTS] > PVOLTS_SANE) {

```



```

00267         E.sane = S_PVOLTS;
00268         return false;
00269     }
00270     if (E.mvar[V_FBAMPS] > BAMPS_SANE) {
00271         E.sane = S_FBAMPS;
00272         return false;
00273     }
00274     return true;
00275 }

```

4.1.2.14 showIP()

```

void showIP (
    void )

00163 {
00164     struct ifaddrs *ifaddr, *ifa;
00165     int s;
00166     char host[NI_MAXHOST];
00167
00168     if (getifaddrs(&ifaddr) == -1) {
00169         perror("getifaddrs");
00170         exit(EXIT_FAILURE);
00171     }
00172
00173     for (ifa = ifaddr; ifa != NULL; ifa = ifa->ifa_next) {
00174         if (ifa->ifa_addr == NULL)
00175             continue;
00176
00177         s = getnameinfo(ifa->ifa_addr, sizeof(struct sockaddr_in), host, NI_MAXHOST, NULL, 0,
00178             NI_NUMERICHOST);
00179
00180         if (ifa->ifa_addr->sa_family == AF_INET) {
00181             if (s != 0) {
00182                 exit(EXIT_FAILURE);
00183             }
00184             printf("\tInterface : <%s>\n", ifa->ifa_name);
00185             printf("\t  Address : <%s>\n", host);
00186         }
00187     }
00188     freeifaddrs(ifaddr);
00189 }
00190 }

```

4.1.2.15 skeleton_daemon()

```

void skeleton_daemon () [static]

00197 {
00198     pid_t pid;
00199
00200     /* Fork off the parent process */
00201     pid = fork();
00202
00203     /* An error occurred */
00204     if (pid < 0) {
00205         printf("\r\n%s DAEMON failure LOG Version %s : MQTT Version %s\r\n", log_time(false),
00206             LOG_VERSION, MQTT_VERSION);
00207         exit(EXIT_FAILURE);
00208     }
00209
00210     /* Success: Let the parent terminate */
00211     if (pid > 0) {
00212         exit(EXIT_SUCCESS);
00213     }
00214
00215     /* On success: The child process becomes session leader */
00216     if (setsid() < 0) {
00217         exit(EXIT_FAILURE);
00218     }
00219
00220     /* Catch, ignore and handle signals */
00221     /*TODO: Implement a working signal handler */
00222     // signal(SIGCHLD, SIG_IGN);
00223     // signal(SIGHUP, SIG_IGN);
00224
00225     /* Fork off for the second time*/

```

```

00225     pid = fork();
00226
00227     /* An error occurred */
00228     if (pid < 0) {
00229         exit(EXIT_FAILURE);
00230     }
00231
00232     /* Success: Let the parent terminate */
00233     if (pid > 0) {
00234         exit(EXIT_SUCCESS);
00235     }
00236
00237     /* Set new file permissions */
00238     umask(0);
00239
00240     /* Change the working directory to the root directory */
00241     /* or another appropriated directory */
00242     chdir("/");
00243
00244     /* Close all open file descriptors */
00245     int x;
00246     for (x = sysconf(_SC_OPEN_MAX); x >= 0; x--) {
00247         close(x);
00248     }
00249
00250 }

```

4.1.2.16 solar_shutdown()

```

bool solar_shutdown (
    void ) [static]

01008 {
01009     static bool ret = false;
01010
01011     if (E.startup) {
01012         ret = true;
01013         E.startup = false;
01014         return ret;
01015     } else {
01016         ret = false;
01017
01018         /*
01019          * FIXME
01020          *
01021          */
01022     }
01023
01024     if (E.solar_shutdown) {
01025         ret = true;
01026     } else {
01027         ret = false;
01028     }
01029
01030     if ((E.mvar[V_FBEKW] < BAT_CRITICAL) && !E.startup) { // special case for low battery
01031         if (!E.mode.bat_crit) {
01032             ret = true;
01033 #ifndef CRITICAL_SHUTDOWN_LOG
01034             fprintf(fout, "%s Solar BATTERY CRITICAL shutdown comms check ret = %d \r\n",
01035                 log_time(false), ret);
01036             fflush(fout);
01037 #endif
01038             E.mode.bat_crit = true;
01039             return ret;
01040         } else {
01041             E.mode.bat_crit = false;
01042         }
01043
01044         if (E.link.shutdown >= MAX_ERROR) {
01045             ret = true;
01046             if (E.fm80 && E.dumpload && E.iammeter) {
01047                 ret = false;
01048                 E.link.shutdown = 0;
01049             }
01050
01051 #ifndef DEBUG_SHUTDOWN
01052             fprintf(fout, "%s Solar shutdown comms check ret = %d \r\n", log_time(false), ret);
01053             fflush(fout);
01054 #endif
01055         }
01056         return ret;
01057     }

```

4.1.2.17 sync_ha()

```

bool sync_ha (
    void )

01093 {
01094     bool sync = false;
01095     if (E.gti_sw_status != (bool) ((int32_t) E.mvar[V_HDCSW])) {
01096         fprintf(fout, "DC_MM %d %d ", (bool) E.gti_sw_status, (bool) ((int32_t) E.mvar[V_HDCSW]));
01097         mqttt_ha_switch(E.client_p, TOPIC_PDCC, !E.gti_sw_status);
01098         E.dc_mismatch = true;
01099         fflush(fout);
01100         sync = true;
01101     } else {
01102         E.dc_mismatch = false;
01103     }
01104
01105     E.ac_sw_status = (bool) ((int32_t) E.mvar[V_HACSW]); // TEMP FIX for Mismatch errors
01106     if (E.ac_sw_status != (bool) ((int32_t) E.mvar[V_HACSW])) {
01107         fprintf(fout, "AC_MM %d %d ", (bool) E.ac_sw_status, (bool) ((int32_t) E.mvar[V_HACSW]));
01108         mqttt_ha_switch(E.client_p, TOPIC_PACC, !E.ac_sw_status);
01109         E.ac_mismatch = true;
01110         fflush(fout);
01111         sync = true;
01112     } else {
01113         E.ac_mismatch = false;
01114     }
01115     return sync;
01116 }

```

4.1.2.18 timer_callback()

```

void timer_callback (
    int32_t signum)

00286 {
00287     signal(signum, timer_callback);
00288     ha_flag_vars_ss.runner = true;
00289     E.ten_sec_clock++;
00290     E.log_spam++;
00291     E.log_time_reset++;
00292     if (E.log_spam > MAX_LOG_SPAM) {
00293         E.log_spam = 0;
00294     }
00295 }

```

4.1.3 Variable Documentation

4.1.3.1 E

```

struct energy_type E
00110 {
00111     .once_gti = true,
00112     .once_ac = true,
00113     .once_gti_zero = true,
00114     .iammeter = false,
00115     .fm80 = false,
00116     .dumpload = false,
00117     .homeassistant = false,
00118     .ac_low_adj = 0.0f,
00119     .gti_low_adj = 0.0f,
00120     .ac_sw_on = true,
00121     .gti_sw_on = true,
00122     .im_delay = 0,
00123     .gti_delay = 0,
00124     .im_display = 0,
00125     .rc = 0,
00126     .speed_go = 0,
00127     .mode.pid.iMax = PV_IMAX,
00128     .mode.pid.iMin = 0.0f,
00129     .mode.pid.pGain = PV_PGAIN,
00130     .mode.pid.iGain = PV_IGAIN,
00131     .mode.mode_tmr = 0,

```

```

00132     .mode.mode = true,
00133     .mode.in_pid_control = false,
00134     .mode.dl_mqtt_max = PV_DL_MPTT_MAX,
00135     .mode.E = E_INIT,
00136     .mode.R = R_INIT,
00137     .mode.no_float = true,
00138     .mode.data_error = false,
00139     .ac_sw_status = false,
00140     .gti_sw_status = false,
00141     .solar_mode = false,
00142     .solar_shutdown = false,
00143     .mode.pv_bias = PV_BIAS_LOW,
00144     .sane = S_DLAST,
00145     .startup = true,
00146     .ac_mismatch = false,
00147     .dc_mismatch = false,
00148     .mode_mismatch = false,
00149     .link.shutdown = 0,
00150     .mode.bat_crit = false,
00151     .dl_excess = false,
00152     .dl_excess_adj = 0.0f,
00153 };

```

4.1.3.2 ha_flag_vars_ha

```
struct ha_flag_type ha_flag_vars_ha
```

Initial value:

```

= {
    .runner = false,
    .receivedtoken = false,
    .deliveredtoken = false,
    .rec_ok = false,
    .ha_id = HA_ID,
    .var_update = 0,
}
00095                                     {
00096     .runner = false,
00097     .receivedtoken = false,
00098     .deliveredtoken = false,
00099     .rec_ok = false,
00100     .ha_id = HA_ID,
00101     .var_update = 0,
00102 };

```

4.1.3.3 ha_flag_vars_pc

```
struct ha_flag_type ha_flag_vars_pc
```

Initial value:

```

= {
    .runner = false,
    .receivedtoken = false,
    .deliveredtoken = false,
    .rec_ok = false,
    .ha_id = P8055_ID,
    .var_update = 0,
}
00064                                     {
00065     .runner = false,
00066     .receivedtoken = false,
00067     .deliveredtoken = false,
00068     .rec_ok = false,
00069     .ha_id = P8055_ID,
00070     .var_update = 0,
00071 };

```

4.1.3.4 ha_flag_vars_sd

```
struct ha_flag_type ha_flag_vars_sd
```

Initial value:

```
= {
    .runner = false,
    .receivedtoken = false,
    .deliveredtoken = false,
    .rec_ok = false,
    .ha_id = DUMpload_ID,
    .var_update = 0,
}

00085                                     {
00086     .runner = false,
00087     .receivedtoken = false,
00088     .deliveredtoken = false,
00089     .rec_ok = false,
00090     .ha_id = DUMpload_ID,
00091     .var_update = 0,
00092 };
```

4.1.3.5 ha_flag_vars_ss

```
struct ha_flag_type ha_flag_vars_ss
```

Initial value:

```
= {
    .runner = false,
    .receivedtoken = false,
    .deliveredtoken = false,
    .rec_ok = false,
    .ha_id = FM80_ID,
    .var_update = 0,
    .energy_mode = NORM_MODE,
}

00074                                     {
00075     .runner = false,
00076     .receivedtoken = false,
00077     .deliveredtoken = false,
00078     .rec_ok = false,
00079     .ha_id = FM80_ID,
00080     .var_update = 0,
00081     .energy_mode = NORM_MODE,
00082 };
```

4.2 bsoc.h

```
00001 /*
00002  * File:   bsoc.h
00003  * Author: root
00004  *
00005  * Created on February 10, 2024, 6:24 PM
00006  */
00007
00008 #ifndef BSOC_H
00009 #define BSOC_H
00010
00011 #ifdef __cplusplus
00012 extern "C" {
00013 #endif
00014 #include <math.h>
00015     //#define BSOC_DEBUG
00016
00017 #define MIN_PV_VOLTS    5.0f
00018 #define MIN_BAT_VOLTS   23.0f
00019 #define MIN_BAT_KW      4100.0f
00020
00021 #define DEV_SIZE         10
00022 #define MAX_BATC_DEV     1.5f
00023 #define BAT_C_DRAW       3.0f
00024
```

```

00025 #define PBAL_OFFSET      -50.0f // postive bias for control point
00026 #define PV_FULL_PWR       300.0f
00027 #define PV_MIN_PWR        160.0f
00028 #define PV_V_NOM          60.0f
00029 #define PV_V_FAKE          0.336699f
00030
00031 #define COEF               8.0f
00032 #define COEFN              4.0f
00033 #define COEFF              2.0f
00034
00035 #include <stdlib.h>
00036 #include <stdio.h> /* for printf() */
00037 #include <unistd.h>
00038 #include <stdint.h>
00039 #include <string.h>
00040 #include <stdbool.h>
00041 #include <signal.h>
00042 #include <time.h>
00043 #include <sys/wait.h>
00044 #include <sys/types.h>
00045 #include <sys/time.h>
00046 #include <errno.h>
00047 #include <math.h>
00048 #include "pid.h"
00049 #include "mqtt_rec.h"
00050
00051     bool bsoc_init(void);
00052     bool bsoc_data_collect(void);
00053     double bsoc_ac(void);
00054     double bsoc_gti(void);
00055     double gti_test(void);
00056     double ac_test(void);
00057     double get_batc_dev(void);
00058     bool bat_current_stable(void);
00059     void bsoc_set_std_dev(const double, const uint32_t);
00060
00061     double calculateStandardDeviation(const uint32_t, const double *);
00062
00063     bool bsoc_set_mode(const double, const bool, const bool);
00064
00065     double ac0_filter(const double);
00066     double ac1_filter(const double);
00067     double ac2_filter(const double);
00068     double dc0_filter(const double);
00069     double dc1_filter(const double);
00070     double dc2_filter(const double);
00071     double drive0_filter(const double);
00072     double drive1_filter(const double);
00073
00074 #ifdef __cplusplus
00075 }
00076 #endif
00077
00078 #endif /* BSOC_H */
00079

```

4.3 ha_energy/energy.h File Reference

```

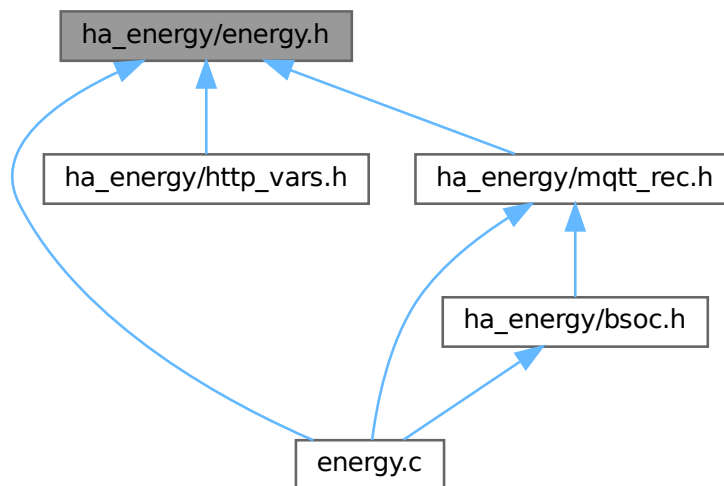
#include <stdlib.h>
#include <stdio.h>
#include <unistd.h>
#include <stdint.h>
#include <string.h>
#include <stdbool.h>
#include <signal.h>
#include <time.h>
#include <sys/wait.h>
#include <sys/types.h>
#include <sys/time.h>
#include <errno.h>
#include <cjson/cJSON.h>
#include <curl/curl.h>
#include <pthread.h>
#include <sys/stat.h>

```

```
#include <syslog.h>
#include <arpa/inet.h>
#include <sys/socket.h>
#include <netdb.h>
#include <ifaddrs.h>
#include "MQTTClient.h"
#include "pid.h"
Include dependency graph for energy.h:
```



This graph shows which files directly or indirectly include this file:



Data Structures

- struct [link_type](#)
- struct [mode_type](#)
- struct [energy_type](#)

Macros

- #define **LOG_VERSION** "V0.75"
- #define **MQTT_VERSION** "V3.11"
- #define **TNAME** "maint9"
- #define **LADDRESS** "tcp://127.0.0.1:1883"
- #define **ADDRESS** "tcp://10.1.1.30:1883"
- #define **CLIENTID1** "Energy_Mqtt_HA1"
- #define **CLIENTID2** "Energy_Mqtt_HA2"

- #define **CLIENTID3** "Energy_Mqtt_HA3"
- #define **TOPIC_P** "mateq84/data/gticmd"
- #define **TOPIC_SPAM** "mateq84/data/spam"
- #define **TOPIC_PACA** "home-assistant/gtiac/availability"
- #define **TOPIC_PDCA** "home-assistant/gtidc/availability"
- #define **TOPIC_PACC** "home-assistant/gtiac/contact"
- #define **TOPIC_PDCC** "home-assistant/gtidc/contact"
- #define **TOPIC_PPID** "home-assistant/solar/pid"
- #define **TOPIC_SHUTDOWN** "home-assistant/solar/shutdown"
- #define **TOPIC_SS** "mateq84/data/solar"
- #define **TOPIC_SD** "mateq84/data/dumpload"
- #define **TOPIC_HA** "home-assistant/status/switch"
- #define **QOS** 1
- #define **TIMEOUT** 10000L
- #define **SPACING_USEC** 500 * 1000
- #define **USEC_SEC** 1000000L
- #define **DAQ_STR** 32
- #define **DAQ_STR_M** DAQ_STR-1
- #define **SBUF_SIZ** 16
- #define **RBUF_SIZ** 82
- #define **SYSLOG_SIZ** 512
- #define **MQTT_TIMEOUT** 900
- #define **SW_QOS** 1
- #define **MQTT_RECONN** 3
- #define **KAI** 60
- #define **NO_CYLON**
- #define **CRITIAL_SHUTDOWN_LOG**
- #define **UNIT_TEST** 2
- #define **NORM_MODE** 0
- #define **PID_MODE** 1
- #define **MAX_ERROR** 5
- #define **IAM_DELAY** 120
- #define **CMD_SEC** 10
- #define **TIME_SYNC_SEC** 30
- #define **BAT_M_KW** 5120.0f
- #define **BAT_SOC_TOP** 0.98f
- #define **BAT_SOC_HIGH** 0.95f
- #define **BAT_SOC_LOW** 0.68f
- #define **BAT_SOC_LOW_AC** 0.72f
- #define **BAT_CRITICAL** 746.0f
- #define **MIN_BAT_KW_BSOC_SLP** 4000.0f
- #define **MIN_BAT_KW_BSOC_HI** 4550.0f
- #define **MIN_BAT_KW_GTI_HI** BAT_M_KW*BAT_SOC_TOP
- #define **MIN_BAT_KW_GTI_LO** BAT_M_KW*BAT_SOC_LOW
- #define **MIN_BAT_KW_AC_HI** BAT_M_KW*BAT_SOC_HIGH
- #define **MIN_BAT_KW_AC_LO** BAT_M_KW*BAT_SOC_LOW_AC
- #define **PV_PGAIN** 0.85f
- #define **PV_IGAIN** 0.12f
- #define **PV_IMAX** 1400.0f
- #define **PV_BIAS** 288.0f
- #define **PV_BIAS_ZERO** 0.0f
- #define **PV_BIAS_LOW** 222.0f
- #define **PV_BIAS_FLOAT** 399.0f
- #define **PV_BIAS_SLEEP** 480.0f
- #define **PV_BIAS_RATE** 320.0f

- #define **PV_DL_MPTT_MAX** 1200.0f
- #define **PV_DL_MPTT_EXCESS** 1300.0f
- #define **PV_DL_MPTT_IDLE** 57.0f
- #define **PV_DL_BIAS_RATE** 75.0f
- #define **PV_DL_EXCESS** 500.0f
- #define **PV_DL_B_AH_LOW** 100.0f
- #define **PV_DL_B_AH_MIN** 150.0f
- #define **PV_DL_B_V_LOW** 23.8f
- #define **PWA_SLEEP** 200.0f
- #define **DL_AC_DC_EFF** 1.24f
- #define **BAL_MIN_ENERGY_AC** -200.0f
- #define **BAL_MAX_ENERGY_AC** 200.0f
- #define **BAL_MIN_ENERGY_GTI** -1400.0f
- #define **BAL_MAX_ENERGY_GTI** 200.0f
- #define **LOG_TO_FILE** "/store/logs/energy.log"
- #define **LOG_TO_FILE_ALT** "/tmp/energy.log"
- #define **MAX_LOG_SPAM** 60
- #define **LOW_LOG_SPAM** 2
- #define **RESET_LOG_SPAM** 120
- #define **IM_DELAY** 1
- #define **IM_DISPLAY** 1
- #define **GTI_DELAY** 1
- #define **PWA_SANE** 1700.0f
- #define **PAMPS_SANE** 16.0f
- #define **PVOLTS_SANE** 150.0f
- #define **BAMPS_SANE** 70.0f
- #define **MAX_IM_VAR** IA_LAST*PHASE_LAST
- #define **L1_P** IA_POWER
- #define **L2_P** L1_P+IA_LAST
- #define **L3_P** L2_P+IA_LAST

Enumerations

- enum **client_id** { ID_C1 , ID_C2 , ID_C3 }
- enum **energy_state** {
 E_INIT , **E_RUN** , **E_WAIT** , **E_IDLE** ,
 E_STOP , **E_LAST** }
- enum **running_state** {
 R_INIT , **R_FLOAT** , **R_SLEEP** , **R_RUN** ,
 R_IDLE , **R_LAST** }
- enum **iammeter_phase** { **PHASE_A** , **PHASE_B** , **PHASE_C** , **PHASE_LAST** }
- enum **iammeter_id** {
 IA_VOLTAGE , **IA_CURRENT** , **IA_POWER** , **IA_IMPORT** ,
 IA_EXPORT , **IA_FREQ** , **IA_PF** , **IA_LAST** }
- enum **mqtt_vars** {
 V_FCCM , **V_FBEKW** , **V_FRUNT** , **V_FBAMPS** ,
 V_FBV , **V_FLO** , **V_FSO** , **V_FACE** ,
 V_BEN , **V_PWA** , **V_PAMPS** , **V_PVOLTS** ,
 V_FLAST , **V_HDCSW** , **V_HACSW** , **V_HSHUT** ,
 V_HMODE , **V_HCON0** , **V_HCON1** , **V_HCON2** ,
 V_HCON3 , **V_HCON4** , **V_HCON5** , **V_HCON6** ,
 V_HCON7 , **V_DVPV** , **V_DPPV** , **V_DPBAT** ,
 V_DVBAT , **V_DCMPPPT** , **V_DPMPPPT** , **V_DAHBAT** ,
 V_DCCMODE , **V_DGTI** , **V_DLAST** }

- enum **sane_vars** {
S_FCCM , **S_FBEKW** , **S_FRUNT** , **S_FBAMPS** ,
S_FBV , **S_FLO** , **S_FSO** , **S_FACE** ,
S_BEN , **S_PWA** , **S_PAMPS** , **S_PVOLTS** ,
S_FLAST , **S_HDCSW** , **S_HACSW** , **S_HSHUT** ,
S_HMODE , **S_DVPV** , **S_DPPV** , **S_DPBAT** ,
S_DVBAT , **S_DCMPPT** , **S_DPMPPT** , **S_DAHBAT** ,
S_DCCMODE , **S_DGTI** , **S_DLAST** }

Functions

- void [timer_callback](#) (int32_t)
- void [connlost](#) (void *, char *)
- void [ramp_up_gti](#) (MQTTClient, bool, bool)
- void [ramp_up_ac](#) (MQTTClient, bool)
- void [ramp_down_gti](#) (MQTTClient, bool)
- void [ramp_down_ac](#) (MQTTClient, bool)
- void [ha_ac_off](#) (void)
- void [ha_ac_on](#) (void)
- void [ha_dc_off](#) (void)
- void [ha_dc_on](#) (void)
- size_t [iammeter_write_callback](#) (char *, size_t, size_t, void *)
- void [iammeter_read](#) (void)
- void [print_im_vars](#) (void)
- void [print_mvar_vars](#) (void)
- bool [sanity_check](#) (void)
- char * [log_time](#) (bool)
- bool [sync_ha](#) (void)
- bool [log_timer](#) (void)

Variables

- struct [energy_type](#) **E**
- struct [ha_flag_type](#) **ha_flag_vars_ss**
- FILE * **fout**

4.3.1 Enumeration Type Documentation

4.3.1.1 client_id

```
enum client_id
00194      {
00195          ID_C1,
00196          ID_C2,
00197          ID_C3,
00198      };
```

4.3.1.2 energy_state

```
enum energy_state
00200      {
00201          E_INIT,
00202          E_RUN,
00203          E_WAIT,
00204          E_IDLE,
00205          E_STOP,
00206          E_LAST,
00207      };
```

4.3.1.3 iammeter_id

```
enum iammeter_id
00225
00226         IA_VOLTAGE, {
00227         IA_CURRENT,
00228         IA_POWER,
00229         IA_IMPORT,
00230         IA_EXPORT,
00231         IA_FREQ,
00232         IA_PF,
00233         IA_LAST,
00234     };
```

4.3.1.4 iammeter_phase

```
enum iammeter_phase
00218
00219         PHASE_A, {
00220         PHASE_B,
00221         PHASE_C,
00222         PHASE_LAST,
00223     };
```

4.3.1.5 mqtt_vars

```
enum mqtt_vars
00236
00237         V_FCCM, {
00238         V_FBEKW,
00239         V_FRUNT,
00240         V_FBAMPS,
00241         V_FBV,
00242         V_FLO,
00243         V_FSO,
00244         V_FACE,
00245         V_BEN,
00246         V_PWA,
00247         V_PAMPS,
00248         V_PVOLTS,
00249         V_FLAST,
00250         V_HDCSW,
00251         V_HACSW,
00252         V_HSHUT,
00253         V_HMODE,
00254         V_HCON0,
00255         V_HCON1,
00256         V_HCON2,
00257         V_HCON3,
00258         V_HCON4,
00259         V_HCON5,
00260         V_HCON6,
00261         V_HCON7,
00262         // add other data ranges here
00263         V_DVPV,
00264         V_DPPV,
00265         V_DPBAT,
00266         V_DVBAT,
00267         V_DCMPTT,
00268         V_DPMPTT,
00269         V_DAHBAT,
00270         V_DCCMODE,
00271         V_DGTI,
00272         V_DLAST,
00273     };
```

4.3.1.6 running_state

```
enum running_state
00209
00210         {
00211         R_INIT,
00212         R_FLOAT,
00213         R_SLEEP,
00214         R_RUN,
00215         R_IDLE,
00216         R_LAST,
};
```

4.3.1.7 sane_vars

```
enum sane_vars
00275
00276         {
00277         S_FCCM,
00278         S_FBEKW,
00279         S_FRUNT,
00280         S_FBAMPS,
00281         S_FBV,
00282         S_FLO,
00283         S_FSO,
00284         S_FACE,
00285         S_BEN,
00286         S_PWA,
00287         S_PAMPS,
00288         S_PVOLTS,
00289         S_FLAST,
00290         S_HDCSW,
00291         S_HACSW,
00292         S_HSHUT,
00293         S_HMODE,
00294         // add other data ranges here
00295         S_DVPV,
00296         S_DPPV,
00297         S_DPBAT,
00298         S_DVBAT,
00299         S_DCMPPPT,
00300         S_DPMPPPT,
00301         S_DAHBAT,
00302         S_DCCMODE,
00303         S_DGTI,
00304         S_DLAST,
};
```

4.3.2 Function Documentation

4.3.2.1 connlost()

```
void connlost (
    void * context,
    char * cause)
```

trouble in River-city

```
00301 {
00302     struct ha_flag_type *ha_flag = context;
00303     int32_t id_num = ha_flag->ha_id;
00304     static uint32_t times = 0;
00305     char * where = "Missing Topic";
00306
00307     switch (ha_flag->cid) {
00308     case ID_C1:
00309         where = TOPIC_SS;
00310         break;
00311     case ID_C2:
00312         where = TOPIC_SD;
00313         break;
00314     case ID_C3:
00315         where = TOPIC_HA;
00316         break;
```

```

00317     }
00318
00319     // bug-out if no context variables passed to callback
00320     if (context == NULL) {
00321         id_num = -1;
00322         goto bugout;
00323     } else {
00324         if (times++ > MQTT_RECONN) {
00325             goto bugout;
00326         } else {
00327
00328             fprintf(fout, "\n%s Connection lost, exit ha_energy program\n", log_time(false));
00329             fprintf(fout, "%s      cause: %s, h_id %d c_id %d %s \n", log_time(false), cause, id_num,
ha_flag->cid, where);
00330             fprintf(fout, "%s MQTT DAEMON failure LOG Version %s : MQTT Version %s\n",
log_time(false), LOG_VERSION, MQTT_VERSION);
00331             fflush(fout);
00332         }
00333     }
00334
00335 bugout:
00336     fprintf(fout, "\n%s Connection lost, exit ha_energy program\n", log_time(false));
00337     fprintf(fout, "%s      cause: %s, h_id %d c_id %d %s \n", log_time(false), cause, id_num,
ha_flag->cid, where);
00338     fprintf(fout, "%s MQTT DAEMON failure LOG Version %s : MQTT Version %s\n", log_time(false),
LOG_VERSION, MQTT_VERSION);
00339     fflush(fout);
00340     exit(EXIT_FAILURE);
00341 }

```

4.3.2.2 ha_ac_off()

```

void ha_ac_off (
    void )

00978 {
00979     mqtt_ha_switch(E.client_p, TOPIC_PACC, false);
00980     E.ac_sw_status = false;
00981 }

```

4.3.2.3 ha_ac_on()

```

void ha_ac_on (
    void )

00984 {
00985     mqtt_ha_switch(E.client_p, TOPIC_PACC, true);
00986     E.ac_sw_status = true;
00987 }

```

4.3.2.4 ha_dc_off()

```

void ha_dc_off (
    void )

00993 {
00994     mqtt_ha_switch(E.client_p, TOPIC_PDCC, false);
00995     E.gti_sw_status = false;
00996 }

```

4.3.2.5 ha_dc_on()

```

void ha_dc_on (
    void )

00999 {
01000     mqtt_ha_switch(E.client_p, TOPIC_PDCC, true);
01001     E.gti_sw_status = true;
01002 }

```

4.3.2.6 iammeter_read()

```

void iammeter_read (
    void )

00076 {
00077
00078     curl = curl_easy_init();
00079     if (curl) {
00080         E.link.iammeter_count++;
00081         curl_easy_setopt(curl, CURLOPT_URL, "http://10.1.1.101/monitorjson");
00082         curl_easy_setopt(curl, CURLOPT_WRITEFUNCTION, iammeter_write_callback);
00083         curl_easy_setopt(curl, CURLOPT_WRITEDATA, E.print_vars); // external data array for iammeter
values
00084
00085         res = curl_easy_perform(curl);
00086         /* Check for errors */
00087         if (res != CURLE_OK) {
00088             fprintf(fout, "curl_easy_perform() failed in iammeter_read: %s\n",
00089                 curl_easy_strerror(res));
00090             E.iammeter = false;
00091             E.link.iammeter_error++;
00092         } else {
00093             E.iammeter = true;
00094         }
00095         curl_easy_cleanup(curl);
00096     }
00097 }

```

4.3.2.7 iammeter_write_callback()

```

size_t iammeter_write_callback (
    char * buffer,
    size_t size,
    size_t nitems,
    void * stream)

00014 {
00015     cJSON *json = cJSON_ParseWithLength(buffer, strlen(buffer));
00016     struct energy_type * e = stream;
00017     uint32_t next_var = 0;
00018
00019     E.link.iammeter_count++;
00020
00021     if (json == NULL) {
00022         const char *error_ptr = cJSON_GetErrorPtr();
00023         E.link.iammeter_error++;
00024         if (error_ptr != NULL) {
00025             fprintf(fout, "Error in iammeter_write_callback %u: %s\n", E.link.iammeter_error,
error_ptr);
00026         }
00027         goto iammeter_exit;
00028     }
00029 #ifdef IM_DEBUG
00030     fprintf(fout, "\n iammeter_read_callback %s \n", buffer);
00031 #endif
00032
00033     cJSON *data_result = cJSON_GetObjectItemCaseSensitive(json, "Datas");
00034
00035     if (!data_result) {
00036         size = 0;
00037         nitems = 0;
00038         goto iammeter_exit;
00039     }
00040
00041     cJSON *jname;
00042     uint32_t phase = PHASE_A;
00043
00044     cJSON_ArrayForEach(jname, data_result)
00045     {
00046         cJSON *ianame;
00047 #ifdef IM_DEBUG
00048         fprintf(fout, "\n iammeter variables ");
00049 #endif
00050
00051         cJSON_ArrayForEach(ianame, jname)
00052         {
00053             uint32_t phase_var = IA_VOLTAGE;
00054             iammeter_get_data(ianame->valuedouble, phase_var, phase);

```

```

00055         e->print_vars[next_var++] = ianame->valuedouble;
00056 #ifdef IM_DEBUG
00057         fprintf(fout, "%8.2f ", im_vars[phase_var][phase]);
00058 #endif
00059         phase_var++;
00060     }
00061     phase++;
00062 }
00063 #ifdef IM_DEBUG
00064     fprintf(fout, "\n");
00065 #endif
00066
00067 iammeter_exit:
00068     cJSON_Delete(json);
00069     return size * nitems;
00070 }

```

4.3.2.8 log_time()

```

char * log_time (
    bool log)

01063 {
01064     static char time_log[RBUF_SIZ] = {0};
01065     static uint32_t len = 0, sync_time = TIME_SYNC_SEC - 1;
01066     time_t rawtime_log;
01067
01068     tzset();
01069     timezone = 0;
01070     daylight = 0;
01071     time(&rawtime_log);
01072     if (sync_time++ > TIME_SYNC_SEC) {
01073         sync_time = 0;
01074         snprintf(time_log, RBUF_SIZ - 1, "VT%lut", rawtime_log); // format for dumpload controller gti
01075     }
01076     time commands
01077     mqtt_gti_time(E.client_p, TOPIC_P, time_log);
01078
01079     sprintf(time_log, "%s", ctime(&rawtime_log));
01080     len = strlen(time_log);
01081     time_log[len - 1] = 0; // munge out the return character
01082     if (log) {
01083         fprintf(fout, "%s ", time_log);
01084         fflush(fout);
01085     }
01086     return time_log;
01087 }

```

4.3.2.9 log_timer()

```

bool log_timer (
    void )

01122 {
01123     bool itstime = false;
01124
01125     if (E.log_spam < LOW_LOG_SPAM) {
01126         E.log_time_reset = 0;
01127         itstime = true;
01128     }
01129     if (E.log_time_reset > RESET_LOG_SPAM) {
01130         E.log_spam = 0;
01131         itstime = true;
01132     }
01133     return itstime;
01134 }

```

4.3.2.10 print_im_vars()

```

void print_im_vars (
    void )

```

```

00111 {
00112     static char time_log[RBUF_SIZ] = {0};
00113     static uint32_t sync_time = TIME_SYNC_SEC - 1;
00114     time_t rawtime_log;
00115     char imvars[SYSLOG_SIZ];
00116
00117     fflush(fout);
00118     snprintf(imvars, SYSLOG_SIZ-1, "House L1 %7.2fW, House L2 %7.2fW, GTI L1 %7.2fW",
E.print_vars[L1_P], E.print_vars[L2_P], E.print_vars[L3_P]);
00119     fprintf(fout, "%s", imvars);
00120     fflush(fout);
00121     time(&rawtime_log);
00122     if (sync_time++ > TIME_SYNC_SEC) {
00123         sync_time = 0;
00124         snprintf(time_log, RBUF_SIZ - 1, "VT%lut", rawtime_log); // format for dumpload controller gti
time commands
00125         mqtt_gti_time(E.client_p, TOPIC_P, time_log);
00126     }
00127 }

```

4.3.2.11 print_mvar_vars()

```

void print_mvar_vars (
    void )

00237 {
00238     fprintf(fout, ", AC Inverter %7.2fW, BAT Energy %7.2fWh, Solar E %7.2fWh, AC E %7.2fWh, PERR
%7.2fW, PBAL %7.2fW, ST %7.2f, GDL %7.2f, %d,%d,%d %d,%d,%d\r",
00239         E.mvar[V_FLO], E.mvar[V_FBEKW], E.mvar[V_FSO], E.mvar[V_FACE], E.mode.error, E.mvar[V_BEN],
E.mode.total_system, E.mode.gti_dumpload, (int32_t) E.mvar[V_HDCSW], (int32_t) E.mvar[V_HACSW],
(int32_t) E.mvar[V_HMODE],
00240         (int32_t) E.dc_mismatch, (int32_t) E.ac_mismatch, (int32_t) E.mode_mismatch);
00241 }

```

4.3.2.12 ramp_down_ac()

```

void ramp_down_ac (
    MQTTClient client_p,
    bool sw_off)

00968 {
00969     if (sw_off) {
00970         mqtt_ha_switch(client_p, TOPIC_PACC, false);
00971         E.ac_sw_status = false;
00972         usleep(500000);
00973     }
00974     E.once_ac = true;
00975 }

```

4.3.2.13 ramp_down_gti()

```

void ramp_down_gti (
    MQTTClient client_p,
    bool sw_off)

00935 {
00936     if (sw_off) {
00937         mqtt_ha_switch(client_p, TOPIC_PDCC, false);
00938         E.once_gti_zero = true;
00939         E.gti_sw_status = false;
00940     }
00941     E.once_gti = true;
00942
00943     if (E.once_gti_zero) {
00944         mqtt_gti_power(client_p, TOPIC_P, "Z#", 7); // zero power
00945         E.once_gti_zero = false;
00946     }
00947 }

```


4.3.2.14 ramp_up_ac()

```

void ramp_up_ac (
    MQTTClient client_p,
    bool start)

00953 {
00954
00955     if (start) {
00956         E.once_ac = true;
00957     }
00958
00959     if (E.once_ac) {
00960         E.once_ac = false;
00961         mqtt_ha_switch(client_p, TOPIC_PACC, true);
00962         E.ac_sw_status = true;
00963         usleep(500000); // wait for voltage to ramp
00964     }
00965 }

```

4.3.2.15 ramp_up_gti()

```

void ramp_up_gti (
    MQTTClient client_p,
    bool start,
    bool excess)

00874 {
00875     static uint32_t sequence = 0;
00876
00877     if (start) {
00878         E.once_gti = true;
00879     }
00880
00881     if (E.once_gti) {
00882         E.once_gti = false;
00883         sequence = 0;
00884         if (!excess) {
00885             mqtt_ha_switch(client_p, TOPIC_PDCC, true);
00886             E.gti_sw_status = true;
00887             usleep(500000); // wait for voltage to ramp
00888         } else {
00889             sequence = 1;
00890         }
00891     }
00892
00893     switch (sequence) {
00894     case 4:
00895         E.once_gti_zero = true;
00896         break;
00897     case 3:
00898     case 2:
00899     case 1:
00900         E.once_gti_zero = true;
00901         if (bat_current_stable() || E.dl_excess) { // check battery current std dev, stop
00902             'motorboating'
00903             sequence++;
00904             if (!mqtt_gti_power(client_p, TOPIC_P, "+#", 3)) {
00905                 sequence = 0;
00906             }; // +100W power
00907         } else {
00908             usleep(500000); // wait a bit more for power to be stable
00909             sequence = 1; // do power ramps when ready
00910             if (!mqtt_gti_power(client_p, TOPIC_P, "-#", 4)) {
00911                 sequence = 0;
00912             }; // - 100W power
00913         }
00914         break;
00915     case 0:
00916         sequence++;
00917         if (E.once_gti_zero) {
00918             mqtt_gti_power(client_p, TOPIC_P, "Z#", 5); // zero power
00919             E.once_gti_zero = false;
00920         }
00921         break;
00922     default:
00923         if (E.once_gti_zero) {
00924             mqtt_gti_power(client_p, TOPIC_P, "Z#", 6); // zero power
00925             E.once_gti_zero = false;
00926         }
00927     }
00928 }

```

```

00925     }
00926     sequence = 0;
00927     break;
00928 }
00929 }

```

4.3.2.16 sanity_check()

```

bool sanity_check (
    void )

00257 {
00258     if (E.mvar[V_PWA] > PWA_SANE) {
00259         E.sane = S_PWA;
00260         return false;
00261     }
00262     if (E.mvar[V_PAMPS] > PAMPS_SANE) {
00263         E.sane = S_PAMPS;
00264         return false;
00265     }
00266     if (E.mvar[V_PVOLTS] > PVOLTS_SANE) {
00267         E.sane = S_PVOLTS;
00268         return false;
00269     }
00270     if (E.mvar[V_FBAMPS] > BAMPS_SANE) {
00271         E.sane = S_FBAMPS;
00272         return false;
00273     }
00274     return true;
00275 }

```

4.3.2.17 sync_ha()

```

bool sync_ha (
    void )

01093 {
01094     bool sync = false;
01095     if (E.gti_sw_status != (bool) ((int32_t) E.mvar[V_HDCSW])) {
01096         fprintf(fout, "DC_MM %d %d ", (bool) E.gti_sw_status, (bool) ((int32_t) E.mvar[V_HDCSW]));
01097         mqtt_ha_switch(E.client_p, TOPIC_PDCC, !E.gti_sw_status);
01098         E.dc_mismatch = true;
01099         fflush(fout);
01100         sync = true;
01101     } else {
01102         E.dc_mismatch = false;
01103     }
01104
01105     E.ac_sw_status = (bool) ((int32_t) E.mvar[V_HACSW]); // TEMP FIX for Mismatch errors
01106     if (E.ac_sw_status != (bool) ((int32_t) E.mvar[V_HACSW])) {
01107         fprintf(fout, "AC_MM %d %d ", (bool) E.ac_sw_status, (bool) ((int32_t) E.mvar[V_HACSW]));
01108         mqtt_ha_switch(E.client_p, TOPIC_PACC, !E.ac_sw_status);
01109         E.ac_mismatch = true;
01110         fflush(fout);
01111         sync = true;
01112     } else {
01113         E.ac_mismatch = false;
01114     }
01115     return sync;
01116 }

```

4.3.2.18 timer_callback()

```

void timer_callback (
    int32_t signum)

00286 {
00287     signal(signum, timer_callback);
00288     ha_flag_vars_ss.runner = true;
00289     E.ten_sec_clock++;
00290     E.log_spam++;
00291     E.log_time_reset++;
00292     if (E.log_spam > MAX_LOG_SPAM) {
00293         E.log_spam = 0;
00294     }
00295 }

```

4.3.3 Variable Documentation

4.3.3.1 E

```

struct energy_type E [extern]
00110     {
00111     .once_gti = true,
00112     .once_ac = true,
00113     .once_gti_zero = true,
00114     .iammeter = false,
00115     .fm80 = false,
00116     .dumpload = false,
00117     .homeassistant = false,
00118     .ac_low_adj = 0.0f,
00119     .gti_low_adj = 0.0f,
00120     .ac_sw_on = true,
00121     .gti_sw_on = true,
00122     .im_delay = 0,
00123     .gti_delay = 0,
00124     .im_display = 0,
00125     .rc = 0,
00126     .speed_go = 0,
00127     .mode.pid.iMax = PV_IMAX,
00128     .mode.pid.iMin = 0.0f,
00129     .mode.pid.pGain = PV_PGAIN,
00130     .mode.pid.iGain = PV_IGAIN,
00131     .mode.mode_tmr = 0,
00132     .mode.mode = true,
00133     .mode.in_pid_control = false,
00134     .mode.dl_mqtt_max = PV_DL_MPTT_MAX,
00135     .mode.E = E_INIT,
00136     .mode.R = R_INIT,
00137     .mode.no_float = true,
00138     .mode.data_error = false,
00139     .ac_sw_status = false,
00140     .gti_sw_status = false,
00141     .solar_mode = false,
00142     .solar_shutdown = false,
00143     .mode.pv_bias = PV_BIAS_LOW,
00144     .sane = S_DLAST,
00145     .startup = true,
00146     .ac_mismatch = false,
00147     .dc_mismatch = false,
00148     .mode_mismatch = false,
00149     .link.shutdown = 0,
00150     .mode.bat_crit = false,
00151     .dl_excess = false,
00152     .dl_excess_adj = 0.0f,
00153 };

```

4.3.3.2 ha_flag_vars_ss

```

struct ha_flag_type ha_flag_vars_ss [extern]
00074     {
00075     .runner = false,
00076     .receivedtoken = false,
00077     .deliveredtoken = false,
00078     .rec_ok = false,
00079     .ha_id = FM80_ID,
00080     .var_update = 0,
00081     .energy_mode = NORM_MODE,
00082 };

```

4.4 energy.h

[Go to the documentation of this file.](#)

```

00001
00004
00005 #ifndef BMC_H
00006 #define BMC_H
00007

```

```

00008 #ifdef __cplusplus
00009 extern "C" {
00010 #endif
00011 #include <stdlib.h>
00012 #include <stdio.h> /* for printf() */
00013 #include <unistd.h>
00014 #include <stdint.h>
00015 #include <string.h>
00016 #include <stdbool.h>
00017 #include <signal.h>
00018 #include <time.h>
00019 #include <sys/wait.h>
00020 #include <sys/types.h>
00021 #include <sys/time.h>
00022 #include <errno.h>
00023 #include <cjson/cJSON.h>
00024 #include <curl/curl.h>
00025 #include <pthread.h>
00026 #include <sys/stat.h>
00027 #include <syslog.h>
00028 #include <arpa/inet.h>
00029 #include <sys/socket.h>
00030 #include <netdb.h>
00031 #include <ifaddrs.h>
00032 #include "MQTTClient.h"
00033 #include "pid.h"
00034
00035
00036 #define LOG_VERSION "V0.75"
00037 #define MQTT_VERSION "V3.11"
00038 #define TNAME "maint9"
00039 #define LADDRESS "tcp://127.0.0.1:1883"
00040 #ifdef __amd64
00041 #define ADDRESS "tcp://10.1.1.172:1883"
00042 #else
00043 #define ADDRESS "tcp://10.1.1.30:1883"
00044 #endif
00045 #define CLIENTID1 "Energy_Mqtt_HA1"
00046 #define CLIENTID2 "Energy_Mqtt_HA2"
00047 #define CLIENTID3 "Energy_Mqtt_HA3"
00048 #define TOPIC_P "mateq84/data/gtiacmd"
00049 #define TOPIC_SPAM "mateq84/data/spam"
00050 #define TOPIC_PACA "home-assistant/gtiac/availability"
00051 #define TOPIC_PDCA "home-assistant/gtidc/availability"
00052 #define TOPIC_PACC "home-assistant/gtiac/contact"
00053 #define TOPIC_PDCC "home-assistant/gtidc/contact"
00054 #define TOPIC_PPID "home-assistant/solar/pid"
00055 #define TOPIC_SHUTDOWN "home-assistant/solar/shutdown"
00056 #define TOPIC_SS "mateq84/data/solar"
00057 #define TOPIC_SD "mateq84/data/dumpload"
00058 #define TOPIC_HA "home-assistant/status/switch"
00059 #define QOS 1
00060 #define TIMEOUT 10000L
00061 #define SPACING_USEC 500 * 1000
00062 #define USEC_SEC 1000000L
00063
00064 #define DAQ_STR 32
00065 #define DAQ_STR_M DAQ_STR-1
00066
00067 #define SBUF_SIZ 16 // short buffer string size
00068 #define RBUF_SIZ 82
00069 #define SYSLOG_SIZ 512
00070
00071 #define MQTT_TIMEOUT 900
00072 #define SW_QOS 1
00073
00074 #define MQTT_RECONN 3
00075 #define KAI 60
00076
00077 #define NO_CYLON
00078 #define CRITIAL_SHUTDOWN_LOG
00079
00080 #define UNIT_TEST 2
00081 #define NORM_MODE 0
00082 #define PID_MODE 1
00083 #define MAX_ERROR 5
00084 #define IAM_DELAY 120
00085
00086 #define CMD_SEC 10
00087 #define TIME_SYNC_SEC 30
00088
00089 /*
00090  * Battery SoC cycle limits parameters
00091  */
00092 #define BAT_M_KW 5120.0f
00093 #define BAT_SOC_TOP 0.98f
00094 #define BAT_SOC_HIGH 0.95f

```

```

00095 #define BAT_SOC_LOW          0.68f
00096 #define BAT_SOC_LOW_AC        0.72f
00097 #define BAT_CRITICAL           746.0f
00098 #define MIN_BAT_KW_BSOC_SLP    4000.0f
00099 #define MIN_BAT_KW_BSOC_HI     4550.0f
00100
00101 #define MIN_BAT_KW_GTI_HI       BAT_M_KW*BAT_SOC_TOP
00102 #define MIN_BAT_KW_GTI_LO       BAT_M_KW*BAT_SOC_LOW
00103
00104 #define MIN_BAT_KW_AC_HI        BAT_M_KW*BAT_SOC_HIGH
00105 #define MIN_BAT_KW_AC_LO        BAT_M_KW*BAT_SOC_LOW_AC
00106
00107 /*
00108  * PV panel cycle limits parameters
00109  */
00110 #define PV_PGAIN                 0.85f
00111 #define PV_IGAIN                 0.12f
00112 #define PV_IMAX                 1400.0f
00113 #define PV_BIAS                 288.0f
00114 #define PV_BIAS_ZERO            0.0f
00115 #define PV_BIAS_LOW             222.0f
00116 #define PV_BIAS_FLOAT           399.0f
00117 #define PV_BIAS_SLEEP           480.0f
00118 #define PV_BIAS_RATE            320.0f
00119 #define PV_DL_MPTT_MAX          1200.0f
00120 #define PV_DL_MPTT_EXCESS       1300.0f
00121 #define PV_DL_MPTT_IDLE         57.0f
00122 #define PV_DL_BIAS_RATE         75.0f
00123 #define PV_DL_EXCESS            500.0f
00124 #define PV_DL_B_AH_LOW         100.0f
00125 #define PV_DL_B_AH_MIN          150.0f // DL battery should be at least 175Ah
00126 #define PV_DL_B_V_LOW           23.8f // Battery low-voltage cutoff
00127 #define PWA_SLEEP               200.0f
00128 #define DL_AC_DC_EFF            1.24f
00129
00130 /*
00131  * Energy control loop parameters
00132  */
00133 #define BAL_MIN_ENERGY_AC        -200.0f
00134 #define BAL_MAX_ENERGY_AC        200.0f
00135 #define BAL_MIN_ENERGY_GTI       -1400.0f
00136 #define BAL_MAX_ENERGY_GTI       200.0f
00137
00138 #define LOG_TO_FILE              "/store/logs/energy.log"
00139 #define LOG_TO_FILE_ALT          "/tmp/energy.log"
00140
00141 #define MAX_LOG_SPAM             60
00142 #define LOW_LOG_SPAM             2
00143 #define RESET_LOG_SPAM          120
00144
00145 // #define IM_DEBUG                // WEM3080T LOGGING
00146 // #define B_ADJ_DEBUG            // debug printing
00147 // #define FAKE_VPV              // NO AC CHARGER for DUMPLoad, batteries are
                                cross-connected to a parallel bank
00148 // #define PSW_DEBUG
00149 // #define DEBUG_SHUTDOWN
00150
00151 // #define AUTO_CHARGE            // turn on dumptload charger during restarts
00152 // #define B_DLE_DEBUG           // Dump Load debugging
00153 // #define BSOC_DEGUB
00154 // #define DEBUG_HA_CMD
00155
00156 #define IM_DELAY                 1 // tens of second updates
00157 #define IM_DISPLAY               1
00158 #define GTI_DELAY                1
00159
00160 /*
00161  * sane limits for system data elements
00162  */
00163 #define PWA_SANE                 1700.0f
00164 #define PAMPS_SANE              16.0f
00165 #define PVOLTS_SANE             150.0f
00166 #define BAMPS_SANE              70.0f
00167
00168 /*
00169  Three Phase WiFi Energy Meter (WEM3080T)
00170  name      Unit      Description
00171  wem3080t_voltage_a  V    A phase voltage
00172  wem3080t_current_a   A    A phase current
00173  wem3080t_power_a     W    A phase active power
00174  wem3080t_importenergy_a kWh A phase import energy
00175  wem3080t_exportgrid_a kWh A phase export energy
00176  wem3080t_frequency_a kHz A phase frequency
00177  wem3080t_pf_a        kWh A phase power factor
00178  wem3080t_voltage_b   V    B phase voltage
00179  wem3080t_current_b   A    B phase current
00180  wem3080t_power_b     W    B phase active power

```

```

00181     wem3080t_importenergy_b kWh B phase import energy
00182     wem3080t_exportgrid_b   kWh B phase export energy
00183     wem3080t_frequency_b    kWh B phase frequency
00184     wem3080t_pf_b           kWh B phase power factor
00185     wem3080t_voltage_c      V      C phase voltage
00186     wem3080t_current_c      A      C phase current
00187     wem3080t_power_c         W      C phase active power
00188     wem3080t_importenergy_c kWh C phase import energy
00189     wem3080t_exportgrid_c   kWh C phase export energy
00190     wem3080t_frequency_c    kWh C phase frequency
00191     wem3080t_pf_c           kWh C phase power factor
00192     */
00193
00194     enum client_id {
00195         ID_C1,
00196         ID_C2,
00197         ID_C3,
00198     };
00199
00200     enum energy_state {
00201         E_INIT,
00202         E_RUN,
00203         E_WAIT,
00204         E_IDLE,
00205         E_STOP,
00206         E_LAST,
00207     };
00208
00209     enum running_state {
00210         R_INIT,
00211         R_FLOAT,
00212         R_SLEEP,
00213         R_RUN,
00214         R_IDLE,
00215         R_LAST,
00216     };
00217
00218     enum iammeter_phase {
00219         PHASE_A,
00220         PHASE_B,
00221         PHASE_C,
00222         PHASE_LAST,
00223     };
00224
00225     enum iammeter_id {
00226         IA_VOLTAGE,
00227         IA_CURRENT,
00228         IA_POWER,
00229         IA_IMPORT,
00230         IA_EXPORT,
00231         IA_FREQ,
00232         IA_PF,
00233         IA_LAST,
00234     };
00235
00236     enum mqtt_vars {
00237         V_FCCM,
00238         V_FBEKW,
00239         V_FRUNT,
00240         V_FBAMPS,
00241         V_FBV,
00242         V_FLO,
00243         V_FSO,
00244         V_FACE,
00245         V_BEN,
00246         V_PWA,
00247         V_PAMPS,
00248         V_PVOLTS,
00249         V_FLAST,
00250         V_HDCSW,
00251         V_HACSW,
00252         V_HSHUT,
00253         V_HMODE,
00254         V_HCON0,
00255         V_HCON1,
00256         V_HCON2,
00257         V_HCON3,
00258         V_HCON4,
00259         V_HCON5,
00260         V_HCON6,
00261         V_HCON7,
00262         // add other data ranges here
00263         V_DVPV,
00264         V_DPPV,
00265         V_DPBAT,
00266         V_DVBAT,
00267         V_DCMPTT,

```

```

00268     V_DPMPT,
00269     V_DAHBAT,
00270     V_DCCMODE,
00271     V_DGTI,
00272     V_DLAST,
00273 };
00274
00275 enum sane_vars {
00276     S_FCCM,
00277     S_FBEKW,
00278     S_FRUNT,
00279     S_FBAMPS,
00280     S_FBV,
00281     S_FLO,
00282     S_FSO,
00283     S_FACE,
00284     S_BEN,
00285     S_PWA,
00286     S_PAMPS,
00287     S_PVOLTS,
00288     S_FLAST,
00289     S_HDCSW,
00290     S_HACSW,
00291     S_HSHUT,
00292     S_HMODE,
00293     // add other data ranges here
00294     S_DVPV,
00295     S_DPPV,
00296     S_DPBAT,
00297     S_DVBAT,
00298     S_DCMPT,
00299     S_DPMPT,
00300     S_DAHBAT,
00301     S_DCCMODE,
00302     S_DGTI,
00303     S_DLAST,
00304 };
00305
00306 #define MAX_IM_VAR  IA_LAST*PHASE_LAST
00307
00308 #define L1_P        IA_POWER
00309 #define L2_P        L1_P+IA_LAST
00310 #define L3_P        L2_P+IA_LAST
00311
00312 struct link_type {
00313     volatile uint32_t iammeter_error, iammeter_count;
00314     volatile uint32_t mqtt_error, mqtt_count;
00315     volatile uint32_t shutdown;
00316 };
00317
00318 struct mode_type {
00319     volatile double error, target, total_system, gti_dumpload, pv_bias, dl_mqtt_max, off_grid,
sequence;
00320     volatile bool mode, in_pid_control, con0, con1, con2, con3, con4, con5, con6, con7, no_float,
data_error, bat_crit;
00321     volatile uint32_t mode_tmr;
00322     volatile struct SPid pid;
00323     volatile enum energy_state E;
00324     volatile enum running_state R;
00325 };
00326
00327 struct energy_type {
00328     volatile double print_vars[MAX_IM_VAR];
00329     volatile double im_vars[IA_LAST][PHASE_LAST];
00330     volatile double mvar[V_DLAST + 1];
00331     volatile bool once_gti, once_ac, iammeter, fm80, dumpload, homeassistant, once_gti_zero;
00332     volatile double gti_low_adj, ac_low_adj, dl_excess_adj;
00333     volatile bool ac_sw_on, gti_sw_on, ac_sw_status, gti_sw_status, solar_shutdown, solar_mode,
startup, ac_mismatch, dc_mismatch, mode_mismatch, dl_excess;
00334     volatile uint32_t speed_go, im_delay, im_display, gti_delay;
00335     volatile int32_t rc, sane;
00336     volatile uint32_t ten_sec_clock, log_spam, log_time_reset;
00337     pthread_mutex_t ha_lock;
00338     struct mode_type mode;
00339     struct link_type link;
00340     MQTTClient client_p, client_sd, client_ha;
00341 };
00342
00343 extern struct energy_type E;
00344 extern struct ha_flag_type ha_flag_vars_ss;
00345 extern FILE* fout;
00346
00347 void timer_callback(int32_t);
00348 void connlost(void *, char *);
00349
00350 void ramp_up_gti(MQTTClient, bool, bool);
00351 void ramp_up_ac(MQTTClient, bool);

```

```

00352     void ramp_down_gti(MQTTClient, bool);
00353     void ramp_down_ac(MQTTClient, bool);
00354     void ha_ac_off(void);
00355     void ha_ac_on(void);
00356     void ha_dc_off(void);
00357     void ha_dc_on(void);
00358
00359     size_t iammeter_write_callback(char *, size_t, size_t, void *);
00360     void iammeter_read(void);
00361     void print_im_vars(void);
00362     void print_mvar_vars(void);
00363
00364     bool sanity_check(void);
00365     char * log_time(bool);
00366     bool sync_ha(void);
00367     bool log_timer(void);
00368
00369 #ifdef __cplusplus
00370 }
00371 #endif
00372
00373 #endif /* BMC_H */
00374

```

4.5 http_vars.h

```

00001 /*
00002  * File:   http_vars.h
00003  * Author: root
00004  *
00005  * Created on February 16, 2024, 8:37 AM
00006  */
00007
00008 #ifndef HTTP_VARS_H
00009 #define HTTP_VARS_H
00010
00011 #ifdef __cplusplus
00012 extern "C" {
00013 #endif
00014
00015 #include "energy.h"
00016
00017     extern FILE* fout;
00018
00019 #ifdef __cplusplus
00020 }
00021 #endif
00022
00023 #endif /* HTTP_VARS_H */
00024

```

4.6 mqtt_rec.h

```

00001 /*
00002  * File:   mqtt_rec.h
00003  * Author: root
00004  *
00005  * Created on February 5, 2024, 2:54 PM
00006  */
00007
00008 #ifndef MQTT_REC_H
00009 #define MQTT_REC_H
00010
00011 #ifdef __cplusplus
00012 extern "C" {
00013 #endif
00014
00015 #include "energy.h"
00016 #include "mqtt_vars.h"
00017
00018 #define RDEV_SIZE      10
00019
00020 #define SLEEP_CODE     0
00021 #define FLOAT_CODE     1
00022     //#define DEBUG_REC
00023     //#define GET_DEBUG
00024
00025 #define MBMQTT  1024

```



```

00026
00027     enum mqtt_id {
00028         P8055_ID,
00029         FM80_ID,
00030         DUMPLoad_ID,
00031         HA_ID,
00032         LAST_MQTT_ID,
00033     };
00034
00035     struct ha_flag_type {
00036         volatile MQTTClient_deliveryToken deliveredtoken, receivedtoken;
00037         volatile bool runner, rec_ok;
00038         int32_t ha_id;
00039         volatile int32_t var_update, energy_mode;
00040         volatile enum client_id cid;
00041     };
00042
00043     extern FILE* fout;
00044
00045     int32_t msgarrvd(void *, char *, int, MQTTClient_message *);
00046     void delivered(void *, MQTTClient_deliveryToken);
00047
00048     bool json_get_data(cJSON *, const char *, cJSON *, uint32_t);
00049     bool fm80_float(const bool set_bias);
00050     bool fm80_sleep(void);
00051
00052 #ifdef __cplusplus
00053 }
00054 #endif
00055
00056 #endif /* MQTT_REC_H */
00057

```

4.7 mqtt_vars.h

```

00001 /*
00002  * File:   mqtt_vars.h
00003  * Author: root
00004  *
00005  * Created on February 9, 2024, 6:50 AM
00006  */
00007
00008 #ifndef MQTT_VARS_H
00009 #define MQTT_VARS_H
00010
00011 #ifdef __cplusplus
00012 extern "C" {
00013 #endif
00014
00015     // #define GTI_NO_POWER      // do we actually run power commands
00016
00017     // #define DEBUG_HA_CMD      // show debug text
00018     #define HA_SW_DELAY        400000 // usecs
00019     #define TOKEN_DELAY        250
00020     #define GTI_TOKEN_DELAY    300
00021
00022     #define QOS                1
00023
00024     extern const char* mqtt_name[V_DLAST];
00025
00026     void mqtt_ha_switch(MQTTClient, const char *, const bool);
00027     void mqtt_ha_pid(MQTTClient, const char *);
00028     void mqtt_ha_shutdown(MQTTClient, const char *);
00029     bool mqtt_gti_power(MQTTClient, const char *, char *, uint32_t);
00030     bool mqtt_gti_time(MQTTClient, const char *, char *);
00031
00032 #ifdef __cplusplus
00033 }
00034 #endif
00035
00036 #endif /* MQTT_VARS_H */
00037

```

4.8 pid.h

```

00001 /*
00002  * File:   pid.h
00003  * Author: root

```

```
00004  *
00005  * Created on March 6, 2024, 7:03 AM
00006  */
00007
00008 #ifndef PID_H
00009 #define PID_H
00010
00011 #ifdef __cplusplus
00012 extern "C" {
00013 #endif
00014
00015     struct SPid {
00016         double dState; // Last position input
00017         double iState; // Integrator state
00018         double iMax, iMin; // Maximum and minimum allowable integrator state
00019         double iGain, // integral gain
00020         pGain, // proportional gain
00021         dGain; // derivative gain
00022     };
00023
00024     double UpdatePI(volatile struct SPid * const, const double);
00025     void ResetPI(volatile struct SPid * const);
00026
00027
00028 #ifdef __cplusplus
00029 }
00030 #endif
00031
00032 #endif /* PID_H */
00033
```

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