```
restart;
    with(plots):
y := t \rightarrow \cos(t)
                                                                                                                  (1)
                                               v := t \mapsto \cos(t)
   exact \ speed := t \rightarrow -\sin(t)
                                      exact \ speed := t \mapsto -\sin(t)
                                                                                                                  (2)

ightharpoonup t_val := evalf\left(rac{\mathrm{Pi}}{2}
ight)
                                          t \ val := 1.570796327
                                                                                                                  (3)
> forward\_difference := (t, h) \rightarrow \frac{(y(t+h) - y(t))}{h}
forward\_difference := (t, h) \mapsto \frac{y(t+h) - y(t)}{h}
                                                                                                                  (4)
> central\_difference := (t, h) \rightarrow \frac{(y(t+h) - y(t-h))}{2 \cdot h}
central\_difference := (t, h) \mapsto \frac{y(t+h) - y(t-h)}{2 \cdot h}
                                                                                                                  (5)
   forward\ error := h \rightarrow abs(exact\ speed(t\ val) - forward\ difference(t\ val, h))
     forward error := h \mapsto |exact \ speed(t \ val) - forward \ difference(t \ val, h)|
                                                                                                                  (6)
> central error := h→abs(exact speed(t val) – central difference(t val, h))
       central\ error := h \mapsto |exact\ speed(t\ val) - central\ difference(t\ val, h)|
                                                                                                                  (7)
> loglogplot([central error(h), forward error(h)], h = 10^{-8}..1, color = [red,
         blue])
```

