

# Niclas Scheuer

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## Professional Experience

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### Guidance, Navigation & Control Intern, Rocket Factory Augsburg (RFA) Sep 2024 – Feb 2025

- Took ownership of interdisciplinary engineering projects, interfacing with GNC, OSD, launch, aerodynamics, and regulatory teams to balance technical, operational, and certification requirements.
- Built and validated 6-DOF Simulink models; scripted Monte Carlo failure-injection studies and automated risk-analysis pipelines for day-of-launch readiness.
- Led development of the high-altitude balloon weather station: designed and built the system end-to-end, coordinated with remote teams in Scotland for telemetry integration, and operationalized real-time data delivery.
- Designed and implemented the full GNC launch dashboard from scratch, integrating live launch-site telemetry, weather feeds, and automated FAA/CAA launch-condition evaluation.
- Collaborated with flight safety to certify launch-sequence and dashboard workflows with the CAA.

*Rocket Factory Augsburg is a German launch startup developing the RFA One small-lift orbital launcher. Backed by German satellite manufacturer OHB SE, KKR, and private investors, it has raised €50M+ and was pre-selected in ESA's European Launcher Challenge for potential funding of up to €169M.*

### Lab Supervisor, IDSC Group Onder (ETH Zurich)

Sep 2023 – Sep 2024

- Supervised weekly control systems experiments, maintaining lab equipment, upgrading code, and expanding teaching modules for student use. Mentored 100+ students.

### Robotics Intern, YASKAWA Europe GmbH

Jun – Aug 2021

- Assembled and programmed industrial arms; validated motion routines.

### Software Development Intern, ABB Automation GmbH

Jul – Aug 2020

- Built app features for industrial robot workflows.

## Teaching Experience

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### Head Teaching Assistant, IDSC Group Frazzoli (ETH Zurich)

Feb 2025 – Aug 2025

- Head TA for “Control Systems II” (330 students).
- Led a team of 9 TAs; coordinated weekly recitations.
- Designed and graded weekly programming challenges; controls demonstrations; held office hours.
- Contributed to exam design and evaluation.

### Teaching Assistant, IDSC Group Frazzoli (ETH Zurich)

Jun 2023 – Aug 2024

- TA for “Control Systems I/II”.
- Taught recitations for groups of 30+ students.
- Creation of interactive programming challenges as part of ETH’s Innovendum Project.

## Research & Projects

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### Course Project - Bottleneck Simulation

2025

Authored a conference-style paper on traffic flow using a self-modified Helly-type model; analyzed stability criteria, rigorously proved stabilizability, and demonstrated LQR control design.

### Bachelor’s Thesis, Robotics Systems Lab (ETH Zurich)

2024

Designed and manufactured a wheeled extension for a quadruped robot for hybrid walking/driving motion. Developed robust locomotion policies using reinforcement learning with a teacher–student approach. Extended the ROS2 control stack to support additional wheel actuators and the learned locomotion policies.

<b>K3S Mini-Server</b>	<i>2024</i>
Built a Raspberry Pi cluster for storage, web hosting, and game server applications with automated deployments; also hosted local GitLab and Wikipedia instances.	
<b>Drone Position Controller (Simulink)</b>	<i>2023</i>
Modeled quadrotor dynamics; designed cascaded PID loops; validated tracking in simulation.	
<b>Arduino SVG Plotter</b>	<i>2022</i>
Co-designed and built 2-DOF plotter; implemented G-code style interpreter.	

## Education

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<b>MIT-ETH Exchange</b>	<i>Sep 2025 - Dec 2025</i>
Selected as the sole Mechanical Engineering student from ETH Zürich for a term at MIT.	
<b>ETH Zurich — MSc Mechanical Engineering (Robotics &amp; Control)</b>	<i>Sep 2024 – Jun 2026 (exp.)</i>
Excellence Scholarship and Opportunity Programme (ESOP).	
<b>ETH Zurich — BSc Mechanical Engineering</b>	<i>Sep 2021 – Jun 2024</i>
GPA 5.87/6.0; Graduated with distinction; Double Outstanding Bachelor Award (Top 5).	
<b>International School Frankfurt</b>	<i>– Jul 2021</i>
Bilingual International Baccalaureate 44/45 points, Unweighted GPA: 3.95	

## Skills

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**Programming/Tools:** C++, Python, MATLAB, Simulink, ROS2, Linux  
**Robotics/Mechatronics:** Control design, system ID, MPC, CAD/3D printing, embedded systems  
**CI/CD:** Git, GitLab Pipelines  
**ML (basic):** RL pipelines, TensorFlow/PyTorch (intro)  
**Languages:** English (native), German (native), French (B2)  
**Additional Tools (familiar):** Go, Kafka, WebSockets, FastAPI, Redis, PostgreSQL

## Honors & Awards

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- Excellence Scholarship and Opportunity Programme (ESOP), ETH Foundation 2024–2026
- Outstanding D-MAVT Bachelor Award 2024 (Top 5 overall exams), ETH Zurich 2024
- Outstanding D-MAVT Bachelor Award 2022 (Top 5 first-year exams), ETH Zurich 2022