### Introduction

In this report, the issue "Validation accuracy is incorrect when using fully convolutional models #24" is explored by uncovering the importance of normalization methods as for the 3D-CNN (lee model) [1].

At first, the 3D-CNN 's architecture is fixed as Table 4. Note that, there are two attentive points. Firstly, the author seemed to employ 3D depthwise convolutional layers instead of common 3D convolutional layers, which can be viewed from some discussions of the original paper (see Page 6, Paragraph 3, Line 5-7 and Page 18, Paragraph 3, Line 1-3). Secondly, the author seemed to use two fully connected layers: the first one is named as the F1 layer and the second one is named as the Classification layer, as the Feature Volume of the F1 layer is set to 144 rather than the class number of 9.

Table 4. Architecture of 3D-CNN in Pavia University scene.

Layer	Kernel Size	Kernel Number	Stride	Output Size	Feature Volumes
Input	-	-	-	$5 \times 5 \times 103$	1
Ĉ1	$3 \times 3 \times 7$	2	1	$3 \times 3 \times 97$	2
C2	$3 \times 3 \times 3$	4	1	$1 \times 1 \times 95$	8
F1	-	-	-	$1 \times 1 \times 1$	144
Classification	-	-	-	$1 \times 1 \times 1$	9

Secondly, it is probably to assume that the author resorted to a Band-wise Minmax Norm (*BMN*) before feeding HSI cubes into 3D-CNN, which consequently lead to this low validation accuracy issue when inappropriate normalization method is used. In order to testify to this assumption, I have conducted experiments on the commonly used Indian Pines data set and Pavia University data set using six normalization methods including *None*, Sample-wise L2 Norm (*SL2N*), Band-wise Minmax Norm (*BMN*), Band-wise Standard Norm (*BSN*), Imagewise Minmax Norm (*IMN*), and Image-wise Standard Norm (*ISN*), respectively [2]. These normalizations are introduced as follows.

#### PS:

None: Applying none preprocessing.

SL2N: Normalizing with a unit Euclidean norm along each sample.

BMN: Converting the dynamics to [0, 1] along each band.

BSN: Normalizing first- and second-order moments along each band.

*IMN*: Converting the dynamics to [0, 1] **along the whole image**.

ISN: Normalizing first- and second-order moments along the whole image.

In this report, the following experiment are conducted using **DeepHyperX** with GeForce GTX 1070 (8GB), Intel Xeon E3 CPU, and 16 GB RAM.

## Experiment 1

In the first experiment, we attempted to uncover the significant difference between different normalization methods for 3D-CNN. For the hyperparameter setting, the iteration is set to

20000 for saving running time, thus the training epoch is the quotient of two numbers: the first one is the product of the iteration and the batch size, and the second one is the number of training samples, and others are set referred to the original paper. Then we compared above six normalization methods for 3D-CNN on the two data sets. The classification accuracies on the Indian Pines data set are reported on Table 1, and that on the Pavia University data set are reported on Table 2. As we can see, the *BMN* and the *BSN* probably lead to a better accuracy while the *None* may result in the divergence of training process of 3D-CNN using the aforementioned experimental setting.





set (50% labeled sample per class used for training)						
	Classification result	Training loss	Validation accuracy			
None + 3D-CNN	Accuracy : 43.599% 	Training loss	Validation accuracy			
SL2N + 3D-CNN	Accuracy : 93. 800% 	Training loss	Validation accuracy			
BMN + 3D-CNN	Accuracy : 97.012% 	Training loss	Validation accuracy			
BSN + 3D-CNN	Accuracy : 99.191% 	Training loss	Validation accuracy			
IMN + 3D-CNN	Accuracy : 97.391% F1 scores : Undefined; nam Asphalt: 0.987 Mendows: 0.985 Gravel: 0.905 F1 f1	Training loss	Training loss			
ISN + 3D-CNN	Accuracy : 98.719% 	Training loss	Validation accuracy			

Table 2: Classification accuracies using different normalizations for the Pavia University data

### **Experiment** 2

In the second experiment, our goal is to replicate the results in paper [1] on the two data sets. For the hyperparameter setting, the iteration is set to 100000 referred to the original paper. We employ the *BMN* and the *BSN* respectively as they perform better in *Experiment 1*. The ultimate results are listed in **Table 3**. Note that our results are slightly higher than those of the original paper. For example, in our experiments, 3D-CNN with *BMN* obtained an OA of 99.20% which is 0.13% higher than the OA of 99.07% [1] on the Indian Pines data set, and 3D-CNN with *BMN* obtained an OA of an OA of 99.61% which is 0.22% higher than the OA of 99.39% [1] on the Pavia University data set. This phenomenon may be explained by several reasons: firstly, the randomness existed in the training process and sample selection; secondly, the different initialization of parameters; thirdly, the different numbers of training samples per class. Regardless of this exceptional improvement, this experiment has successfully replicated the results of 3D-CNN on the two data sets, and demonstrated the necessity of choosing an appropriate normalization for 3D-CNN.

training)							
Indian Pines	Classification result	Training loss	Validation accuracy				
BMN + 3D-CNN	Lecuracy : 99.220% 	Training loss	Validation accuracy				
BSN + 3D-CNN	<pre>Accuracy : 08.060h </pre>	Training loss	Validation accuracy				
Pavia University	Classification result	Training loss	Validation accuracy				
BMN + 3D-CNN	Accuracy : 99.607% F1 scores : Uddefined: nan Asphalt: 0.998 Meadows: 0.999 Gravel: 0.982 Treves: 0.982 Prese: 0.982 Bare Soil: 0.998 Bitumon: 0.992 Solf=Blocking Bricks: 0.988 Shadows: 0.999 Kappa: 0.995	Training loss	Validation accuracy				
BSN + 3D-CNN	Accuracy : 99.649% F1 scores : Undefined: nan Acphalt: 0.997 Meadows: 0.999 Graves: 0.990 Treves: 0.980 Bitument: 0.997 Stilfelooking Bricks: 0.984 Shadows: 1.000 Kappa: 0.995	Training loss	Validation accuracy				

Table 3: Classification accuracies for the two data set (50% labeled sample per class used for training)

## Conclusion

In summary, even though the original author clearly delineated that 3D-CNN does not rely on any preprocessing, choosing a suitable normalization method is vital for its training process. In this circumstance, **DeepHyperX** tools can realize similar or even higher accuracy of 3D-CNN if an appropriate normalization is used. In a word, the discussed issue may be the consequence of an unsuitable normalization method.

# Reference

[1] Li Y, Zhang H, Shen Q. Spectral–spatial classification of hyperspectral imagery with 3D convolutional neural network[J]. Remote Sensing, 2017, 9(1): 67.

[2] N. Audebert, B. Le Saux and S. Lefevre, "Deep Learning for Classification of Hyperspectral Data: A Comparative Review," in *IEEE Geoscience and Remote Sensing Magazine*, vol. 7, no. 2, pp. 159-173, June 2019, doi: 10.1109/MGRS.2019.2912563.