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> restart : with(LinearAlgebra) : with(plots) : with(plottools) : with(inttrans) :
  with(VectorCalculus) : SetCoordinates('cartesian'[x, y, z]) :
> r_t := simplify(VectorField([diff(a*cos(theta))*(1+cos(theta)), theta$1),
  diff(a*sin(theta)*(1+cos(theta)), theta$1), 0]))
  r_t := (a sin(θ) (−1−2 cos(θ))) ex + ((2 cos(θ)2 + cos(θ) − 1) a) ey + (0) ez (1)
> ds := simplify(sqrt((a sin(θ) (−1−2 cos(θ)))2 + ((2 cos(θ)2 + cos(θ)
  − 1) a)2))
  ds := √2 √a2 (1 + cos(θ)) (2)
> M := int(ds, theta = 0..Pi)
  M := 4 a csgn(a) (3)
> M_x := 1/M · int(ds · (a · cos(theta) · (1 + cos(theta))), theta = 0..Pi)
  M_x := 4 a / 5 (4)
> M_y := 1/M · int(ds · (a · sin(theta) · (1 + cos(theta))), theta = 0..Pi)
  M_y := 4 a / 5 (5)
>

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