

Zero to Hero: WiMo

Niels Savvides

2024/10/30

1 Analyse in 1 veranderlijke: enkele aspecten

1.1 Continuïteitseigenschappen van functies

Functie $f(x)$ is continue over $]a, b[$ als:

1. $f(x)$ bestaat in elk punt
2. de limiet van $f(x)$ bestaat in elk punt

Continue afgeleide: $f(x)$ is continue (zie hierboven) en $f'(x)$ bestaat in elk punt. Dit kan:

1. gladde functies zijn: elk afgeleide is continue
2. stuksgewijs: $f(x)$ heeft een singulariteit, maar het bestaat in deel intervallen $]a, c[$ $]c, b[$

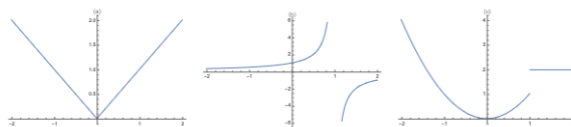


Figure 1: a) Continue functie, stuksgewijs continue afgeleide (als je afleid krijg je een singulariteit) b) Heeft een singulariteit, dus stuksgewijs continue, stuksgewijs glad continue afleidbaar c) Deze is glad stuksgewijs continue afleidbaar, is ook stuksgewijs continue

1.2 Taylorontwikkeling

We willen zaken gaan benaderen. Hiervoor gebruiken we:

$$f(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \frac{f'''(a)}{3!}(x-a)^3 + \dots$$

waarbij a het **werkpunt** is.

Veel voorkomende Taylorontwikkelingen:

See Figure 2.

Storingsrekening

Zie Figuur 4.

Of Maple solution 3.

1.3 Twee eenvoudige differentiaalvergelijkingen

1.3.1 Eerste orde differentiaalvergelijking

$$y'(x) = \lambda y(x)$$

$$\begin{aligned}
- e^x &= 1 + x + \frac{x^2}{2} + \frac{x^3}{3!} + \dots + \frac{x^n}{n!} \\
- \sin x &= 0 + x + \frac{x^2}{2} \cdot (\sin(0)) - \frac{x^3}{6} + \dots + \frac{(-1)^n \cdot x^{2n+1}}{(2n+1)!} \\
- \cos x &= \frac{(-1)^n \cdot x^{2n}}{2n!} \\
- \frac{1}{1-x} &= 1 + x + \dots + x^n \quad \text{convergeert voor } x \in]-1, 1[\\
&\quad \text{↳ eigenschap: de afgeleide van } \frac{1}{1-x} \text{ maakt negatief} \\
&\quad \text{maar door } -x \text{ chain wordt het positief.} \\
- \ln(1-x) &= -\left(x + \frac{x^2}{2} + \frac{x^3}{3} + \dots + \frac{x^n}{n}\right) \quad \text{voor } x \in]-1, 1[
\end{aligned}$$

Figure 2: Simply use the formulas

Als we dit uitwerken krijgen we:

$$\ln(y(x)) = \lambda x + C$$

$$y(x) = e^{\lambda x + C} = e^C e^{\lambda x} = C e^{\lambda x} \text{ met } C = y(0)$$

$$y(x) = y(0) e^{\lambda x}$$

Radioactief verval

Zie Figuur 5.

1.3.2 Tweede orde differentiaalvergelijking

$$y''(x) = \lambda y(x)$$

Hierbij heb je 3 gevallen:

1. $\lambda > 0$: $y(t) = A e^{\sqrt{\lambda} t} + B e^{-\sqrt{\lambda} t}$
2. $\lambda = 0$: $y(t) = A + B t$
3. $\lambda < 0$: $y(t) = A \cos(\sqrt{-\lambda} t) + B \sin(\sqrt{-\lambda} t)$

1.3.3 Complexe getallen

Algemene vorm: $z = a + bi$

waarbij a reeel, b imaginair en $i^2 = -1$

$$\text{inverse: } (a + bi)^{-1} = \frac{a - bi}{a^2 + b^2}$$

$$\text{complement: } z = a + bi \rightarrow z^* = a - bi$$

$$\text{modulus: } |z| = \sqrt{a^2 + b^2}$$

in polaire vorm:

$$e^{i\theta} = \cos(\theta) + i \sin(\theta) \text{ (Dit kan via Taylor bewezen worden (zie oefeningen))}$$

Okey, nu nog een paar goniometrische formules:

```

> #  $x^3 + \text{epsilon} \cdot x = 1$ 
>
>  $f := x \mapsto x^3 + \text{epsilon} \cdot x = 1$ 
                                      $f := x \mapsto x^3 + e \cdot x = 1$  (1)
> # When epsilon is null, we get  $x = 1$ 
>  $g := 1 + u \cdot \text{epsilon} + v \cdot \text{epsilon}^2$ 
                                      $g := v e^2 + u e + 1$  (2)
>  $f\_subs := \text{subs}(x = g, f(x))$ 
                                      $f\_subs := (v e^2 + u e + 1)^3 + e(v e^2 + u e + 1) = 1$  (3)
>  $f\_expand := \text{expand}(f\_subs)$ 
 $f\_expand := e^6 v^3 + 3 e^5 u v^2 + 3 e^4 u^2 v + 3 e^4 v^2 + e^3 u^3 + 6 e^3 u v + e^3 v + 3 e^2 u^2$  (4)
 $+ e^2 u + 3 v e^2 + 3 u e + e + 1 = 1$ 
> # First keep the left hand side
>  $\text{left\_hand\_side} := \text{lhs}(f\_expand)$ 
 $\text{left\_hand\_side} := e^6 v^3 + 3 e^5 u v^2 + 3 e^4 u^2 v + 3 e^4 v^2 + e^3 u^3 + 6 e^3 u v + e^3 v$  (5)
 $+ 3 e^2 u^2 + e^2 u + 3 v e^2 + 3 u e + e + 1$ 
> # Extract coeff 1 and 2
>  $\text{coeff\_1} := \text{coeff}(\text{left\_hand\_side}, \text{epsilon}, 1)$ 
                                      $\text{coeff\_1} := 3 u + 1$  (6)
>  $\text{coeff\_2} := \text{coeff}(\text{left\_hand\_side}, \text{epsilon}, 2)$ 
                                      $\text{coeff\_2} := 3 u^2 + u + 3 v$  (7)
>  $\text{solve}(\{\text{coeff\_1} = 0, \text{coeff\_2} = 0\}, \{u, v\})$ 
                                      $\left\{u = -\frac{1}{3}, v = 0\right\}$  (8)
> # Final result
>  $\text{result} := \text{subs}\left(\left\{u = -\frac{1}{3}, v = 0\right\}, g\right)$ 
                                      $\text{result} := -\frac{e}{3} + 1$  (9)
>

```

Figure 3: Maple solution

Stringrekening

$$x^3 + \epsilon x = 1$$

$$1) \text{ if } \epsilon = 0 \Rightarrow x = 1$$

$$\Rightarrow x_0 = 1 + a_1 \epsilon + a_2 \epsilon^2$$

$$\text{Vul in: } (1 + a_1 \epsilon + a_2 \epsilon^2)^3 + \epsilon(1 + a_1 \epsilon + a_2 \epsilon^2) = 1$$

$$(1 + a_1 \epsilon + a_2 \epsilon^2)^3 = 1 + 3a_1 \epsilon + 3a_2 \epsilon^2 + 3a_1^2 \epsilon^2 + 3a_1 a_2 \epsilon^3 + a_2^3 \epsilon^3$$

$$1) 1$$

$$2) 3a_1 \epsilon \text{ (first order)}$$

$$3) 3a_2 \epsilon^2 + 3a_1^2 \epsilon^2$$

$$(a+b)^3 = a^3 + 3a^2b + 3ab^2 + b^3$$

$$1 + 3a_1 \epsilon + \epsilon^2(3a_2 + 3a_1^2) + \epsilon(1 + a_1 \epsilon + a_2 \epsilon^2) = 1$$

$$\begin{cases} 1 = 1 \\ 3a_1 + 1 = 0 \Rightarrow a_1 = -\frac{1}{3} \\ a_2 = 0 \end{cases}$$

$$\Rightarrow x = 1 - \frac{1}{3}\epsilon$$

Figure 4: 1. Merk op dat als epsilon 0 is, dan is $x = 1$. Dus we benaderen value 1: $1 + \epsilon \cdot u + \epsilon^2 \cdot v$. Vul dit in the main equation. Gebruik maple om dit op te lossen en vul u en v in x_1

radioact.

$$N'(t) = -\lambda N(t)$$

$$\Leftrightarrow \frac{N'(t)}{N(t)} = -\lambda$$

$$\Leftrightarrow \ln(N(t)) = -\lambda t + C$$

$$\Leftrightarrow N(t) = e^{-\lambda t} \cdot \underbrace{e^C}_{= N_0} = N_0(t)$$

$$\Leftrightarrow N(t) = N_0(t) \cdot e^{-\lambda t}$$

$$\text{halveringstijd: } \frac{N_0}{2}$$

$$\Rightarrow \frac{N_0(t)}{2} = N_0(t) \cdot e^{-\lambda t}$$

$$\Leftrightarrow \frac{1}{2} = e^{-\lambda t_{1/2}}$$

$$\Leftrightarrow \ln\left(\frac{1}{2}\right) = \ln(e^{-\lambda t_{1/2}}) = -\lambda t_{1/2}$$

$$\Leftrightarrow \ln(2) = \lambda t_{1/2}$$

$$\Leftrightarrow \frac{\ln(2)}{\lambda} = t_{1/2}$$

Figure 5: Vindt eerst de differentiaalvergelijking (zie eerste differentiaalvergelijking). Dan kunnen we de oplossing gelijkstellen aan $N_0/2$. Werk dit uit en je hebt $t_{1/2}$ gevonden

$$\sin^2(x) + \cos^2(x) = 1$$

$$\sin(x) = \frac{e^{ix} - e^{-ix}}{2i}$$

$$\sin(2x) = 2\sin(x)\cos(x)$$

$$\cos(x) = \frac{e^{ix} + e^{-ix}}{2}$$

$$\cos(2x) = \cos^2(x) - \sin^2(x)$$

1.3.4 Hoofdstelling van de algebra

Als we een kwadratisch veelterm hebben: $ax^2 + bx + c = 0$

Dan vinden we de nulpunten (oplossingen) met:

$$x_1 = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$$

$$x_2 = \frac{-b - \sqrt{b^2 - 4ac}}{2a}$$

met $b = -4 * a * c$ vinden we de discriminant.

Formularium

Taylorontwikkeling

$$- f(x) = f(a) + f'(a)(x - a) + \frac{f''(a)}{2!}(x - a)^2 + \frac{f'''(a)}{3!}(x - a)^3 + \dots$$

$$- \sin(x) = x \text{ voor kleine } x$$

Differentiaalvergelijkingen

$$- y'(x) = \lambda y(x)$$

$$- y''(x) = \lambda y(x) \text{ (hier werden 3 gevallen besproken)}$$

Complexe getallen

$$- z = a + bi \text{ (algemene vorm)}$$

$$- i^2 = -1$$

$$- \text{inverse: } (a + bi)^{-1} = \frac{a - bi}{a^2 + b^2}$$

$$- \text{complement: } z = a + bi \rightarrow z^* = a - bi$$

$$- \text{modulus: } |z| = \sqrt{a^2 + b^2}$$

$$- e^{i\theta} = \cos(\theta) + i\sin(\theta)$$

$$- \sin^2(x) + \cos^2(x) = 1$$

$$- \sin(x) = \frac{e^{ix} - e^{-ix}}{2i}$$

$$- \sin(2x) = 2\sin(x)\cos(x)$$

$$- \cos(x) = \frac{e^{ix} + e^{-ix}}{2}$$

$$- \cos(2x) = \cos^2(x) - \sin^2(x)$$

Hoofdstelling van de algebra

$$x_1 = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$$

$$x_2 = \frac{-b - \sqrt{b^2 - 4ac}}{2a}$$

met $b = -4 * a * c$

Oefeningen

Huis 1

```

> restart : with(LinearAlgebra) :
> t := taylor(sqrt(x + 4)^3, x = 0, 3);
v := sqrt(y + 4)^3;
                                t := 8 + 3 x +  $\frac{3}{16} x^2 + O(x^3)$ 
                                v := (y + 4)3/2
(1)
# voor 53/2 nemen we x = 1
> x_1 := evalf(8 + 3 +  $\frac{3}{16}$ )
                                x_1 := 11.18750000
(2)
# Wat is de fout? Wel, dat zal de derde term zijn (O(x^3))
> error_1 := abs( $\frac{x^3}{6} \cdot \text{diff}(v, y\$3)$ );
error_1 := evalf(subs(y = 0, x = 1, error_1))
                                error_1 :=  $\frac{|x|^3}{16|y + 4|^{3/2}}$ 
                                error_1 := 0.007812500000
(3)
# voor 63/2 nemen we x = 2
> x_2 := evalf(8 + 3·2 +  $\frac{3}{16} \cdot 2^2$ )
                                x_2 := 14.75000000
(4)
> error_2 := abs( $\frac{x^3}{6} \cdot \text{diff}(v, y\$3)$ )
                                error_2 :=  $\frac{|x|^3}{16|y + 4|^{3/2}}$ 
(5)
> error_2 := evalf(subs(x = 2, y = 0, error_2))
                                error_2 := 0.06250000000
(6)
> # Waarom nemen we y = 0? Omdat dit de grootste fout zou maken, we
    nemen altijd max. Dus fout \element {0, 1, 2}
>

```

Figure 6: Exercise 1

```

> restart:
> # i
> limit( $\frac{\sin(3 \cdot x)}{\sinh(x)}$ , x = 0)
3 (1)
> # ii
> limit( $\frac{(\tan(x) - \tanh(x))}{\sinh(x) - x}$ , x = 0)
4 (2)
> # iii
> limit( $\frac{(\sqrt{1 - a \cdot x} - \sqrt{1 + a \cdot x})}{x}$ , x = 0)
-a (3)
> # IV
> limit( $\frac{(\ln(1 + x) + \ln(1 - x))}{x^2}$ , x = 0)
-1 (4)
>

```

Figure 7: Exercise 2

$$\exp(i\theta) = \cos\theta + i\sin\theta \quad B:$$

$$\begin{aligned} e^{i\theta} &= \sum \frac{e^{i\theta n}}{n!} \rightarrow e^{i\theta} = \sum \frac{(i\theta)^n}{n!} \\ &= 1 + i\theta - \frac{\theta^2}{2} - i\frac{\theta^3}{6} + \frac{\theta^4}{24} + \dots \\ &= \underbrace{i\left(\theta - \frac{\theta^3}{6} + \dots\right)}_{\sin\theta} + \underbrace{\left(-\frac{\theta^2}{2} + \frac{\theta^4}{24} + \dots\right)}_{\cos\theta} \\ &= \cos\theta + i\sin\theta \end{aligned}$$

Figure 8: Exercise 3

$$\begin{aligned} a &= \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \quad b = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \\ a \cdot b &= 1 \cdot (-1) + (1 \cdot 1) + (-1 \cdot 0) = 0 \\ A &= a b^T = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \cdot (-1, 1, 0) \\ &= \begin{pmatrix} -1 & 1 & 0 \\ -1 & 1 & 0 \\ 1 & -1 & 0 \end{pmatrix} \end{aligned}$$

Figure 9: Exercise 4

WC 1

```

> p := x→x·(x-1) - a
p := x→x·(x-1) - a (1)
# i
> p_i := subs(a = 0, p(x))
p_i := x(x-1) (2)
> solve(p_i = 0)
0, 1 (3)
# Dus lambda = 0, en lambda = 1
# Benader naar x = 0
> x_0 := 0 + u·a + v·a^2
x_0 := v a^2 + u a (4)
> p_subs_0 := subs(x = x_0, p(x))
p_subs_0 := (v a^2 + u a) (v a^2 + u a - 1) - a (5)
> p_expand_0 := expand(p_subs_0)
p_expand_0 := a^4 v^2 + 2 a^3 u v + a^2 u^2 - v a^2 - u a - a (6)
> coeff_1_0 := coeff(p_expand_0, a, 1)
coeff_1_0 := -u - 1 (7)
> coeff_2_0 := coeff(p_expand_0, a, 2)
coeff_2_0 := u^2 - v (8)
> solve_0 := solve({coeff_1_0 = 0, coeff_2_0 = 0}, {u, v})
solve_0 := {u = -1, v = 1} (9)
> result_0 := subs(u = rhs(solve_0[1]), v = rhs(solve_0[2]), x_0)
result_0 := a^2 - a (10)
# Benader 1
> x_1 := 1 + u·a + v·a^2
x_1 := v a^2 + u a + 1 (11)
> p_subs_1 := subs(x = x_1, p(x))
p_subs_1 := (v a^2 + u a + 1) (v a^2 + u a) - a (12)
> p_expand_1 := expand(p_subs_1)
p_expand_1 := a^4 v^2 + 2 a^3 u v + a^2 u^2 + v a^2 + u a - a (13)
> coeff_1_1 := coeff(p_expand_1, a, 1)
coeff_1_1 := u - 1 (14)
> coeff_1_2 := coeff(p_expand_1, a, 2)
coeff_1_2 := u^2 + v (15)
> solve_1 := solve({coeff_1_1 = 0, coeff_1_2 = 0}, {u, v})
solve_1 := {u = 1, v = -1} (16)
> result_1 := subs(u = rhs(solve_1[1]), v = rhs(solve_1[2]), x_1)

```

Figure 10: Exercise 1

```

> # Define the Taylor expansion for a forward approximation
Taylor_y := (h, t) → y(t) + h*diff(y(t), t) + (1/2)*h^2*diff(y(t), t$2) + (1/6)
    *h^3*diff(y(t), t$3) + (1/24)*h^4*diff(y(t), t$4) :

# Define the Taylor expansion for a backward approximation
Taylor_g := (h, t) → y(t) - h*diff(y(t), t) + (1/2)*h^2*diff(y(t), t$2) - (1/6)
    *h^3*diff(y(t), t$3) + (1/24)*h^4*diff(y(t), t$4) :

# Define the result expression
result := (h, t) → (Taylor_y(h, t) + Taylor_g(h, t) - 2*y(t)) / h^2 :

# Simplify the result
simplified_result := simplify(result(h, t));


$$\text{simplified\_result} := \frac{h^2 \left( \frac{d^4}{dt^4} y(t) \right)}{12} + \frac{d^2}{dt^2} y(t) \quad (1)$$


>
> #i) kwadratisch
> #ii
> restart;
> with(plots) :
> with(plottools) :

t_val := evalf( Pi / 3 );

# Define the function y and its 2nd derivative
y := t → -cos(t);

# Define the error function as a function of h for a specific t
err := (h) → abs( y(t_val)
    - (cos(h + t_val) + cos(h - t_val) - 2*cos(t_val)) / h^2 );

# Plot the error as a function of h with log-log scale
loglogplot(err(h), h = 10^(-8) .. 10^3);
t_val := 1.047197551
y := t → -cos(t)
err := h → | y(t_val) - (cos(h + t_val) + cos(h - t_val) - 2*cos(t_val)) / h^2 |

```

Figure 11: Exercise 2

$$\begin{aligned}
 3) \quad v_1 &= \begin{pmatrix} 2i \\ -1 \\ 0 \\ 0 \end{pmatrix}, v_2 = \begin{pmatrix} 4 \\ 0 \\ 2 \\ 1 \end{pmatrix}, v_3 = \begin{pmatrix} 1 \\ 1-i \\ 0 \\ 1 \end{pmatrix}, v_4 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ i \end{pmatrix} \\
 \vec{u}_1 &= \frac{\vec{v}_1}{\|\vec{v}_1\|} = \frac{(2i, -1, 0, 0)^T}{\sqrt{(2i)^2 + (-1)^2}} = \frac{1}{\sqrt{2i \cdot (-2i) + 1}} \\
 &= \left(\frac{2i}{\sqrt{5}}, -\frac{1}{\sqrt{5}}, 0, 0 \right)^T \\
 \vec{u}_2 &= \vec{v}_2 - \sum_{k=1}^{n-1} \langle \vec{u}_k, \vec{v}_2 \rangle \cdot \vec{u}_k = \\
 \vec{u}_3 &= \vec{v}_3 - \sum_{k=1}^{n-1} \langle \vec{u}_k, \vec{v}_3 \rangle \cdot \vec{u}_k \\
 &\vdots \\
 &\vdots
 \end{aligned}$$

$$\begin{aligned}
 2) \quad \text{span} \langle u_1, u_2 \rangle \\
 w'' &= \langle u_1, w \rangle u_1 + \langle u_2, w \rangle u_2 \\
 \text{Remainder: } w &= w'' + w^\perp
 \end{aligned}$$

Figure 12: Exercise 3

```

> #ii)
> with(LinearAlgebra):
> v_1 := Vector([2*I, -1, 0, 0])

```

$$v_1 := \begin{bmatrix} 2I \\ -1 \\ 0 \\ 0 \end{bmatrix} \quad (1)$$

```

> v_2 := Vector([I, 0, 3, 1])

```

$$v_2 := \begin{bmatrix} I \\ 0 \\ 3 \\ 1 \end{bmatrix} \quad (2)$$

```

> u_1 := v_1 / Norm(v_1, 2)

```

$$u_1 := \begin{bmatrix} \frac{2I}{5} \sqrt{5} \\ -\frac{\sqrt{5}}{5} \\ 0 \\ 0 \end{bmatrix} \quad (3)$$

```

> u_2 := (v_2 - (u_1 • v_2) • u_1) / Norm(v_2 - (u_1 • v_2) • u_1, 2)

```

$$u_2 := \begin{bmatrix} \frac{I}{255} \sqrt{255} \\ \frac{2\sqrt{255}}{255} \\ \frac{\sqrt{255}}{17} \\ \frac{\sqrt{255}}{51} \end{bmatrix} \quad (4)$$

```

> w := Vector([3, 1 - I, 2 + I, 1])

```

$$(5)$$

Figure 13: Exercise 3

Bord 1

```

> p := x→x·(x-1)·(x-2)·(x-4) - a
      p := x→x·(x-1)·(x-2)·(x-4) - a (1)
> x_0 := u·a + v·a^2
      x_0 := v a^2 + u a (2)
> p_subs := subs(x = x_0, p(x))
      p_subs := (v a^2 + u a) (v a^2 + u a - 1) (v a^2 + u a - 2) (v a^2 + u a - 4) - a (3)
> p_expand := expand(p_subs)
p_expand := a^8 v^4 + 4 a^7 u v^3 + 6 a^6 u^2 v^2 - 7 a^6 v^3 + 4 a^5 u^3 v - 21 a^5 u v^2 + a^4 u^4
      - 21 a^4 u^2 v + 14 a^4 v^2 - 7 a^3 u^3 + 28 a^3 u v + 14 a^2 u^2 - 8 v a^2 - 8 u a - a (4)
> # Only keep the 1st order and second order
>
> coeff_1 := coeff(p_expand, a, 1)
      coeff_1 := -8 u - 1 (5)
> coeff_2 := coeff(p_expand, a, 2)
      coeff_2 := 14 u^2 - 8 v (6)
> solve({coeff_1 = 0, coeff_2 = 0}, {u, v})
      {u = -1/8, v = 7/256} (7)
>

```

Figure 14: Exercise 1

$$2) i) y'(t_n) \approx v_n = \frac{y_{n+1} - y_n}{h}$$

$$\begin{cases} c = t_n \\ t_{n+1} = t_n + h \end{cases}$$

$$y(t_{n+1}) = y(t_n) + h \cdot y'(t_n) + \frac{h^2}{2} y''(\xi) \quad \xi \in [t_n, t_{n+1}]$$

$$\begin{aligned} \Rightarrow v_n &= \frac{y_{n+1} - y_n}{h} = \frac{\cancel{y(t_n)} + h y'(t_n) + \frac{h^2}{2} y''(\xi) - \cancel{y(t_n)}}{h} \\ &= y'(t_n) + \frac{h}{2} y''(\xi) \end{aligned}$$

$$\text{fout: } |y'(t_n) - v_n| = \frac{h}{2} y''(\xi) = \frac{h}{2} c \rightarrow \text{linear.}$$

↳ calculate visual zo zijn.

ii)

$$y'(t_n) = v_n = \frac{y_{n+1} - y_{n-1}}{2h}$$

$$y(t_{n+1}) = y(t_n) + h \cdot y'(t_n) + \frac{h^2}{2} y''(t_n) + \frac{h^3}{6} y'''(\xi) \quad \xi \in [t_n, t_{n+1}]$$

$$y(t_{n-1}) = y(t_n) - h \cdot y'(t_n) + \frac{h^2}{2} y''(t_n) - \frac{h^3}{6} y'''(\xi) \quad \xi \in [t_{n-1}, t_n]$$

$$\begin{aligned} y'(t_n) = v_n &= \frac{\cancel{y(t_n)} - h \cancel{y'(t_n)} + \frac{h^2}{2} \cancel{y''(t_n)} + \frac{h^3}{6} y'''(\xi_1)}{2h} \\ &= \frac{(\cancel{y(t_n)} - h \cancel{y'(t_n)} + \frac{h^2}{2} \cancel{y''(t_n)} - \frac{h^3}{6} y'''(\xi_2))}{2h} \\ &= y'(t_n) + \frac{h^2}{12} (y'''(\xi_1) + y'''(\xi_2)) \end{aligned}$$

$$|y'(t_n) - v_n| = \frac{h^2}{6} |y'''(\xi)| = \frac{h^2}{6} c \rightarrow \text{using maple you can see this.}$$

Figure 15: Exercise 2

```

> restart;
> with(plots):
>
> y := t→cos(t)
                                y := t→cos(t)
(1)
> exact_speed := t→-sin(t)
                                exact_speed := t→-sin(t)
(2)
> t_val := evalf( (Pi/2) )
                                t_val := 1.570796327
(3)
>
> forward_difference := (t, h)→ (y(t+h) - y(t))/h
                                forward_difference := (t, h)→ (y(t+h) - y(t))/h
(4)
> central_difference := (t, h)→ (y(t+h) - y(t-h))/(2·h)
                                central_difference := (t, h)→ (y(t+h) - y(t-h))/(2·h)
(5)
>
> forward_error := h→abs(exact_speed(t_val) - forward_difference(t_val, h))
                                forward_error := h→|exact_speed(t_val) - forward_difference(t_val, h)|
(6)
> central_error := h→abs(exact_speed(t_val) - central_difference(t_val, h))
                                central_error := h→|exact_speed(t_val) - central_difference(t_val, h)|
(7)
> loglogplot([central_error(h), forward_error(h)], h = 10-8..1, color = [red,
                                blue])

```

Figure 16: Exercise 2 part 2 Maple

3) $\vec{v}_1 = (2, 3, 0)$ und $\vec{v}_2 = (1, -2, 3)$ inner product = dot product

i)
1) $\vec{u}_1 = \vec{v}_1$

2) $\vec{u}_2 = \vec{v}_2 - \frac{\langle \vec{v}_2, \vec{u}_1 \rangle}{|\vec{u}_1|^2} \cdot \vec{u}_1$

3) $\vec{u}_3 = \vec{v}_3 - \frac{\langle \vec{v}_3, \vec{u}_1 \rangle}{|\vec{u}_1|^2} \cdot \vec{u}_1 - \frac{\langle \vec{v}_3 - \vec{u}_2, \vec{u}_2 \rangle}{|\vec{u}_2|^2} \cdot \vec{u}_2$

< My, kann ich v_1 & $v_2 = v_3 \rightarrow$ brauchen werden doch.

$$\vec{u}_k = \vec{v}_k - \sum_{k=1}^{k-1} \frac{\langle \vec{v}_k - \vec{u}_k, \vec{u}_k \rangle}{|\vec{u}_k|^2} \cdot \vec{u}_k$$

$$\vec{u}_1 = \frac{(2, 3, 0)}{\sqrt{4+9}} = \left(\frac{2}{\sqrt{13}}, \frac{3}{\sqrt{13}}, 0 \right) = \left(\frac{2\sqrt{13}}{13}, \frac{3\sqrt{13}}{13}, 0 \right)$$

$$\vec{u}_2 = \frac{\vec{v}_2 - (\vec{u}_1 \cdot \vec{v}_2) \cdot \vec{u}_1}{\|\vec{v}_2 - (\vec{u}_1 \cdot \vec{v}_2) \cdot \vec{u}_1\|} \quad \text{im maple:}$$

$$\left(\frac{2\sqrt{13}}{13}, \frac{3\sqrt{13}}{13}, 0 \right) \cdot (1, -2, 3)$$

$$= \left(\frac{2\sqrt{13}}{13}, -\frac{6\sqrt{13}}{13}, 0 \right) \cdot \left(\frac{2\sqrt{13}}{13}, \frac{3\sqrt{13}}{13}, 0 \right)$$

$$= \left(\frac{52}{169}, \frac{-18 \cdot 13}{169}, 0 \right)$$

ii) zie maple

iii) dargestellt \vec{u}_1 und \vec{u}_2 diese 2 Basisvektoren
spannen als \vec{v}_1 und \vec{v}_2 kennen we:

$$\vec{y} = (\vec{y} \cdot \vec{u}_1) \cdot \vec{u}_1 + (\vec{y} \cdot \vec{u}_2) \cdot \vec{u}_2$$

$$\text{dann } \vec{y}^\perp = \vec{y} - \vec{y}^\parallel \quad \Rightarrow \quad \vec{y} = \vec{y}^\perp + \vec{y}^\parallel$$

```

restart;
with(plots):
[annulus, arc, arrow, circle, cone, cuboid, curve, cutout, cylinder, disk, dodecahedron, ellipse, ellipticArc, exportplot, extrude, geodata, hemisphere, hexahedron, homothety, hyperbola, icosahedron, importplot, line, octahedron, parallelepiped, pieSlice, point, polygon, polygonbyname,
prism, project, rectangle, reflect, rotate, scale, sector, semitorus, sphere, stellate, tetrahedron, torus, transform, translate, triangulate]
v1 := (2|3|0)

v2 := (1, -2, 3)

u1 := (2*sqrt(13)/13 | 3*sqrt(13)/13 | 0)
u2 := (52/169 | -18/169 | 0)

origin := (0|0|0);
line_v1 := line(origin, v1, color=blue);
line_v2 := line(origin, v2, color=red);
line_u1 := line(origin, u1, color=green);
line_u2 := line(origin, u2, color=yellow);

# Display the lines together
display(line_v1, line_v2, line_u1, line_u2, axes=normal, scaling=constrained);

```

$$v1 := \begin{bmatrix} 2 & 3 & 0 \end{bmatrix}$$

$$v2 := \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix}$$

$$u1 := \left(\frac{2\sqrt{13}}{13} \mid \frac{3\sqrt{13}}{13} \mid 0 \right)$$

$$u2 := \left(\frac{52}{169} \mid -\frac{18}{169} \mid 0 \right)$$

$$u1 := \begin{bmatrix} \frac{2\sqrt{13}}{13} & \frac{3\sqrt{13}}{13} & 0 \end{bmatrix}$$

$$u2 := \begin{bmatrix} \frac{4}{13} & -\frac{18}{13} & 0 \end{bmatrix}$$

$$origin := \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$$

$$line_v1 := CURVES \left(\begin{bmatrix} 0 & 0 & 0 \\ 2 & 3 & 0 \end{bmatrix}, COLOUR(RGB, 0, 0, 1.00000000) \right)$$

$$line_v2 := CURVES \left(\begin{bmatrix} 0 & 0 & 0 \\ 1 & -2 & 3 \end{bmatrix}, COLOUR(RGB, 1.00000000, 0, 0) \right)$$

$$line_u1 := CURVES \left(\begin{bmatrix} 0 & 0 & 0 \\ 0.554700196225229 & 0.832050294337844 & 0 \end{bmatrix}, COLOUR(RGB, 0, 1.00000000, 0) \right)$$

$$line_u2 := CURVES \left(\begin{bmatrix} 0 & 0 & 0 \\ 0.307692307692308 & -1.38461538461538 & 0 \end{bmatrix}, COLOUR(RGB, 1.00000000, 1.00000000, 0) \right)$$

Figure 18: Exercise 3 - plot

```

> restart;
> with(LinearAlgebra) : with(plottools) : with(plots) :
> #i
v_1 := Vector([2, 3, 0])

```

$$v_1 := \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} \quad (1)$$

```

> v_2 := Vector([1, -2, 3])

```

$$v_2 := \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} \quad (2)$$

```

> u_1 :=  $\frac{v_1}{\text{Norm}(v_1, 2)}$ 

```

$$u_1 := \begin{bmatrix} \frac{2\sqrt{13}}{13} \\ \frac{3\sqrt{13}}{13} \\ 0 \end{bmatrix} \quad (3)$$

```

> u_2 :=  $\frac{(v_2 - (u_1 \cdot v_2) \cdot u_1)}{\text{Norm}(v_2 - (u_1 \cdot v_2) \cdot u_1, 2)}$ 

```

$$u_2 := \begin{bmatrix} \frac{21\sqrt{2158}}{2158} \\ -\frac{7\sqrt{2158}}{1079} \\ \frac{3\sqrt{2158}}{166} \end{bmatrix} \quad (4)$$

```

> # ii
> null_vector := Vector([0, 0, 0])

```

$$\text{null_vector} := \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad (5)$$

```

> line_v1 := line(null_vector, v_1, color = purple)
line_v1 := CURVES  $\left( \begin{bmatrix} 0. & 0. & 0. \\ 2. & 3. & 0. \end{bmatrix}, \text{COLOUR}(\text{RGB}, 0.50196078, 0., \right.$ 

```

$$(6)$$

Figure 19: Exercise 3