

Linear Algebra I

Summary of Lectures: Quadratic and Hermitian Forms

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1. **Definition 7.1:** Given a symmetric bilinear form F on a real vector space V , we define a map $Q : V \rightarrow \mathbb{R}$ by $Q(v) = F(v, v)$; Q is called the quadratic form associated with the symmetric bilinear form F .
2. **Lemma 7.2:** Given a symmetric bilinear form F on a real vector space V , and the quadratic form Q associated with F , then

$$F(v, w) = \frac{1}{2} (Q(v + w) - Q(v) - Q(w)) , \quad \forall v, w \in V .$$

3. **Definition 7.3:** Given a conjugate-symmetric sesquilinear form F on a complex vector space V , we define a map $H : V \rightarrow \mathbb{R}$ by $H(v) = F(v, v)$; H is called the Hermitian form associated with the conjugate-symmetric sesquilinear form F .
4. **Lemma 7.4:** Given a conjugate-symmetric sesquilinear form F on a complex vector space V , and the Hermitian form H associated with F , then $\forall v, w \in V$:

$$\begin{aligned} F(v, w) &= \frac{1}{2} (H(v + w) + iH(v - iw) - (1 + i)(H(v) + H(w))) , \\ F(v, w) &= \frac{i}{4} (H(v + w) - iH(v - w) + iH(v - iw) - iH(v + iw)) . \end{aligned}$$

5. **Proposition 7.5:** If Q is a quadratic form on a real vector space V , then

$$Q(\lambda x) = \lambda^2 Q(x) , \quad \forall \lambda \in \mathbb{R} , \text{ and } \forall x \in V .$$

Similarly if H is a Hermitian form on a complex vector space V , then

$$H(\lambda x) = |\lambda|^2 H(x) , \quad \forall \lambda \in \mathbb{C} , \text{ and } \forall x \in V .$$

6. **Proposition 7.6:** Let $V = \mathbb{R}^n$. Then every quadratic form on V is given by a homogeneous function of the coordinates of degree 2. Conversely every homogeneous function of degree 2 of the coordinates is a quadratic form.
7. **Theorem 7.7:** (Sylvester's law of inertia part I.) Let V be an n dimensional real vector space, and let F be a symmetric bilinear form on V . Then there are non-negative integers k and m , and a basis $\{w_1, w_2, \dots, w_n\}$ of V such that:

$$\begin{aligned} F(w_i, w_j) &= 0 \quad \forall i \neq j , \\ F(w_i, w_i) &= 1 \quad \text{for } i \leq k , \\ F(w_i, w_i) &= -1 \quad \text{for } k < i \leq k + m , \\ F(w_i, w_i) &= 0 \quad \text{for } k + m < i . \end{aligned}$$

8. **Lemma 7.8:** Let F be a symmetric bilinear form on a real vector space V , and suppose that $F(v, v) = 0 \forall v \in V$. Then $F(v, w) = 0 \forall v, w \in V$.
9. **Lemma 7.9:** Let F be a bilinear form on a real vector space V and suppose that w_1, w_2, \dots, w_n are vectors from V which are orthogonal with respect to F . For all scalars $\lambda_i \in \mathbb{R}$ if

$$\lambda_1 w_1 + \lambda_2 w_2 + \dots + \lambda_n w_n = 0$$

then $\lambda_j = 0 \forall j$ such that $F(w_j, w_j) = 0$.

10. **Lemma 7.10:** Let F be a bilinear form on a real vector space V and suppose that w_1, w_2, \dots, w_k are vectors from V which are orthogonal with respect to F , and that $F(w_i, w_i) \neq 0 \forall i \leq k$. Then $\forall v \in V \exists u \in V$ such that $F(w_i, u) = 0 \forall i \leq k$, and v is a linear combination of w_1, w_2, \dots, w_k, u . I.e.

$$V = \text{span}(U \cup \{w_1, w_2, \dots, w_k\})$$

where

$$U = \{u \in V : F(w_i, u) = 0, \forall i \leq k\}.$$

11. **Theorem 7.11:** (Sylvester's law of inertia part II.) Let V be an n dimensional real vector space, and let F be a symmetric bilinear form on V , with two diagonal matrix representations \mathbf{A} and \mathbf{A}' , as in theorem 7.7, with respect to the bases e_1, e_2, \dots, e_n and e'_1, e'_2, \dots, e'_n of V . If \mathbf{A} has k positive diagonal entries and m negative diagonal entries, and \mathbf{A}' has k' positive diagonal entries and m' negative diagonal entries, then $k = k'$ and $m = m'$.
12. **Definition 7.12:** Let V be an n dimensional real vector space, and let F be a symmetric bilinear form on V , with a diagonal matrix representation \mathbf{A} , with k and m as in theorem 7.7.

$k + m$ is the rank of F .

$k - m$ is the signature of F .

13. **Proposition 7.13:** With the same notation as definition 7.12, F is positive definite (i.e. is an inner product) iff $k = n$ and $m = 0$.
14. **Lemma 7.14:** Suppose F is a symmetric bilinear form on a real vector space V , and let v_1, v_2, \dots, v_n be a basis of V . If $F(v_i, v_i) > 0 \forall i$ and $F(v_i, v_j) > 0 \forall i \neq j$ then F is positive definite.