```
restart: with(LinearAlgebra):
    # Define the function
> f := (x, y) \rightarrow x^3 \cdot \exp(-(x^2 + y^2));
                                          f := (x, y) \mapsto x^3 \cdot e^{-y^2 - x^2}
                                                                                                                   (1)
 \rightarrow df dx := diff(f(x, y), x);
    df dv := diff(f(x, y), y);
                                  df_{-}dx := 3 x^2 e^{-x^2 - y^2} - 2 x^4 e^{-x^2 - y^2}
                                         df dv := -2 x^3 v e^{-x^2 - y^2}
                                                                                                                   (2)
 > stationary points := solve(\{df \ dx = 0, df \ dy = 0\}, \{x, y\});
            stationary points := \{x = 0, y = y\}, \{x = RootOf(2 \ Z^2 - 3), y = 0\}
                                                                                                                   (3)
 \rightarrow d2f\ dx2 := diff(f(x, y), x, x);
    d2f dy2 := diff(f(x, y), y, y);
    d2f \ dxdy := diff(f(x, y), x, y);
    Hessian := Matrix([[d2f dx2, d2f dxdy], [d2f dxdy, d2f dy2]]);
                      d2f dx2 := 6 x e^{-x^2 - y^2} - 14 x^3 e^{-x^2 - y^2} + 4 x^5 e^{-x^2 - y^2}
                              d2f dy2 := -2 x^3 e^{-x^2-y^2} + 4 x^3 v^2 e^{-x^2-y^2}
                            d2f_dxdy := -6 x^2 y e^{-x^2 - y^2} + 4 x^4 y e^{-x^2 - y^2}
 Hessian ≔
                                                                                                                   (4)
        6 x e^{-x^2 - y^2} - 14 x^3 e^{-x^2 - y^2} + 4 x^5 e^{-x^2 - y^2} - 6 x^2 y e^{-x^2 - y^2} + 4 x^4 y e^{-x^2 - y^2} 
 -6 x^2 y e^{-x^2 - y^2} + 4 x^4 y e^{-x^2 - y^2} -2 x^3 e^{-x^2 - y^2} + 4 x^3 y^2 e^{-x^2 - y^2} 
 ►

➤ Hessian at _points := subs(stationary_points, Hessian);
                                    Hessian\_at\_points := \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}
                                                                                                                   (5)
 \rightarrow eigenvalues := LinearAlgebra:-Eigenvalues(Hessian at points);
                                           eigenvalues := \begin{bmatrix} 0 \\ 0 \end{bmatrix}
                                                                                                                   (6)
# Analyse the behaviour along the y-axis if needed
 \rightarrow df dx at x0 := subs(x = 0, df dx);
    df dy at x0 := subs(x = 0, df dy);
                                              df dx at x0 = 0
                                              df dy at x0 = 0
                                                                                                                   (7)
```